

CALCULATION OF THE ELASTIC MODULI
of a
TWO LAYER PAVEMENT SYSTEM
from
MEASURED SURFACE DEFLECTIONS

by

Frank H. Scrivner
Chester H. Michalak
William M. Moore

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A System Analysis of Pavement Design
and Research Implementation
Research Study Number 1-8-69-123

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Preface

This is the sixth report issued under Research Study 1-8-69-123, A System Analysis of Pavement Design and Research Implementation. The study is being conducted jointly by principal investigators and their staffs in three agencies -- The Texas Highway Department, The Center for Highway Research at Austin and The Texas Transportation Institute -- as a part of the cooperative research program with the Department of Transportation, Federal Highway Administration.

Previous reports emanating from Study 123 are the following:

Report No. 123-1, "A Systems Approach Applied to Pavement Design and Research," by W. Ronald Hudson, B. Frank McCullough, Frank H. Scrivner, and James L. Brown, describes a long-range comprehensive research program to develop a pavement systems analysis and presents a working systems model for the design of flexible pavements.

Report No. 123-2, "A Recommended Texas Highway Department Pavement Design System Users Manual," by James L. Brown, Larry J. Buttler, and Hugo E. Orellana, is a manual of instructions to Texas Highway Department personnel for obtaining and processing data for flexible pavement design system.

Report No. 123-3, "Characterization of the Swelling Clay Parameter Used in the Pavement Design System," by Arthur W. Witt, III, and B. Frank McCullough, describes the results of a study of the swelling clay parameter used in pavement design system.

Report No. 123-4, "Developing A Pavement Feedback Data System," by R. C. G. Haas, describes the initial planning and development of a pavement feedback data system.

Report No. 123-5, "A Systems Analysis of Rigid Pavement Design," by Ramesh K. Kher, W. R. Hudson, and B. F. McCullough, describes the development of a working systems model for the design of rigid pavements.

The authors are indebted to Messrs. Robert E. Long and James L. Brown, both of the Texas Highway Department, for furnishing the pavement deflection data used in the sample problems presented in Chapter 6.

The opinions, findings and conclusions expressed in this publication are those of the authors and not necessarily those of the Department of Transportation, Federal Highway Administration.

Abstract

This report gives the theoretical background and a description of a new computer program, ELASTIC MODULUS, capable of converting deflections measured by a Dynaflect on the surface of a highway pavement-subgrade (two-layer elastic) system, to the elastic moduli of the pavement and subgrade. Included with the report are instructions for the use of the program, a complete documentation of its operation, and the solutions of several example problems.

Summary

A sub-system of the flexible pavement design system described in the first report of Study 123 (see Preface), estimates the life of a trial design based solely on surface deflections computed from an empirical equation. In an attempt to improve the reliability of this sub-system (a primary objective of Study 123) it is intended, eventually, to base estimates of pavement life on stresses and strains computed from elasticity theory at critical points within the pavement structure. The use of elasticity theory, however, requires a knowledge of the in situ values of the elastic modulus, E , of each of the pavement materials in common use, as well as the subgrades, in the various Highway Department Districts.

According to elasticity theory, the moduli of a pavement and its subgrade can be estimated from surface deflections rather easily, provided the pavement structure above the subgrade is predominately a single material of known thickness, and the subgrade is reasonably uniform in stiffness to a considerable depth.

For determining the elastic moduli of the two materials composing such a pavement, a mathematical process has been developed, computerized, and is made available herewith to the Texas Highway Department. The method envisions the use of the Dynaflect for making the necessary measurements of surface deflections. The data collection and processing procedures, and the output format of the computer program, are exactly the same as those now employed in estimating the "stiffness coefficients"

used in the present version of the flexible pavement design system, with the following exceptions:

1. The program described in this report prints elastic moduli in lieu of stiffness coefficients.
2. The program prints a verbal description of both pavement and subgrade, instead of the pavement alone.

The computer program has been given the name ELASTIC MODULUS. By a slight modification, it can be used to predict Dynaflect deflections, given the pavement thickness and the moduli of pavement and subgrade. In this form the predictions of ELASTIC MODULUS were compared with those of another program, BISTRO*. Agreement was excellent, except in the instance of a pavement with a modulus much smaller than that of its subgrade, a case not likely to arise often in practice.

To illustrate the results obtained when using ELASTIC MODULUS to estimate pavement and subgrade moduli, Dynaflect data taken at several points on seven short sections of flexible pavements near College Station, Texas, were processed by the program. The ordering of the resulting pavement moduli, as judged by the verbal descriptions of the materials and local knowledge of their service performance, appeared reasonable. In the case of the subgrade moduli, the range was too small to permit a judgement of the validity of the results.

When using the results of the program to characterize materials in a pavement design system based on elasticity theory, it is recommended that the values of the computer moduli be halved before use. This recommendation is based on extensive field correlation studies between deflections produced by the Dynaflect and those produced by heavily loaded vehicles.

* Used by courtesy of Koninklijke/Shell-Laboratorium, Amsterdam.

Implementation Statement

The program ELASTIC MODULUS was written in the expectation that eventually the Texas Highway Department's Flexible Pavement Design System will, in the prediction of pavement life, use the stresses, strains and displacements computed throughout the structure from the theory of linear elastic layered systems, instead of solely the surface deflections calculated by the present empirical equation. When such a change occurs in the design system, in situ values of elastic moduli will be needed. This need probably can be met, at least to some degree, by the computer program described herein.

The published version of this report may be obtained by addressing your request as follows:

R. L. Lewis, Chairman
Research & Development Committee
Texas Highway Department - File D-8
11th and Brazos
Austin, Texas 78701 (Phone 512/475-2971)

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1. Introduction

Recently the Texas Highway Department began to implement, on a trial basis, a flexible pavement design system that characterizes each material in a proposed or existing pavement structure by a so-called "stiffness coefficient" (1, 2). The in situ coefficient for a material proposed for a new pavement is found from Dynaflect deflection data (3, 4) taken on existing highways that can be assumed to consist essentially of two layers -- a subgrade layer (regarded in theory to be infinitely thick), and a pavement layer composed predominately of a single material (for example, a base material with a surface treatment). The Dynaflect data are then used in an empirical equation that yields a composite stiffness coefficient for the pavement material or materials, and another (usually smaller) coefficient for the subgrade or foundation (1, 5). The coefficients, which vary numerically from about 0.15 for a weak, wet clay to about 1.00 for asphaltic concrete, are calculated by means of a Texas Highway Department computer program, STIFFNESS COEFFICIENT (6). The coefficients, along with other pertinent data, are used in the design process to predict a certain characteristic -- the "surface curvature index" -- of the deflection basin of a trial design composed of the tested materials, and from this characteristic, to predict the life of the design.

This report gives the theoretical background and a description of a new computer program, given the name ELASTIC MODULUS, that accepts and prints the same Dynaflect and other data (identification, location,

special comments, etc.) as the program STIFFNESS COEFFICIENT, but computes and prints out the in situ values of Young's modulus of pavement and subgrade instead of their stiffness coefficients. Linear elastic theory, with Poisson's ratio set to 1/2 for both layers, is used in the computations.

The program ELASTIC MODULUS was written in the expectation that eventually the Texas Highway Department's Flexible Pavement Design System will, in the prediction of pavement life, use the stresses, strains and displacements computed throughout the structure from the theory of linear elastic layered systems, instead of solely the surface deflections calculated by the present empirical equation (7). When such a change occurs in the design system, in situ values of elastic moduli will be needed. This need probably can be met, at least to some degree, by the computer program described herein.

2. Surface Deflection Equation for Two Layer Elastic System

This chapter describes the geometry of the Dynaflect loading and develops the applicable equation for surface deflections due to a point load acting perpendicular to the horizontal surface of a half-space consisting of two horizontal layers of infinite lateral extent.

2.1 The Loading Device (Dynaflect)

Through two steel wheels the trailer-mounted Dynaflect exerts two vertical loads, separated by 20 inches and varying sinusoidally in phase at 8 Hz, as indicated in Figure 1. The total load, exerted by rotating weights, varies from 500 pounds upward to 500 pounds downward. The upward thrust is overcome by the dead weight of the trailer so that the load wheels are always in contact with the pavement. The load-pavement contact areas are small and are considered to be points, rather than areas, in order to simplify the mathematics.

From the symmetry of Figure 1 it can be seen that one load of 1000 pounds can be substituted for the two loads shown, without affecting the vertical motion at points along the line of sensors. For this reason, in what follows only one point load, P , of 1000 lbs., will be considered to be acting on the surface of the pavement.

2.2 List of Symbols

Following is a list of the mathematical symbols used in this report. A list of FORTRAN symbols used in ELASTIC MODULUS, together with their mathematical equivalents, will be found in Appendix 1.

P = vertical force acting at a point in the horizontal surface of a two-layer elastic half space.

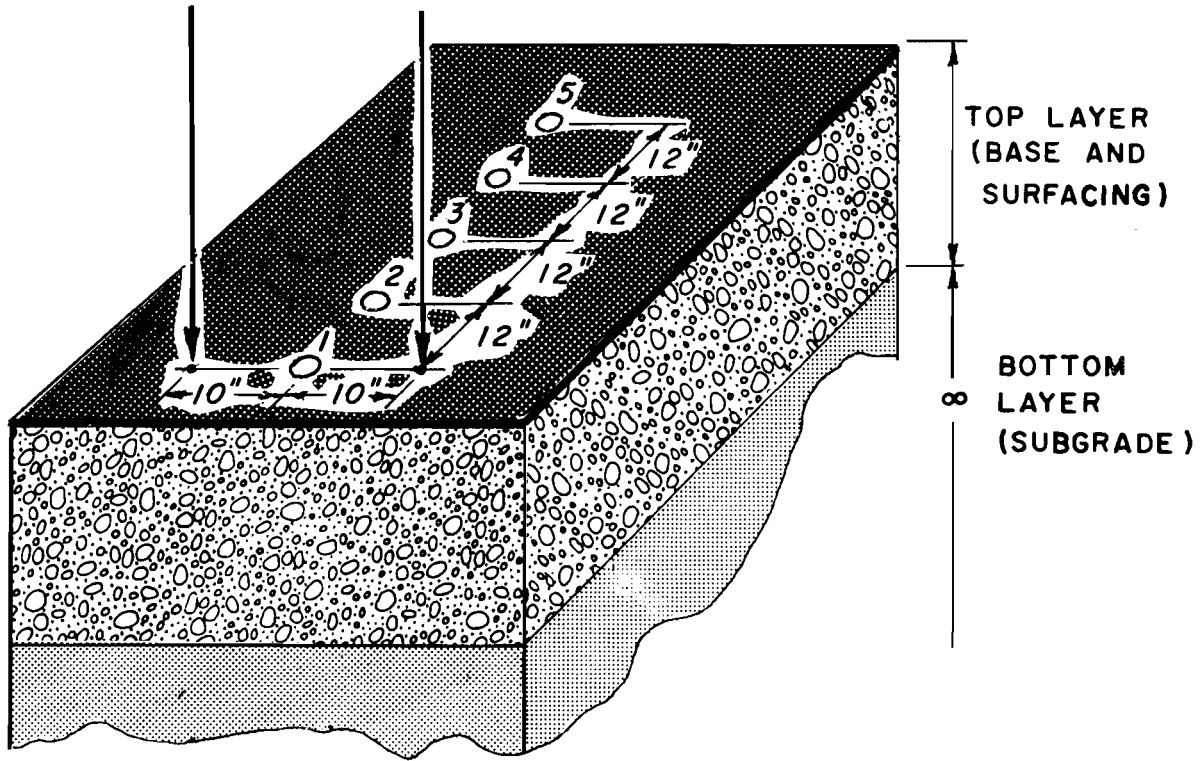


Figure 1: Relative position of Dynaflect loads and sensors. The sensors are usually placed in the outer wheel path, on a line paralleling the center line of the highway.

h = thickness of upper layer.

E_1 = Young's modulus of upper layer.

E_2 = Young's modulus of lower layer.

w = the vertical displacement of a point in the surface.

r, z = cylindrical coordinates. (The tangential coordinate, θ , does not appear because only one load is used as explained on page 3, and the resulting vertical deflections are symmetrical about the z -axis.)

The load P acts downward at the point $r = 0, z = 0$. Positive z is measured downward.

m = a parameter.

$x = mr/h$.

$J_0(x)$ = Bessel Function of the first kind and zero order with argument x .

V = a function of m and N (see Equations (1) and (2)).

N = a function of E_1 and E_2 (see Equation (2a)).

2.3 Development of the Equation

A vertical load, P (Figure 2), is applied at the point, 0 , in the horizontal, plane surface of a two-layer elastic system. The point of load application is the origin of cylindrical coordinates, r and z . Positive values of z are measured vertically downward.

The thickness of the upper layer is h and its elastic modulus is E_1 . The thickness of the lower layer is infinite, and its elastic modulus is E_2 . Poisson's ratio for both layers is taken as $1/2$.

It can be shown from Burmister's early work in elastic layered systems (8) that the deflection, w , of a surface point at the horizontal distance, r , from the point, 0 , is related to the constants, h, E_1 and E_2 , by the equation

$$\frac{4\pi E_1}{3P} wr = \int_{x=0}^{\infty} V \cdot J_0(x) dx, \quad (1)$$

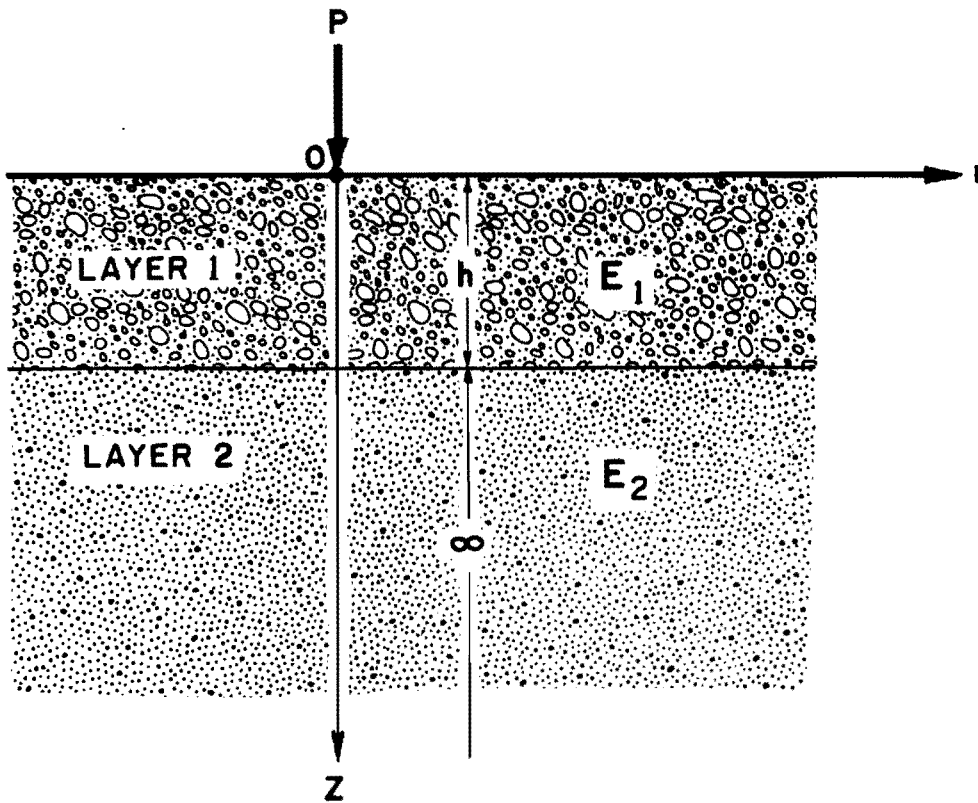


FIGURE 2 - Two-layer elastic system loaded at a point on the surface.

where $x = mr/h$, (1a)

$m =$ a parameter,

$$V = \frac{1 + 4Nme^{-2m} - N^2e^{-4m}}{1 - 2N(1 + 2m^2)e^{-2m} + N^2e^{-4m}}, \quad (2)$$

and
$$N = \frac{1 - E_2/E_1}{1 + E_2/E_1} = \frac{E_1 - E_2}{E_1 + E_2} \quad (2a)$$

2.4 An Approximation of the Deflection Equation

The integration indicated in Equation 1 must be performed by numerical means. This task is made easier by taking advantage of the fact that (1) as x varies from zero to infinity in the integration process, m varies over the same range, while r and h are held constant, (2) as m varies from zero to infinity, the function V varies monotonically from E_1/E_2 to 1.0 and (3) for practical ranges of the ratio E_2/E_1 , V approaches its limiting value of 1.0 at surprisingly low values of m . For example, it was found, as indicated in Table 1, that if m is set equal to 10, and E_2/E_1 is restricted to the range from zero to 1000, then $V = 1.0 \pm .000001$. Thus, we conclude that for practical purposes, when m is in the range from zero to 10, V is given by Equation 2, and when m is in the range from 10 to infinity, $V = 1$. This approximation can be expressed algebraically as follows:

$$\int_{x=0}^{\infty} V \cdot Jo(x) dx \sim \int_{x=0}^{10r/h} V \cdot Jo(x) dx + \int_{x=10r/h}^{\infty} Jo(x) dx \quad (3)$$

The second integral on the right side of Equation 3 is equivalent to the difference of two integrals, as indicated below:

$$\int_{x=10r/h}^{\infty} Jo(x) dx = \int_{x=0}^{\infty} Jo(x) dx - \int_0^{10r/h} Jo(x) dx = 1 - \int_{x=0}^{10r/h} Jo(x) dx. \quad (4)$$

Table 1: Values of the function, V, corresponding to selected values of the parameter m and the modular ratio E_2/E_1 .

m	E_2/E_1							
	0	.001	.01	.1	1	10	100	1000
0.0	Infinite	1000	100	10	1	0.1	0.01	0.001
0.1	6012.	855.6	98.14	9.967	1	0.1006	0.01065	0.001655
0.5	50.49	47.94	32.98	8.056	1	0.1542	0.06727	0.05854
1.0	7.382	7.363	6.826	4.112	1	0.3250	0.2491	0.2414
3.0	1.137	1.137	1.134	1.110	1	0.9058	0.8888	0.8869
5.0	1.006	1.006	1.005	1.005	1	0.9955	0.9946	0.9945
10.0	1.000001	1.000001	1.000001	1.000001	1	0.9999993	0.9999991	0.9999991
Inf.	1.	1.	1.	1.	1	1.	1.	1.

By making the obvious substitution from Equation 4 in Equation 3 we have

$$\int_{x=0}^{\infty} V \cdot J_0(x) dx \approx \int_{x=0}^{10r/h} V \cdot J_0(x) dx + 1 - \int_{x=0}^{10r/h} J_0(x) dx, \text{ or}$$

$$\int_{x=0}^{\infty} V \cdot J_0(x) dx \approx 1 + \int_{x=0}^{10r/h} (V - 1) J_0(x) dx.$$

Comparing the last approximation, above, with Equation 1, we arrive at the approximation,

$$\frac{4\pi E_1}{3P} wr \approx 1 + \int_{x=0}^{10r/h} (V - 1) J_0(x) dx \quad (5)$$

where all symbols are as previously defined.

It is of interest to note from Equation 2 that $V = 1$ when $E_2 = E_1$ (that is, when the layered system of Figure 1 degenerates into a homogeneous elastic half-space), and that for this case Equation 5 reduces to

$$\frac{4\pi E_1}{3P} wr \approx 1.$$

The correct equation for this case, according to Timoshenko (9), is

$$\frac{4\pi E_1}{3P} wr = 1.$$

Thus, for the homogeneous case Equation 5 becomes exact.

3. Numerical Integration of Deflection Equation

To use Equation 5 it was necessary to employ some form of numerical integration process for evaluating the integral in that equation. The method known as Simpson's Rule was selected (11). This procedure required that a small but finite increment, Δx , be chosen, and that the integral be calculated at $x = 0$, $x = \Delta x$, $x = 2\Delta x$, etc. over the specified range of integration. The smaller the value assigned to Δx , the greater would be the accuracy of the result; on the other hand, the larger the value of Δx , the less would be the required computer time. Thus a compromise between computer time and accuracy had to be made.

Noting that the integral of Equation 5 is the product of the factor, $V - 1$, which is a function of m and N , and $J_0(x)$, which is a function of $x = mr/h$ (see Equation 1a), two safeguards against inaccurate results had to be incorporated into the program: (1) Δm had to be small enough to insure a sufficiently accurate numerical representation of the function V , and (2) Δx had to be small enough to insure an accurate numerical representation of the function $J_0(x)$.

After some study of the numerical values of V given in Table 1, and of the values of $J_0(x)$ available from numerous sources (see, for example, Reference 10), the following rules were incorporated into the computer program for solving Equation 5:

- (a) In the range $m = 0$ to $m = 3$, $\Delta m \leq 0.01$. (In FORTRAN, DELM1 .LE. XK1.)
- (b) In the range $m = 3$ to $m = 10$, $\Delta m \leq 0.10$. (In FORTRAN, DELM2 .LE. XK2.)

(c) In the entire range of x from 0 to $10r/h$, not less than 61 values of $J_0(x)$ are computed as x increases from any value $x = c$, to the value $x = c + 3$. This also insures that the number of values of $J_0(x)$ computed between successive zeroes of that alternating function exceeds 61. (In FORTRAN, $XNO = 61$.)

Since Δx and Δm are interdependent according to Equation 1(a), that is,

$$\Delta x = \Delta m \cdot r/h, \quad (1b)$$

the computer program had to insure that the rules (a), (b) and (c) given above were consistent with Equation 1(b). The details of how this was done may be found in the accompanying listing of the computer program and its flow diagram. Suffice it to say here that the accuracy of the solutions obtained (or the computer time used) can be changed by altering the values assigned to the FORTRAN variables $XK1$, $XK2$ and XNO mentioned in (a), (b) and (c) above and further defined in Appendix 1.

To explain briefly how Equation 5 is used in ELASTIC MODULUS to find pavement and subgrade moduli, consider the following:

Suppose that w_1 has been measured on the surface of a pavement structure at the distance r_1 from either Dynaflect load, and w_2 at the distance r_2 . The thickness, h , of the pavement is known.

Now let F represent the function on the right side of Equation 5. We may then write two equations:

$$\frac{4\pi E_1}{3P} w_1 r_1 \approx F(E_2/E_1, r_1/h) \quad (6a)$$

$$\frac{4\pi E_1}{3P} w_2 r_2 \approx F(E_2/E_1, r_2/h) \quad (6b)$$

By dividing Equation 6a by 6b we obtain

$$\frac{w_1 r_1}{w_2 r_2} = \frac{F(E_2/E_1, r_1/h)}{F(E_2/E_1, r_2/h)}, \quad (7)$$

where E_2/E_1 is the only unknown.

By a convergent process of trial and error, a value of E_2/E_1 usually can be found that satisfies Equation 7 to the desired degree of accuracy. After this has been done, E_1 is calculated from Equation (6a), and finally E_2 is found from the relation

$$E_2 = E_1 \left(\frac{E_2}{E_1} \right).$$

4. Accuracy Check

As mentioned earlier (Section 2.1) a point load was substituted in ELASTIC MODULUS for the area loads exerted by the Dynaflect. To check the effect of this assumption on accuracy, as well as the effect of the approximations described in Chapters 2 and 3, the following procedure was followed.

The contact area of each load wheel was measured approximately by inserting light sensitive paper between each wheel and the pavement, running the Dynaflect for a short time in strong sunlight, then removing the paper and measuring the unexposed areas.

From these measurements it was concluded that each 500 lb. load could be represented by a uniform pressure of 80 psi acting on a circular area with a radius of 1.41 inches. Furthermore, because of the symmetry of the load-geophone configuration, it was reasoned that the effect of both loads could be represented by a pressure of 160 psi acting on one circular area of the radius given above (1.41 inches).

The surface deflections w_1 and w_2 (see Figure 1) occurring at the distances $r = 10$ inches and $r = \sqrt{10^2 + 12^2} = 15.62$ inches from the center of the circle, could then be calculated from the program BISTRO, written by Koninklijke/Shell-Laboratorium, Amsterdam, and compared with deflections obtained by the program ELASTIC MODULUS modified slightly to receive as inputs E_1 , E_2 , h and r and to print out w_1 and w_2 .

The two programs were compared as described above over a range of the ratio, E_1/E_2 , from 0.1 to 1000, and a range of the thickness, h , from 5 to 40 inches. The results are recorded in Table 2 in the same manner that Dynaflect deflections are recorded -- that is, in milli-inches to two decimal places.

The table shows near perfect agreement in the range $1 \leq E_1/E_2 \leq 1000$ for which the pavement is stiffer than the subgrade. On the other hand, with the subgrade much stiffer than the pavement ($E_1/E_2 = 0.1$ in Table 2), the agreement was not as good. In addition, up-heavals occurred, as indicated by the negative signs of some of the deflections. In these cases the deflected surface is very irregular and Dynaflect data from such a pavement would be difficult to interpret since this device is not equipped to distinguish phase differences between load and geophone.

Since most pavements of the type illustrated in Figure 1 are obviously intended to be stiffer than their subgrades, and in view of the fact that irregular basin shapes are seldom encountered in practice, it is concluded from the data presented in Table 2 that ELASTIC MODULUS represents the theory of elasticity with sufficient accuracy to accomplish the purpose for which it was designed.

Table 2: Comparison of ELASTIC MODULUS with BISTRO

E ₁ (psi)	E ₂ (psi)	E ₁ /E ₂	h (in.)	Computed Deflections (mils)			
				w ₁		w ₂	
				ELASTIC MODULUS	BISTRO	ELASTIC MODULUS	BISTRO
10,000,000	10,000	1,000	5	0.99	0.99	0.93	0.93
			10	0.52	0.52	0.51	0.51
			20	0.26	0.26	0.26	0.26
			40	0.13	0.13	0.13	0.13
1,000,000	10,000	100	5	1.86	1.85	1.55	1.55
			10	1.07	1.07	0.99	0.99
			20	0.57	0.57	0.55	0.55
			40	0.30	0.30	0.30	0.30
100,000	10,000	10	5	2.65	2.65	1.77	1.77
			10	1.94	1.93	1.56	1.56
			20	1.20	1.20	1.06	1.06
			40	0.74	0.74	0.64	0.64
10,000	10,000	1	5	2.39	2.39	1.53	1.53
			10	2.39	2.39	1.53	1.53
			20	2.39	2.39	1.53	1.53
			40	2.39	2.39	1.53	1.53
1,000	10,000	0.1	5	-0.11	-0.40	0.85	0.86
			10	-0.15	-0.06	-0.58	-0.57
			20	7.45	7.52	1.30	1.32
			40	14.9	14.9	6.68	6.69

Note: ELASTIC MODULUS: Point load of 1000 lbs.

BISTRO: Circular loaded area with radius of 1.41 in., pressure of 160 psi, load of 1000 lbs.

Both programs: Vertical deflection computed at the points $r = 10''$, $z = 0$ and $r = 15.62''$, $z = 0$.

5. Non-Unique Solutions

To investigate the possibility that the use of the program could lead to more than one solution -- that is, to more than one value of the ratio E_1/E_2 -- or perhaps to no solution at all in some cases, ELASTIC MODULUS was modified slightly to receive as inputs selected values of E_1/E_2 and the layer thickness h , and to compute the corresponding ratio, w_1r_1/w_2r_2 (see Equation 7). The results of these computations were plotted as contours of the layer thickness, h , in Figure 3. The range of input data was limited to the largest range that might be expected from field deflection tests made on real highways of the type illustrated in Figure 1.

To facilitate interpretation, Figure 3 has been divided into four quadrants as indicated on the graph. For example, by referring to quadrants I and II it can be seen that if the measured inputs to ELASTIC MODULUS satisfy the inequalities $w_1r_1/w_2r_2 > 1$ and $h \geq 9.2''$ (see the dashed contour), a unique solution satisfying the inequality $E_1/E_2 < 1$ exists, and in this case the program finds and prints the two moduli. If, on the other hand, $w_1r_1/w_2r_2 > 1$ (as before) but $h < 9.2''$, the possibility of two solutions exists -- or of no solution at all if the measured ratio w_1r_1/w_2r_2 is sufficiently great. In this case, i.e. $w_1r_1/w_2r_2 > 1$ and $h < 9.2''$, the program abandons the search for a solution and prints the message "NO UNIQUE SOLUTION".

By examining quadrants III and IV, it can be concluded that if $w_1r_1/w_2r_2 < 1$ and $h \geq 9.2''$, a unique solution satisfying the inequality $E_1/E_2 > 1$ exists. In this case the program finds the solution and prints the two moduli. On the other hand if $w_1r_1/w_2r_2 < 1$ as before, but $h < 9.2''$ there are two possible solutions, one in quadrant III for $E_1/E_2 > 1$, and another

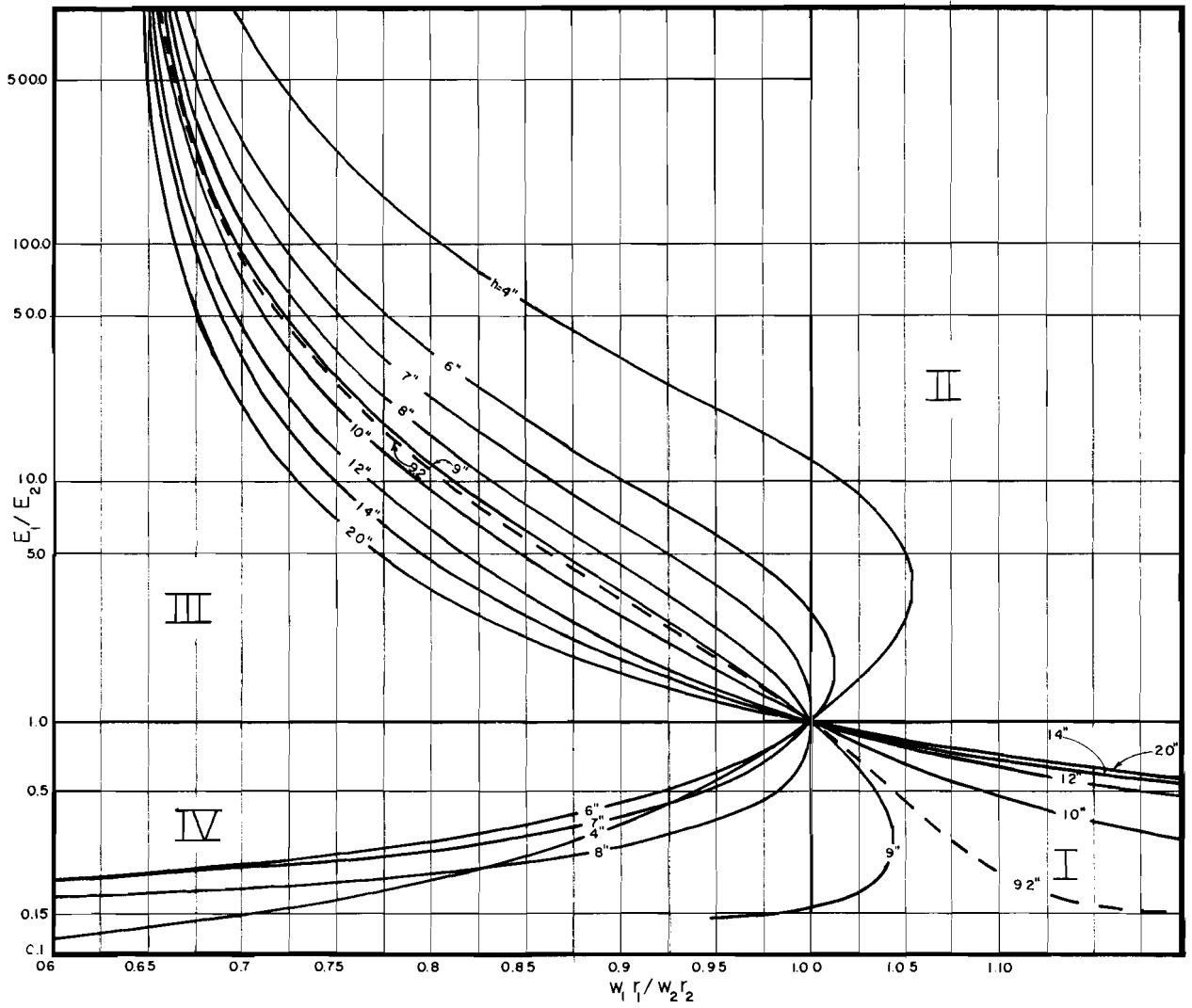


Figure 3: Contours of pavement thickness, h , plotted as a function of the ratios E_1/E_2 and w_1r_1/w_2r_2 .

in quadrant IV for $E_1/E_2 < 1$. Of these two solutions the one in quadrant III, representing a pavement whose elastic modulus is greater than that of the subgrade, is the more probable; therefore, the program seeks out the quadrant III solution, prints the corresponding moduli, and ignores the quadrant IV solution.

The information deduced above from Figure 3, and used in the control of the program ELASTIC MODULUS, is summarized in Table 3.

Table 3: Summary of Information from Figure 3 Used
in the Control of the Program, ELASTIC MODULUS

Measured Input Data		Unique Solution	Layer Having The Greater Modulus	Program Printout
$w_1 r_1 / w_2 r_2$	Thickness, h (in.)			
Greater than 1	Greater than 9.2	Yes	Subgrade	Subgrade and Pavement moduli
Greater than 1	Less than 9.2	No	May be either	"NO UNIQUE SOLUTION"*
Less than 1	Greater than 9.2	Yes	Pavement	Subgrade and pavement moduli
Less than 1	Less than 9.2	No	May be either, but the more probable of two possible solu- tions is selected	Subgrade and pavement moduli for solution having $E_1/E_2 > 1$

* When the experimental data $w_1 r_1 / w_2 r_2$ exceeds unity, and h is less than 9.2", some cases can arise for which no solution at all is possible.

6. Examples of Solutions Obtained by ELASTIC MODULUS

In May, 1968, Dynaflect deflections were measured at ten points in the outer wheel path on each of several 500-ft. sections of highways in the vicinity of College Station, Texas, originally for the purpose of gaining experience in the determination of the "stiffness coefficient" mentioned in the Introduction of this report (page 1). Some of these data, including thicknesses obtained by coring at five points in each section, were used as inputs to the computer program discussed herein for the purpose of illustrating its use in obtaining the elastic moduli of pavements and subgrades. The results are summarized in Tables 4 and 5, while the computer print-outs -- in the standard format of the program -- are shown in Tables 6a through 6g. In the latter group of tables the readings of each of the five geophones at each test station are given, although only the greatest deflections, w_1 and w_2 , were actually used in estimating the moduli E_1 and E_2 .

Tables 4 and 5 are arranged in descending order of the magnitude of the average modulus of pavement and subgrade, respectively. In comparing these two tables it is of interest to note that the variability of the pavement modulus, as indicated by the coefficient of variation in the last column, is generally greater than that of the subgrade. In addition it is apparent that the range of E_1 (13,900 psi to 283,200 psi) is much greater than the range of E_2 (11,700 psi to 20,000 psi). Finally, it should be pointed out that the pavement of Section 12, at the bottom of the list in Table 4, had an average modulus (13,900 psi) of approximately the same magnitude as that of its subgrade (14,400 psi).

The low pavement modulus found for Section 12 invites some discussion. The low value obtained may be due to the relatively poor quality of the major component of the pavement, a sandstone which, according to local engineers, has in some cases performed poorly. In any event the surfacing of this section had been overlaid -- because of map cracking -- shortly before it was tested in 1968, then again developed severe map cracking that required sealing in 1970. The seal coat failed to arrest the progress of surface deterioration, and at this writing (June, 1971) it is again being overlaid with one inch of hot-mix asphaltic concrete. In short, the contrast between the stiffness of the surfacing material and that of the base seems to be at the root of the trouble in this section.

Beyond these remarks concerning Section 12, and the additional fact that the ordering of the other materials appears reasonable, any other discussion of the ordering of the materials in Tables 3 and 4 is considered to be beyond the scope of this report.

Table 4: Average Pavement Modulus, E_1 , for Seven 500-ft. Sections
of Highways near College Station, Texas
(Deflection measurements made May 21, 1968)

Test Section	Pavement Materials and Thicknesses		Pavement Thickness, h		No.* Solutions	Pavement Modulus, E_1		
	Surfacing	Base	Average Value (In.)	Standard Deviation		Average Value (PSI)	Standard Deviation	Coefficient of Variation (percent)
15	1.2" Asph. Conc.	14.0" Cement stabilized limestone	15.2	1.2	10	283,200	76,100	27
4	0.5" Seal Coat	7.5" Asphalt stabilized gravel	8.0	0.4	2	78,900	8,200	10
16	1.0" Asph. Conc.	6.5" Asph. emulsion stab. gravel	7.5	0.4	10	73,900	13,800	19
17	0.5" Seal Coat	7.8" Iron ore gravel	8.3	0.7	8	36,600	24,700	67
5	0.5" Seal Coat	11.5" Lime stabilized sandstone	12.0	2.8	10	32,300	15,100	47
3	0.5" Seal Coat	12.0" Red sandy gravel	12.5	1.0	10	24,700	6,000	24
12	3.7" Asph. Conc.	16.2" Sandstone	19.9	0.5	10	13,900	2,700	19

* Measurements were made at 10 locations in each section. Less than 10 solutions occur in cases where $w_1r_1/w_2r_2 > 1$ and $h < 9.2"$, as explained in Chapter 4.

Table 5: Average Subgrade Modulus, E_2 , for Seven 500-ft. Sections
of Highways near College Station, Texas

(Deflection measurements made May 21, 1968)

Section	Thickness Investigated	Subgrade Material		Subgrade Modulus, E_2			
		Description	Formation	No.* Solutions	Average Value (PSI)	Standard Deviation	Coefficient of Variation (percent)
15	32"	Red sandy clay, some gravel	Stone City	10	20,000	900	5
3	23"	Sand over clay	Spiller Sandstone Member of Cook Mountain Formation	10	19,000	1600	8
4	25"	Grey sandy clay	Spiller Sandstone Member of Cook Mountain Formation	2	14,900	800	5
5	24"	Tan sandy clay	Caddell	10	14,500	1400	10
12	22"	Black stiff clay	Lagarto	10	14,400	900	6
17	21"	Grey sandy clay	Spiller Sandstone Member of Cook Mountain Formation	8	12,700	1700	13
16	18"	Brown clay	Alluvium deposit of Brazos River	10	11,700	700	6

* Measurements were made at 10 locations in each section. Less than 10 solutions occur in cases where $w_1r_1/w_2r_2 > 1$ and $h < 9.2"$, as explained in Chapter 4.

TEXAS HIGHWAY DEPARTMENT

DISTRICT 17 - DESIGN SECTION

DYNAFLECT DEFLECTIONS AND CALCULATED ELASTIC MODULI

THIS PROGRAM WAS RUN - 06/21/71

DIST. COUNTY
17 BRAZOS

CONT. SECT. JOB HIGHWAY DATE DYNAFLECT
1560 1 1 FM 1687 5-21-68 1

PAV. THICK. = 12.50 INCHES

SEAL COAT 0.50 RED SANDY GRAVEL 12.00
GREY & BRWN SAND SUB 0.0

STATION	W1	W2	W3	W4	W5	SCI	** ES	** ** EP	** REMARKS
1 - A	1.170	0.770	0.520	0.310	0.219	0.400	20200.	23500.	
1 - B	1.140	0.770	0.510	0.310	0.213	0.370	20500.	28200.	
2 - A	1.290	0.840	0.490	0.300	0.204	0.450	18400.	20300.	
2 - B	1.200	0.840	0.490	0.300	0.201	0.360	19000.	33300.	
3 - A	1.140	0.770	0.470	0.300	0.195	0.370	20500.	28200.	
3 - B	1.110	0.770	0.460	0.300	0.201	0.340	20700.	33900.	
4 - A	1.470	0.960	0.490	0.320	0.222	0.510	16100.	18100.	
4 - B	1.380	0.900	0.470	0.310	0.213	0.480	17200.	19000.	
5 - A	1.290	0.870	0.500	0.340	0.231	0.420	18100.	24600.	
5 - B	1.260	0.800	0.460	0.310	0.219	0.460	19000.	18100.	
AVERAGES	1.245	0.829	0.486	0.310	0.212	0.416	18970.	24720.	
STANDARD DEVIATION						0.057	1551.	5996.	
NUMBER OF POINTS IN AVERAGE =						10	10	10	

W1 DEFLECTION AT GEOPHONE 1
W2 DEFLECTION AT GEOPHONE 2
W3 DEFLECTION AT GEOPHONE 3
W4 DEFLECTION AT GEOPHONE 4
W5 DEFLECTION AT GEOPHONE 5
SCI SURFACE CURVATURE INDEX (W1 MINUS W2)
ES ELASTIC MODULUS OF THE SUBGRADE FROM W1 AND W2
EP ELASTIC MODULUS OF THE PAVEMENT FROM W1 AND W2

Table 6a: Computer print-out for Section 3.

TEXAS HIGHWAY DEPARTMENT
DISTRICT 17 - DESIGN SECTION
DYNAFLECT DEFLECTIONS AND CALCULATED ELASTIC MODULI

THIS PROGRAM WAS RUN - 06/21/71

DIST. COUNTY
17 BRAZOS

CONT. SECT. JOB HIGHWAY DATE DYNAFLECT
2824 2 1 FM 2776 5-21-68 1

PAV. THICK. = 8.00 INCHES

SEAL COAT 0.50 ASPHALT STAB. GRAVEL 7.50

GREY SANDY CLAY SUBG 0.0

STATION	W1	W2	W3	W4	W5	SCI	** ES	** ** EP	**	REMARKS
1 - A	1.650	1.200	0.870	0.660	0.500	0.450	14300.	84700.		
1 - B	1.560	1.110	0.810	0.610	0.490	0.450	15500.	73100.		
2 - A	2.310	1.470	0.930	0.710	0.530	0.840	NO UNIQUE	SOLUTION		
2 - B	2.310	1.410	0.900	0.670	0.510	0.900	NO UNIQUE	SOLUTION		
3 - A	2.430	1.500	0.930	0.670	0.490	0.930	NO UNIQUE	SOLUTION		
3 - B	2.490	1.530	0.930	0.670	0.500	0.960	NO UNIQUE	SOLUTION		
4 - A	2.490	1.470	0.900	0.640	0.480	1.020	NO UNIQUE	SOLUTION		
4 - B	2.430	1.410	0.840	0.610	0.470	1.020	NO UNIQUE	SOLUTION		
5 - A	2.340	1.440	0.870	0.620	0.450	0.900	NO UNIQUE	SOLUTION		
5 - B	2.430	1.470	0.930	0.650	0.470	0.960	NO UNIQUE	SOLUTION		
AVERAGES	2.244	1.401	0.891	0.651	0.489	0.843	14900.	78900.		
STANDARD DEVIATION						0.214	849.	8202.		
NUMBER OF POINTS IN AVERAGE =						10	2	2		

W1 DEFLECTION AT GEOPHONE 1
W2 DEFLECTION AT GEOPHONE 2
W3 DEFLECTION AT GEOPHONE 3
W4 DEFLECTION AT GEOPHONE 4
W5 DEFLECTION AT GEOPHONE 5
SCI SURFACE CURVATURE INDEX (W1 MINUS W2)
ES FLASTIC MODULUS OF THE SUBGRADE FROM W1 AND W2
EP ELASTIC MODULUS OF THE PAVEMENT FROM W1 AND W2

Table 6b: Computer print-out for Section 4.

TEXAS HIGHWAY DEPARTMENT
DISTRICT 17 - DESIGN SECTION
DYNAFLECT DEFLECTIONS AND CALCULATED ELASTIC MODULI

THIS PROGRAM WAS RUN - 06/21/71

DIST. COUNTY
17 BURLESON

CONT. SECT. JOB HIGHWAY DATE DYNAFLECT
1399 1 1 FM 1361 5-21-68 1

PAV. THICK. = 12.00 INCHES

SEAL COAT 0.50 LIME STAB. SANDSTONE 11.50

TAN SANDY CLAY SUBGR 0.0

STATION	W1	W2	W3	W4	W5	SCI	** ES	** ** EP	**	REMARKS
1 - A	1.500	1.110	0.710	0.470	0.330	0.390	14500.	41600.		
1 - B	1.560	1.230	0.780	0.480	0.330	0.330	12700.	65800.		
2 - A	1.650	1.200	0.670	0.400	0.243	0.450	13500.	33100.		
2 - B	1.440	1.050	0.640	0.380	0.246	0.390	15400.	38500.		
3 - A	1.500	1.050	0.600	0.370	0.267	0.450	15300.	27900.		
3 - B	1.440	0.990	0.580	0.370	0.261	0.450	16100.	25800.		
4 - A	1.500	1.050	0.560	0.340	0.216	0.450	15300.	27900.		
4 - B	1.380	0.990	0.540	0.330	0.213	0.390	16300.	35900.		
5 - A	1.920	1.260	0.650	0.400	0.280	0.660	12400.	14400.		
5 - B	1.800	1.140	0.630	0.420	0.310	0.660	13300.	12500.		
AVERAGES	1.569	1.107	0.636	0.396	0.270	0.462	14480.	32340.		
STANDARD DEVIATION						0.112	1413.	15108.		
NUMBER OF POINTS IN AVERAGE =						10	10	10		

W1 DEFLECTION AT GEOPHONE 1
W2 DEFLECTION AT GEOPHONE 2
W3 DEFLECTION AT GEOPHONE 3
W4 DEFLECTION AT GEOPHONE 4
W5 DEFLECTION AT GEOPHONE 5
SCI SURFACE CURVATURE INDEX (W1 MINUS W2)
ES ELASTIC MODULUS OF THE SUBGRADE FROM W1 AND W2
EP ELASTIC MODULUS OF THE PAVEMENT FROM W1 AND W2

Table 6c: Computer print-out for Section 5.

TEXAS HIGHWAY DEPARTMENT

DISTRICT 17 - DESIGN SECTION

DYNAFLECT DEFLECTIONS AND CALCULATED ELASTIC MODULII

THIS PROGRAM WAS RUN - 06/21/71

DIST. COUNTY
17 WASHINGTON

CONT. SECT. JOB HIGHWAY DATE DYNAFLECT
186 5 1 SH 36 5-21-68 1

PAV. THICK. = 19.90 INCHES

HOT MIX ASPH. CONC. 3.75 SANDSTONE 16.15
BLACK CLAY SUBGRADE 0.0

STATION	W1	W2	W3	W4	W5	SCI	** ES	** ** EP	**	REMARKS
1 - A	1.680	1.020	0.610	0.420	0.300	0.660	15200.	12400.		
1 - B	1.830	1.080	0.610	0.420	0.310	0.750	14400.	10700.		
2 - A	1.740	1.080	0.670	0.470	0.360	0.660	14300.	12700.		
2 - B	1.950	1.170	0.690	0.490	0.370	0.780	13200.	10400.		
3 - A	1.680	1.080	0.680	0.500	0.380	0.600	14100.	14400.		
3 - B	1.710	1.080	0.670	0.480	0.370	0.630	14200.	13500.		
4 - A	1.680	1.110	0.750	0.570	0.460	0.570	13600.	15600.		
4 - B	1.560	1.080	0.730	0.550	0.440	0.480	13800.	19400.		
5 - A	1.500	0.960	0.590	0.440	0.330	0.540	15900.	15900.		
5 - B	1.590	0.990	0.600	0.430	0.330	0.600	15500.	14000.		
AVERAGES	1.692	1.065	0.660	0.477	0.365	0.627	14420.	13900.		
STANDARD DEVIATION						0.091	861.	2661.		
NUMBER OF POINTS IN AVERAGE =						10	10	10		

W1 DEFLECTION AT GEOPHONE 1
W2 DEFLECTION AT GEOPHONE 2
W3 DEFLECTION AT GEOPHONE 3
W4 DEFLECTION AT GEOPHONE 4
W5 DEFLECTION AT GEOPHONE 5
SCI SURFACE CURVATURE INDEX (W1 MINUS W2)
ES ELASTIC MODULUS OF THE SUBGRADE FROM W1 AND W2
EP ELASTIC MODULUS OF THE PAVEMENT FROM W1 AND W2

Table 6d: Computer print-out for Section 12.

TEXAS HIGHWAY DEPARTMENT
DISTRICT 17 - DESIGN SECTION
DYNAFLECT DEFLECTIONS AND CALCULATED ELASTIC MODULI

THIS PROGRAM WAS RUN - 06/21/71

DIST. COUNTY
17 ROBERTSON

CONT. SECT. JOB HIGHWAY DATE DYNAFLECT
49 8 1 US 190 5-21-68 1

PAV. THICK. = 15.20 INCHES

HOT MIX ASPH. CONC. 1.25 CEM. STAB. LIMESTONE 13.95

RED SANDY CLAY SUBGR 0.0

STATION	W1	W2	W3	W4	W5	SCI	** ES	** ** EP	**	REMARKS
1 - A	0.680	0.590	0.490	0.390	0.310	0.090	21000.	230200.		
1 - B	0.680	0.600	0.490	0.390	0.310	0.080	19500.	280500.		
2 - A	0.720	0.630	0.510	0.390	0.310	0.090	19100.	240900.		
2 - B	0.700	0.620	0.490	0.390	0.310	0.080	18600.	284100.		
3 - A	0.750	0.650	0.520	0.390	0.300	0.100	19000.	209200.		
3 - B	0.760	0.650	0.510	0.390	0.300	0.110	19800.	179000.		
4 - A	0.600	0.540	0.450	0.350	0.280	0.060	20100.	402600.		
4 - B	0.580	0.520	0.430	0.330	0.880	0.060	21000.	405200.		
5 - A	0.620	0.550	0.450	0.350	0.910	0.070	20800.	327800.		
5 - B	0.650	0.570	0.470	0.360	0.280	0.080	21000.	271700.		
AVERAGES	0.674	0.592	0.481	0.373	0.419	0.082	19990.	283180.		
STANDARD DEVIATION						0.016	926.	76113.		
NUMBER OF POINTS IN AVERAGE =						10	10	10		

W1 DEFLECTION AT GEOPHONE 1
W2 DEFLECTION AT GEOPHONE 2
W3 DEFLECTION AT GEOPHONE 3
W4 DEFLECTION AT GEOPHONE 4
W5 DEFLECTION AT GEOPHONE 5
SCI SURFACE CURVATURE INDEX (W1 MINUS W2)
ES ELASTIC MODULUS OF THE SUBGRADE FROM W1 AND W2
EP ELASTIC MODULUS OF THE PAVEMENT FROM W1 AND W2

Table 6e: Computer print-out for Section 15.

TEXAS HIGHWAY DEPARTMENT

DISTRICT 17 - DESIGN SECTION

DYNAFLECT DEFLECTIONS AND CALCULATED ELASTIC MODULI

THIS PROGRAM WAS RUN - 06/21/71

DIST. COUNTY
17 BRAZOS

CONT. SECT. JOB HIGHWAY DATE DYNAFLECT
1560 1 1 FM 1687 5-21-68 1

PAV. THICK. = 7.50 INCHES

ASPHALT SURFACING 1.00 ASPH EMUL STAB GRAVL 6.50
BROWN CLAY SUBGRADE 0.0

STATION	W1	W2	W3	W4	W5	SCI	** ES **	** EP **	REMARKS
1 - A	2.160	1.500	0.960	0.660	0.520	0.660	11500.	49700.	
1 - B	2.130	1.530	0.960	0.650	0.510	0.600	11300.	70200.	
2 - A	1.920	1.410	0.930	0.640	0.490	0.510	12300.	94300.	
2 - B	1.860	1.350	0.900	0.630	0.500	0.510	12800.	88100.	
3 - A	2.040	1.470	0.930	0.630	0.490	0.570	11800.	75000.	
3 - B	2.070	1.500	0.960	0.650	0.500	0.570	11600.	77300.	
4 - A	2.220	1.620	1.020	0.670	0.490	0.600	10700.	77500.	
4 - B	2.220	1.590	1.020	0.650	0.490	0.630	10900.	65300.	
5 - A	1.980	1.380	0.900	0.610	0.470	0.600	12500.	56900.	
5 - B	1.980	1.440	0.930	0.610	0.460	0.540	12000.	84800.	
AVERAGES	2.058	1.479	0.951	0.640	0.492	0.579	11740.	73910.	
STANDARD DEVIATION						0.049	679.	13843.	
NUMBER OF POINTS IN AVERAGE =						10	10	10	

W1 DEFLECTION AT GEOPHONE 1
W2 DEFLECTION AT GEOPHONE 2
W3 DEFLECTION AT GEOPHONE 3
W4 DEFLECTION AT GEOPHONE 4
W5 DEFLECTION AT GEOPHONE 5
SCI SURFACE CURVATURE INDEX (W1 MINUS W2)
ES ELASTIC MODULUS OF THE SUBGRADE FROM W1 AND W2
EP ELASTIC MODULUS OF THE PAVEMENT FROM W1 AND W2

Table 6f: Computer print-out for Section 16.

TEXAS HIGHWAY DEPARTMENT

DISTRICT 17 - DESIGN SECTION

DYNAFLECT DEFLECTIONS AND CALCULATED ELASTIC MODULI

THIS PROGRAM WAS RUN - 06/21/71

DIST. COUNTY
17 BRAZOS

CONT. SECT. JOB HIGHWAY DATE DYNAFLECT
540 3 1 FM 974 5-21-68 1

PAV. THICK. = 8.30 INCHES

SEAL COAT 0.50 IRON ORE GRAVEL 7.80
GREY SANDY CLAY SUBG 0.0

STATION	W1	W2	W3	W4	W5	SCI	** ES	** ** EP	** REMARKS
1 - A	2.400	1.530	0.960	0.680	0.500	0.870	NO UNIQUE	SOLUTION	
1 - B	2.250	1.440	0.900	0.630	0.480	0.810	NO UNIQUE	SOLUTION	
2 - A	1.770	1.170	0.820	0.600	0.480	0.600	14000.	25600.	
2 - B	1.800	1.200	0.820	0.620	0.490	0.600	13800.	28000.	
3 - A	1.650	1.170	0.840	0.640	0.510	0.480	14600.	60100.	
3 - B	1.590	1.170	0.840	0.610	0.510	0.420	14600.	88300.	
4 - A	2.250	1.470	0.990	0.750	0.600	0.780	11000.	16700.	
4 - B	2.340	1.590	1.050	0.790	0.630	0.750	10600.	27000.	
5 - A	2.220	1.470	0.990	0.710	0.550	0.750	11200.	21000.	
5 - B	2.100	1.410	0.960	0.680	0.530	0.690	11800.	26100.	
AVRAGES	2.037	1.362	0.917	0.671	0.528	0.675	12700.	36600.	
STANDARD DEVIATION						0.146	1710.	24675.	
NUMBER OF POINTS IN AVERAGE =						10	8	8	

- W1 DEFLECTION AT GEOPHONE 1
- W2 DEFLECTION AT GEOPHONE 2
- W3 DEFLECTION AT GEOPHONE 3
- W4 DEFLECTION AT GEOPHONE 4
- W5 DEFLECTION AT GEOPHONE 5
- SCI SURFACE CURVATURE INDEX (W1 MINUS W2)
- ES ELASTIC MODULUS OF THE SUBGRADE FROM W1 AND W2
- EP ELASTIC MODULUS OF THE PAVEMENT FROM W1 AND W2

Table 6g: Computer print-out for Section 17.

7. Adjustment of Moduli for Practical Use in Pavement Design

As previously noted, the elastic moduli estimated by the computer program are based on deflections produced and measured by the Dynaflect system. Correlation studies of Dynaflect deflections with those produced by a 9000-lb. dual-tired wheel load and measured by means of the Benkelman Beam on highways in Illinois and Minnesota in 1967 (3) indicated that the 9000-lb. wheel load deflection could, with reasonable accuracy, be estimated from the Dynaflect deflection, w_1 , by multiplying w_1 by 20.

But the peak-to-peak load of the Dynaflect is 1000-lbs.; thus, one would expect that the multiplying factor would be about 9, rather than 20 as found by actual field experience.

Various explanations could be advanced to explain this discrepancy. However, they would not alter the fact, brought out by the correlation study, that if one desires to use the values of E_1 and E_2 found from Dynaflect deflections to calculate the deflection of a linear elastic layered system acted on by a heavy vehicle, then he should approximately halve these moduli before using them in his calculations.

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Appendix 1

The variable names used in ELASTIC MODULUS are listed on the following pages. The variable names and their definitions are in alphabetical order in the following sequence:

MAIN Program Variables

Subroutine EMOD Variables

Function BESJO Variables

Function V Variables

MAIN Program Variables

- A - Dummy array used with subroutine CORE to select the correct input format for each card read
- AAP2 - Sum of pavement moduli
- AAS2 - Sum of subgrade moduli
- AAP2V - Average pavement modulus
- AAS2V - Average subgrade modulus
- AP2 - Elastic modulus of the pavement, rounded to nearest 100 (appears as EP on printout)
- AS2 - Elastic modulus of the subgrade, rounded to nearest 100 (appears as ES on printout)
- ASC1 - Sum of (W1 - W2). W1 - W2 = surface curvature index.
- ASC1V - Average surface curvature index
- AW1 - Sum of Geophone 1 deflections
- AW2 - Sum of Geophone 2 deflections
- AW3 - Sum of Geophone 3 deflections
- AW4 - Sum of Geophone 4 deflections
- AW5 - Sum of Geophone 5 deflections
- AW1V - Average Geophone 1 deflection
- AW2V - Average Geophone 2 deflection
- AW3V - Average Geophone 3 deflection
- AW4V - Average Geophone 4 deflection
- AW5V - Average Geophone 5 deflection
- COMM - Comments related to the project
- CORE - Subroutine to re-read a card under format control
- C01, C02, C03, C04 - County Name

D1 - Geophone 1 reading
 D2 - Geophone 1 multiplier
 D3 - Geophone 2 reading
 D4 - Geophone 2 multiplier
 D5 - Geophone 3 reading
 D6 - Geophone 3 multiplier
 D7 - Geophone 4 reading
 D8 - Geophone 4 multiplier
 D9 - Geophone 5 reading
 D10 - Geophone 5 multiplier
 DAP - Pavement elastic modulus (unrounded) as calculated in subroutine
 EMOD
 DAS - Subgrade elastic modulus (unrounded) as calculated in subroutine
 EMOD
 DATE - An IBM subroutine that returns the current month, day, & year
 DP - Total pavement thickness
 EMOD - Subroutine to calculate pavement & subgrade moduli
 HWY1, HWY2 - Highway name & number
 I - Pointer for data read into storage
 ICK - Switch to indicate last data card
 ICONT - Contract number for the highway
 IDAY - Day the deflections were taken
 IDIST - District number
 IDYNA - Dynaflect number
 IJOB - THD job number
 ISECT - THD section number for the highway
 IXDATE - Return arguments for subroutine DATE (month, day, year)
 IYEAR - Year the deflections were taken

LA1 - Description of material in Layer 1
 LA2 - Description of material in Layer 2
 LA3 - Description of material in Layer 3
 LA4 - Description of material in Layer 4
 LA5 - Description of material in Layer 5
 LA6 - Description of material in Layer 6
 M - Month the deflections were taken
 N - Counter for number of error free data cards read
 NO - Counter for data cards omitted because of errors
 NI - Counter to control printing of 30 lines per page
 NCARD - Denotes card type
 100 = Project identification card
 200 = Existing pavement description card (layers 1, 2, & 3)
 300 = Existing pavement description card (layers 4, 5, & 6)
 400 = Data card (geophone readings and multipliers)
 PN - Number of test points to be used in the analysis
 REM - Any pertinent remarks related to any test point
 ROUND - Statement function to round a given value of E1 or E2 to the
 nearest 100 psi
 SCI - Surface curvature index, W1 - W2, in mils
 SE1 - Standard deviation of surface curvature index
 SE2 - Standard deviation of subgrade moduli
 SE3 - Standard deviation of pavement moduli
 SR1 - Variance of surface curvature index
 SR2 - Variance of subgrade moduli
 SR3 - Variance of pavement moduli
 STA - Station number
 T1 - Layer 1 thickness

T2 - Layer 2 thickness
T3 - Layer 3 thickness
T4 - Layer 4 thickness
T5 - Layer 5 thickness
T6 - Layer 6 thickness
W1 - Deflection at Geophone number 1
W2 - Deflection at Geophone number 2
W3 - Deflection at Geophone number 3
W4 - Deflection at Geophone number 4
W5 - Deflection at Geophone number 5
XLANE - Traffic lane & direction

Subroutine EMOD Variables

- ACC - Test for convergence in iteration for finding E2/E1
- AREA1 - Result of the integration from $x = 0$ to $x = 3r/h$
- AREA2 - Result of the integration from $X = 3r/h$ to $X = 10r/h$
- BESJO - Function subroutine to return the Bessel Function $J_0(x)$ for each x used
- DELM1 - Increment of m used in interval from $m = 0$ to $m = 3$
- DELM2 - Increment of m used in interval from $m = 3$ to $m = 10$
- DELTA - Incremental value for E2/E1 (Subgrade modulus divided by Pavement modulus) used in iteration process
- DELX1 - Increment of x in integration from $x = 0$ to $x = 3r/h$
- DELX2 - Increment of x in integration from $x = 3r/h$ to $x = 10r/h$
- E1 - Pavement modulus (E1)
- E2 - Subgrade modulus (E2)
- ER - Input specifying the accuracy of the iteration in calculating the ratio E2/E1
- E2E1 - Ratio of subgrade modulus to pavement modulus (E2/E1)
- ERROR - $(F1F2 - \text{RATIO})$, where F1F2 is calculated and RATIO is observed
- FF - Function defined as $\frac{4\pi E_1}{3P} w_1 r_1$ (See Eq. 5)
- F1F2 - Ratio of FF with $i = 1$ to FF with $i = 2$
- H - Pavement thickness, h
- ISW - Switch used in iterating to find E2/E1, indicates first time through the iteration loop
- MINUS - Switch used in iterating to find E2/E1, indicates a negative ERROR
- N1 - Number of intervals used for integration from $x = 0$ to $x = 3r/h$

N2 - Number of intervals used for integration from $x = 3r/h$ to $x = 10r/h$
 P - Dynaflect load = 1000#
 PART1 - Sum of interior ordinates of first integration
 PART2 - Sum of end ordinates of first integration
 PART3 - Sum of interior ordinates of second integration
 PART4 - Sum of end ordinates of second integration
 PLUS - Switch used in iterating to find $E2/E1$, indicates a positive
 ERROR
 RH - Radius (distance of geophone from load wheel) divided by pavement
 thickness, (r/h)
 R1 - Distance from load to Geophone 1
 R2 - Distance from load to Geophone 2
 RATIO - $(W1R1/W2R2)$
 SAVE - Contains the previous ERROR calculated that is closest to the
 convergence criterion in iterating to find $E2/E1$
 V - Function subroutine to return the value of V for each $E2/E1$ and
 XM1 values used
 W1 - Geophone 1 deflection (mils)
 W2 - Geophone 2 deflection (mils)
 X1 - Value of any x in the interval $x = 0$ to $x = 3r/h$
 X2 - Value of any x in the interval $x = 3r/h$ to $x = 10r/h$
 XK1 - Maximum value of Δm in the interval $m = 0$ to $m = 3$ (now set
 at 0.01)
 XK2 - Maximum value of Δm in the interval $m = 3$ to $m = 10$ (now set
 at 0.10)
 XM1 - Value of any m in the interval $m = 0$ to $m = 3$
 XM2 - Value of any m in the interval $m = 3$ to $m = 10$
 XN - $(E1 - E2)/(E1 + E2)$

- XNO - Minimum number of values of $J_0(x)$ calculated in the interval from x to $x + 3$, in the calculation by Simpson's Rule of AREA1 and AREA2. XNO must be an odd number and is now set at $XNO = 61$
- Y - Array to store ordinates to be used in integration from $x = 0$ to $x = 10r/h$

Function BESJO Variables

- X - Value x in the interval $x = 0$ to $x = 10r/h$
- X3 - $X/3$, or $3/X$ if $X > 3$
- X32 - X3 Squared
- X33 - X3 Cubed
- X34 - X3 to the Fourth Power
- X35 - X3 to the Fifth Power
- X36 - X3 to the Sixth Power

Function V Variables

EXPM2M - Exponential, e^{-2m}

EXPM4M - Exponential, e^{-4m}

XM - Value of any m in the interval $m = 0$ to $m = 10$

XN - $(E1 - E2)/(E1 + E2)$

Appendix 2

A narrative of the procedure used by ELASTIC MODULUS to calculate pavement and subgrade elastic moduli is contained on the following pages.

Description of ELASTIC MODULUS Program

The ELASTIC MODULUS program consists of a main program, two subroutines, and two function subroutines. The main program reads the input data, performs certain data transformations, and outputs the results. Subroutine CORE is called by the main program and is used to allow the user to select the input format to be used to read a certain card. The elastic moduli of the pavement and subgrade for each test point are calculated in subroutine EMOD. The function subroutines BESJO and V are called by EMOD and are used in the numerical integration used in calculating the elastic moduli.

The main program reads each input data card into a storage area and uses subroutine CORE to select the read statement and data format to read each data card. Subroutine CORE allows a FORTRAN program to read under format control from a storage area which contains alphabetic character codes of a card image. Each data card has a code punched in the first three columns that designates the card type. If the code is 100 the card contains control information about the job, location, date, and total pavement thickness (see Appendix 4). Card code 200 indicates a card that contains word descriptions and thicknesses of the first three layers of the pavement (see Appendix 4). The word descriptions and thicknesses of layers 4, 5, and 6 (if present) are on cards with code 300 (see Appendix 4). If the card code is 400 or is blank, the card contains the station number and geophone readings and multipliers for each observation (see Appendix 4). Card code 100 also

indicates the beginning of data cards for each job (or set of observations) and all counters and sums are set to their initial values. The information on Data Cards 1 and 2 (and Data Card 3, if present) is read and printed in the heading of the output.

The deflections at each geophone are calculated from the geophone readings and multipliers on each Data Card 4. $SCI = W1 - W2$ is also calculated. If either $W1$ or $W2$ is zero, or if $W1$ is less than $W2$, an error message is printed, the observation is not included in the analysis, and the next card is read. If the quantity $W1R1/W2R2$ is greater than 1 and the total pavement thickness is less than 9.2" the observation is not included in the analysis, an error message is printed, and the next card is read. If $W1$ and $W2$ are valid observations they are converted to inches and are passed to Subroutine EMOD along with the total pavement thickness for the elastic moduli calculation.

The pavement and subgrade moduli returned from EMOD are rounded to the nearest 100, $W1$ and $W2$ are converted back to mils, the sums of the deflections, SCI , pavement modulus, and subgrade modulus are incremented by the individual observations of each of these variables. The counter N (the sum of the valid observations) is incremented and a line of output consisting of the station number, $W1$, $W2$, $W3$, $W4$, $W5$, SCI , subgrade modulus, pavement modulus, and remarks is printed. The program will then skip to a new page before going back to read the next card if 30 lines of output have been printed. If all the data cards have been read the program calculates and prints averages of all deflections, SCI , pavement modulus, and the subgrade modulus. The variances and standard deviations of SCI , pavement modulus and subgrade modulus are calculated and printed and the program reads Data Card 1 of the next set of observations or terminates normally if there is no more data.

Subroutine EMOD uses the W1, W2, and total pavement thickness from the main program in the integration process and iteration scheme used to calculate the pavement modulus, E1 and the subgrade modulus, E2. All calculations in EMOD and the function subroutines BESJO and V are done in double precision to preserve the accuracy of the numerical integration. The user has the option to change the following variables or leave them at their present values:

P = 1000, ER = 0.001, XNO = 61.0, XK1 = 0.01, XK2 = 0.10

All switches and counters are initialized, r/h ratios are calculated and the variable RATIO (used in determining the convergence criterion in iteration for finding E2/E1) is calculated.

DELM1 is calculated and tested against the maximum assigned value for this variable. DELM1 is then set to the maximum value or the calculated value (whichever is the smaller value) and is used in calculating DELX1. DELM2 is calculated and tested in the same manner. The starting values of DELTA and E2E1 are selected and XN for the first iteration is calculated. The iteration loop begins with the calculation of each XN value for each E2E1 value used.

The number of intervals for each integration, N1 and N2, are calculated. (Note -- N1 and N2 must be odd integers.) The ordinates for each x in each integration interval are calculated and stored in the vector Y. The area of each integration interval is calculated according to Simpson's Rule (See Reference 11) and the function $FF(1) = AREA1 + AREA2 + 1$ is calculated (See Equation 5). $FF(2)$ is calculated as above except $RH(2)$ is used in calculating DELM1 and DELM2.

ERROR is calculated and tested against the convergence criterion. If ERROR is $< ACC$, E1 and E2 are calculated and EMOD returns to the main program. Otherwise a new value of E2E1 is calculated and the iteration loop is repeated.

The iteration method consists of trying values of E2E1 until ERROR is within the convergence criterion. The ERROR for any trial value of E2E1 that is closest to the convergence criterion is saved so that E2E1 values for subsequent trials can be adjusted to "home in" on the convergence criterion in a minimum number of trials.

For the first trial value of E2E1, if ERROR is not within the convergence criterion, ERROR is stored in SAVE and ISW is set to 1. If $ERROR > 0$, PLUS is set to 1 and MINUS is set to 0. This indicates ERROR is positive since PLUS was set to 0 and minus was set to 1 initially. For each successive pass through the iteration loop the sign of ERROR determines the segment of code executed to adjust E2E1 for the next trial until the convergence criterion is met.

When ERROR is positive, E2E1 is adjusted for the next trial in the following manner. PLUS is set to 1 to indicate ERROR is positive. If ERROR from the previous trial was positive, E2E1 is decreased for the next trial and the iteration loop is repeated. If ERROR from the previous trial was negative, DELTA is decreased by 50%, and the test for $SAVE < 0$ is made. If SAVE is positive, ERROR is stored in SAVE, E2E1 is decreased for the next trial and the iteration loop is repeated. If SAVE is negative, the test for $|SAVE| > ERROR$ is made. A true condition indicates the iteration method is approaching convergence on this trial from the positive direction so ERROR is stored in SAVE, E2E1 is decreased for the next trial and the iteration loop is repeated. A false condition indicates

ERROR is departing from convergence in the positive direction, so E2E1 is decreased for the next trial and the iteration loop is repeated.

E2E1 is adjusted for the next trial in the following manner when ERROR is negative. MINUS is set to 1 to indicate ERROR is negative. If ERROR from the previous trial was negative the iteration method is approaching the convergence criterion from the negative direction, so E2E1 is increased for the next trial and the iteration loop is repeated. If ERROR from the previous trial was positive, DELTA is decreased by 50% and the test for $SAVE > 0$ is made. A false condition indicates the previous ERROR was negative also so the test for $|SAVE| > |ERROR|$ is made. A true condition indicates the iteration method is closer to convergence on this trial than on the previous trial so ERROR is stored in SAVE, and E2E1 is increased for the next trial and the iteration loop is repeated. A false condition to the above test indicates the previous ERROR was closer to convergence so increase E2E1 for the next trial and repeat the iteration loop. If the test for $SAVE > 0$ is true, then the test for $|ERROR| > SAVE$ is made. A false condition indicates the iteration method is closer to convergence on this trial on the negative side than the previous trial was on the positive side, so ERROR is stored in SAVE, E2E1 is increased for the next trial and the iteration loop is repeated. For a true condition to the test for $|ERROR| > SAVE$ the steps following the test for $|SAVE| > |ERROR|$ are repeated.

The function subroutine BESJO calculates the Bessel Function $J_0(x)$ using polynomial approximation (See Reference 12) for each value of X in the integration interval $X = 0$ to $X = 10r/h$.

The function subroutine V calculates the value of V (See Equation 2) for each XN and XM1 or XM2 value used.

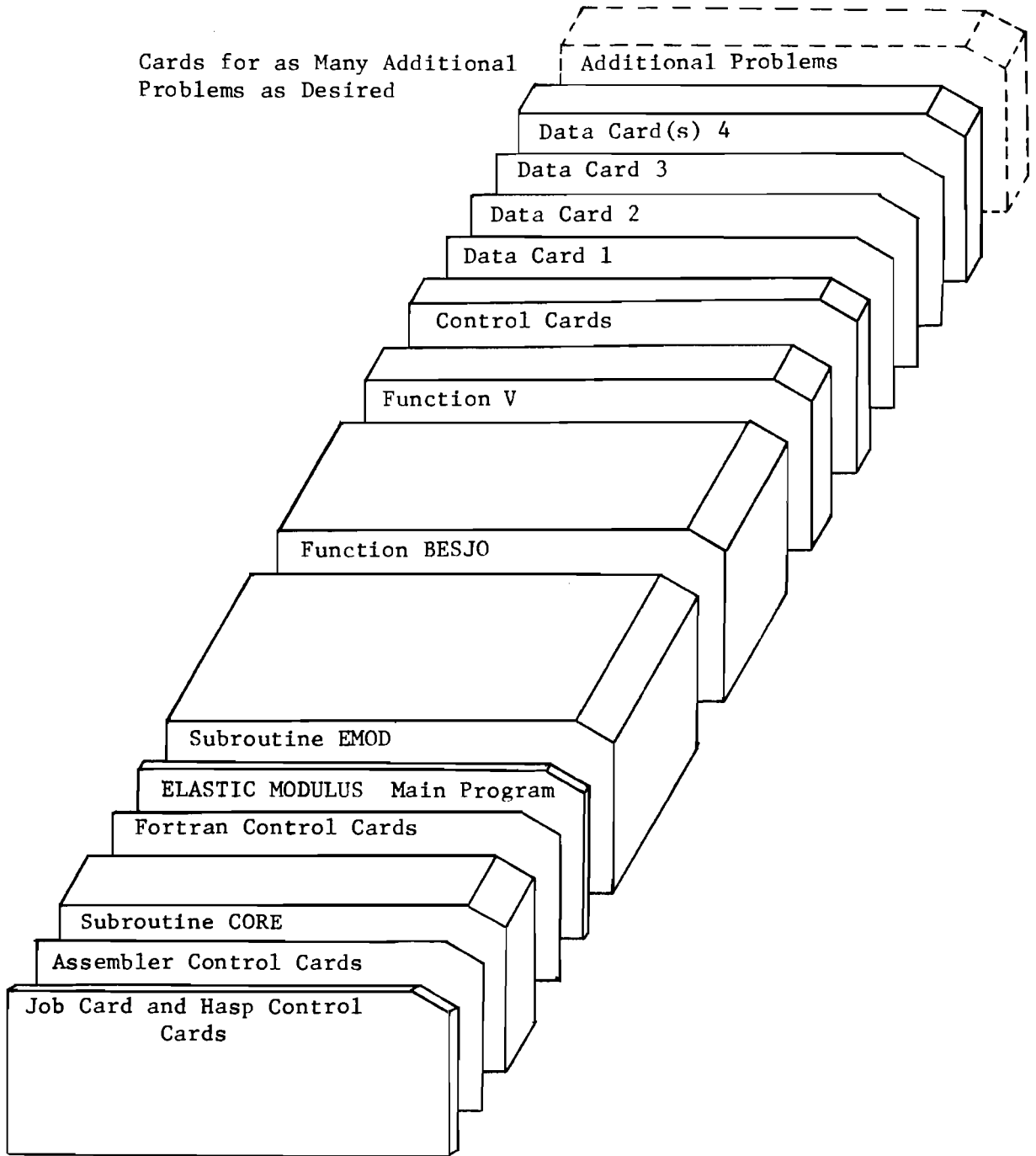
Appendix 3

This appendix contains the ELASTIC MODULI program source deck set-up.

Deck Set-Up

The ELASTIC MODULUS program was written in FORTRAN IV, Version G. The user is advised to change the first read statement in the main program if the "END=" option of the FORTRAN read is not implemented at his installation. The user can also substitute any other "Re-read" routine for Subroutine CORE if this is desired. ELASTIC MODULUS requires approximately 100k of core storage and execution time is approximately 7 seconds per test point. The source deck set-up is shown on the following page.

Source Deck Set-Up for ELASTIC MODULUS Program

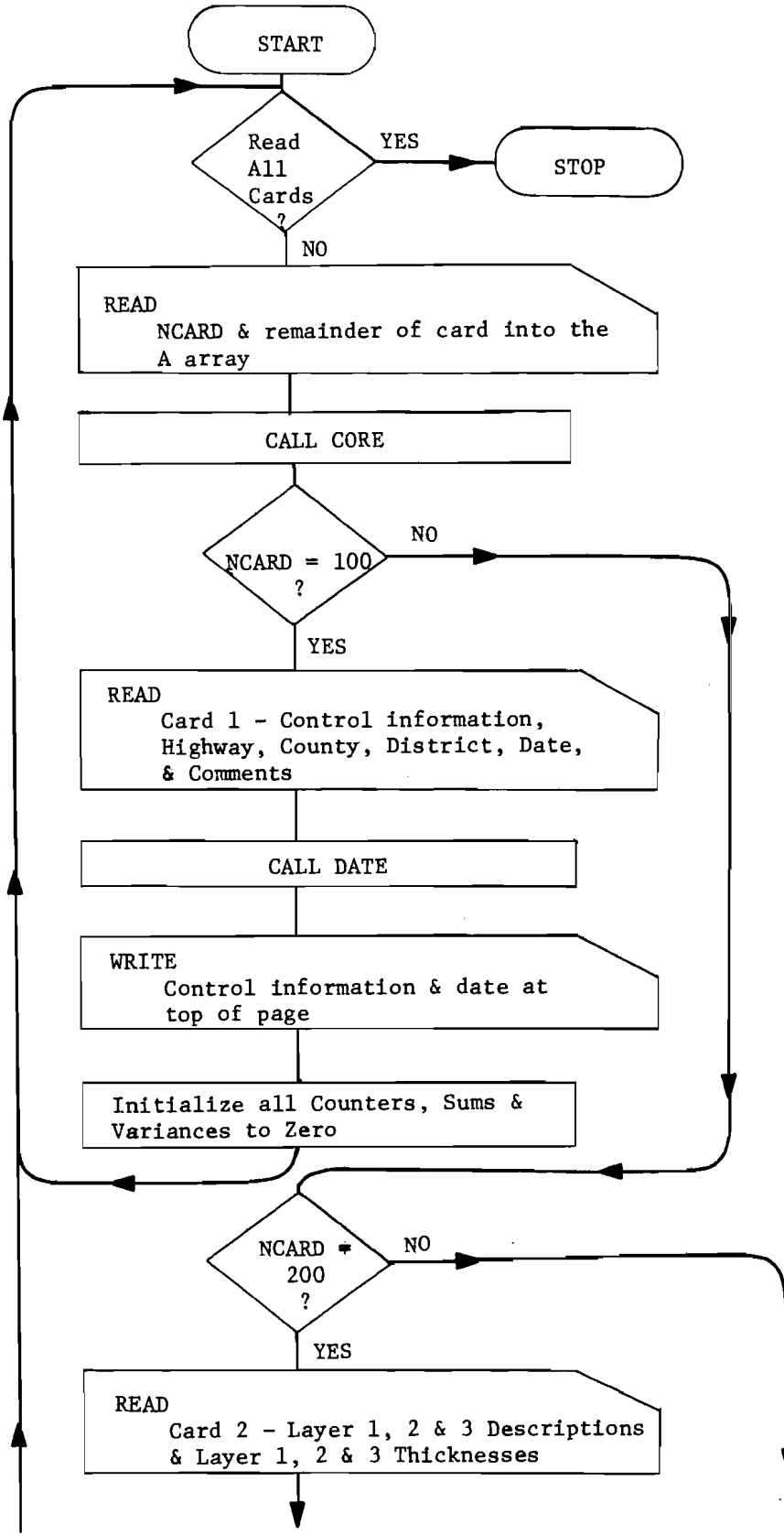


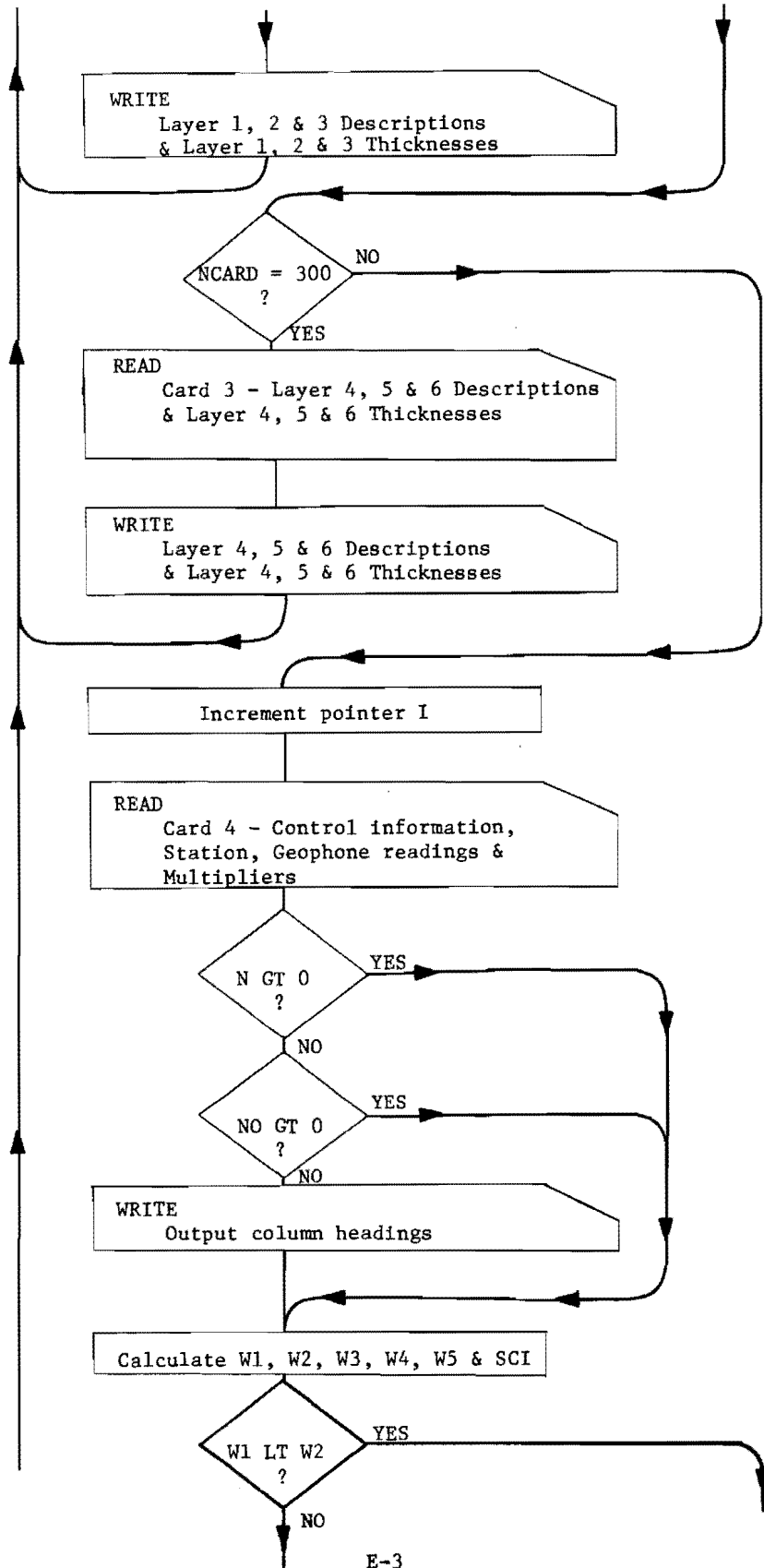
Appendix 4

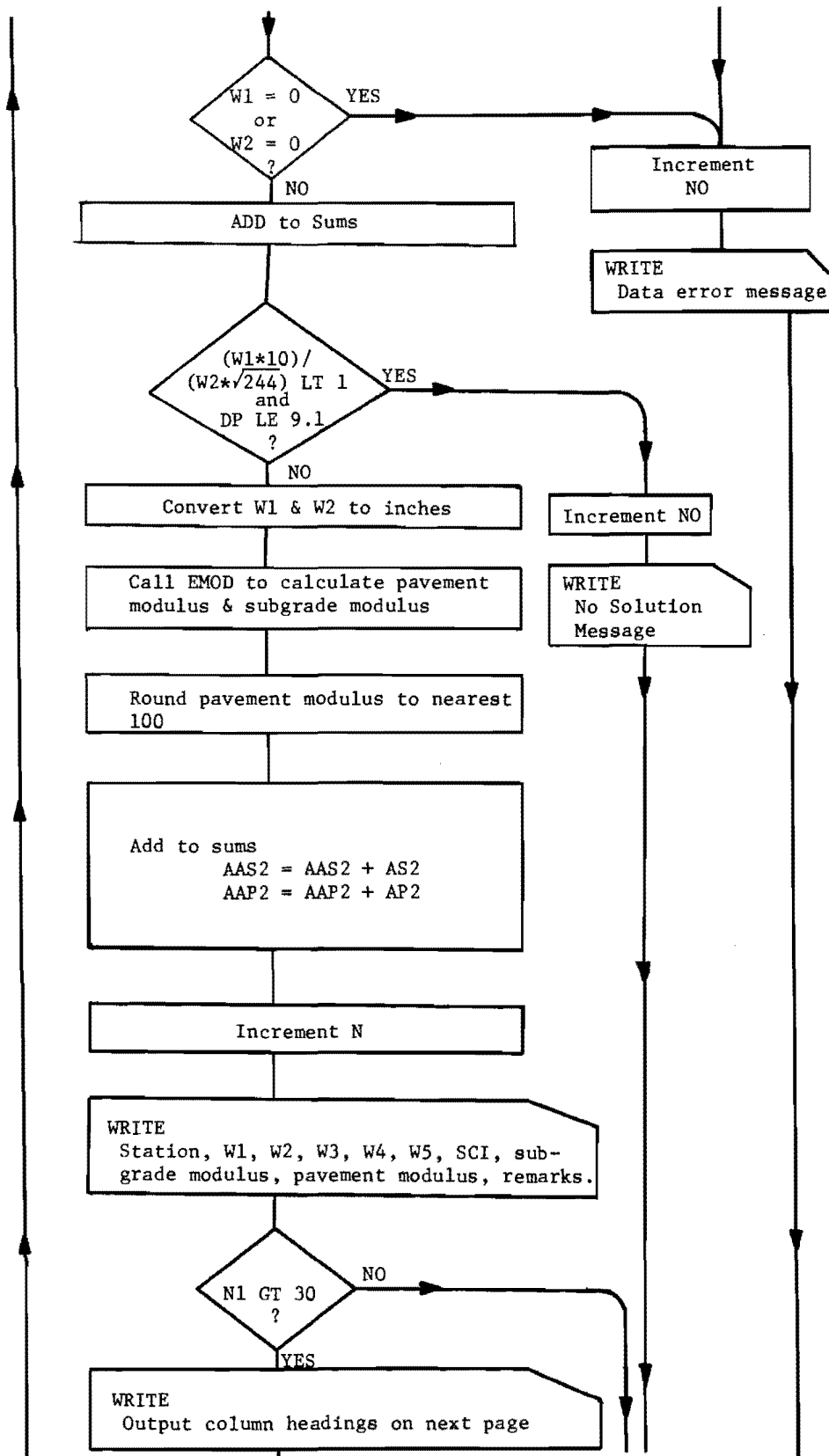
The input format for each data card type used by ELASTIC MODULUS is included on the following pages. The fields of each card are delineated and examples of typical data entries for each field are shown.

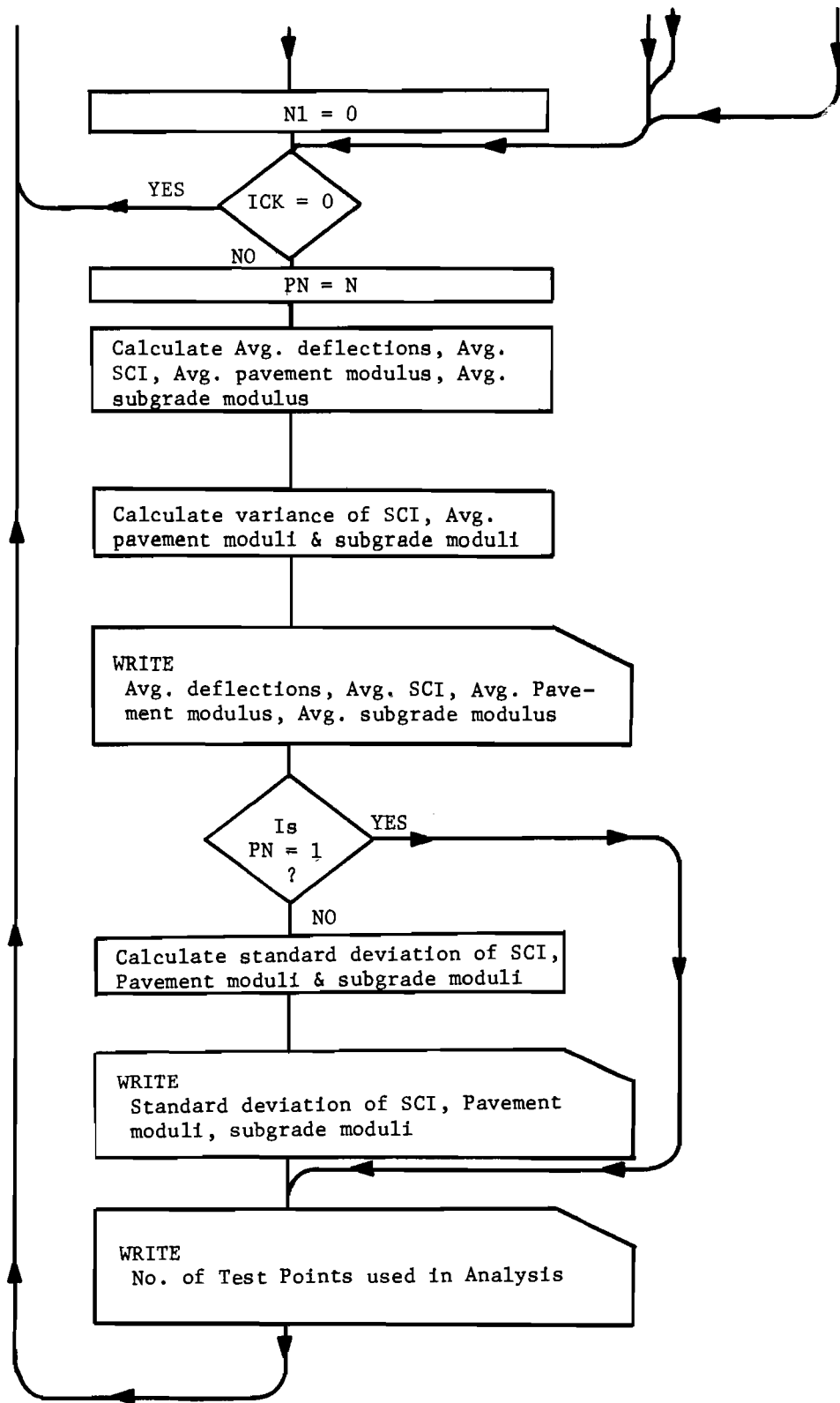
Appendix 5

This appendix contains the flowchart of the procedure used in ELASTIC MODULUS to calculate a pavement or subgrade modulus.

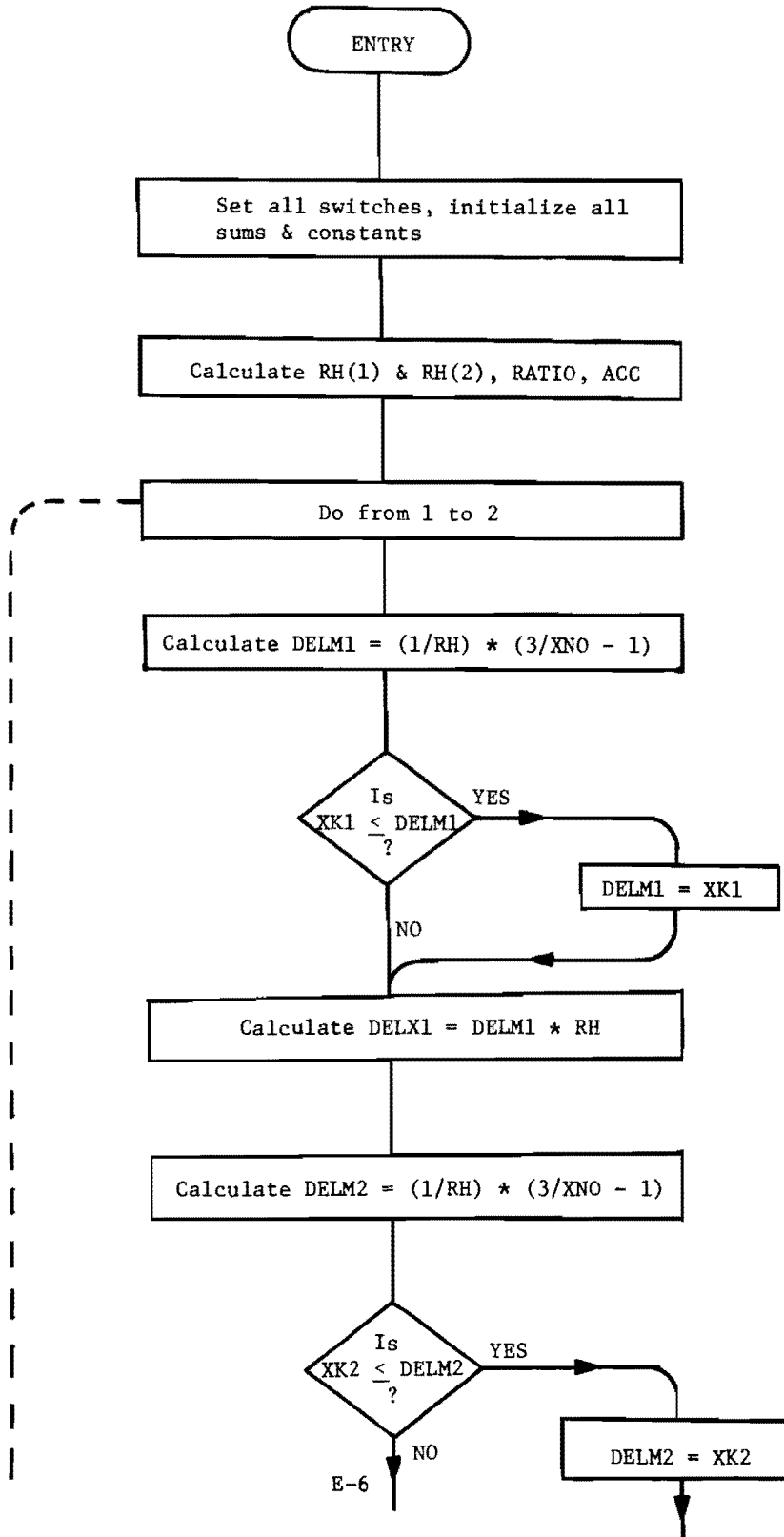


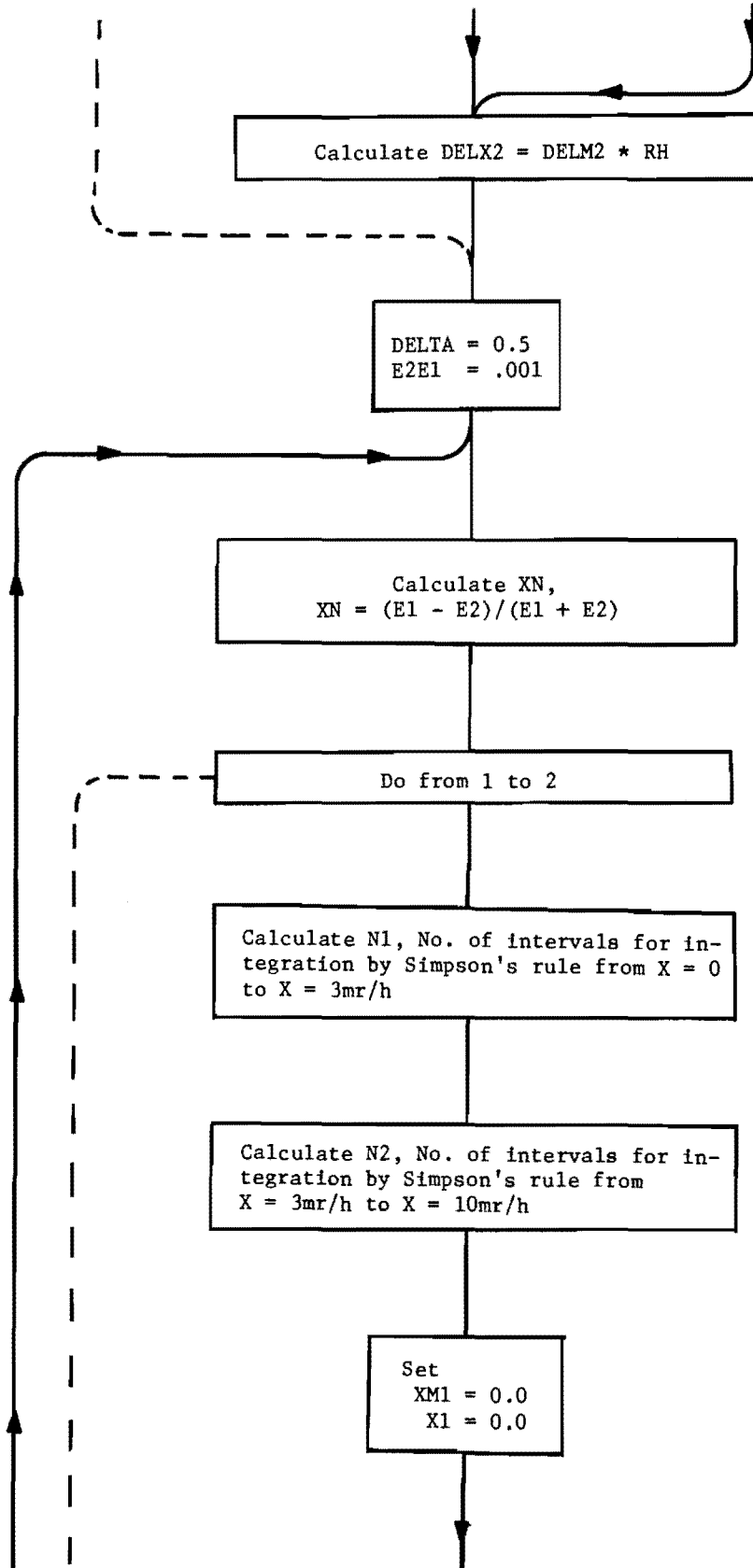


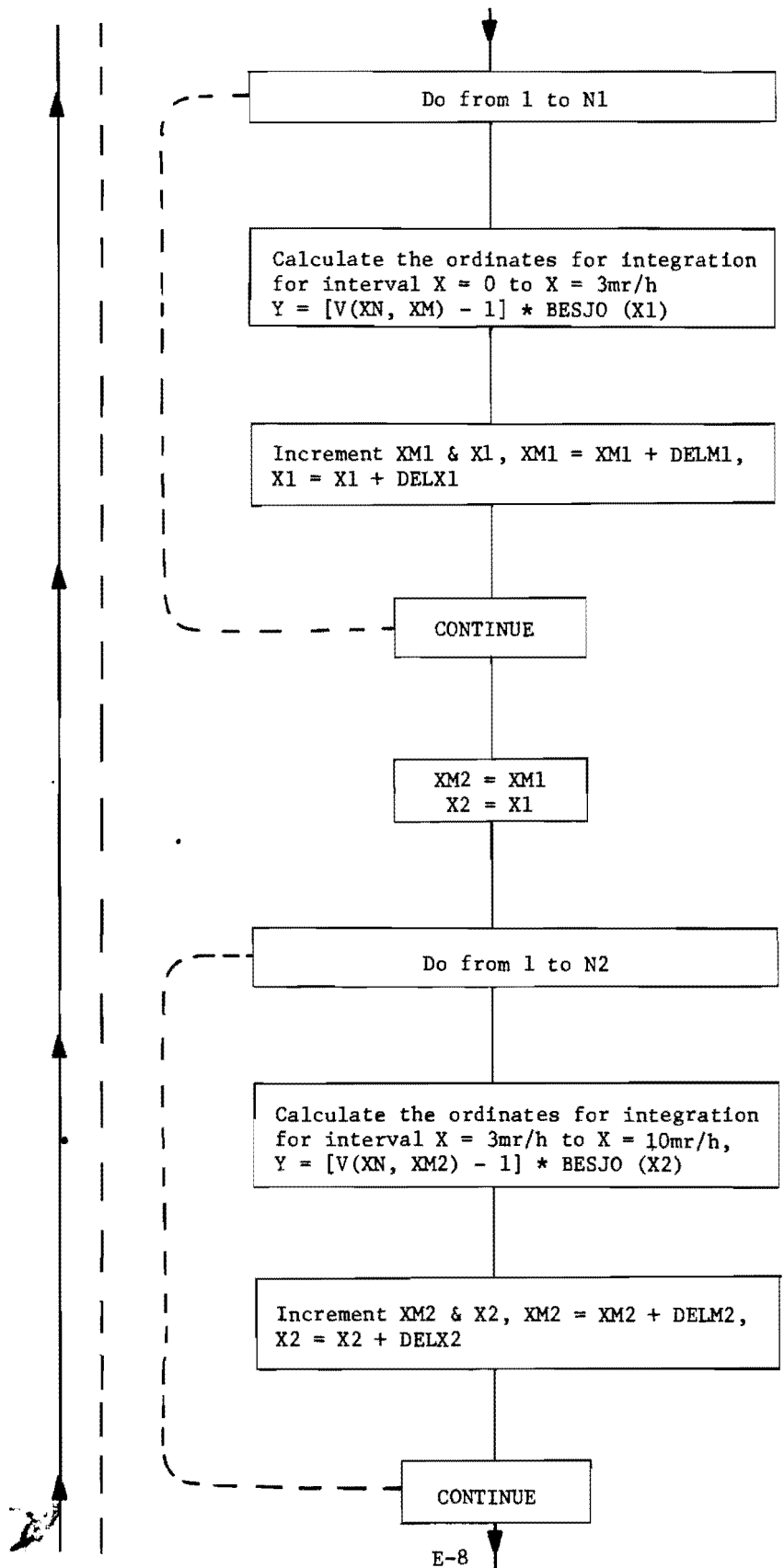


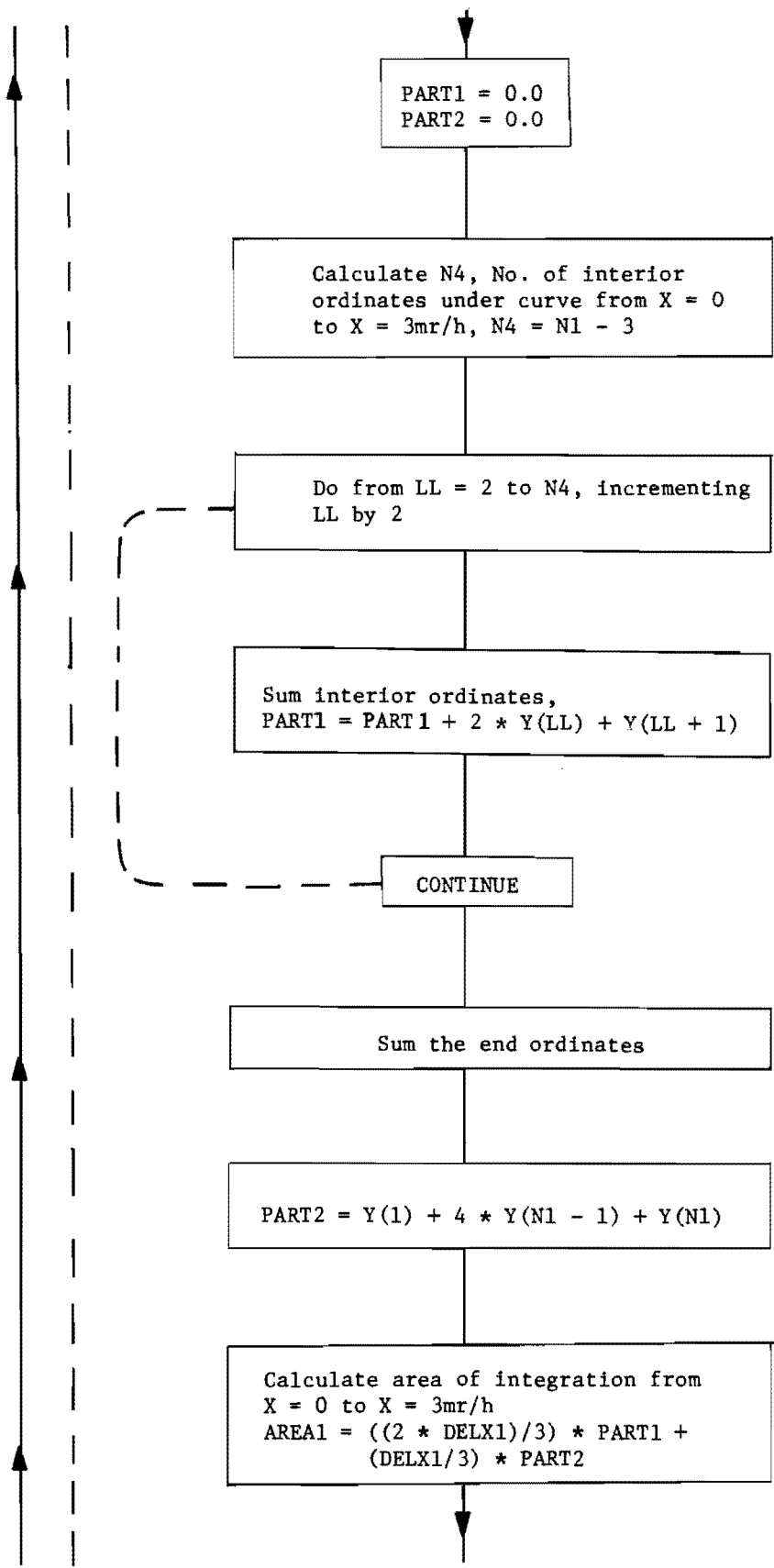


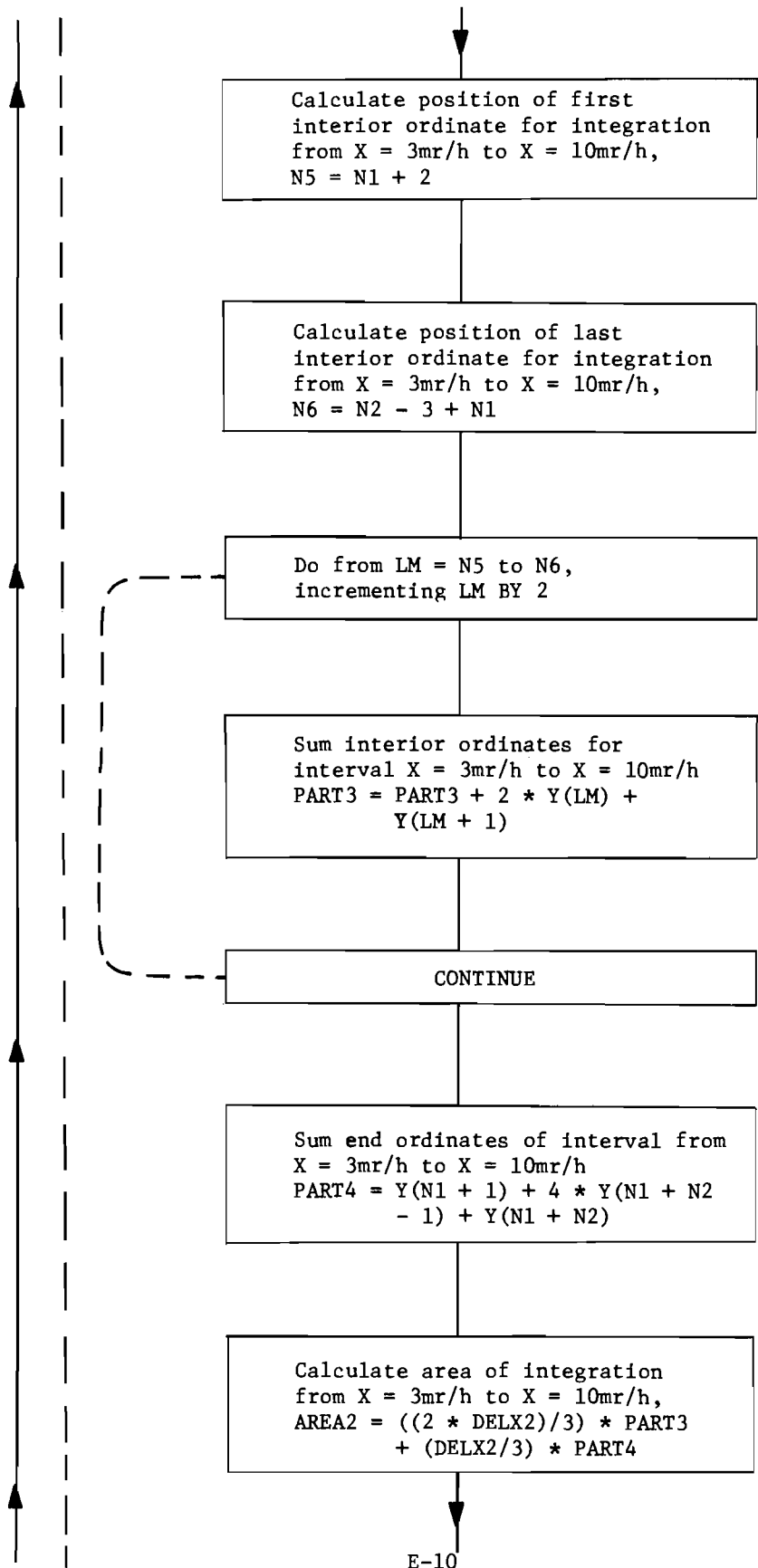
SUBROUTINE EMOD

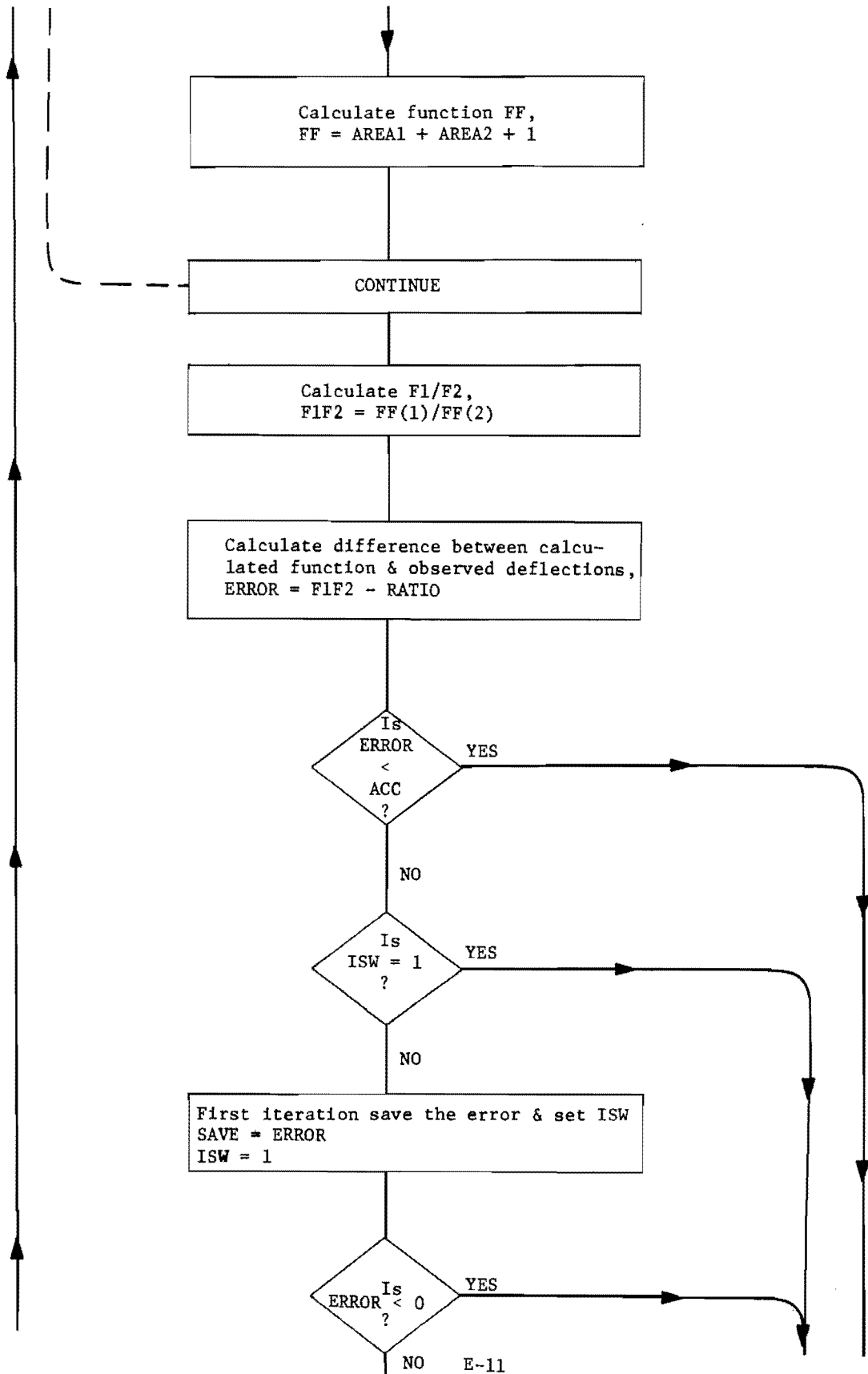


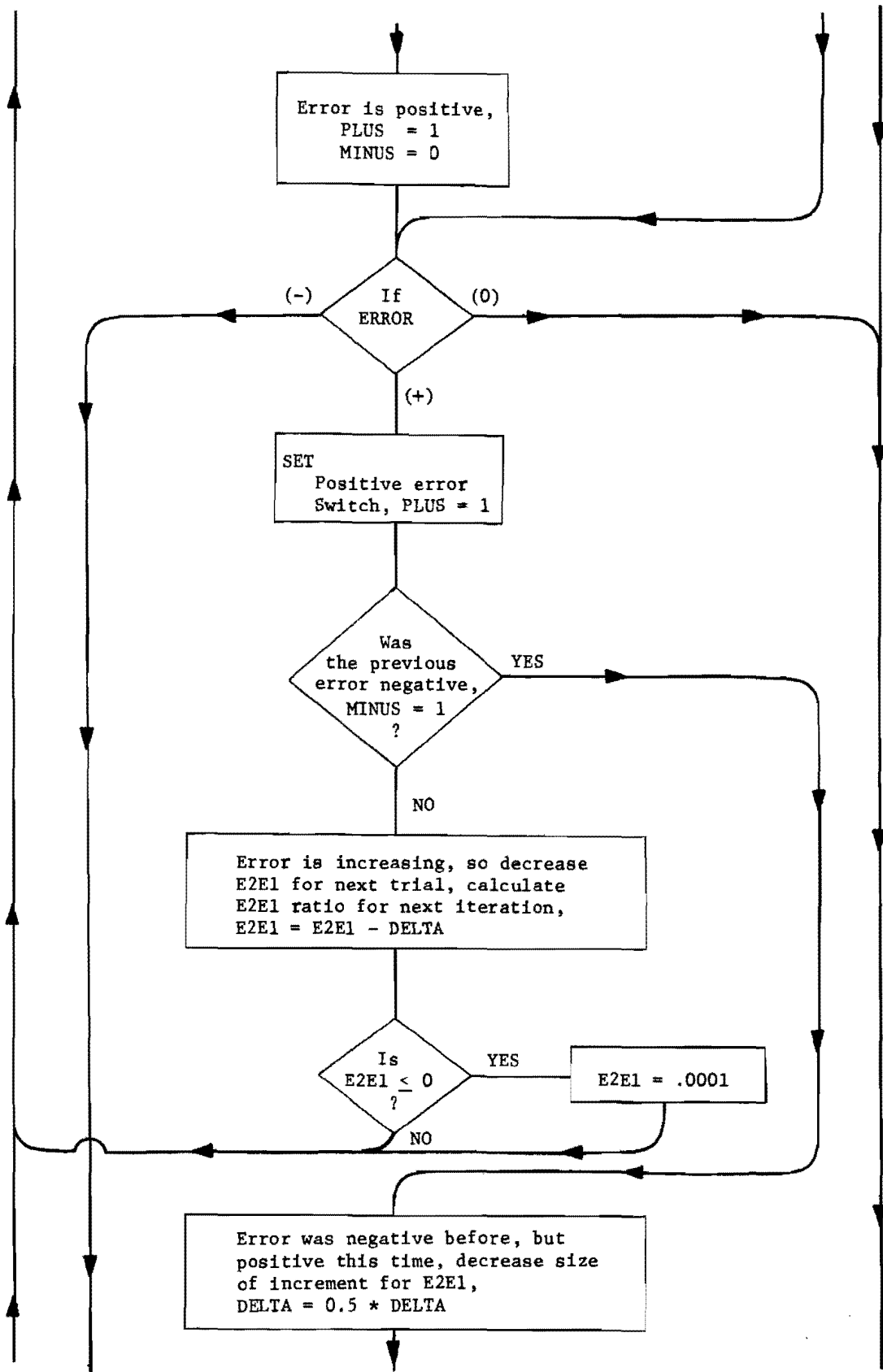


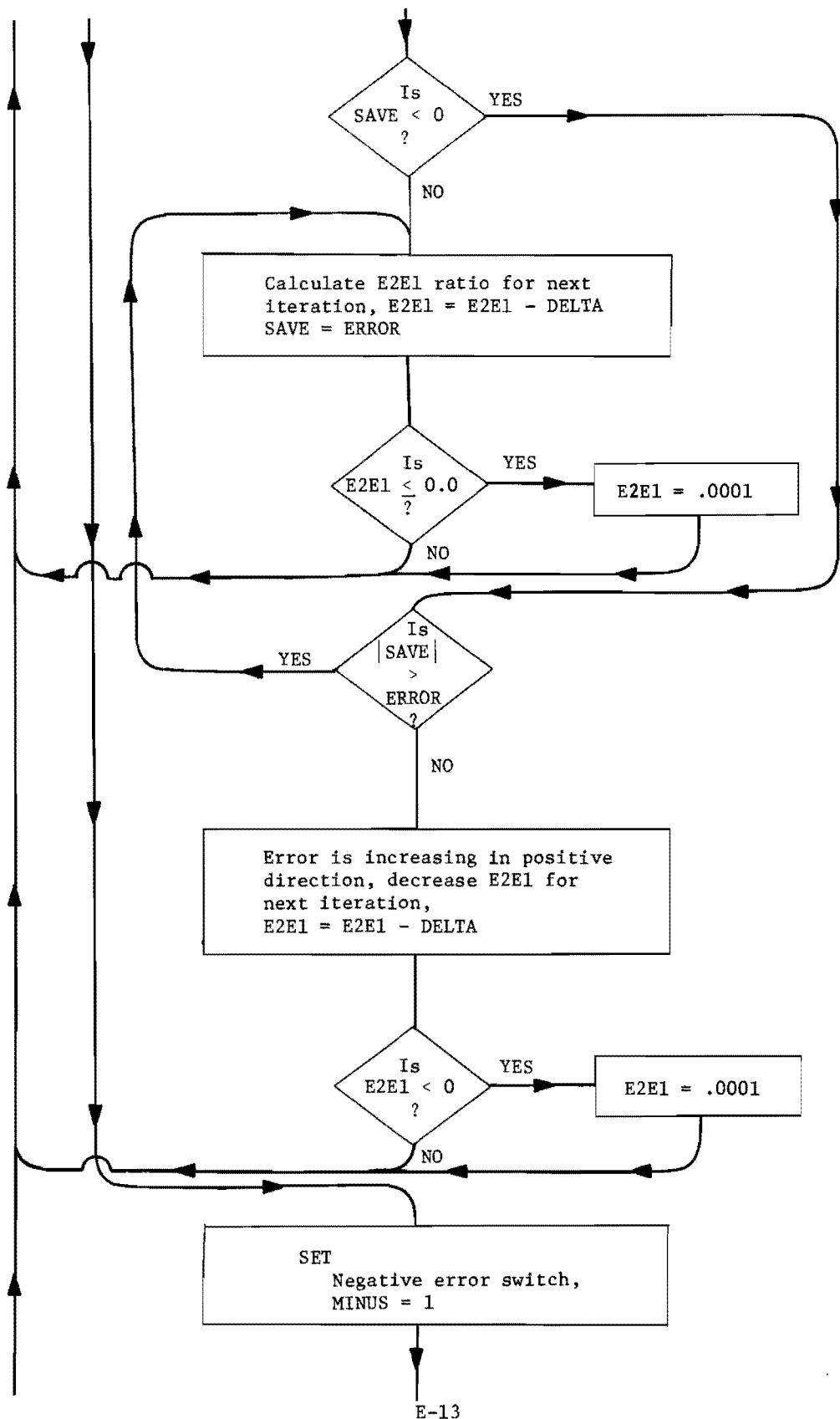


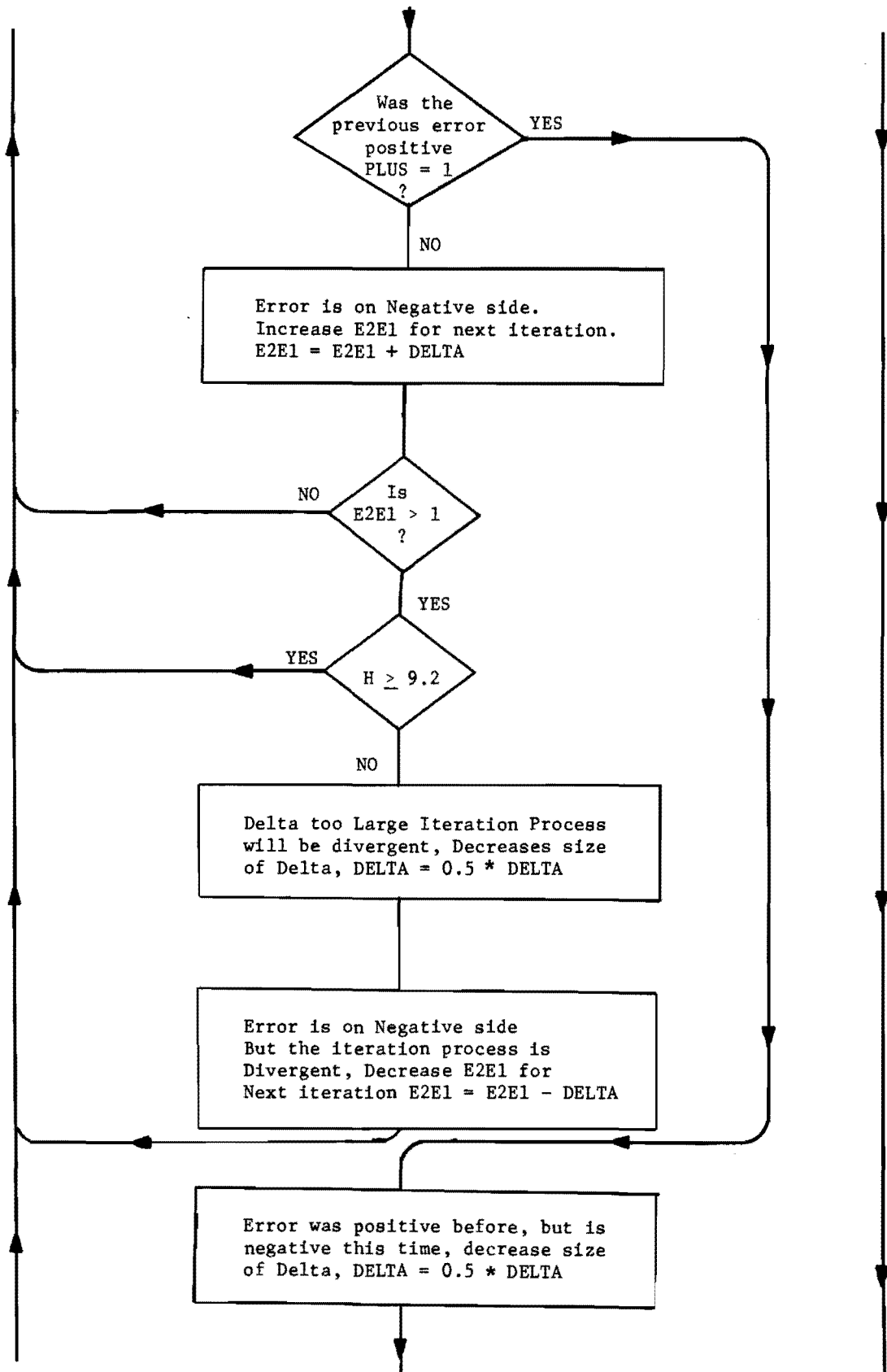


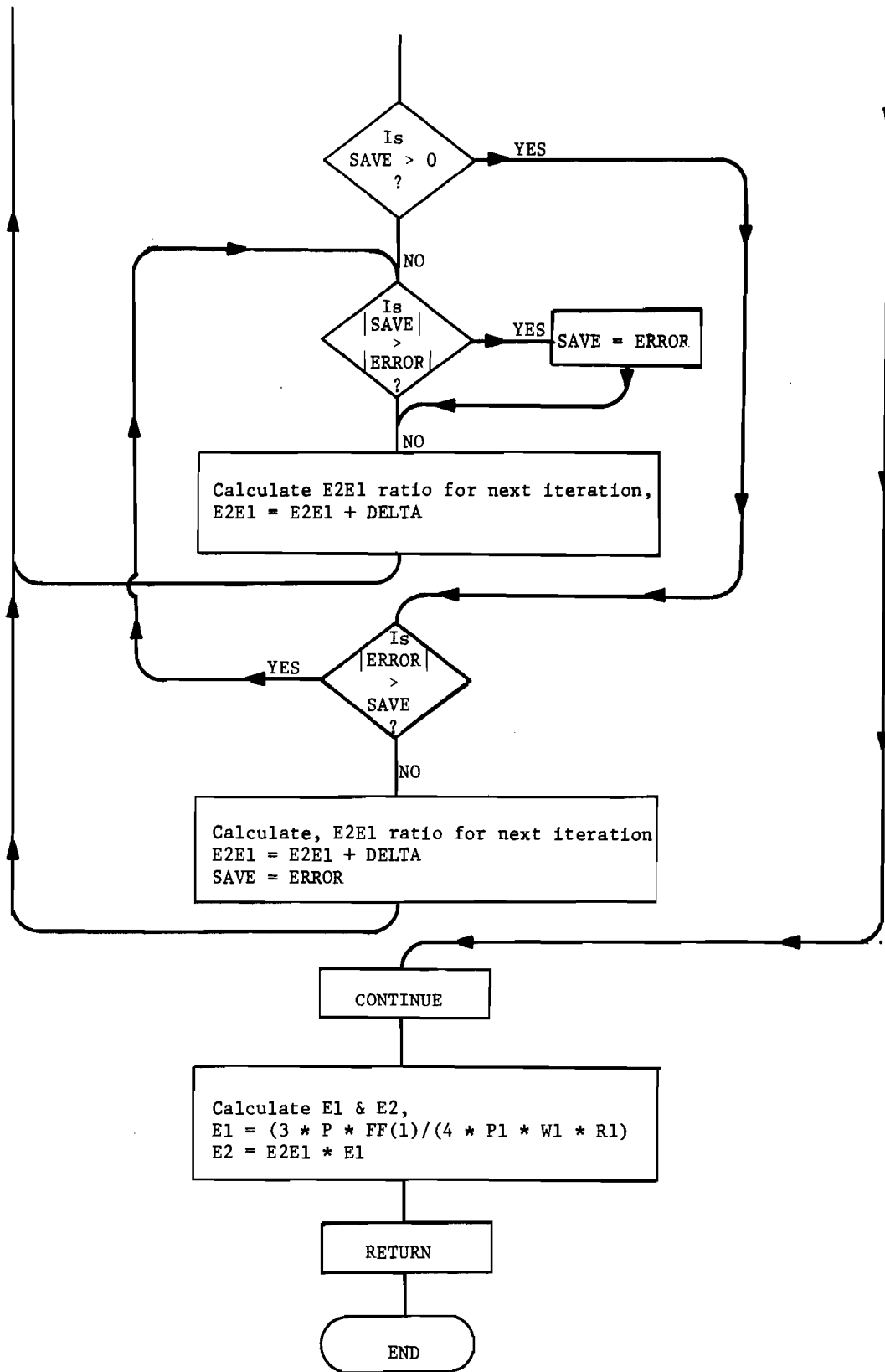




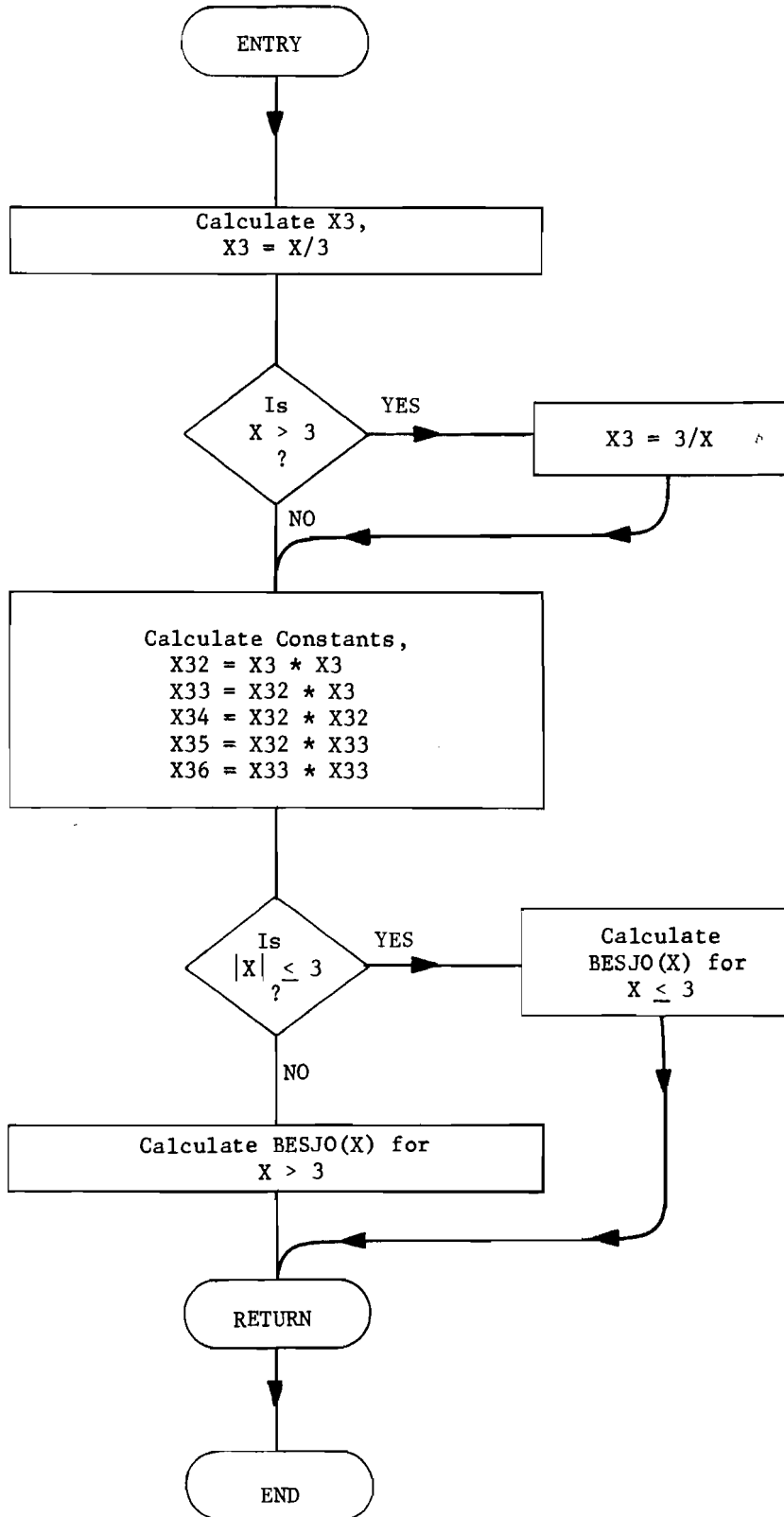




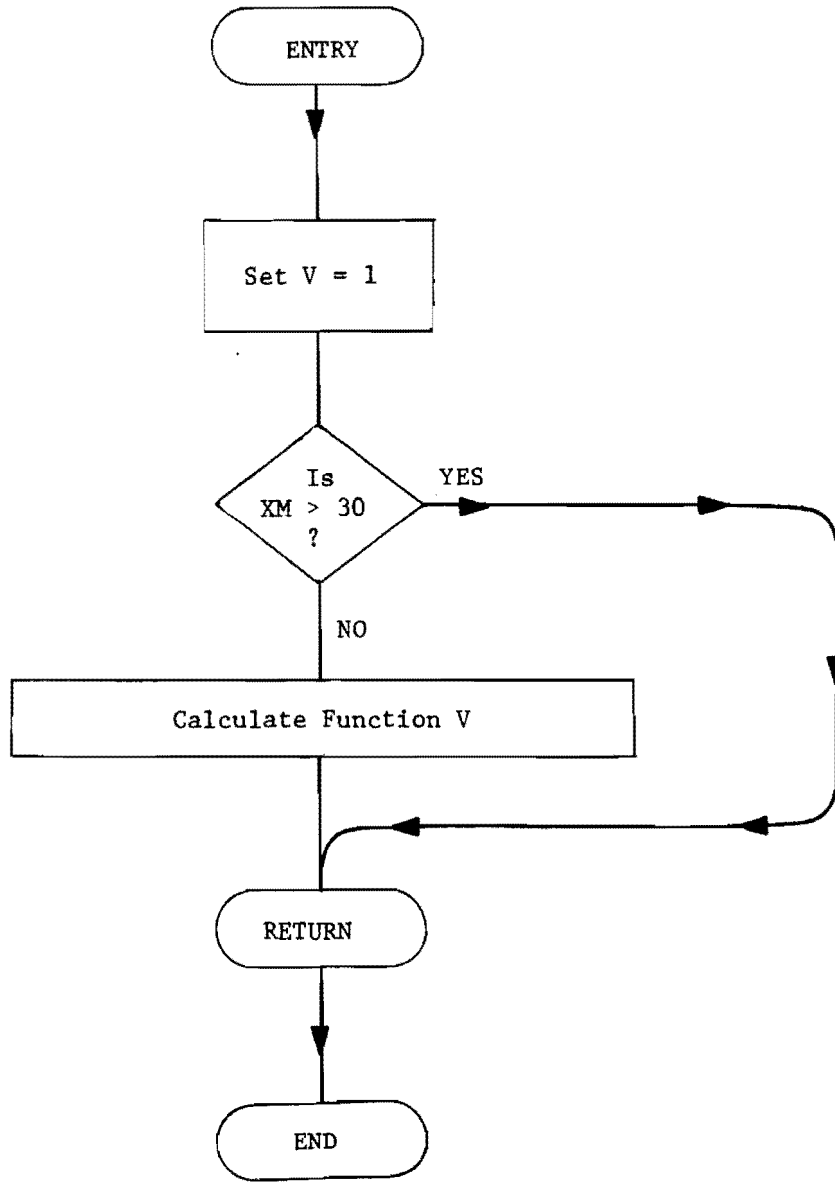




FUNCTION BESJO



FUNCTION V



Appendix 6

On the following pages is a listing of ELASTIC MODULUS with the output from a sample problem. The input data cards for the sample problem are listed after the program output.

```

C
C
C   ELASTIC MODULII  --  MAIN PROGRAM
C
0001  DIMENSION STA(200),W1(200),W2(200),W3(200),W4(200),
      * AP2(200),LA1(5),LA2(5),LA3(5),LA4(5),LA5(5),LA6(5),
      * W5(200),AS2(200),A(20),SCI(200),
0002  * IXDATE(3),COMM(7),REM(4)
      REAL * 8 STA, DAS , DAP, DBLE
C
C
C   NOTE -- THE PRINT & FORMAT STATEMENTS ARE FOR
C   OUTPUT ON 8 1/2 X 11 PAPER.  FOR OUTPUT ON 11 X 14
C   PAPER USE THE PRINT & FORMAT STATEMENTS WITH 'C' IN
C   COLUMN 1.
C
C
CCC  STATEMENT FUNCTION TO ROUND 'X' TO NEAREST 'EVEN'
C
0003  ROUND( X, EVEN ) = AINT( ( X + EVEN * .5 ) / EVEN )
      * * EVEN
C
0004  10 CONTINUE
C
C   READ CARD CODE & REMAINDER OF CARD INTO A - ARRAY
C
0005  READ(5,1,END=1000) NCARD, ( A(I), I = 1 , 20 )
C
0006  1 FORMAT( I3, 19A4, A1 )
0007  CALL CORE ( A, 80 )
C
C   TEST FOR DATA CARD 1
C
0008  IF(NCARD.EQ.100) GO TO 11
C
C   TEST FOR DATA CARD 2
C
0009  IF(NCARD.EQ.200) GO TO 12
C
C   TEST FOR DATA CARD 3
C
0010  IF(NCARD.EQ.300) GO TO 13
C
C   I IS A POINTER TO DATA IN STORAGE
C
0011  14 I=N+1

```

```

C
C   READ DATA CARD 4
C
0012  READ(5,6) ICONT,ISECT,M,IDAY,IYEAR,STA(I),D1,D2,D3,
      * D4, D5, D6, D7, D8,
      *D9,D10,(REM(J),J=1,4),ICK
C
0013  6 FORMAT(   I4,4I2,A7,3X, 5(F2.1,F3.2),8X,4A4,I2)
C
0014  IF( N.GT. 0 ) GO TO 555
0015  IF(NO.GT.0) GO TO 555
C
C   PRINT OUTPUT COLUMN HEADINGS
C
0016  PRINT 61
C 61 FORMAT(/,1X,'STATION   W1     W2     W3     W4     ',
C      = 'W5     SCI   ** ES   ** ** EP   **   REMARKS' / )
0017  61 FORMAT(/ 7X,'STATION   W1     W2     W3     W4     W5',
C      = '   SCI   ** ES   ** ** EP   **   REMARKS' / )
C
C   CALCULATE DEFLECTIONS & SCI ( DEFLECTIONS IN MILS )
C
0018  555 W1(I)=D1*D2
0019      W2(I)=D3*D4
0020      W3(I)=D5*D6
0021      W4(I)=D7*D8
0022      W5(I)=D9*D10
0023      SCI(I)=W1(I)-W2(I)
C
C   TEST FOR W1 OR W2 = 0, AND W1 LESS THAN W2
C
0024  IF (W1(I).EQ.0.OR.W2(I).EQ.0) GO TO 64
0025  IF(W1(I).LT.W2(I)) GO TO 66
C
0026  AW1 =AW1 +W1 (I)
0027  AW2 =AW2 +W2 (I)
0028  AW3 =AW3 +W3(I)
0029  AW4 =AW4 +W4(I)
0030  AW5 =AW5 +W5(I)
0031  ASCI=ASCI+SCI(I)
0032  AS2(I) = 0.0
0033  AP2(I) = 0.0
C
C
0034  IF( ( W1(I) * 10.0 ) / ( W2(I) * SQRT( 244.0 ) )
      = .GT. 1.0 .AND. DP .LE. 9.1 ) GO TO 60
C
C

```

```

C      CONVERT W1 & W2 TO INCHES
C
0035      W1(I) = W1(I) / 1000.
0036      W2(I) = W2(I) / 1000.
C
C      PASS W1, W2, & TOTAL PAVEMENT THICKNESS TO EMOD,
C      EMOD RETURNS UNROUNDED VALUES OF PAVEMENT & SUBGRADE
C      MODULII AS DAP & DAS
C
0037      CALL EMOD ( DBLE(W1(I)), DBLE(W2(I)), DBLE(DP),DAP, DAS)
C
C      CONVERT W1 & W2 TO MILS
C
0038      W1(I) = W1(I) * 1000.
0039      W2(I) = W2(I) * 1000.
C
C
C      ROUND PAVEMENT & SUBGRADE MODULII TO NEAREST 100
C
0040      DAS = ROUND( DAS, 100. )
0041      DAP = ROUND( DAP, 100. )
C
C      PUT PAVEMENT & SUBGRADE MODULII IN STORAGE
C
0042      AS2(I) = DAS
0043      AP2(I) = DAP
C
C      ADD TO THE SUMS OF THE DEFLECTIONS, SCI, PAVEMENT,
C      AND SUBGRADE MODULII
C
0044      AAS2=AAS2+AS2(I)
0045      AAP2=AAP2+AP2(I)
C
C      ADD TO N, THE NUMBER OF VALID TEST POINTS
C
0046      N=N+1
C
C      PRINT A LINE OF OUTPUT
C
C      PRINT 63,STA(I),W1(I),W2(I),W3(I),W4(I),W5(I),SCI(I),
C      = AS2(I), AP2(I), ( REM(J),J=1,4 )
C 63 FORMAT(1X, A7, 3X, 5(F5.3,2X ), F5.3,2F11.0,5X,4A4 )
0047      PRINT 63,STA(I),W1(I),W2(I),W3(I),W4(I),W5(I),SCI(I),
C      * AS2(I), AP2(I), (REM(J),J=1,2)
0048      63 FORMAT( 7X,A7,1X,6(F6.3), 2F10.0,2X, 2A4 )
0049      N1 = N1 + 1

```



```

0050          IF(N1.LT.30) GO TO 88
      C
      C      SKIP TO NEXT PAGE & PRINT OUTPUT COLUMN HEADINGS IF
      C      THIRTY LINES HAVE BEEN PRINTED
      C
0051          84 CONTINUE
0052          PRINT 51
      C      PRINT 56
      C      PRINT 57, IDIST, CO1, CO2, CO3, CO4, ICONT, ISECT, IJOB, HWY1,
      C      * HWY2, XLANE, M, IDAY, IYEAR, IDYNA
0053          PRINT 56, IDIST, CO1, CO2, CO3, CO4
0054          56 FORMAT( T35, 'DIST. COUNTY' / T36, I2, 9X, 3A4, A2 /)
0055          PRINT 57, ICONT, ISECT, IJOB, HWY1, HWY2, M, IDAY, IYEAR, IDYNA
0056          57 FORMAT( T19, 'CONT. SECT. JOB HIGHWAY DATE',
      C      ' DYNAFLECT' / T19, I4, 2I7, 4X, A4, A3, I4, 2( '- ', I2), I9 /)
0057          PRINT 61
0058          N1 = 0
0059          88 CONTINUE
      C
      C      CHECK FOR LAST DATA CARD 4
      C
0060          IF (ICK.EQ.0) GO TO 10
0061          GO TO 80
      C
      C      READ DATA CARD 1
      C
0062          11 READ(5, 2) IDIST, CO1, CO2, CO3, CO4, ICONT, ISECT, IJOB, HWY1,
      C      * HWY2, XLANE, DP, M, IDAY, IYEAR, IDYNA, (COMM(I), I=1, 7)
0063          2 FORMAT( I2, 3A4, A2, I4, 2I2, A4, A3, A3, F5.2, 4I2, 7A4)
      C
      C      PRINT HEADING
      C
0064          PRINT 51
0065          51 FORMAT( '1' )
      C
0066          PRINT 52
      C      52 FORMAT(33X, 'TEXAS HIGHWAY DEPARTMENT', /)
0067          52 FORMAT(35X, 'TEXAS HIGHWAY DEPARTMENT' /)
      C
0068          PRINT 53, IDIST
      C      53 FORMAT(31X, 'DISTRICT ', I2, ' - DESIGN SECTION', /)
0069          53 FORMAT(33X, 'DISTRICT ', I2, ' - DESIGN SECTION' /)
      C
0070          PRINT 54
      C      54 FORMAT(16X, 'DYNAFLECT DEFLECTIONS AND CALCULATED ',
      C      = 'ELASTIC MODULII' / )
0071          54 FORMAT(21X, 'DYNAFLECT DEFLECTIONS AND CALCULATED ',
      C      * 'ELASTIC MODULII' / )

```

```

C
C   GET CURRENT DATE
C
0072  CALL DATE ( IXDATE(1), IXDATE(2), IXDATE(3) )
C
0073  PRINT 55,IXDATE
C   55 FORMAT(30X,'THIS PROGRAM WAS RUN - ', 2A3,A2 / )
0074  55 FORMAT(32X,'THIS PROGRAM WAS RUN - ', 2A3,A2 / )
C
C   PRINT 56
C   56 FORMAT( 1X,'DIST.      COUNTY      CONT.   SECT.',
C   *'  JOB  HIGHWAY  DATE      DYNAFLECT')
0075  PRINT 56, IDIST, CO1, CO2, CO3, CO4
C
C   PRINT CONTROL INFORMATION FROM DATA CARD 1
C
C   PRINT 57, IDIST, CO1, CO2, CO3, CO4, ICONT, ISECT, IJOB, HWY1,
C   * HWY2, XLANE, M, IDAY, IYEAR, IDYNA
C   57 FORMAT( 2X, I2, 5X, 3A4, A2, 3X, I4, 4X, I2, 5X, I2, 2X, A4, A3,
C   * A3, 2X, I2, '- ', I2, '- ', I2, 6X, I2 / )
0076  PRINT 57, ICONT, ISECT, IJOB, HWY1, HWY2, M, IDAY, IYEAR, IDYNA
C
0077  PRINT 58, (COMM(I), I=1, 7), DP
0078  58 FORMAT(10X, 7A4, 2X, 'PAV. THICK. = ', F5.2, ' INCHES', /)
C
C   INITIALIZE ALL SUMS & COUNTERS
C
0079  N=0
0080  N1 = 0
0081  NO = 0
0082  AW1= 0.
0083  AW2=0.
0084  AW3=0.
0085  AW4=0.
0086  AW5=0.
0087  ASCI=0.
0088  AAS2=0.
0089  AAP2=0.
0090  SR1= 0.
0091  SR2= 0.
0092  SR3= 0.
C
0093  GO TO 10
C   READ & PRINT INFORMATION ON DATA CARD 2
C
0094  12 READ(5, 3) (LA1(I), I=1, 5), T1, (LA2(I), I=1, 5), T2,
C   * (LA3(I), I=1, 5), T3
0095  3 FORMAT( 5A4, F4.2, 5A4, F4.2, 5A4, F4.2)

```

```

C      PRINT 59, (LA1(I), I=1, 5), T1, (LA2(I), I=1, 5), T2,
C      * (LA3(I), I=1, 5), T3
C 59  FORMAT( 1X, 5A4, 1X, F5.2, 2X, 5A4, 1X, F5.2, 2X, 5A4, 1X, F5.2)
0096      PRINT 59, (LA1(I), I=1, 5), T1, (LA2(I), I=1, 5), T2
0097      PRINT 59, ( LA3(I), I=1, 5), T3
0098      59  FORMAT(16X, 5A4, 1X, F5.2, 5X, 5A4, 1X, F5.2/)
0099      GO TO 10

C
C      READ & PRINT INFORMATION ON DATA CARD 3, IF PRESENT
C
0100      13 READ(5, 3) (LA4(I), I=1, 5), T4, (LA5(I), I=1, 5), T5,
C      * (LA6(I), I=1, 5), T6
C      PRINT 59, (LA4(I), I=1, 5), T4, (LA5(I), I=1, 5), T5,
C      * (LA6(I), I=1, 5), T6
0101      PRINT 59, (LA4(I), I=1, 5), T4, (LA5(I), I=1, 5), T5
0102      PRINT 59, ( LA6(I), I=1, 5), T6
0103      GO TO 10
0104      66 NO = NO+1

C
C      PRINT NEGATIVE SCI MESSAGE
C
0105      PRINT 82, STA(I), W1(I), W2(I), (REM(J), J=1, 4)
0106      82  FORMAT(1X, A7, 3X, F5.3, 2X, F5.3, 2X, 'NEGATIVE SCI OTHER ',
C      * 'CALCULATIONS OMITTED', 4X, 4A4)

C
0107      N1=N1+1
0108      IF( N1 .LT. 30 ) GO TO 88
0109      GO TO 84
0110      64 NO = NO + 1

C
C      PRINT ERROR MESSAGE
C
0111      PRINT 81, STA(I), (REM(J), J=1, 4)
0112      81  FORMAT( 1X, A7, 3X, 'DATA ERROR ASSUMED A ZERO VALUE RE',
C      * 'AD FOR W1 OR W2', 5X, 4A4 )

C
0113      N1 = N1+ 1
0114      IF( N1 .LT. 30 ) GO TO 88
0115      GO TO 84

C
C
0116      60 CONTINUE
0117      N = N + 1
0118      NO = NO + 1
0119      PRINT 85, STA(I), W1(I), W2(I), W3(I), W4(I),
C      W5(I), SCI(I)
0120      85  FORMAT( 7X, A7, 1X, 6F6.3, 2X,
C      'NO UNIQUE SOLUTION' )

```

```

0121          N1 = N1 + 1
0122          IF( N1 .LT. 30 ) GO TO 88
0123          GO TO 84
C
C
C
C          ALL CARDS READ FOR AN ANALYSIS, CALCULATE AVERAGE
C          DEFLECTIONS, AVERAGE SCI, AVERAGE PAVEMENT MODULUS,
C          AND AVERAGE SUBGRADE MODULUS
C
0124          80 PN=N
0125          N1 = N - NO
0126          IF( N1 .LE. 0 ) N1 = 1
0127          AW1V= AW1/PN
0128          AW2V= AW2/PN
0129          AW3V= AW3/PN
0130          AW4V= AW4/PN
0131          AW5V= AW5/PN
0132          ASCIV=ASCI/PN
0133          AAS2V=AAS2/N1
0134          AAP2V=AAP2/N1
C
C          CALCULATE VARIANCE OF SCI, SUBGRADE MODULUS & PAVE-
C          MENT MODULUS
C
0135          DO 62 I=1,N
0136          IF(W1(I).EQ.0.OR.W2(I).EQ.0) GO TO 62
0137          SR1 = SR1 + ((ASCIV- SCI(I))**2)
0138          IF( AS2(I) .EQ. 0.0) GO TO 62
0139          SR2= SR2+((AAS2V-AS2(I))**2)
0140          SR3= SR3+((AAP2V- AP2(I))**2)
0141          62 CONTINUE
C
C          PRINT AVERAGES
C
0142          PRINT 65,AW1V,AW2V,AW3V,AW4V,AW5V,ASCIV,AAS2V,AAP2V
C          65 FORMAT(/1X,'AVERAGES', 6(2X, F5.3 ), 2F11.0 )
0143          65 FORMAT(/ 7X, 'AVERAGES', 6(F6.3), 2F10.0 )
C
C          CALCULATE STANDARD DEVIATION OF SCI, SUBGRADE
C          MODULUS, AND PAVEMENT MODULUS
C
0144          IF( PN .EQ. 1 ) GO TO 90
0145          SE1 = SQRT(SR1/(PN-1))
0146          IF( N1 .LE. 1 ) GO TO 90
0147          SE2 = SQRT(SR2/(N1-1))
0148          SE3 = SQRT(SR3/(N1-1))
C
C          PRINT STANDARD DEVIATIONS

```

```

C
0148          PRINT 71,SE1,SE2,SE3
C 71 FORMAT( 1X,'STANDARD DEVIATION',27X,F5.3, 2F11.0  )
0149          71 FORMAT( 7X,'STANDARD DEVIATION', 20X,F6.3,2F10.0)
C
0150          90 CONTINUE
0151          IF( N .EQ. 1 ) N1 = 1
0152          PRINT 99,N, N1, N1
C 99 FORMAT(1X,'NUMBER OF POINTS IN AVERAGE = ',
C = I14, I9, I10 )
0153          99 FORMAT( 7X,'NUMBER OF POINTS IN AVERAGE = ',
C = I14, I9, I10 )
C
0154          PRINT 91
C 91 FORMAT( /,5X,'W1 DEFLECTION AT GEOPHONE 1' )
0155          91 FORMAT(/10X,'W1 DEFLECTION AT GEOPHONE 1' )
C
0156          PRINT 92
C 92 FORMAT( 5X,'W2 DEFLECTION AT GEOPHONE 2' )
0157          92 FORMAT( 10X,'W2 DEFLECTION AT GEOPHONE 2' )
C
0158          PRINT 93
C 93 FORMAT( 5X,'W3 DEFLECTION AT GEOPHONE 3' )
0159          93 FORMAT( 10X,'W3 DEFLECTION AT GEOPHONE 3' )
C
0160          PRINT 94
C 94 FORMAT( 5X,'W4 DEFLECTION AT GEOPHONE 4' )
0161          94 FORMAT( 10X,'W4 DEFLECTION AT GEOPHONE 4' )
C
0162          PRINT 95
C 95 FORMAT( 5X,'W5 DEFLECTION AT GEOPHONE 5' )
0163          95 FORMAT( 10X,'W5 DEFLECTION AT GEOPHONE 5' )
C
0164          PRINT 96
C 96 FORMAT( 5X,'SCI SURFACE CURVATURE INDEX ( W1 MIN',
C = 'US W2)' )
0165          96 FORMAT( 10X,'SCI SURFACE CURVATURE INDEX ( W1 MIN',
C * 'US W2)' )
C
0166          PRINT 97
C 97 FORMAT( 5X,'ES ELASTIC MODULUS OF THE SUBGRADE FRO',
C = 'M W1 AND W2' )
0167          97 FORMAT( 10X,'ES ELASTIC MODULUS OF THE SUBGRADE FRO',
C * 'M W1 AND W2' )
C
0168          PRINT 98
C 98 FORMAT( 5X,'EP ELASTIC MODULUS OF THE PAVEMENT FROM',
C = ' W1 AND W2' )

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```
0169          98 FORMAT( 10X,'EP ELASTIC MODULUS OF THE PAVEMENT FRO',  
                * 'M W1 AND W2' )  
C  
C  
0170          GO TO 10  
0171          1000 CONTINUE  
0172          END
```

```

0001      SUBROUTINE EMOD ( W1, W2, H, E1, E2 )
          C
          C
0002      IMPLICIT REAL * 8 ( A-H, O-Z )
0003      DIMENSION RH( 2), FF( 2), Y(4000), DELM1(2),
          DELM2(2), DELX1(2), DELX2(2)
          C
0004      DATA P / 1000.000 / , ER / .00100 /
0005      DATA XNO / 61.000 / , XK1 / 0.0100 / , XK2 / 0.1000 /
          C
          C      P, XNO, XK1, XK2, R1 & R2 CAN BE CHANGED IF DESIRED
          C
0006      INTEGER PLUS
          C
          C      INITIALIZE SWITCHES & SAVE
          C
0007      R1 = 10.000
0008      R2 = DSQRT( 244.000 )
0009      MINUS = 1
0010      PLUS = 0
0011      ISW = 0
0012      SAVE = 0.000
          C
          C      CALCULATE R/H, RATIO, & ACC ( ACC IS THE CONVERGENCE
          C      CRITERION )
          C
0013      RH(1) = R1 / H
0014      RH(2) = R2 / H
0015      RATIO = ( W1 * R1 ) / ( W2 * R2 )
0016      ACC = ER * RATIO
          C
          C
0017      DO 2 KL = 1 , 2
          C
          C      CALCULATE AND TEST DELM1
          C
0018      DELM1(KL) = ( 1.000 / RH(KL) ) * ( 3.000 /
          * ( XNO - 1.000 ) )
          C
0019      IF( XK1 .LE. DELM1(KL) ) DELM1(KL) = XK1
          C
          C      CALCULATE DELX1
          C
0020      DELX1(KL) = DELM1(KL) * RH(KL)
          C
          C      CALCULATE AND TEST DELM2
          C
0021      DELM2(KL) = ( 1.000 / RH(KL) ) * ( 3.000 /

```

```

      * ( XN0 - 1.000 ) )
0022      C      IF( XK2 .LE. DELM2(KL) ) DELM2(KL) = XK2
      C
      C      CALCULATE DELX2
      C
0023      C      DELX2(KL) = DELM2(KL) * RH(KL)
0024      C      2 CONTINUE
      C
      C      GET INITIAL VALUE OF E2/E1 AND DELTA
      C
0025      C      DELTA = 0.500
0026      C      E2E1 = 0.00100
      C
      C      START ITERATION LOOP FOR EACH E2/E1 VALUE USED
      C
0027      C      4 CONTINUE
0028      C      XN = ( 1.000 - E2E1 ) / ( 1.000 + E2E1 )
      C
      C      THE FUNCTIONS FF(1) AND FF(2) (SEE EQN. 5) ARE
      C      CALCULATED IN THE FOLLOWING DO LOOP.
      C
0029      C      DO 29 KK = 1 , 2
      C
      C      CALCULATE NO. OF INTERVALS FOR SIMPSON'S RULE FOR
      C      EACH INTEGRATION. N1 & N2 MUST BE ODD INTEGERS.
      C
0030      C      N1 = ( 3.000 * RH(KK) ) / DELX1(KK) + 1.000
0031      C      IF((N1 / 2) * 2 .EQ. N1) N1 = N1 + 1
      C
0032      C      N2 = ( 7.000 * RH(KK) ) / DELX2(KK) + 1.000
0033      C      IF((N2 / 2) * 2 .EQ. N2) N2 = N2 + 1
      C
      C      CALCULATE ORDINATES FOR SIMPSON'S RULE FOR FIRST
      C      INTEGRATION
      C
0034      C      XM1 = 0.000
0035      C      X1 = 0.000
0036      C      DO 28 JJ = 1, N1
0037      C      Y(JJ) = ( V( XN, XM1 ) - 1.000 ) * BESJO( X1 )
0038      C      XM1 = XM1 + DELM1(KK)
0039      C      X1 = X1 + DELX1(KK)
0040      C      28 CONTINUE
      C
      C      CALCULATE ORDINATES FOR SIMPSON'S RULE FOR SECOND
      C      INTEGRATION

```



```

C
0041      XM2 = XM1
0042      X2 = X1
0043      DO 27  KL = 1,N2
0044      Y(N1 + KL) = ( V( XN, XM2 ) - 1.000 ) * BESJO( X2 )
0045      XM2 = XM2 + DELM2(KK)
0046      X2 = X2 + DELX2(KK)
0047      27  CONTINUE

C
C      SUM ORDINATES TO CALCULATE AREA UNDER THE CURVE OF FIRST
C      INTEGRATION
C
0048      PART1 = 0.000
0049      PART3 = 0.000

C
C      N4 IS NO. OF INTERIOR ORDINATES OF FIRST INTEGRATION
C
0050      N4 = N1 - 3

C
C      SUM INTERIOR ORDINATES
C
0051      DO 26  LL = 2 , N4, 2
0052      26  PART1 = PART1 + ( 2.000 * Y(LL) + Y(LL+1) )

C
C      SUM END ORDINATES
C
0053      PART2 = Y(1) + 4.000 * Y(N1-1) + Y(N1)

C
C      CALCULATE AREA OF FIRST INTEGRATION.
C
0054      AREA1 = ((2.000 * DELX1(KK)) / 3.000) *
      PART1 + ( DELX1(KK) / 3.000) * PART2

C
C      SUM ORDINATES TO CALCULATE AREA UNDER THE CURVE OF
C      SECOND INTEGRATION
C
C
C      THE LAST ORDINATE OF THE FIRST INTERVAL OF INTEGRAT-
C      ION IS ALSO THE FIRST ORDINATE OF THE SECOND INTERVAL
C
C
C      N5 IS THE POSITION IN THE Y VECTOR OF THE FIRST
C      INTERIOR ORDINATE OF THE SECOND INTEGRATION INTERVAL
C
0055      N5 = N1 + 2

C
C      N6 IS THE POSITION IN THE Y VECTOR OF THE LAST
C      INTERIOR ORDINATE OF THE SECOND INTEGRATION INTERVAL

```

```

C
0056      N6 = N2 - 3 + N1
C
C      SUM INTERIOR ORDINATES
C
0057      DO 25 LM = N5 , N6 , 2
0058      25 PART3 = PART3 + ( 2.000 * Y(LM) + Y(LM+1) )
C
C      SUM END ORDINATES
C
0059      PART4 = Y(N1+1) + 4.000 * Y(N1 + N2 - 1) + Y(N1 + N2)
C
C      CALCULATE AREA OF SECOND INTEGRATION.
C
0060      AREA2 = ((2.000 * DELX2(KK)) / 3.000) *
          PART3 + ( DELX2(KK) / 3.000) * PART4
C
C      CALCULATE THE FUNCTION.
C
0061      FF(KK) = AREA1 + AREA2 + 1.000
0062      29 CONTINUE
C
C      CALCULATE F1/F2 AND CHECK FOR CONVERGENCE
C
0063      F1F2 = FF(1) / FF(2)
0064      ERROR = F1F2 - RATIO
0065      IF(DABS( ERROR ) .LT. ACC ) GO TO 31
C
C      SET ISW AND SAVE ON FIRST TIME THROUGH ITERATION LOOP
C
0066      IF( ISW .NE. 0 ) GO TO 6
0067      ISW = 1
0068      SAVE = ERROR
0069      IF( ERROR .LT. 0.000 ) GO TO 6
C
C      SIGN OF FIRST ERROR IS '+'
C
0070      PLUS = 1
0071      MINUS = 0
0072      6 CONTINUE
C
C      TEST FOR SIGN OF ERROR
C
0073      IF( ERROR ) 30, 31, 32
C
C      SIGN OF ERROR IS '+'
C
0074      32 PLUS = 1

```

```

0075          IF( MINUS .NE. 0 ) GO TO 40
      C
      C      ERROR IS POSITIVE, DECREASE E2E1 FOR NEXT TRIAL
      C
0076          E2E1 = E2E1 - DELTA
0077          IF( E2E1 .LE. 0.000 ) E2E1 = 0.000100
0078          GO TO 4
      C
      C
      C      ERROR WAS NEGATIVE, NOW POSITIVE, CHANGE DELTA
      C
0079          40 DELTA = 0.500 * DELTA
0080          IF( SAVE .LT. 0.000 ) GO TO 42
      C
      C      SET SAVE = ERROR, DECREASE E2E1 FOR NEXT TRIAL
      C
0081          41 SAVE = ERROR
0082          E2E1 = E2E1 - DELTA
0083          IF( E2E1 .LE. 0.000 ) E2E1 = 0.000100
0084          GO TO 4
      C
      C      ERROR IS INCREASING IN POSITIVE DIRECTION, DECREASE
      C      E2E1 FOR NEXT TRIAL
      C
0085          42 IF( DABS( SAVE ) .GT. ERROR ) GO TO 41
0086          E2E1 = E2E1 - DELTA
0087          IF( E2E1 .LE. 0.000 ) E2E1 = 0.000100
0088          GO TO 4
      C
      C      SIGN OF ERROR IS '-'
      C
0089          30 MINUS = 1
0090          IF( PLUS .NE. 0 ) GO TO 45
      C
      C      ERROR IS NEGATIVE, INCREASE E2E1 FOR NEXT TRIAL
      C
0091          E2E1 = E2E1 + DELTA
0092          IF( E2E1 .GT. 1.000 ) GO TO 44
0093          GO TO 4
      C
      C
0094          44 CONTINUE
0095          IF( H .GE. 9.200 ) GO TO 4
0096          DELTA = 0.5 * DELTA
0097          E2E1 = E2E1 - DELTA
0098          GO TO 4
      C
      C      ERROR IS NEGATIVE NOW, WAS POSITIVE BEFORE, CHANGE

```

```
C      DELTA
C
0099      45 DELTA = 0.500 * DELTA
0100      IF( SAVE .GT. 0.000 ) GO TO 47
C
C      TEST FOR ERROR LESS THAN SAVE
C
0101      46 IF(DABS ( SAVE ) .GT.DABS ( ERROR ) )SAVE = ERROR
C
C      INCREASE E2E1 FOR NEXT TRIAL
C
0102      E2E1 = E2E1 + DELTA
0103      IF( E2E1 .GT. 1.000 ) GO TO 44
0104      GO TO 4
C
C      TEST FOR ERROR GREATER THAN SAVE
C
0105      47 IF(DABS ( ERROR ) .GT. SAVE ) GO TO 46
C
C      ERROR IS APPROACHING CONVERGENCE FROM NEGATIVE SIDE,
C      SET SAVE = ERROR, INCREASE E2E1 FOR NEXT TRIAL
C
0106      SAVE = ERROR
0107      E2E1 = E2E1 + DELTA
0108      IF( E2E1 .GT. 1.000 ) GO TO 44
0109      GO TO 4
0110      31 CONTINUE
C
C      CONVERGENCE CRITERION IS MET, CALCULATE E1 & E2
C
0111      E1 = (3.000 * P * FF(1)) / (4.000 * 3.1415900 * W1 * R1)
0112      E2 = E2E1 * E1
C
0113      RETURN
0114      END
```

```

0001      REAL FUNCTION BESJO * 8 ( X )
          C
          C
          C      A FUNCTION TO CALCULATE BESSEL FUNCTION JO(X) USING
          C      POLYNOMIAL APPROXIMATION - REFERENCE HANDBOOK OF MATH.
          C      FUNCTIONS, BUREAU OF STANDARDS, PAGES 369-370
          C
0002      DOUBLE PRECISION X3, X32, X33, X34, X35, X36, DCOS,
          * DSQRT, DABS, X
          C
          C      CALCULATE X/3 OR 3/X
          C
0003      X3 = X/3.0
0004      IF( X.GT. 3.0) X3 = 3.0/ X
          C
          C      CALCULATE POWERS OF X
          C
0005      X32= X3*X3
0006      X33=X32*X3
0007      X34=X32*X32
0008      X35=X32*X33
0009      X36=X33*X33
          C
0010      2 IF ( DABS (X) .LE. 3.0D0 ) GO TO 3
          C
          C      CALCULATE BESJO(X) FOR VALUES OF X GREATER THAN 3
          C
0011      BESJO=((.79788456-.77E-6 * X3 - 0.552740D-02 *
          * X32 - .9512E-04 * X33 + .137237D-02 * X34 -
          * .72805E-03 * X35 + .14476E-03 * X36 ) / DSQRT(X) )
          * * DCOS( X - .78539816 - .04166397 * X3 - .3954E-04
          * * X32 + .262573D-02 * X33 - .54125D-03 * X34 -
          * .29333E-03 * X35 + .13558E-03 * X36 )
          C
0012      RETURN
          C
          C      CALCULATE BESJO(X) FOR VALUES OF X LESS THAN 3
          C
0013      3 BES JO= 1.0 - 2.2499997 * X32 + 1.2656208 * X34
          * - .3163866 * X36 + .0444479 * ( X34 * X34 ) -
          * .0039444 * ( X35 * X35 ) + .000210 * ( X36 * X36 )
          C
0014      RETURN
0015      END

```

```

0001      REAL FUNCTION V * 8 ( XN , XM )
          C
          C
0002      DOUBLE PRECISION XN, XM, EXPM2M, EXPM4M, DEXP
          C
          C      V - A FUNCTION OF 'E2E1', AND 'M'
          C      'E2E1' IS THE E2/E1 RATIO, TESTED FROM .001 TO 1000.
          C      'M' TESTED USING VALUES FROM 0.0 TO 150. WHICH IS
          C      10 * (R/H)
          C
          C      V APPROACHES 1 FOR LARGE VALUES OF M
0003      V = 1.0
0004      IF( XM .GT. 30 ) RETURN
          C
          C
          C      CALCULATE EXPONENTIALS
0005      EXPM2M = DEXP ( -2.000 * XM )
0006      EXPM4M= EXPM2M*EXPM2M
          C
          C      CALCULATE FUNCTION V FOR THE XN & XM1 OR XM2 VALUES
0007      V = ( 1.000 + ( 4.000 * XN * XM * EXPM2M ) -
          * ( XN * XN * EXPM4M ) ) / ( 1.000 - ( 2.000 * XN
          * * ( 1.000 + 2.000 * XM * XM ) * EXPM2M ) +
          * ( XN * XN * EXPM4M ) )
          C
0008      RETURN
0009      END

```

LOC	OBJECT	CODE	ADDR1	ADDR2	STMT	SOURCE	STATEMENT
000000					1	CORE#	START 0
					2		ENTRY CORE
					3		EXTRN IBCOM#
					4		EXTRN FIOCS#
000000					5		USING *,15
000000	47F0	F00C		0000C	6	CORE	BC 15,#+12
000004	07000000				7		DC XL4'07000000'
000008	C3D6D9C5				8		DC CL4'CORE'
00000C	90E4	D00C		0000C	9		STM 14,4,12(13)
000010	9823	1000		00000	10		LM 2,3,0(1)
000014	5833	0000		00000	11		L 3,0(3)
000018	9023	F090		00090	12		STM 2,3,BUFADR
00001C	4110	F02F		0002E	13		LA 1,CORE2
000020	4130	F074		00074	14		LA 3,CLOAD
000024	0523				15		BALR 2,3
000026	98E4	D00C		0000C	16		LM 14,4,12(13)
00002A	1BFF				17		SR 15,15
00002C	07FE				18		BCR 15,14
					19		DROP 15
00002E					20		USING *,1
00002E	5040	106E		0009C	21	CORE2	ST 4,SAVE4
000032	1841				22		LR 4,1
00002E					23		USING CORE2,4
					24		DROP 1
000034	1810				25		LR 1,0
000036	910F	1001	00001		26		TM 1(1),X'0F'
00003A	4710	4022		00050	27		BC 1,OUTPUT
00003E	5810	4076		000A4	28		L 1,VFIOCS
000042	4130	4046		00074	29		LA 3,CLOAD
000046	0523				30		BALR 2,3
000048	9823	4062		00090	31		LM 2,3,BUFADR
00004C	47F0	4036		00064	32		BC 15,RETURN
000050	9823	4062		00090	33	OUTPUT	LM 2,3,BUFADR
000054	9240	2000	00000		34		MVI 0(2),X'40'
000058	0630				35		BCTR 3,0
00005A	0630				36		BCTR 3,0
00005C	4430	4040		0006E	37		EX 3,DMOVE
000060	4133	0002		00002	38		LA 3,2(3)
000064	5840	406E		0009C	39	RETURN	L 4,SAVE4
000068	1810				40		LR 1,0
					41		DROP 4
00006A	47F1	0006		00006	42		BC 15,6(1)
00006E	D200	2001	2000	00001	00000	DMOVE	MVC 1(0,2),0(2)
000074					44		USING *,3
000074	50F0	3024		00098	45	CLOAD	ST 15,SAVE
000078	58F0	302C		00CA0	46		L 15,VIBCOM
00007C	9250	F04A	0004A		47		MVI 74(15),X'50'
000080	440F	004A		0004A	48		EX 0,74(15)
000084	9258	F04A	0004A		49		MVI 74(15),X'58'
000088	58F0	3024		00098	50		L 15,SAVE
00008C	07F2				51		BCR 15,2
000090					52	BUFADR	DS 2F
000098					53	SAVE	DS F
00009C					54	SAVE4	DS F
0000A0	00000000				55	VIBCOM	DC A(IBC0M#)

LOC	OBJECT CODE	ADDR1	ADDR2	STMT	SOURCE	STATEMENT
0000A4	00000000			56	VFIOCS	DC A(FIOCS#)
				57		END

NOTE: Program printouts of sample problems will
be found in the main body of the report,
Tables 6a through 6g.

LISTING OF DATA CARDS FOR SAMPLE PROBLEMS

100178PAZOS	1560	1	1FM	1687SBL	12.5	52168	1		
200SFAL COAT				0.5 RED SANDY GRAVEL		12.0	OGREY & BRWN SAND SUB		
1560	1	52168	1	- A	39.3	77.1	52.1	31.1	73.03
1560	1	52168	1	- B	38.3	77.1	51.1	31.1	71.03
1560	1	52168	2	- A	43.3	28.3	49.1	30.1	68.03
1560	1	52168	2	- B	40.3	28.3	49.1	30.1	67.03
1560	1	52168	3	- A	38.3	77.1	47.1	30.1	65.03
1560	1	52168	3	- B	37.3	77.1	46.1	30.1	67.03
1560	1	52168	4	- A	49.3	32.3	49.1	32.1	74.03
1560	1	52168	4	- B	46.3	30.3	47.1	31.1	71.03
1560	1	52168	5	- A	43.3	29.3	50.1	34.1	77.03
1560	1	52168	5	- B	42.3	80.1	46.1	31.1	73.03

LISTING OF DATA CARDS FOR SAMPLE PROBLEMS

10017BRAZOS 2824 2 1FM 2776NBL 8.0 52168 1

200SEAL COAT 0.5 ASPHALT STAB. GRAVEL 7.5GREY SANDY CLAY SUBG

2824	2	52168	1	-	A	55.3	40.3	29.3	66.1	50.1
2824	2	52168	1	-	B	52.3	37.3	81.1	61.1	49.1
2824	2	52168	2	-	A	77.3	49.3	31.3	71.1	53.1
2824	2	52168	2	-	B	77.3	47.3	30.3	67.1	51.1
2824	2	52168	3	-	A	81.3	50.3	31.3	67.1	49.1
2824	2	52168	3	-	B	83.3	51.3	31.3	67.1	50.1
2824	2	52168	4	-	A	83.3	49.3	30.3	64.1	48.1
2824	2	52168	4	-	B	81.3	47.3	28.3	61.1	47.1
2824	2	52168	5	-	A	78.3	48.3	29.3	62.1	45.1
2824	2	52168	5	-	B	81.3	49.3	31.3	65.1	47.1

LISTING OF DATA CARDS FOR SAMPLE PROBLEMS

10017BURLFSON	1399 1 IFM 1361EBL 12.0 52168 1
200SEAL COAT	0.5 LIME STAB. SANDSTONE11.5TAN SANDY CLAY SUBGR
1399 1 52168 1 - A	50.3 37.3 71.1 47.1 33.1
1399 1 52168 1 - B	52.3 41.3 78.1 48.1 33.1
1399 1 52168 2 - A	55.3 40.3 67.1 40.1 81.03
1399 1 52168 2 - B	48.3 35.3 64.1 38.1 82.03
1399 1 52168 3 - A	50.3 35.3 60.1 37.1 89.03
1399 1 52168 3 - B	48.3 33.3 58.1 37.1 87.03
1399 1 52168 4 - A	50.3 35.3 56.1 34.1 72.03
1399 1 52168 4 - B	46.3 33.3 54.1 33.1 71.03
1399 1 52168 5 - A	64.3 42.3 65.1 40.1 28.1
1399 1 52168 5 - B	60.3 38.3 63.1 42.1 31.1

LISTING OF DATA CARDS FOR SAMPLE PROBLEMS

10017 WASHINGTON 186 5 1SH 36 NBL 19.9 52168 1

200HOT MIX ASPH. CONC. 3.75 SANDSTONE

1615 BLACK CLAY SUBGRADE

186	5	52168	1	-	A	56.3	34.3	61.1	42.1	30.1
186	5	52168	1	-	B	61.3	36.3	61.1	42.1	31.1
186	5	52168	2	-	A	58.3	36.3	67.1	47.1	36.1
186	5	52168	2	-	B	65.3	39.3	69.1	49.1	37.1
186	5	52168	3	-	A	56.3	36.3	68.1	50.1	38.1
186	5	52168	3	-		57.3	36.3	67.1	48.1	37.1
186	5	52168	4	-	A	56.3	37.3	75.1	57.1	46.1
186	5	52168	4	-	B	52.3	36.3	73.1	55.1	44.1
186	5	52168	5	-	A	50.3	32.3	59.1	44.1	33.1
186	5	52168	5	-	B	53.3	33.3	60.1	43.1	33.1

LISTING OF DATA CARDS FOR SAMPLE PROBLEMS

10017ROBERTSON 49 R IUS 190 NBL 15.2 52168 1

200HOT MIX ASPH. CONC. 1.25CEM. STAB. LIMESTONE1395RED SANDY CLAY SUBGR

49	R	52168	1	-	A	68.1	59.1	49.1	39.1	31.1
49	R	52168	1	-	B	68.1	60.1	49.1	39.1	31.1
49	R	52168	2	-	A	72.1	63.1	51.1	39.1	31.1
49	R	52168	2	-	B	70.1	62.1	49.1	39.1	31.1
49	R	52168	3	-	A	75.1	65.1	52.1	39.1	30.1
49	R	52168	3	-	B	76.1	65.1	51.1	39.1	30.1
49	R	52168	4	-	A	60.1	54.1	45.1	35.1	28.1
49	R	52168	4	-	B	58.1	52.1	43.1	33.1	28.1
49	R	52168	5	-	A	62.1	55.1	45.1	35.1	28.1
49	R	52168	5	-	B	65.1	57.1	47.1	36.1	28.1

LISTING OF DATA CARDS FOR SAMPLE PROBLEMS

10017BRAZOS 1560 1 1FM 1687NBL 7.5 52168 1

200ASPHALT SURFACING 1.0 ASPH EMUL STAB GRAVL 6.5BROWN CLAY SUBGRADE

1560 1	52168	1	-	A	72.3	50.3	32.3	66.1	52.1
1560 1	52168	1	-	B	71.3	51.3	32.3	65.1	51.1
1560 1	52168	2	-	A	64.3	47.3	31.3	64.1	49.1
1560 1	52168	2	-	B	62.3	45.3	30.3	63.1	50.1
1560 1	52168	3	-	A	68.3	49.3	31.3	63.1	49.1
1560 1	52168	3	-	B	69.3	50.3	32.3	65.1	50.1
1560 1	52168	4	-	A	74.3	54.3	34.3	67.1	49.1
1560 1	52168	4	-	B	74.3	53.3	34.3	65.1	49.1
1560 1	52168	5	-	A	66.3	46.3	30.3	61.1	47.1
1560 1	52168	5	-	B	66.3	48.3	31.3	61.1	46.1

LISTING OF DATA CARDS FOR SAMPLE PROBLEMS

100178PAZOS	540 3 1FM 974 FBL 8.3 52168 1
200SEAL COAT	0.5 IRON ORE GRAVEL 7.8GREY SANDY CLAY SUBG
540 3 52168 1 - A	80.3 51.3 32.3 68.1 50.1
540 3 52168 1 - B	75.3 48.3 30.3 63.1 48.1
540 3 52168 2 - A	59.3 39.3 82.1 60.1 48.1
540 3 52168 2 - B	60.3 40.3 82.1 62.1 49.1
540 3 52168 3 - A	55.3 39.3 28.3 64.1 51.1
540 3 52168 3 - B	53.3 39.3 28.3 61.1 51.1
540 3 52168 4 - A	75.3 49.3 33.3 75.1 60.1
540 3 52168 4 - B	78.3 53.3 35.3 79.1 63.1
540 3 52168 5 - A	74.3 49.3 33.3 71.1 55.1
540 3 52168 5 - B	70.3 47.3 32.3 68.1 53.1