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A DESIGN SYSTEM FOR RIGID PAVEMENT REHABILITATION

by

Stephen B. Seeds, B.F. McCullough, and W.R. Hudson

Research Report Number 249-2

Implementation of Rigid Pavement Overlay and Design System

Research Project 3-8-79-249

conducted for

Texas

State Department of Highways and Public Transportation

in cooperation with the  
U.S. Department of Transportation  
Federal Highway Administration

by the

CENTER FOR TRANSPORTATION RESEARCH

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THE UNIVERSITY OF TEXAS AT AUSTIN

January 1982

The contents of this report reflect the views of the authors, who are responsible for the facts and the accuracy of the data presented herein. The contents do not necessarily reflect the official views or policies of the Federal Highway Administration. This report does not constitute a standard, specification, or regulation.

## PREFACE

This report was completed at The University of Texas Center for Transportation Research, under Project 3-8-79-249, as part of the Cooperative Research Program between The University of Texas and the Texas State Department of Highways and Public Transportation. One of the main objectives of the project is the implementation of the Texas Rigid Pavement Overlay Design (RPOD) procedure. This report represents one phase of this implementation, the incorporation of RPOD into a rigid pavement rehabilitation design system (RPRDS).

The bulk of this report was prepared with the aid of The University of Texas Decsystem-10 computer, to ease the task of review and modification for possible publication. Thanks are extended to all those who helped in the preparation of this report: Eve Falcon, Elaine Hamilton and Sue Tarpley for typing; Julie Muckelroy, Jimmy Holmes, and Ana Aranofsky for drafting; and Barbara Allen for coordination. Gratitude is also expressed to the many students who provided technical advice and assistance during the study, particularly, Arthur Taute, David Potter, David Luhr, and Bary Eagleson. Thanks are also extended to Gerald Peck and Richard Rogers at the Texas SDHPT for their advice and cooperation.

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## LIST OF PREVIOUS REPORTS

Report No. 249-1, "Improvements to the Material Characterization and Fatigue Life Prediction Methods of the Texas Rigid Pavement Overlay Design Procedure," by Arthur Taute, B. Frank McCullough, and W. Ronald Hudson, presents certain improvements to the Texas Rigid Pavement Overlay Design Procedure (PROD2) with regard to materials characterization and fatigue life predictions.

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## ABSTRACT

This report describes the development, use, and applicability of a rigid pavement rehabilitation design system, RPRDS, developed for use by the Texas State Department of Highways and Public Transportation. Like other pavement design systems, RPRDS makes use of the systems approach to incorporate a number of pavement design and analytical models into a computer program, RPRDS-1, for the generation, analysis, and comparison of numerous pavement design strategies. Unlike other pavement design systems, RPRDS considers only structural rehabilitation, i.e., overlay construction, where the design model used is an improved and extended version of the ARE, Inc./FHWA and Texas State Department of Highways and Public Transportation rigid pavement overlay design procedures, RPOD1 and RPOD2. In addition, provision is made in RPRDS for the consideration of other factors which affect pavement performance and accompany overlay construction. These include ACP, CRCP, and JCP type overlays; concrete shoulder construction; and variable concrete flexural strength; as well as variable overlay thickness.

Basically, RPRDS generates a number of feasible overlay design strategies based on user inputs, performs a present value cost analysis on each, and then presents those which are optimal. The other design and analytical models used to complete this task include (1) a distress/maintenance prediction model, (2) a traffic delay cost (during

overlay construction) model, and (3) a model for the prediction of overlay construction cost.

It is hoped this paper will provide not only a description of RPRDS but also some basis for its use nationwide.

KEYWORDS: Overlay, rehabilitation, design system, fatigue, damage, remaining life, distress prediction, cost analysis.

## SUMMARY

Many of the pavements which make up our Interstate Highway System are approaching the end of their serviceable lifetimes. Consequently, the need arose for a rational rehabilitation design method. One method, RPOD, a mechanistic rigid pavement overlay design procedure developed under the sponsorship of the FHWA, seemed to be very practical to the Texas State Department of Highways and Public Transportation, and was therefore modified, adapted and partially implemented into department practice.

This report discusses the next logical step in the evolutionary process of development and implementation of this new procedure: its incorporation into a system program for the analysis of alternative rehabilitation strategies. This first generation program, RPRDS-1, allows the highway design engineer to consider several factors associated with overlay design and construction in the selection of an optimum rehabilitation strategy. The most significant of these factors include overlay type, time of placement, maintenance costs, traffic delay costs, construction costs, and time value of money. Finally, RPRDS-1 is designed to be modular in nature so as to ease the systematic process of feedback modification and improvement.

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## IMPLEMENTATION STATEMENT

A rigid pavement rehabilitation design system (RPRDS) has been developed for the Texas State Department of Highways and Public Transportation as the next major phase in the implementation of the Department's rigid pavement overlay design (RPOD) procedure. Since most of the models incorporated into RPRDS may be expected. The RPRDS-1 computer program was developed using ANSI Fortran standards and should, therefore, run automatically on the State Department of Highways and Public Transportation's IBM computer.

The system should be introduced, gradually, by trial application on several design projects in the various districts. Then, as confidence in the procedure grows, it can be implemented on a statewide basis. Finally, the program should be continually improved and modified based upon feedback from the districts and any advancements in the state-of-the-art.

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## CHAPTER 1. INTRODUCTION

### BACKGROUND

There are many factors which affect the design and performance of a roadway. Some of these are traffic, load, material properties, temperature, moisture, availability of raw materials, construction methods and controls, costs, and the variations of many of these, both in time and space. Due to the large number of these factors and the fact that many of them interact with each other, any rational pavement design method which attempts to consider them will necessarily be complex. However, this was not the case for the early pavement design methods.

Because of a lack of precise analytical techniques for predicting pavement response and performance, these early methods were very simple and thus unable to adequately consider many of the important factors. They depended mainly on experience and empiricism; i.e., the view that what has worked in the past will work in the future. The fact that they were simple does not imply, however, that they were always erroneous. In fact, the methods did provide designs which were adequate for many cases. Unfortunately, their simplicity set a precedent which has become very hard to change, even with the development of modern computers to handle the new, complex analytical techniques. It may also be stated that, although these early design methods did provide adequate designs, they did not necessarily

provide ones which were optimal as far as performance and economics are concerned.

Compared to other areas of engineering, the analysis and design of highway (and airport) pavements is in its infancy. Recognition of the nation's large investment in its highway system is probably the factor most responsible for the research and development made thus far in this area. This research and development began with the design and analysis of new pavements and has only recently been extended to overlays and other forms of rehabilitation.

The AASHO Road Test (Ref 4), conducted in the early 1960's, provided the most complete experimental data upon which to base a rational pavement design method. The AASHTO Interim Guide for Design of Pavement Structures - 1972 (Ref 5) is a result of combining the data obtained from the experiment with pavement response models available at the time. Though these response models, i.e., the Spangler and Westergaard Equations, were relatively simple, they did consider some of the key factors which affect pavement performance. This along with the fact that they were correlated with a large amount of field data insured reasonableness and wide use of the design method.

Another significant development at the AASHO Road Test was the attempt to define pavement failure. The term "failure" is very ambiguous when used in connection with pavement design because pavements seldom "fail", at least not in the traditional catastrophic sense. The approach adopted at the Road Test was the serviceability concept, which provided not only for the point where a pavement becomes unserviceable and/or ceases to provide adequate service to the user but also for the concept of pavement performance. Performance, which is the serviceability history of a pavement, allows the designer to compare alternative designs based on an overall level of service

provided during their lifetimes. This comparison may, in some cases, be more important than the total cost comparison.

In spite of these efforts at the AASHO Road Test, "failure" continues to be used loosely to identify everything from a localized pavement defect to a point during the pavement's life when maintenance costs become excessive. The reasons for these different definitions are sometimes excusable, however, since the development of different types of design and analytical models require different definitions for failure criteria.

With the development of these better design methods, it was recognized that it was possible to develop a procedure for analyzing a large number of feasible pavement design alternatives on an economic basis. This method, known as the systems approach to pavement design (Ref 10), attempts to systematically consider most of the factors which have an effect on pavement performance and cost. In Texas, this approach has manifested itself in two design systems, the Flexible Pavement System, FPS (Refs 12 and 8), and the Rigid Pavement System, RPS (Refs 11 and 7). Both have been significantly modified to improve their capabilities for predicting total cost and reliability of the designs. Since a large portion of the new pavements constructed in Texas are asphaltic concrete, FPS has been widely used and is, consequently, highly developed. Most PCC pavements, on the other hand, were constructed well before the development of RPS and, therefore, RPS has not been fully implemented in Texas.

Most PCC pavements were built in the 1950's and early 1960's, many of which are suffering or have begun to suffer significant distress and loss of structural integrity. Fortunately, the Federal Highway Administration (FHWA) recognized that these pavements (particularly those on the Interstate network) were approaching the end of their service life and would soon

require major rehabilitation. Consequently, they sponsored a project in 1975 to develop a design method for pavement rehabilitation. The result was the Rigid Pavement Overlay Design procedure (RPOD) completed in 1977 (Ref 1). RPOD represents the first practical mechanistic design procedure since it uses advanced analytical techniques (layer theory and plate theory) to predict pavement response and extend the use of the AASHO Road Test data to the design of overlays.

Since there was very little data on the performance of overlays, it was necessary to develop new failure criteria for use in RPOD. According to the new criteria, when a pavement reaches a certain level of distress (i.e., initial class 3 and 4 cracking for PCC pavements), it loses its load-carrying capacity and begins to deteriorate rapidly. Although this point does not necessarily lie in a region of unacceptable serviceability, it does correspond to a level below which there would be excessive development of severe distress manifestations. This, in turn, implies high maintenance costs and, eventually, poor riding quality.

The Texas State Department of Highways and Public Transportation (SDHPT) considered the FHWA procedure viable and launched their own project to adapt the procedure for use in Texas (Ref 9), begin its implementation into department practice, and to develop a systems program for rigid pavement rehabilitation which uses the new procedure as its design model.

#### OBJECTIVES OF THE STUDY

The goal of this study, then, is to develop a rigid pavement rehabilitation design system in the form of a computer program (RPRDS-1)

which can provide the user with specific criteria for the selection of an optimal rigid pavement rehabilitation strategy for a given project. The specific objectives for achieving this goal are as follows:

- (1) The system should use the most recent version of the Texas SDHPT rigid pavement overlay design procedure as its primary method of rehabilitation.
- (2) The system should be able to consider many of the factors which influence a design strategy. Moreover, the system should be able to consider several levels of the factors over which the designer has control, i.e. overlay type and thickness, shoulder construction, etc.
- (3) The system should use the available proven models for distress/maintenance prediction and overall cost prediction to insure consistency with other existing design systems.
- (4) The computer program which performs the analysis should be modular in nature and amenable to future modification. It should also be written to insure compatibility with most computers. This includes minimizing computer time and storage requirements.

#### SCOPE

This report includes: (a) the systems methodology and its application in rigid pavement rehabilitation (Chapter 2), (b) descriptions of each of the specific models incorporated into the RPRDS-1 computer program (Chapters 2,

3, 4 and 5), (c) a user's manual to describe the input and output of the program (Chapter 6), (d) a summary of the results of the study (Chapter 7), (e) conclusions drawn from the study results (Chapter 7), and finally (f) recommendations for improvements and further work on the design system.

## CHAPTER 2. RIGID PAVEMENT REHABILITATION DESIGN SYSTEM - RPRDS

Chapter 1 discusses the history of the development of pavement design methods from the early empirical methods up to the methods which took advantage of the systems approach to pavement design and finally the FHWA and Texas SDHPT overlay design procedures (Refs 1 and 9). Logically, the next step in the chain of development is the incorporation of the new overlay design procedures into a comprehensive pavement rehabilitation design system. This is the main goal of this study.

### SYSTEMS METHODOLOGY

Haas and Hudson (Ref 32) provide a detailed description of the systems methodology. They state generally that

the structure or framework of any problem-solving process should provide for systematic incorporation of all the technical, economic, social, and political factors of interests. Moreover, it should be a logical simulation of the progression of activities involved in efficiently solving a problem.

In effect,

systems methodology comprises a body of knowledge that has been developed for efficient planning, design, and implementation of new systems, and for structuring the state of knowledge on an existing system or modeling its operation.

The systems methodology is not as complicated as it may sound. It is basically a method for handling or managing a network of interrelated problems and/or tasks on a global basis to achieve the maximum utility or benefit. This may mean, in some cases, accepting a suboptimal solution to one problem for the benefit of the entire system. Therein lies the contrast with the piecemeal approach to problem-solving that is prevalent in many of today's decision making and management processes.

Figure 2.1 provides an illustration of how the components of the systems methodology fit together. Haas and Hudson state:

In this general form, it (Fig 2.1) is applicable to a wide variety of engineering and other problems. The diagram illustrates that the recognition of a problem comes from some perceived inadequacy or need in the environment. It leads to a definition of the problem that involves a more in-depth understanding. This provides the basis for proposing alternative solutions. These alternatives are then analyzed in order to predict their probable outputs or consequences. Evaluation of the outputs is the next step in order that an optimal solution may be chosen. Implementation involves putting this solution into service, and its operation. Feedback for improving the future solutions, or checking on how well the system is fulfilling its function, is provided by periodic performance measurements.

Also, since new problems are always developing and the feedback from the solutions to old problems is continuous, the process shown in Fig 2.1 is continuous, and it is hoped, this will lead to constant improvement of the system.

Another factor associated with the systems approach is its ability to analyze a problem at different levels, depending on how the system is formulated. For the case of highway pavement analysis, systems programs have been developed for two basic levels of application, project and network. Project level systems programs generally provide criteria for the selection of an optimum pavement design strategy for a specific section of road. On the other hand, systems programs at the network level are basically

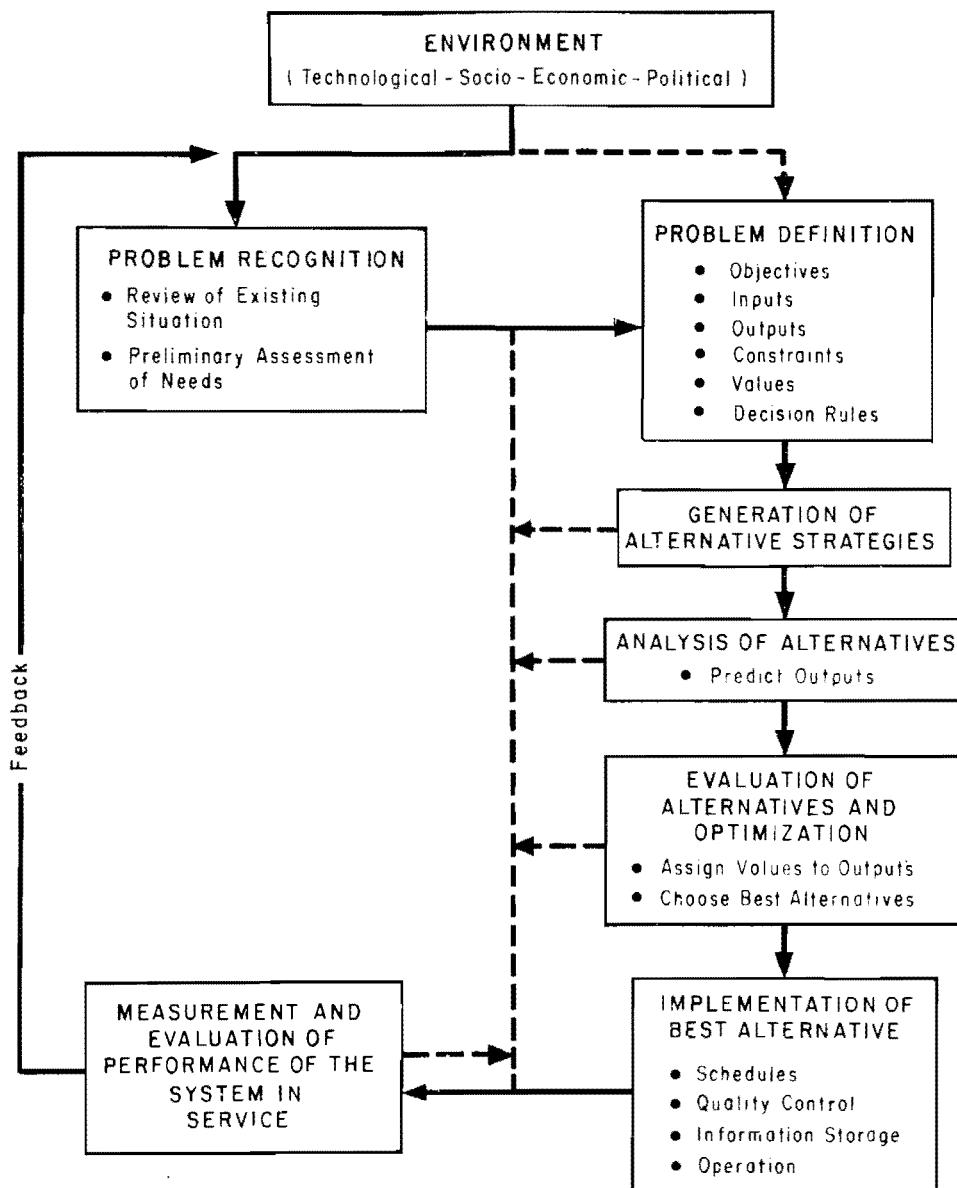


Fig 2.1. Major phases and components of the systems method (Ref 32).

management oriented. (Examples of management type functions include the establishment of priorities for various design or construction projects, the best use for funds in a limited budget, and the selection of optimum maintenance policies for the entire network.) Obviously, the advantage of a network level system is its ability to minimize total overall costs while maximizing utility. The disadvantage of network level systems, however, is that their design models are necessarily simple and therefore do not adequately consider all the factors associated with design at the project level. This separation between the two system levels also exists for pavement rehabilitation and makes it necessary to define what system level RPRDS was designed for.

## RPRDS-1

Ideally, a systems model for pavement rehabilitation should encompass the entire management and decision making process for design, construction, and maintenance for both the project and network levels. Unfortunately, such a system is not presently possible, politically or technologically. Consequently, the first version of the Rigid Pavement Rehabilitation Design System, RPRDS-1, begins at the project level. At this level, the problem or task is to select a pavement rehabilitation strategy for a given length of roadway which will provide the maximum service to the user over a given period of time and at a minimum overall cost.

Basically, RPRDS-1 attempts to solve this problem by analyzing a large number of rehabilitation strategies on a total cost basis where the primary method of rehabilitation considered is overlay construction. Though there

are some other promising methods, such as pressure grouting, precast slab repair, polymer concrete patching, prestressed concrete overlays, and flexible overlays with either a sulfur or sulfur-asphalt binder, they cannot be considered in RPRDS-1 at this time due to a lack of experience and performance data on these methods. The methods that are considered in RPRDS-1, however, include a multitude of factors dealing with overlay construction such as (1) concrete shoulder construction, (2) type of overlay (ACP, CRCP and JCP), (3) number of overlays (one or two during the analysis period), (4) aggregate type, (5) overlay thickness, and (6) flexural strength. These are all discussed in later chapters.

It is appropriate now to present a general flowchart of RPRDS-1 (Fig 2.2) and discuss the logical structure and components of the program.

First of all, the inputs to the system are read and printed by the INPUT routine. These inputs are summarized as follows:

- (1) Any data which affect the performance of an overlay strategy (i.e., material properties, layer thicknesses, construction methods, maintenance, etc.).
- (2) Cost data (i.e., materials, construction, maintenance, user, discount rate, etc.).
- (3) Constraints (i.e., analysis period, minimum time between overlays, maximum overlay thickness, etc.).

Detailed discussion of these is presented in the RPRDS-1 User's Manual in Chapter 6.

Next, the interior pavement responses required for the appropriate overlay design strategies are generated by the CONRSP routine. Discussion of

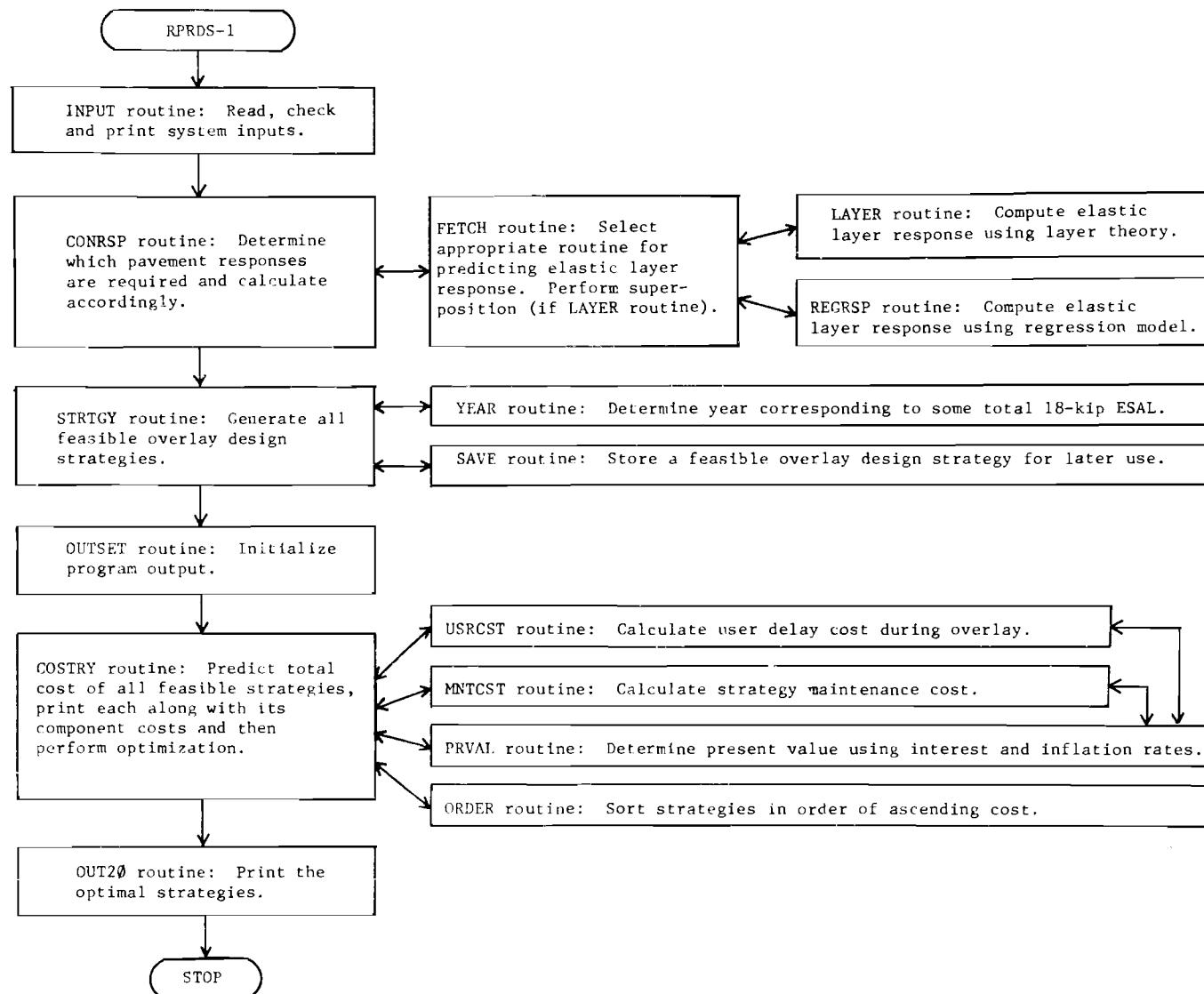


Fig 2.2. General flow diagram of the rigid pavement rehabilitation design system computer program, RPRDS-1.

the specific function of this routine and the routines it uses to predict the required responses, FETCH, LAYER, and REGRSP, is presented in Chapter 3.

Thirdly, all feasible overlay design strategies (i.e., those which meet the constraints) are generated by the STRTGY routine. The discussion of (a) fatigue life prediction and the available overlay design strategies, (b) the method of distress prediction, and (c) how feasible strategies are selected and stored is presented in Chapter 4.

Fourth, each feasible overlay design strategy is analyzed (by the COSTRY routine) on the basis of net present value where (a) overlay construction costs, (b) user delay costs during overlay construction (TDCSY routine), (c) maintenance costs (MNTCST routine), (d) value of extended life, (e) salvage value, and (f) a form of discount rate (PRVAL routine) are considered. In the process, strategies which have the least overall cost are stored in order of increasing cost (ORDER routine). This analysis is discussed in Chapter 5.

Fifth, the details and predicted costs of the optimal strategies are printed for user inspection by the OUTSET, PRNTST, and OUT20 routines. The discussion of how the output of the RPRDS-1 program should be interpreted so that the best overall rehabilitation alternative can be selected is presented in the RPRDS-1 User's Manual in Chapter 6 of this report.

Finally, Chapter 7 provides a summary of the results of this study and the applicability of RPRDS-1 to overlay design problems. Chapter 7 also provides some conclusions that can be derived from the results of the study and some recommendations for improvements and further work in this area.

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## CHAPTER 3. PREDICTION OF PAVEMENT RESPONSE

In order to predict how a pavement structure will perform during its lifetime, it is necessary in any rational or mechanistic design method to predict how the pavement will respond under load. The purpose of this chapter then, is to describe the mechanism through which these responses, i.e., stress, strain, and displacement, are generated for use in RPRDS-1. Accordingly, three specific topics concerning pavement response prediction will be discussed.

The first is the RPRDS-1 routine called CONRSP (see Fig 2.2) which controls the generation of the required responses. This includes identifying the types of pavement structures that can be considered and the responses required for each.

The second topic discussed is the approach used for predicting pavement response in RPRDS-1, which is a combination of elastic layer theory and the finite element method to achieve maximum precision with minimum computation time. The third topic addressed is elastic layer theory, the history of its development and its use in two submodels incorporated into RPRDS-1.

## CONTROL ROUTINE FOR GENERATING RESPONSES

RPRDS-1 can consider a variety of different overlay strategies (as discussed in Chapter 2). Since this multitude of possible strategies requires an even larger number of pavement responses for predicting their lifetimes, it was not considered feasible to calculate or recalculate responses every time they are needed. Consequently, a computer routine, CONRSP, was developed for RPRDS-1 to generate the required responses. It is capable of (1) making the appropriate decisions on what responses are required for each strategy, (2) preparing the necessary inputs to calculate each response, (3) calling the appropriate routine to calculate the response, and (4) storing the response for later use. A simplified flowchart of this routine is presented in Appendix A of this report.

A method of coding each required response was developed and is used in the CONRSP flowchart. In this code, the first letter indicates whether a given response is a stress, S, or strain, E. The second character, a number, indicates the location in the pavement of the response. A zero indicates a response in the original pavement, a one indicates a response in the first structural overlay, and a two indicates a response in the second structural overlay. The next characters in the string (shown in Table 3.1 identify the pavement structure. The subscript,  $i$ , at the end of a string means that the response takes on multiple values depending on the thickness of first overlay. The subscript,  $ij$ , means that the response depends on the thicknesses of both the first and second overlays.

Figure 3.1, which is a section of the CONRSP flowchart in Appendix A, is provided to help illustrate this coding method. In the bottom box of this figure, one of the pavement structures considered in RPRDS-1 is illustrated.

TABLE 3.1. CHARACTERS OF A CODE WHICH IDENTIFY A PARTICULAR PAVEMENT STRUCTURE FOR WHICH RESPONSES ARE DETERMINED

Characters	First Overlay	Second Overlay	Remarks
(None)	(None)	(None)	No overlays
A	AC	(None)	
AA	AC	AC	
AP	AC	PCC	
AP1	AC	PCC	Original PCC uncracked
AP2	AC	PCC	Original PCC cracked
BP	Bonded PCC	(None)	
BPA	Bonded PCC	AC	
UP	Unbonded PCC	(None)	
UP1	Unbonded PCC	(None)	Original PCC uncracked
UP2	Unbonded PCC	(None)	Original PCC cracked
UPA	Unbonded PCC	AC	
UPA1	Unbonded PCC	AC	Original PCC uncracked
UPA2	Unbonded PCC	AC	Original PCC cracked

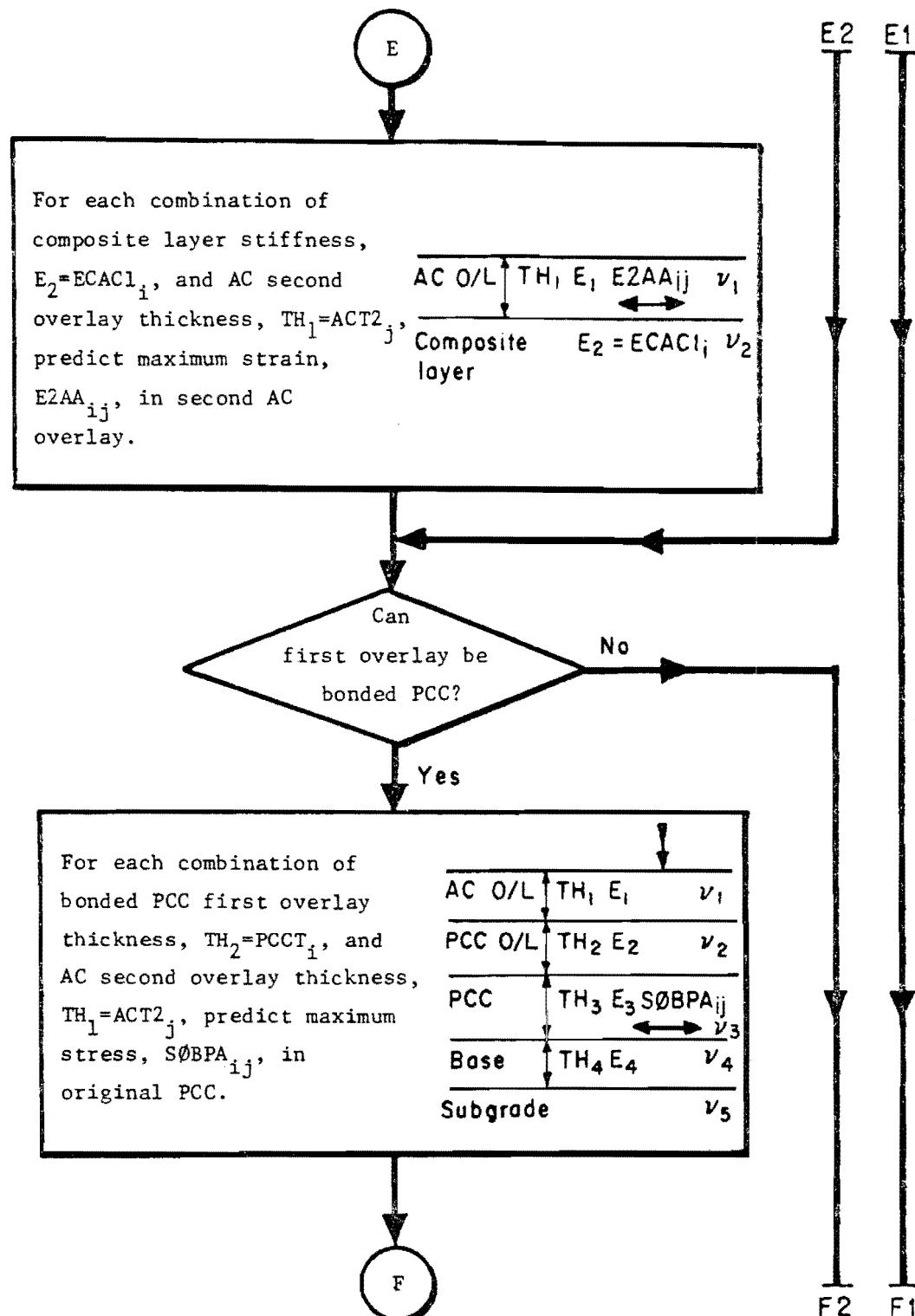


Fig 3.1. Section of CONRSP flowchart, illustrating the method for coding the required responses.

Note that it consists of the original PCC pavement, a bonded PCC first overlay, and an AC second overlay. The desired response, coded SOBPA , is shown at the bottom of the third layer. Since the first letter of the code is an S, the response is a stress; and, since the second character is a 0, this stress exists in the original pavement. Referring to Table 3.1, then, it is evident that the next three characters, BPA, indicate that the first overlay consists of bonded PCC while the second consists of asphaltic concrete. The subscript, ij, indicates that this stress corresponds to the i-th thickness of the first overlay and the j-th thickness of the second overlay. The other variables depicted in the figure, TH, E, and V, represent (respectively) the layer thicknesses, elastic moduli, and Poisson's ratios used to calculate the desired response. Using this coding method, it should be apparent then, that E2AA in the top box of Fig 3.1 represents a strain in an AC second overlay where the first overlay was also AC.

Inspection of the flowchart in Appendix A (and the top box of Fig 3.1) shows that in some cases, a cracked pavement structure will be characterized as a single composite layer (with a composite stiffness) prior to placing of an AC overlay. This method of characterization, developed by Schnitter (Ref 9), insures that the AC overlay will carry the load which cannot be carried by the underlying cracked layers. The composite stiffness is determined by matching the 18-kip single axle deflections of the cracked and composite pavement structures. This is discussed in greater detail in Chapter 4.

## APPROACH TO PREDICTING CRITICAL PAVEMENT RESPONSE

RPRDS-1 uses a combination of elastic layer theory and the finite element method to predict the critical pavement response required for estimating the lifetime of an overlay strategy. This approach is similar to that adopted for use in the FHWA and Texas SDHPT overlay design procedures (Refs 1, 3, and 9). The combination of the two methods was necessary because (1) layer theory cannot predict pavement response at a discontinuity such as a pavement edge or crack and (2) computer models based on finite element theory require too much data preparation and computer time for practical use in RPRDS-1.

The marriage of the two methods can briefly be described as follows. First, prediction models based on layer theory are used to predict the pavement response for the interior condition (away from an edge, corner or crack). Then this interior response is adjusted for the other conditions using relationships developed from finite element theory in which the response at a discontinuity is correlated with the interior response. For example, if the stress near a pavement edge were required, it would be determined by computing the interior stress using the layer theory model and then multiplying by an edge stress factor developed from finite element theory.

A description of elastic layer theory is provided in the next section of this chapter; however, a description of the finite element method and its use in RPRDS-1 is not discussed until Chapter 4.

## ELASTIC LAYER THEORY

The development of layer theory, as documented by McCullough (Ref 2), began with the Boussinesq solution of stresses and deflection for what is technically considered a one-layer problem. Burmister (Ref 16) extended the solution to two layers assuming no slippage at the interface and conceptually established the solution for three-layered problems. He also developed a formulation for the state of stress directly beneath the wheel load (Ref 17). Unlike the Boussinesq approach, Burmister considered the modulus of elasticity (Young's modulus) of the layers, a factor which has a considerable effect on the state of stress and strain in the pavement structure. Hank and Scrivner (Ref 18) and Peattie and Jones (Ref 19) provided the physical solution to Burmister's conceptual solution for the three-layered problem and also solved for the complete state of stress and strain in the pavement structure. Hank and Scrivner also provided the solution for the case of varying friction between the layers.

The advent of the computer in the 1960's provided the means for the solution to multi-layered problems. Chevron Research Corporation developed the CHEV5L (5 layer) and CHEV15L (15 layer) computer programs which permitted the determination of the complete state of stress at any point in the pavement structure (Ref 20). Both treated elastic moduli, Poisson's ratio, and thicknesses of the layers as variables and both also assumed full friction at the interfaces between the layers. They were limited, however, to predicting only stress and deflection and the consideration of only one vertical load at the surface. Ahlborn (Ref 21) extended the CHEV5L program to develop ELSYM5 which could predict strain and could handle up to ten vertical loads. In this program, the principle of superposition was used to

predict the effect of multiple loads at any one point. Additionally, ELSYMS was capable of using a Mohr's circle type analysis to compute the principal stresses and strains at any point.

The Shell Oil Company, meanwhile, also developed a computer program, BISAR (an improved version of their earlier BISTRO program), for analyzing the state of stress and strain in multi-layered elastic systems (Refs 22 and 23). It not only had the capability to handle multiple loads and multiple layers, but it could also consider varying degrees of friction at the interfaces between the layers and horizontal as well as vertical surface loads. This made BISAR the most flexible and the most precise computer model available for elastic layer simulation. Unfortunately, all these capabilities make BISAR relatively slow and unsuitable for use in RPRDS-1.

The pertinent assumptions inherent in elastic layer theory and all of these computer models are as follows:

- (1) The theory of linear elasticity (and all its inherent assumptions) are applicable.
- (2) Each layer extends to an infinite distance horizontally and the materials of each are assumed to be weightless, homogeneous, and isotropic.
- (3) The surface of the top layer is assumed to be free of normal and shearing stresses outside the loaded area.
- (4) Stresses, strains, and deflections in the bottom layer must be equal to zero at infinite depth.

The third and fourth assumptions are certainly valid for pavement applications and although the second assumption never applies to cases in the

field, its effects may be neglected or indirectly considered when applying adjustments from finite element theory to the response. These adjustments are discussed in Chapter 4.

There are two alternatives available in RPRDS-1 for predicting interior response. Both are based on elastic layer theory and the first, the LAYER submodel, is a computer model similar to ELSYM5 (Ref 21). Unlike ELSYM5, it can consider only one load. It does, however, give the same results as ELSYM5 for a one-load problem and is approximately 30 percent faster.

The second alternative for predicting interior response is the LAYER regression submodel called REGRSP. It represents a series of regression equations developed from the LAYER submodel and is approximately five times faster. Unfortunately, though they are quite accurate, their results, when used in conjunction with the fatigue equations, are often significantly different from those using the LAYER submodel. Consequently, it is recommended that the LAYER submodel be used for any practical application of RPRDS-1 on highway design problems.

#### LAYER Submodel

The computer model in RPRDS-1 used to predict the precise elastic response is a version of the CHEV15L program which has gone through several modifications. The first resulted in the LAYER15 program (Refs 20, and 24), which was then modified at Texas A & M University (Ref 26) for compatibility with IBM machines. The version used here, labelled LAYER, represents a modified version of LAYER15. The allowable number of layers was decreased from fifteen to eight to reduce computer storage requirements. The program was also modularized to fit within the RPRDS-1 framework.

LAYER was selected for use in RPRDS-1 mainly because of its minimal computer time and storage requirements. The problem of multiple loads was overcome by considering the effect of superposition externally from LAYER. Also, it was decided that there was no need for considering variable friction between the layers since McCullough (Ref 2) determined that the effect was negligible for pavement applications.

The model can basically be described using Fig 3.2. An elastic layer system which simulates the pavement structure may consist of up to eight layers in which the thickness, D, elastic modulus, E, and Poisson's ratio,  $\nu$ , for each must be defined. The coordinate system is two-dimensional axis symmetric where r represents the horizontal (or radial) axis and z the vertical axis. The origin ( $r=0$ ,  $z=0$ ) is at the surface directly beneath the load. The load is defined by some magnitude, F, with some pressure, p. Note also that the model is independent of units (so long as they are consistent).

The response at any point ( $r,z$ ) consists of radial stresses and strains (along a horizontal line passing through the z-axis), tangential stresses and strains (along a horizontal line perpendicular to a line passing through the z-axis), shear stresses and strains, bulk stresses and strains, and, finally, vertical stress and vertical displacement.

The load used to predict the responses required by RPRDS-1 is a simulated 18-kip single axle used in the FHWA and Texas SDHPT overlay design procedures (Ref 1, 3, 9). Figure 3.3 provides an illustration of the 18-kip single load and how it is simulated. The figure also shows how the total response at a given point is determined using the principle of superposition.

Although the actual 18-kip single axle consists of four tires, the simulation used considers only two tires, or one-half the axle. This is to remain consistent with the fatigue equations (Refs 6 and 31), which were

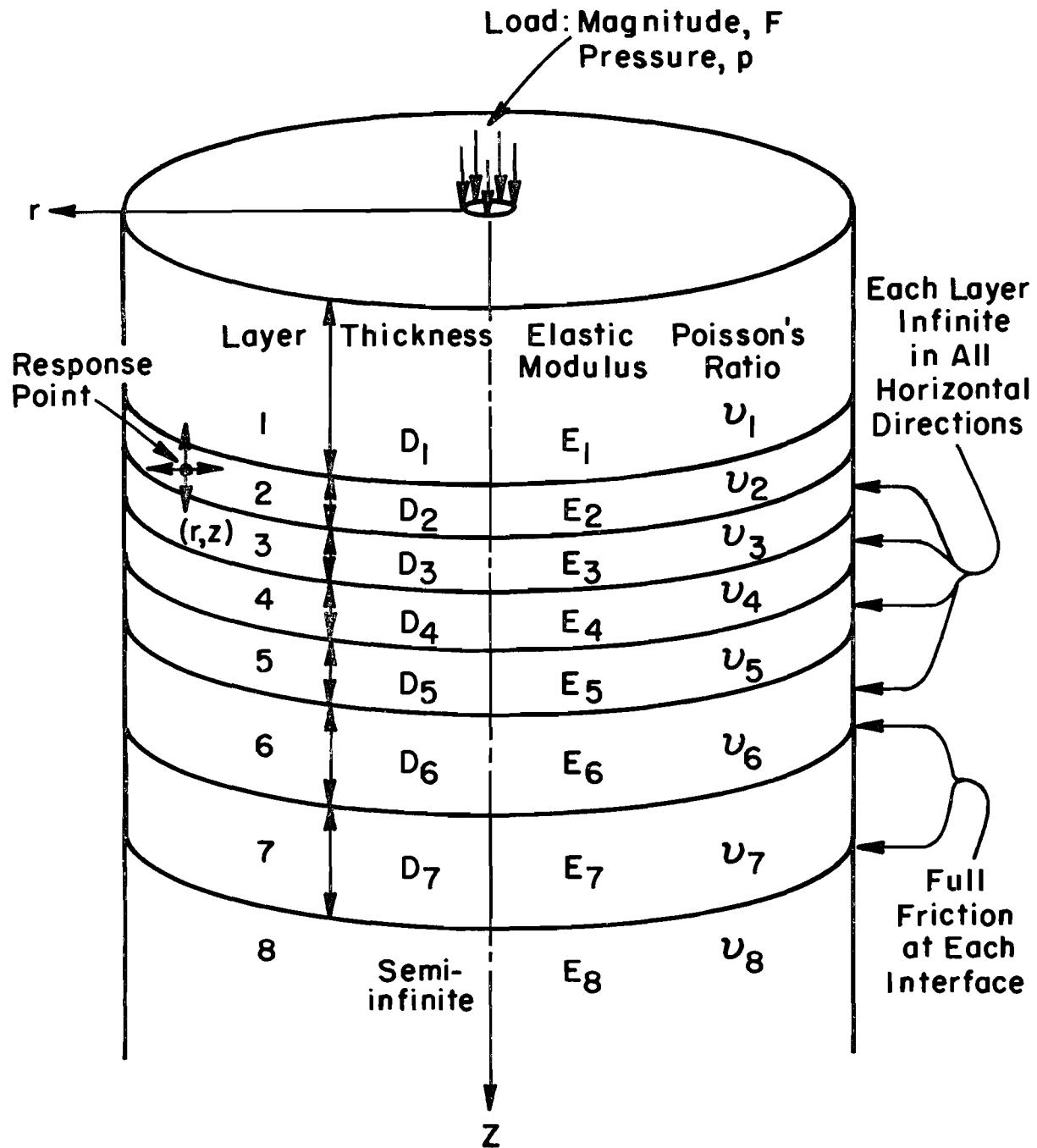
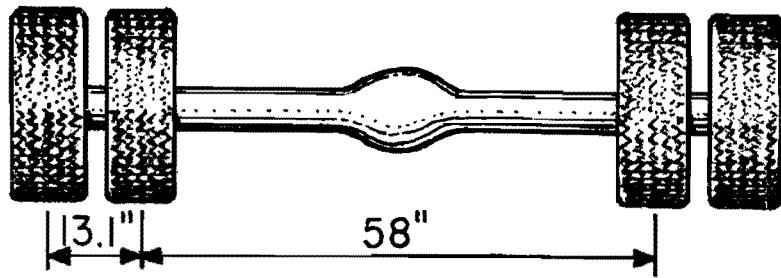
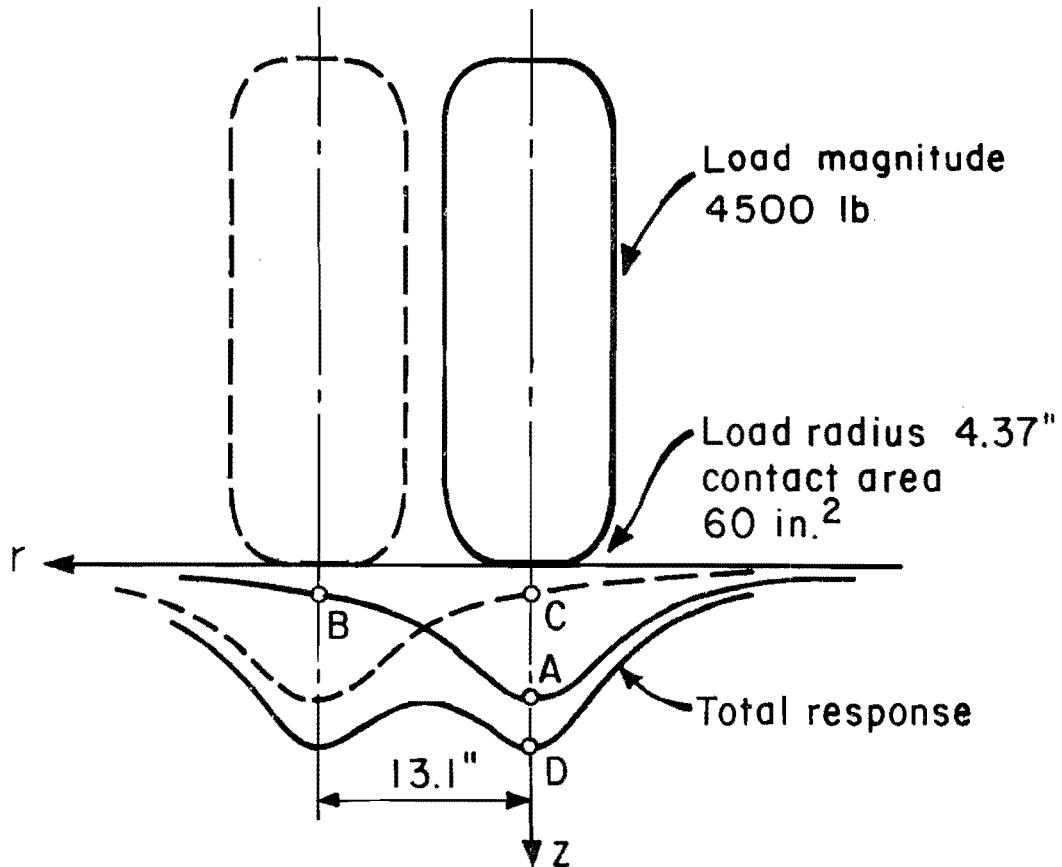


Fig 3.2. Illustration of an elastic layer system.



(a) Standard 18-kip single axle: 4 tires,  
each 4500 lb. at 75 psi tire pressure.



(b) Simulated 18-kip axle load (half the standard axle)  
and illustration of superposition of responses.

Fig 3.3. Standard 18-kip axle configuration and  
simulation used in RPRDS-1.

developed using this half-axle simulation. Part (b) of Fig 3.3, then, illustrates how the total response (due to the two loads) at a particular point is determined. Point A represents the maximum response due to a single load. Since there is some effect (point C) due to the second load nearby, it must be estimated and then added to the response at point A to get the total response, point D. Also, since the two loads are identical, the effect of point C is equivalent to that at point B. Therefore, the total response at point D is simply the algebraic sum of the responses at points A and B due to a single load. It should be noted, however, that this superposition of responses gets much more complicated for multiple load configurations.

#### LAYER Regression Submodel (REGRSP)

This submodel was developed as part of this study in an effort to reduce RPRDS-1 computer time requirements and in anticipation of the need to incorporate some measure of reliability into the program. Comparison of this submodel (called REGRSP) with the other available model (LAYER) shows that REGRSP takes less than one-fifth the computer time with greater than 85 percent (generally 95 percent) accuracy. Unfortunately, due to the precision required by the equations for predicting pavement fatigue lives, there is usually a significant difference between the fatigue lives predicted by each submodel. Consequently, the LAYER submodel is strongly recommended for specific highway design applications. The REGRSP submodel is more than accurate enough, however, for use in developing a reliability model for the RPRDS-1 program.

Basically, the REGRSP submodel consists of 12 regression equations (presented in Appendix B) which predict a particular response in one of the

various pavement structures considered in RPRDS-1. These equations were developed from designed experiments on the LAYER submodel where advantage is taken of the fact that (1) the design 18-kip single axle load is fixed (as in Fig 3.3), (2) the effect of superposition of loads on the design axle can be considered within each equation, and (3) the variation of Poisson's ratio for each of the layer materials has little effect on the predicted response.

The specific procedure followed for the development of each equation is simple. It should be noted here, however, that each equation represents an expression for a single response within a particular pavement structure. This may help to avoid confusion later when the case arises in which there are two responses required from a particular pavement structure.

The first step of the procedure was to select a particular pavement structure and the location of the desired response. These were selected on the basis of what responses were required by RPRDS-1 to predict the fatigue lives of the available strategies.

The second step, then, was to design an experiment (Refs 27 and 28) where the significant factors (the independent variables) which affect the response (dependent variable) predicted by LAYER could be varied to produce a factorial of LAYER solutions. Three equally spaced levels (high, medium, and low) of each significant factor were used in the experiments. Less significant factors, such as Poisson's ratio, were fixed according to the types of materials making up the layers of the pavement structure. In the experiments where there were more than five significant factors, a full factorial of solutions would have required exorbitant amounts of computer time and money, (3 or 59,049 LAYER solutions for the ten-factor case); consequently, fractional factorials as recommended by Connor and Zelen

(Ref 27) were used to generate the required set of LAYER solutions. This resulted in 243 observations (data points) in all but one of the experiments.

The third step of the procedure was to perform an analysis of variance on the data. This was accomplished using a computer program, SUMSQ2 (Ref 29), which computes the sums of squares about the grand mean for all main effects (original factors), both linear and quadratic, and the two-factor interactions of each. So, for a term such as the interaction between layer one thickness,  $D$ , and layer two modulus squared, ( $E$ ), a large sums of squares indicates that the term explains much of the variation observed in the data. The objective, then, was to select the terms which explained the most variation and use them in the equation to predict response. However, a practical limit of 20 terms (less than one-tenth the number of observations) was imposed on each multi-factor regression equation.

Preliminary results showed that most of the variation of a linear dependent variable could not be explained with the available terms. Consequently, it was necessary to try to explain the variation using different transformations of the dependent variable. Trial and error showed that a considerable amount of the variation (greater than 98 percent) in the log (base 10) of the response could be explained. Therefore, this transformation was used in all of the experiments.

The fourth and final step of the procedure was to perform a stepwise regression analysis on the data using the log transform of the response as the dependent variable and the terms which explained most of its variation. The STEP01 computer program (Ref 30) was used to perform the regression analysis. Significant information about the constraints on each equation and plots of the accuracy of each equation, as well as the regression equations, themselves are presented in Appendix B of this report.

Another coding system was developed to aid in identifying each equation. The first letter indicates whether the response is a stress, S, or strain, E. The second letter (if there is one) indicates whether the first PCC overlay is bonded, B, or unbonded, U, by means of a bond breaker. The first number indicates how many different layers are considered and the second number identifies in which layer (counting from the top down) the response is determined. The letter C at the end of a code means that an underlying concrete layer is considered to be cracked.

There are two other important things that were discussed previously but should be emphasized again. One is that the equations are based on a fixed axle load, as shown in Fig 3.3, and the other is that the effect of superposition is considered within the equations.

## CHAPTER 4. GENERATION OF FEASIBLE OVERLAY DESIGN STRATEGIES

The purpose of this chapter, basically, is to show how feasible overlay design strategies are generated. Accordingly, several topics dealing with design constraints and fatigue life prediction will be discussed. Note here, too, that this chapter specifically describes the components of the routine called STRTGY, which is incorporated into RPRDS-1 (refer to Fig 2.2) to generate the feasible overlay design strategies.

### DESIGN CONSTRAINTS

There are several types of design constraints which differentiate between overlay design strategies which are feasible and those which are not. These constraints are, for the most part, defined by the highway designer and therefore are largely subjective. The constraints which are considered within the Rigid Pavement System, RPS (Ref 7), include

- (1) maximum funds available for initial construction,
- (2) maximum allowable slab thickness,
- (3) minimum allowable time to first overlay,
- (4) minimum allowable time between overlays,
- (5) length of analysis period or minimum life of strategy,

- (6) maximum ACP and PCC overlay thicknesses, and
- (7) minimum ACP and PCC overlay thicknesses.

All of these types of constraints seem practical for use in any type of pavement design system; therefore, a discussion of their applicability and use in RPRDS-1 is in order.

To begin with, it should be pointed out that RPS is a design system for pavements which are to be constructed from scratch, whereas RPRDS-1 is a design system for pavement rehabilitation only. Though RPS can consider strategies where an overlay is required during the analysis period, the model it uses to predict the life of such an alternative is very primitive and may be subject to gross inaccuracy. The model RPS uses for PCC overlay design is an extension of the Corps of Engineers method for airfield pavements (Refs 13 and 15), while the method for ACP overlay design is based on an equivalent thickness concept (Ref 11). In any case, RPRDS-1 is recommended for design of rehabilitation for existing rigid pavements, but, due to its nature, some of the constraints which are considered in RPS are not considered in RPRDS-1. Such is the case for the first three constraints listed.

The constraints on maximum funds available for initial construction and maximum allowable slab thickness do not apply in RPRDS-1 as it is assumed that a rigid pavement structure already exists. This also applies to some extent to the constraint on the minimum allowable time to first overlay. In most overlay design problems, the existing pavement is available for an "immediate" overlay, and, consequently, it doesn't matter how long ago it was constructed. The constraint is still considered indirectly, however, since

the program requires that the designer specify certain levels of pavement life at which the first overlay may be placed.

The fourth constraint listed is the minimum allowable time between overlays. This is considered directly within RPRDS-1. Any strategy in which a second overlay is required too soon after the first overlay will be eliminated from further consideration.

Due to the type of maintenance cost model used in RPRDS-1, the fifth constraint, minimum strategy life, is handled differently than in RPS. RPRDS-1 allows the user to specify some maximum period of heavy maintenance, which, in effect, allows some strategies to be considered which do not quite last the analysis period without some period of heavy maintenance. The result is that only strategies which require a longer period of heavy maintenance to last the analysis period are removed from further consideration. This is explained in further detail in Chapter 5.

The sixth and seventh constraints listed are the maximum and minimum thicknesses of ACP and PCC overlays. These constraints are also considered within RPRDS-1, but in a slightly different way. First of all, RPRDS-1 requires that the designer select the specific thicknesses of ACP and PCC overlay to be considered. Therefore, infeasible thicknesses are eliminated immediately. Second, the program allows the designer to specify a maximum total overlay thickness. Consequently, a strategy in which the combined thickness of two overlays is so great that it does not provide adequate bridge clearance will be eliminated.

Finally, RPRDS-1 attempts to limit the number of thickness design alternatives by omitting those which provide excessive lifetimes. Once a feasible thickness design is generated, no further designs are considered in which only the overlay thickness is greater. For example, if a 4-inch ACP

overlay is found to be feasible, there is no need to consider a 5-inch overlay.

In summary, an RPRDS-1 strategy is constrained by how long it will last, the total allowable thickness of overlay, and the time at which a second overlay (if used) is placed.

#### PREDICTION OF FATIGUE LIFE

The basic method used in RPRDS-1 for predicting the fatigue life of an overlay design strategy is that suggested by McCullough (Ref 2) and developed by Austin Research Engineers, Inc., for the Federal Highway Administration (Ref 1). That original method has experienced significant improvements during adaptation and implementation for the Texas SDHPT. The process of improvement and adaptation began with a study by Schnitter, Hudson, and McCullough (Ref 9). Further improvements to the design method were accomplished by Taute (Ref 31) in the areas of materials characterization and fatigue relationships for CRCP. The latter accomplishments were a result of practical implementation on several overlay projects in Texas.

Finally, there were several improvements which took place as a part of this study to consider some factors not considered before. These include concrete shoulder construction, two overlays (instead of just one) to provide the desired lifetime, and the consideration of the additional life left in an overlay after the original PCC loses its load carrying capacity.

The effect of all of these improvements along with the basic approach to fatigue life prediction are discussed in this section.

### Details of the Approach

The overall approach to predicting the fatigue life of a pavement structure is very simple, even for the case of an overlaid pavement structure. The reader may, however, find the jargon and the logic difficult at first to understand. Therefore, this discussion will begin with the simplest problem imaginable, a two layer pavement structure, concrete and subgrade, subject to cyclic loading of a fixed magnitude. This is analogous to a repeated load flexural beam test in the lab.

First, an estimate of the maximum tensile stress in the concrete is obtained from the available analytical methods. In this case, the method used is elastic layer theory with finite element adjustments for the particular types of discontinuities considered. The use of this analytical method requires the determination of thicknesses of each layer; material properties, elastic modulus, and Poisson's ratio for each layer, and the flexural strength of the concrete.

Then, the maximum tensile stress and concrete flexural strength are used in a fatigue equation (discussed later) based on AASHO Road Test data. The result, then, is an estimated number of load cycles the structure will carry before it reaches the level of "failure" inherent in the fatigue equation. This may be when 10 percent of the surface area is cracked.

The discussion of elastic layer theory and how it is used to predict response was presented in Chapter 3 while the discussion of how material properties are to be determined is presented in Chapter 6 (the RPRDS-1 User's Manual). Discussion of how fatigue lives are predicted for the various types of overlay strategies considered in RPRDS-1, the finite element adjustments to elastic layer stresses, and the fatigue equation used is presented later

in this chapter, but, first, it is important to complete the discussion of the approach to fatigue life prediction.

The discussion above describes how RPRDS-1 predicts the fatigue life for the simplest possible case, the original pavement structure. This should, however, provide the foundation necessary for understanding how the fatigue lives are predicted for the more complex overlay problems.

As mentioned previously, McCullough (Ref 2) first suggested the approach to predicting the fatigue life of an overlaid pavement and, later, Austin Research Engineers, Inc., developed it for the Federal Highway Administration (Ref 1). The method assumes that Miner's linear damage hypothesis is valid for such applications and uses it to develop the concepts of pavement damage and remaining life.

The term damage is used to identify a certain amount of pavement deterioration. Damage due to the cyclic application of a constant stress level may be mathematically expressed by the following relationship

$$d_i = n_i / N_i \quad (4.1)$$

where

$n_i$  = number of applied cycles at some  $i^{\text{th}}$  constant stress,

$N_i$  = allowable number of cycles at that  $i^{\text{th}}$  constant stress, and

$d_i$  = damage experienced by the pavement after  $n_i$  cycles.

For example, if the allowable number of cycles to failure,  $N_i$ , was 100 and the number of applied cycles,  $n_i$ , was 40, then the damage,  $d_i$ ,

experienced by the structure due to those 40 applications would be 0.40 or 40 percent.

The linear damage assumption, now, says that the individual damages,  $d_i$ , may be algebraically summed to determine the total damage due to the application of a variety of stress levels. This may be expressed mathematically as

$$d_T = \sum_{i=1}^m d_i = \sum_{i=1}^m (n_i/N_i) \quad (4.2)$$

where  $n_i$  and  $N_i$  are as defined before and

$d_T$  = total damage due to the application of a variety of stress levels,  $i$ , and

$m$  = number of different stress levels.

In the example, if the damage due to 600 cycles of another stress level (in which the allowable number of cycles was one thousand) is accumulated according to Miner's hypothesis, then, the total damage the structure would suffer is

$$d_T = 0.40 + 600/1000 = 1.0$$

Or, in other words, the damage to the structure is 100 percent, which implies that it has reached the failure level inherent in the fatigue equation.

Now, to illustrate how this is used to predict the fatigue life of a structure after it is overlaid, consider the example of placing a bonded PCC

overlay on an existing PCC which has already experienced some fatigue damage.

Equation 4.2 will become

$$d_T = n_1/N_1 + n_2/N_2 \quad (4.3)$$

where

$N_1$  = fatigue life obtained from the fatigue equation using predicted maximum stress due to the design 18-kip single axle load on the original pavement (see Fig 4.1a),

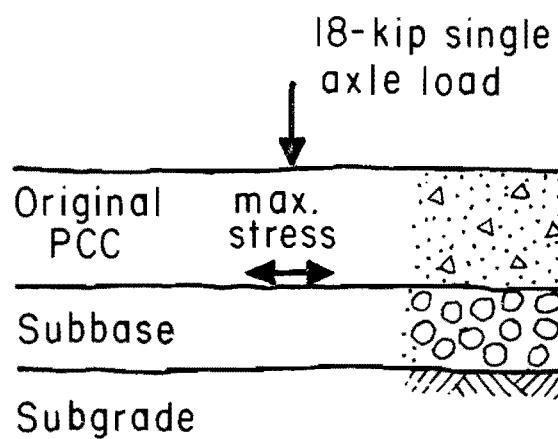
$n_1$  = the number of 18-kip equivalent single axle loads (ESAL) the original pavement was subjected to before overlay (this is determined from past traffic estimates),

$N_2$  = fatigue life obtained from the fatigue equation using the predicted maximum stress in the original PCC due to an 18-kip single axle load on the overlaid structure (see Fig 4.1b),

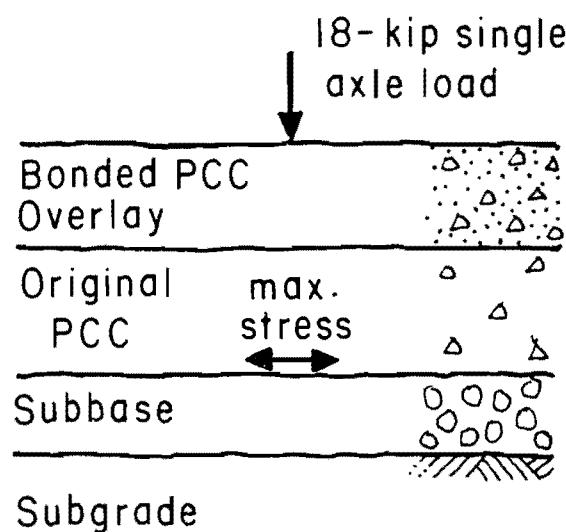
$n_2$  = the number of 18-kip ESAL the pavement structure can carry after overlay, and

$d_T = 1.0$ , since the damage to the pavement at the end of its lifetime is 100 percent.

The meaning of each term can be expressed graphically in a plot of damage versus 18-kip cycles as shown in Fig 4.2a. Line 1 represents the deterioration (or fatigue) of the original PCC. Line 2 represents the deterioration of the original PCC if the bonded PCC overlay was placed before any damage to the original PCC had occurred. It should be apparent now, that line 3 must represent the deterioration of the original PCC in which the

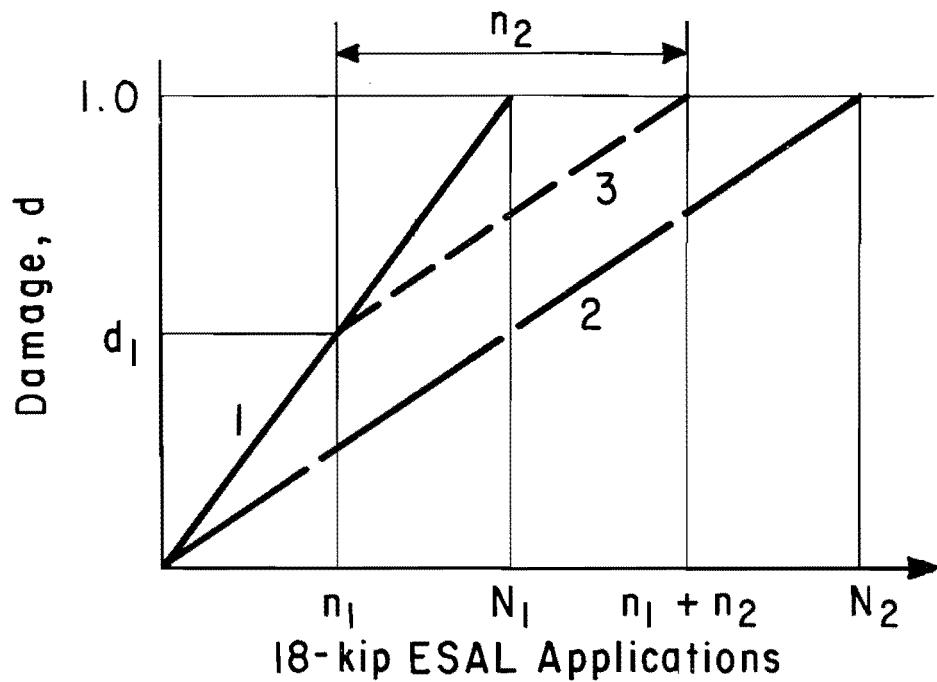


(a) Maximum stress in original PCC before overlay.

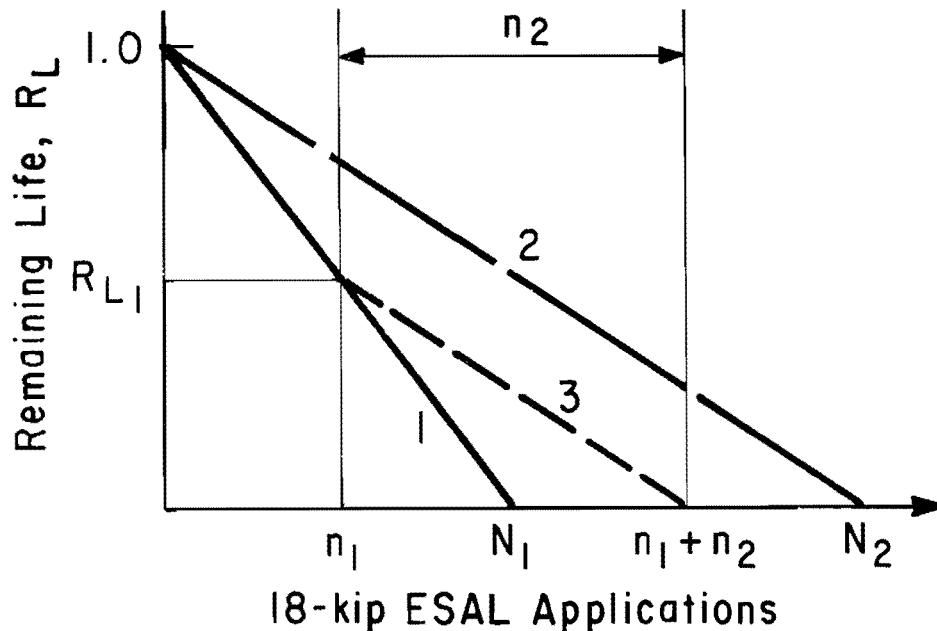


(b) Maximum stress in original PCC after bonded PCC overlay is considerably lower than before overlay.

Fig 4.1. Illustration of the maximum stresses in original PCC layer before and after a bonded PCC overlay.



(a) Plot of damage versus 18-kip ESAL applications.



(b) Plot of remaining life versus 18-kip ESAL applications.

Fig 4.2. Graphs illustrating the deterioration of the original PCC for the bonded PCC overlay example.

bonded PCC overlay was placed after  $n_1$  cycles of the 18-kip single axle load. It should be apparent, also, that the slopes of lines 2 and 3 are identical. Finally, it should be noted that it is the slopes of these lines that are the most affected by the different overlay strategies.

Since  $n_2$ , the life of the pavement structure after overlay, in this case is the number required to estimate the year in which the strategy will "fail", its value can be determined by rearranging Eq 4.3:

$$n_2 = (d_T - n_1/N_1) N_2 \quad (4.4)$$

where  $d_T$ ,  $N_1$ ,  $n_1$ , and  $N_2$  are known quantities.

Now that the equation for predicting the fatigue life of the original PCC after overlay has been derived, an explanation of the concept of remaining life is in order.

Remaining life may be defined as the amount of damage left in a pavement layer after it has been subjected to cyclic loading. It is the term in parentheses in Eq 4.4,  $d_T - n_1/N_1$ , where  $d_T$  is equal to one. The notation adopted for remaining life is  $R_L$ ; therefore,

$$R_L = 1 - d_1 = 1 - n_1/N_1 . \quad (4.5)$$

It can be expressed as either a fraction or a percent. If Fig 4.2a were plotted with remaining life on the vertical axis, it would result in the graph shown in Fig 4.2b.

There are two reasons why the remaining life concept was adopted. One was to allow the designer to estimate the amount of life left in a pavement where there is little past traffic data available. The second and more important reason is that remaining life is considered to be highly correlated with data gathered from field observations or condition surveys of the distressed pavement. The development of such a relationship would help eliminate the need for precise past traffic information and allow the designer to rely on up-to-date surveys of in-service pavements for overlay design problems.

#### Improvements to the Approach

Up to now, the discussion has been on the approach to predicting the fatigue life of a single concrete layer, the original PCC. In general, this is the extent of the FHWA and Texas SDHPT design procedures (Refs 1 and 9); the life of a specific overlay design strategy is expressed only in terms of the fatigue life of a single load carrying layer. This approach is certainly conservative, but, in some cases, it may be too conservative. An extension of the approach is to consider the life left in the overlay after the original PCC loses its load-carrying capacity.

The extension of the approach can be described with the aid of Fig 4.3. At the time of overlay placement, the original PCC has already experienced a certain amount of damage and, therefore, is at some level of remaining life,  $R_{L_e}$ , which is well below 100 percent. The overlay, however, has experienced no damage and has a remaining life of 100 percent. Then as fatigue applications due to heavy trucks continue, the overlay will deteriorate to a point,  $R_{L_o}$ , where the original PCC would have no load

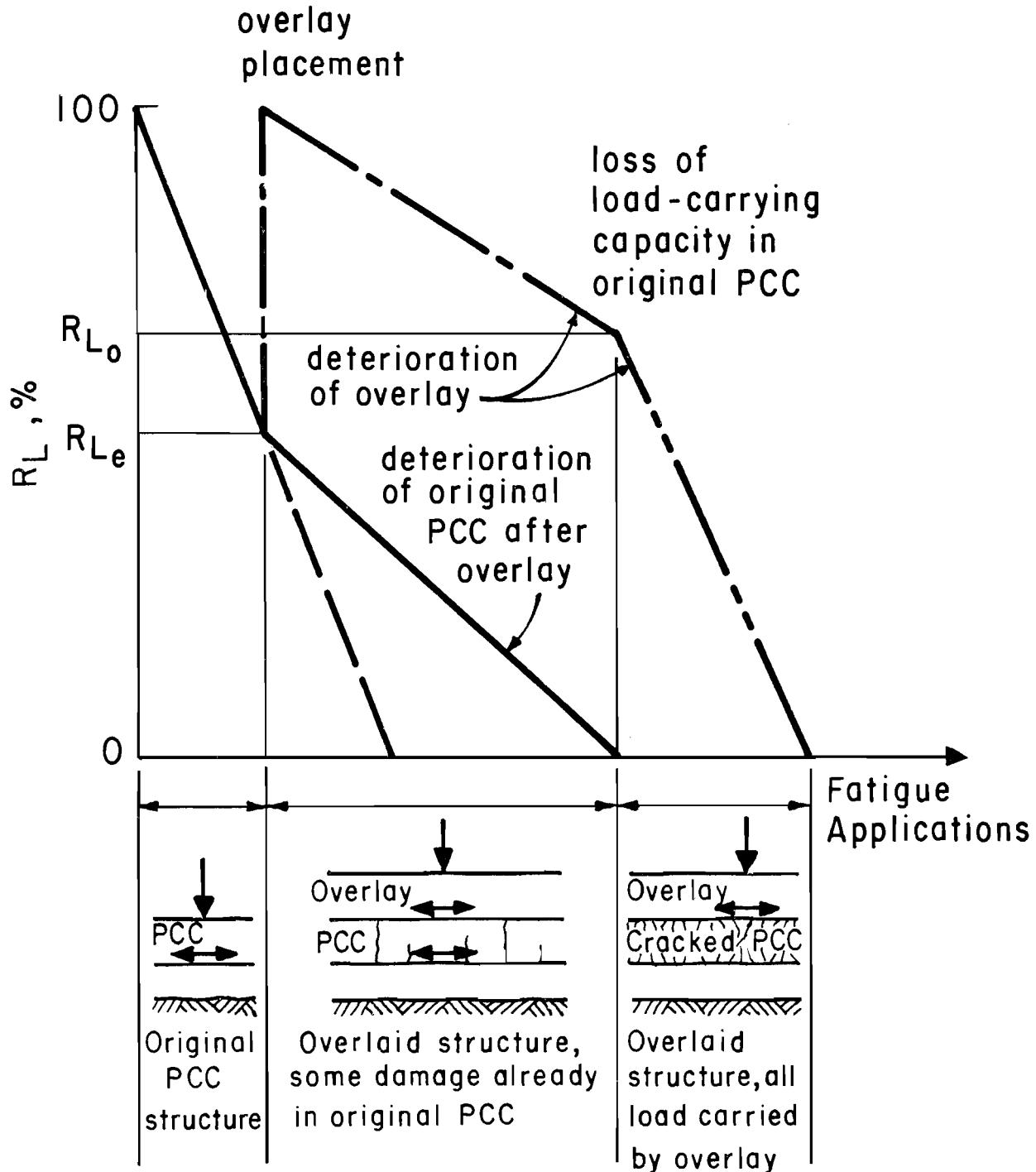


Fig 4.3. Graph of remaining life versus fatigue applications, which illustrates how the approach to predicting the pavement fatigue life (after overlay) was extended to consider the additional life left in the overlay after the original PCC loses its load-carrying capacity.

carrying capacity. The fact that the original PCC has become totally damaged does not necessarily mean the overlay has. Depending on the type of overlay and how it was placed, the structure may yet be able to carry a significant number of load applications. This is definitely the case for ACP and unbonded PCC overlays.

Since the load-carrying capacity of a layer is dependent on the amount of cracking it has incurred, remaining life must be a function of cracking. So, when predicting how the overlay will deteriorate, it is important to consider how cracking in the underlying PCC layer will affect the cracking (and therefore remaining life) of the overlay. In the bonded PCC overlay example discussed previously, experience has shown that any crack which exists or originates in the original PCC will always propagate up through the bonded PCC overlay. (This is known as reflection cracking and may be explained by the existence of stress concentrations above a crack once it is initiated). After a short period of time, the cracking and remaining life of the bonded PCC overlay will be identical to that of the original PCC. Accordingly, by the time the original PCC reaches the level of no remaining life, the bonded PCC overlay will also. This is illustrated in Fig 4.4.

As for the ACP and unbonded PCC overlays, their deterioration is as shown previously in Fig 4.3. Generally, the remaining life for both overlay types will be significantly high at the point when the original PCC reaches the level of zero remaining life. The explanations for this high level of remaining life for each overlay type are, however, quite different.

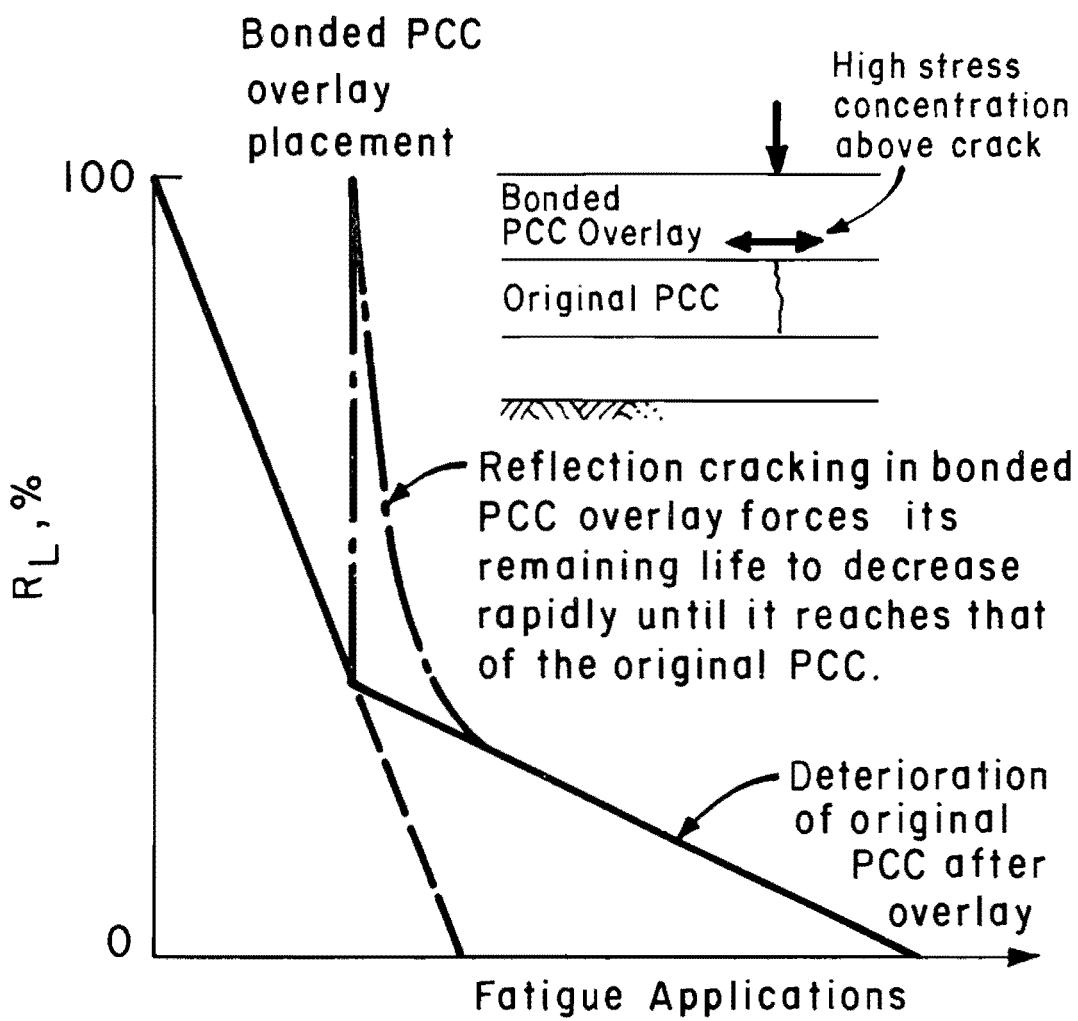


Fig 4.4. Graph of remaining life versus fatigue applications which illustrates effect of reflection cracking on the deterioration of a bonded PCC overlay.

For the case of the unbonded PCC overlay, the fact that there is a bond breaker between the two PCC layers (to help absorb any differential movement which may lead to reflection cracking) insures that the overlay will deteriorate primarily due to its own fatigue. In fact, the tensile stresses which cause fatigue in the overlay can be computed using elastic layer theory (with finite element adjustments for discontinuities). The bond breaker which separates the two PCC layers usually consists of a thin layer of low-stiffness asphaltic concrete which not only helps shield reflection cracking but also acts as a level-up course.

Unlike an unbonded PCC overlay, an ACP overlay comes into intimate contact with the surface of the original PCC, much like a bonded PCC overlay. But, unlike those of the bonded PCC overlay, material properties peculiar to asphaltic concrete help keep it from reflecting a crack which may exist in the underlying PCC. Results of an experimental overlay project on an existing CRCP along IH-45 in Walker County, Texas, obtained from studies by McCullough (Ref 2) and McCullough and Chesney (Ref 33) and from several condition surveys of the project (conducted by the Center for Highway Research at The University of Texas) indicate that structural ACP overlays (those at least 3 inches thick) are much less susceptible to reflection cracking than bonded PCC overlays, particularly on existing CRC pavements. For one thing, asphaltic concrete is not as brittle as portland cement concrete and can develop greater horizontal tensile strains (i.e., those due to temperature drop related movements of the underlying pavement) without cracking (so long as the underlying horizontal movements at the crack are not as large as they are at the joint of a JCP). Secondly, asphaltic concrete tends to relax and heal itself at higher temperatures, which, in turn, interrupts the reflection cracking process. Finally, it is apparent that

since CRC pavements depend on aggregate interlock for load transfer across a crack, there is little differential vertical movement across the crack and therefore the induced vertical shear strains in an ACP overlay are low. The combination of all these tends to limit the reflection of underlying cracks through an ACP overlay as long as the underlying PCC pavement has some load-carrying capacity. Even so, reflection cracking is still the ultimate mechanism of distress which destroys the structural integrity of the ACP overlay. Since this is not the usual process of fatigue, it was necessary to adopt a different approach to predicting the allowable number of 18-kip single axle cycles an ACP overlay can carry.

Earlier, it was pointed out that an ACP overlay is placed so that it will "stick" to the existing surface (a delamination between the two layers may lead to serious problems with pop-outs). Because of this, the ACP overlay, theoretically, can not carry any bending tensile stresses (or strains) since most of it, if not all, is above the neutral axis of the two-layer combination (see Fig 4.5). This is even true for the case in which the original PCC has no load carrying capacity, since the effective stiffness of the two layers is almost the same. The stiffness of the original PCC, however, is usually not indicative of the kind of tensile stresses and strains it can carry since it is based only on measured Benkelman Beam deflections at the AASHO Road Test. Recognizing this, Schnitter (Ref 9) developed a model which does not allow the underlying PCC to carry any tensile stresses if it is cracked and has no load-carrying capacity. In the model, the cracked pavement below the ACP overlay is characterized as a single semi-infinite layer with a composite stiffness. Then, a fatigue strain which hopefully simulates the reflection cracking strain is calculated and used in the ACP fatigue equation. The composite stiffness is determined

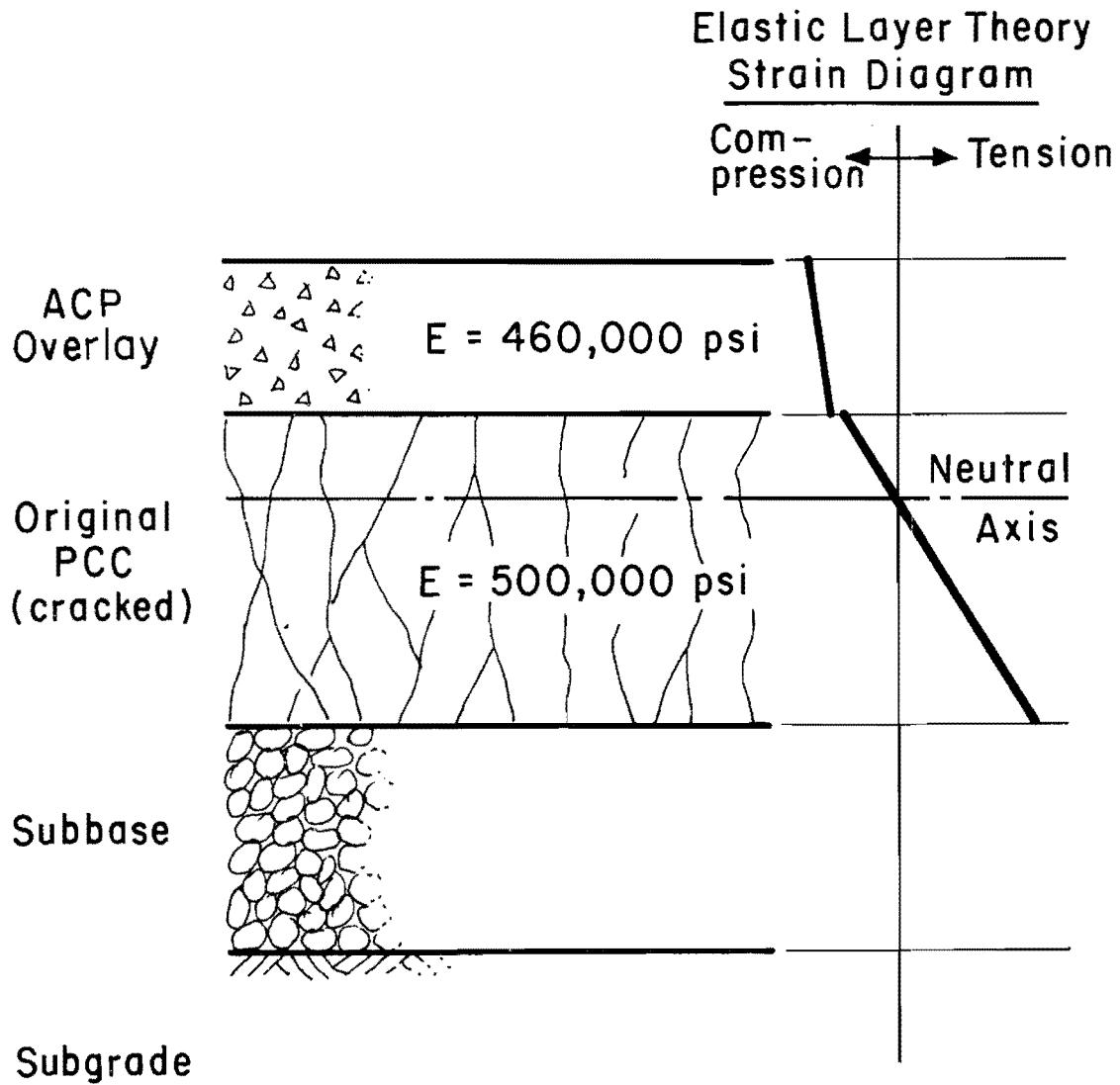


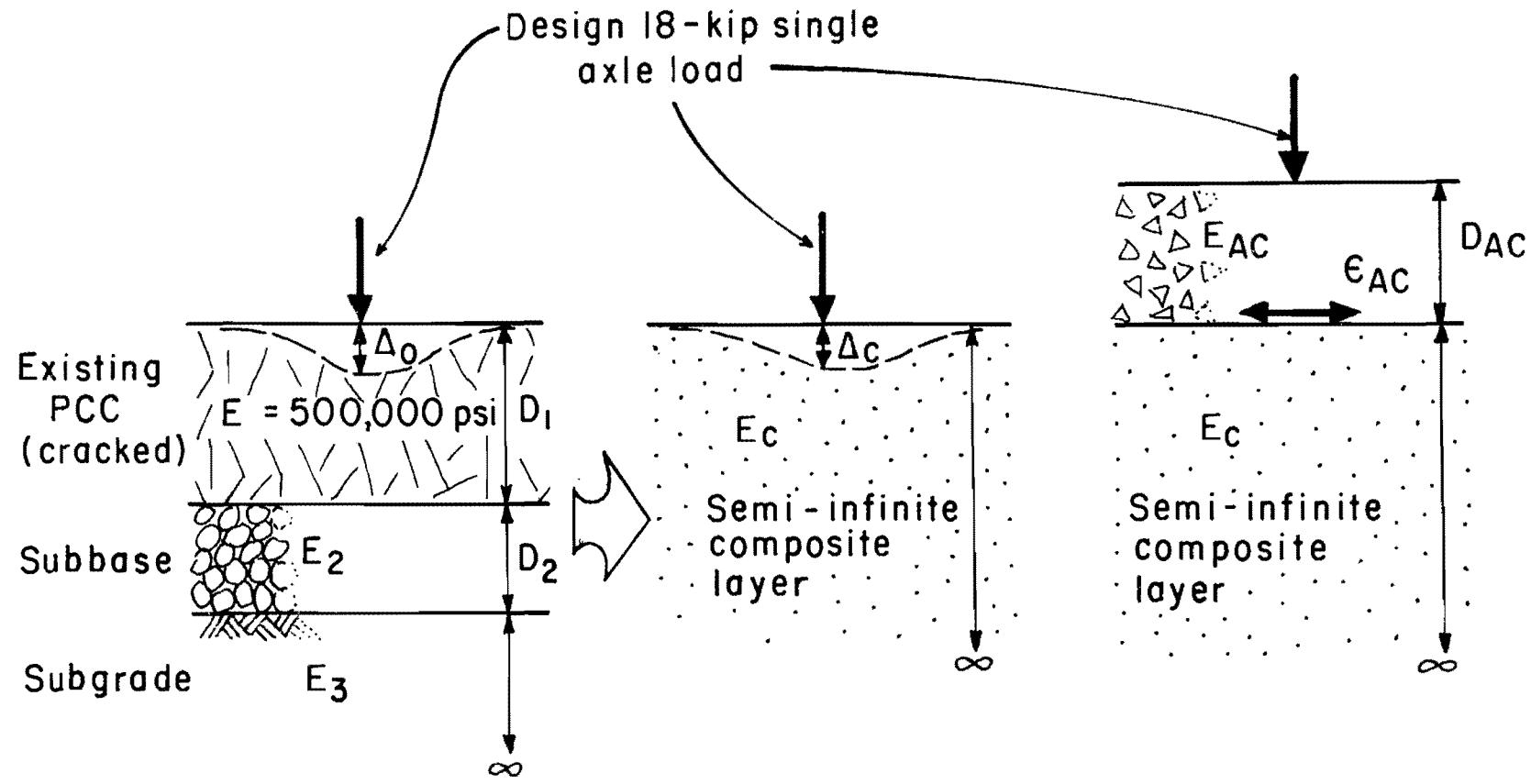
Fig 4.5. Strain diagram for a cracked PCC structure with an ACP overlay.

by matching the deflection under the design 18-kip single axle load for the composite and cracked structures. This model is illustrated in Fig 4.6 and is similar to the approach used in the AASHTO Interim Guide (Ref 5) for determining a composite k-value for a subbase layer on top of a subgrade.

The model temporarily solves the problem for an ACP overlay on an existing PCC pavement. Unfortunately, it does not solve the problem of an ACP overlay on a PCC pavement which still has load-carrying capacity. For this case, it is necessary to assume that the damage incurred by the overlay due to a single load cycle is equivalent to that incurred by the underlying PCC (or, in other words, assume the rate of deterioration of the ACP overlay is the same as that of the original PCC). Though this assumption is not necessarily conservative, it was found that its effects, when it is used in conjunction with the AC fatigue equation, were negligible for ACP overlays less than 8 inches thick. Still, a better overall approach would be to estimate the maximum strains which cause reflection cracking using finite element theory and then correlate them with field measurements of load transfer, horizontal movement at the crack or joint, and 18-kip equivalent single axle traffic. The lack of this data, however, makes it impossible to develop such a relationship at this time.

#### Available Overlay Strategies

Now that the background of the overlay design model has been presented, it is convenient to discuss the overlay design strategies available in RPRDS-1. Figure 4.7 illustrates the alternatives which are possible with regard to the type of the existing pavement and the type of overlay. Note that a two-overlay strategy can be considered but that at least one of the



Deflection,  $\Delta_0$ , under cracked original pavement is determined. Stiffness at composite layer,  $E_c$ , is varied until its deflection,  $\Delta_c$ , matches  $\Delta_0$ .

AC overlay is placed on composite layer. Maximum tensile strain,  $\epsilon_{AC}$ , is then determined

Fig 4.6. Illustration of the method for determining the tensile strain in an ACP overlay on a cracked PCC pavement.

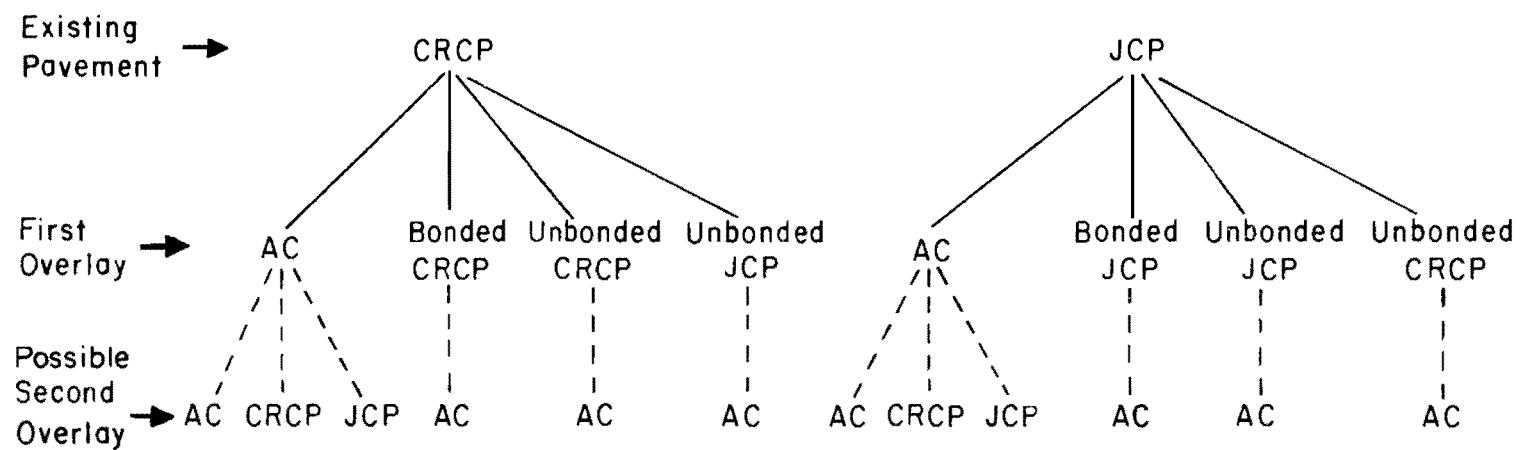


Fig 4.7. Illustration of the overlay design strategies available in RPRDS-1 with regard to existing pavement and overlay type.

two must consist of asphaltic concrete. Though the discussion of the approach to predicting fatigue life did not cover the method for a two-overlay combination, it will become apparent later when the specific models for each possible design are presented.

Besides the type of overlay, the other variable components of an overlay strategy include

- (1) remaining life of the existing surface layer at time of overlay placement,
- (2) overlay thickness,
- (3) flexural strength of a PCC overlay, and
- (4) concrete shoulder construction.

The remaining life of the existing surface layer at the time of overlay construction is considered to be an important component of a strategy since it corresponds to a particular future year which, due to discount rate, may significantly affect the net present value of a given strategy. The method in which the future year is determined for a given value of remaining life is discussed later in this chapter.

The other three variable components are considered because of their effect on the life of a given strategy. There are two things, however, that should be kept in mind about the overlay flexural strength and concrete shoulder construction components. The first is that although concrete flexural strength is highly correlated with concrete stiffness (elastic modulus), the variation of the stiffness is not taken into consideration because of the additional computer time and storage it would require. Also, there is some question as to the validity of varying the overlay's flexural

strength since the concrete fatigue equation (discussed later) is based only on the mean flexural strength of the AASHO Road Test sections (690 psi).

The second important thing to keep in mind is that concrete shoulder construction can be considered only if a concrete overlay is to be constructed at the same time. This leaves out the option of constructing a concrete shoulder at grade with the original structure. This option is not considered practical or economically feasible due to the amount of work involved with tying the PCC shoulder into the original structure.

The best way to show how each component is considered and at the same time present the equations which predict the fatigue life of each possible strategy is to present a flowchart of the RPRDS-1 routine (STRATEGY) which performs the analysis. The flowchart of STRATEGY is presented in Appendix C.

Each strategy that is generated is identified by ten different indices. A feasible strategy is stored with this set of indices and other design factors relating to time of overlay placement and time of overlay failure (loss of load carrying capacity). This set of indices is described below.

- (1) IRL1 - Index of the remaining life of the original pavement at the time of the first overlay. IRL1 varies from 1 to NRL1 for each user-specified remaining life (10 maximum).
- (2) IOV1 - Index to the type of first overlay (1=ACP, 2=Bonded CRCP, 3=Unbonded CRCP, 4=Bonded JCP, 5=Unbonded JCP).
- (3) IC1 - Index which identifies whether a concrete shoulder is constructed at the time of first overlay (0=No, 1=Yes). Concrete shoulder construction cannot be considered if the first overlay is ACP.

- (4) IFR1 - Index to the level of the flexural strength of the first overlay. IFR1 varies from 1 to NFROV, the number of user-specified flexural strengths to consider (5 maximum). IFR1 will be zero if the first overlay is ACP.
- (5) IOV1T - Index to the thickness of first overlay. IOV1T varies from 1 to NACT1 for an ACP first overlay and from 1 to NPCCT for a PCC first overlay (8 maximum for both cases).
- (6) IRL2 - Index of the remaining life of the first overlay at the time of the second overlay. IRL2 varies from 1 to NRL2 for each user-specified remaining life (10 maximum). IRL2 is zero if a second overlay is not part of the strategy.
- (7) IOV2 - Index to the type of second overlay (1=ACP, 2=CRCP, 3=JCP).
- (8) IC2 - Index which identifies whether a concrete shoulder is constructed at the time of second overlay (0=No, 1=Yes). Concrete shoulder construction cannot be considered if the second overlay is ACP.
- (9) IFR2 - Index to the level of flexural strength of the first overlay. IFR2 varies from 1 to NFROV, the number of user-specified flexural strengths to consider (5 maximum). IFR2 will be zero if the second overlay is ACP.
- (10) IOV2T - Index to the thickness of second overlay. IOV2T varies from 1 to NACT2 for an ACP second overlay and from 1 to NPCCT for a PCCT second overlay (8 maximum for both cases).

There are several submodels used by the STRTGY routine which are not explained in Appendix C. These include

- (1) the fatigue equations,
- (2) the method for adjusting the elastic layer stresses for the particular discontinuities associated with a given alternative, and
- (3) the method for predicting the year corresponding to some cumulative traffic.

They are discussed next, in the order shown.

#### The Fatigue Equations

The term fatigue equation is used in this context to identify the relationship between the response of a pavement under load (i.e., stress or strain) and the number of cycles of that load the pavement can carry before it reaches some failure criteria. RPRDS-1 uses three fatigue equations: two for portland cement concrete (PCC) and one for asphaltic concrete (AC).

PCC Equations. The concrete fatigue equations used in RPRDS-1 are the result of an analysis performed by Taute (Ref 31) on AASHO Road Test data (Ref 4) and data from statewide condition surveys in Texas (Ref 44). They represent an improvement over the original equation developed by Austin Research Engineers (ARE) for the Federal Highway Administration (Ref 1), since the seasonal variation of subgrade strength was taken into account during their development. One of the equations also attempts to account for the better moisture environment provided by the placement of an overlay. These two equations along with the original ARE equation are shown in Fig 4.8. In order to better understand the use of these equations in RPRDS-1, it is useful to first describe (and contrast) their development.

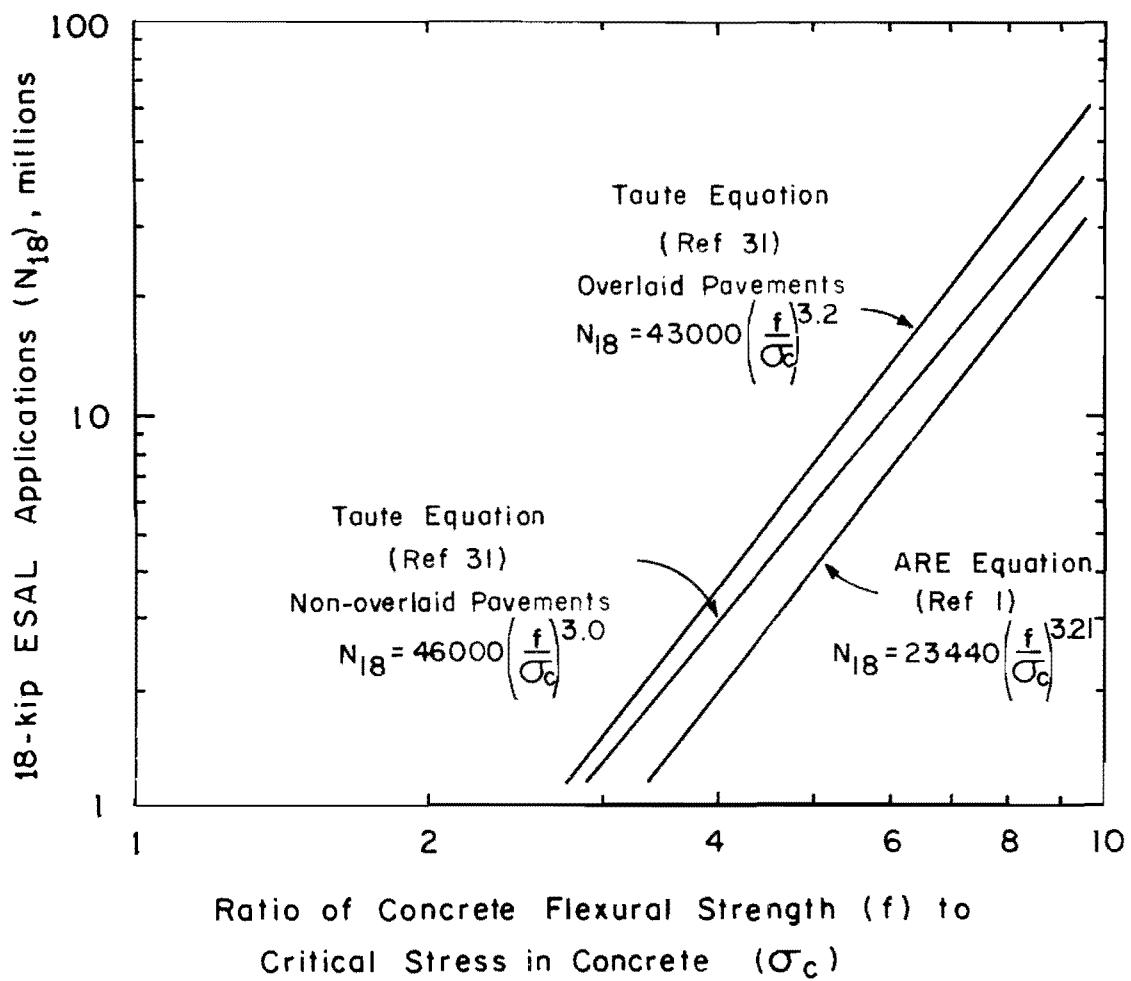


Fig 4.8. PCC fatigue equations.

Development of the ARE equation began with the characterization of the material properties of the PCC sections at the Road Test. The significant aspects that should be pointed out here are that a mean subgrade stiffness (elastic modulus) of 5000 psi and a concrete flexural strength,  $f$ , of 690 psi were used for all sections in the analysis.

The elastic layer program, ELSYM5 (Ref 21), was then used to predict the critical stress,  $\sigma_c$ , under the simulated 18-kip axle load for each section. (Note that since the outer wheel path for approximately 90 percent of the applications was well away from the pavement edge, an interior stress condition was assumed. This, in turn, eliminated the need for adjustments for higher stress conditions near the edge.) Equivalency factors developed at the Road Test were then used to estimate the equivalent 18-kip single axle applications,  $N_{18}$ , carried by each section. A regression analysis was then performed to determine the "best-fit" line through this data. Also, it should be pointed out that the failure criterion used for this equation was the point when the pavement first exhibited Class 3 and 4 cracking.

A slightly different approach was used by Taute (Ref 31) to develop the two new PCC equations. First of all, a higher level of distress (a cracking index of 50 feet per 1000 square feet, AASHO definition) was selected for the failure criteria for non-overlaid pavements. This point seemed to correspond with a point (determined from the statewide condition survey of CRCP in Texas) where distress levels began to increase rapidly. This point is assumed to correspond to a loss of pavement load-carrying capacity and no remaining life.

Next, the strength of the subgrade was characterized (using Benkelman Beam deflections) for two main seasons, one when the subgrade was firm and the other when the subgrade was weakened due to spring thaw. Like the ARE

development, a mean value of 690 psi was used for the concrete flexural strength for all sections since little variation was observed in the data. Once again, ELSYM5 was used to predict the interior concrete stress for both seasons; however, some adjustments were applied in estimating the average critical stress,  $\sigma_c$ , for each section. These adjustments were to account for the distribution of wheel loads across the pavement. It is important to note, also, that these stresses were determined using a simulation of the actual axle loads used at the Road Test and not a simulation of the 18-kip equivalent single axle used in the ARE development. This eliminated the need for using AASHO equivalency factors to estimate the equivalent 18-kip single axle traffic on each section. (Some equivalency factors were used, however, to account for the difference in load duration between single and tandem axles.)

The next step of the iterative process was to estimate an equivalent critical stress for each section, using Miner's linear damage hypothesis and the traffic and critical stresses for each season. A regression analysis was then performed to generate a new fatigue equation using the equivalent critical stress as an independent variable and the total traffic as the dependent variable. The iterative process would continue until the new fatigue equation differed insignificantly from the assumed fatigue equation.

Though this equation was developed with as few limiting assumptions as possible, Taute points out four factors to consider when using it:

- (1) The AASHO rigid pavement sections were all jointed and had only granular subbases which often exhibited extreme amounts of pumping.

- (2) The effects of spring thaw at the Road Test were severe, which may not be the cases in many areas, especially in Texas.
- (3) The Road Test sections had only granular shoulders, which are certainly not common on today's Interstate Highway system.
- (4) There was very little traffic encroachment near the pavement edge at the Road Test, which is, once again, not the case for many of today's highways.

Furthermore, this equation is recommended for use only with non-overlaid pavements or those which have poor moisture environments.

For overlaid pavements, Taut recommends the use of the second PCC equation (shown in Fig 4.8). This equation is basically an adjustment of the first equation based on results that showed that overlaid pavements in Texas were far exceeding their design life predicted by the previous design method (Ref 9). This was attributed to the improved moisture environment provided by overlay placement. Because of this, the new equation is also used in RPRDS-1 for predicting the life of pavements which have a concrete shoulder, since they are not subject to water ponding at the pavement edge.

AC Equation. The fatigue equation used in RPRDS-1 for the design of asphaltic concrete (AC) overlays is the original one developed by Austin Research Engineers, Inc. (ARE), for the Federal Highway Administration (Ref 6). Like the PCC equations, this one was based on data from the AASHO Road Test (Ref 4); however, this one was not based directly on field data. The AC equation represents a correlation with the AASHO cracking equation (Eq 4.6) which is a function of the pavement structure and axle load:

$$\begin{aligned}\log W_c = & 5.484 + 7.275 \log(0.33D_1 + 0.10D_2 + 0.08D_3 + 1) \quad (4.6) \\ & + 2.947 \log L_2 - 3.136 \log(L_1 + L_2)\end{aligned}$$

where

$W_c$  = allowable load applications before Class 2 cracking (the failure criteria),

$D_1$ ,  $D_2$ ,  $D_3$  = pavement layer thicknesses,

$L_1$  = axle load, and

$L_2$  = 1 for single axle configuration and 2 for tandem.

The AASHO equation had a squared correlation coefficient of 0.79 and the AC equation used here (see Fig 4.9), which attempts to model it using elastic layer theory, has a squared correlation coefficient of 0.93. The materials characterization method used to develop the AC equation is similar to that used to develop the ARE concrete fatigue equation. Table 4.1 shows the characteristics used in the elastic layer analysis.

It should be noted that the critical tensile strains predicted for the AASHO Road Test sections were relatively high (greater than 10 in./in.). This, in turn, limits the application of the AC fatigue equation used in RPRDS-1 to ACP overlay thicknesses of less than 8 inches.

#### Finite Element Adjustments

As discussed in an earlier section of this chapter, elastic layer theory is used to predict pavement response in RPRDS-1. Unfortunately, real pavements are not as simple as those modelled by elastic layer theory. They have joints, cracks, edges, corners, nonuniform support, and other similar types of discontinuities which have a large effect on pavement response. This section, then, describes how finite-element adjustment factors were developed to account for these types of discontinuities in overlay design.

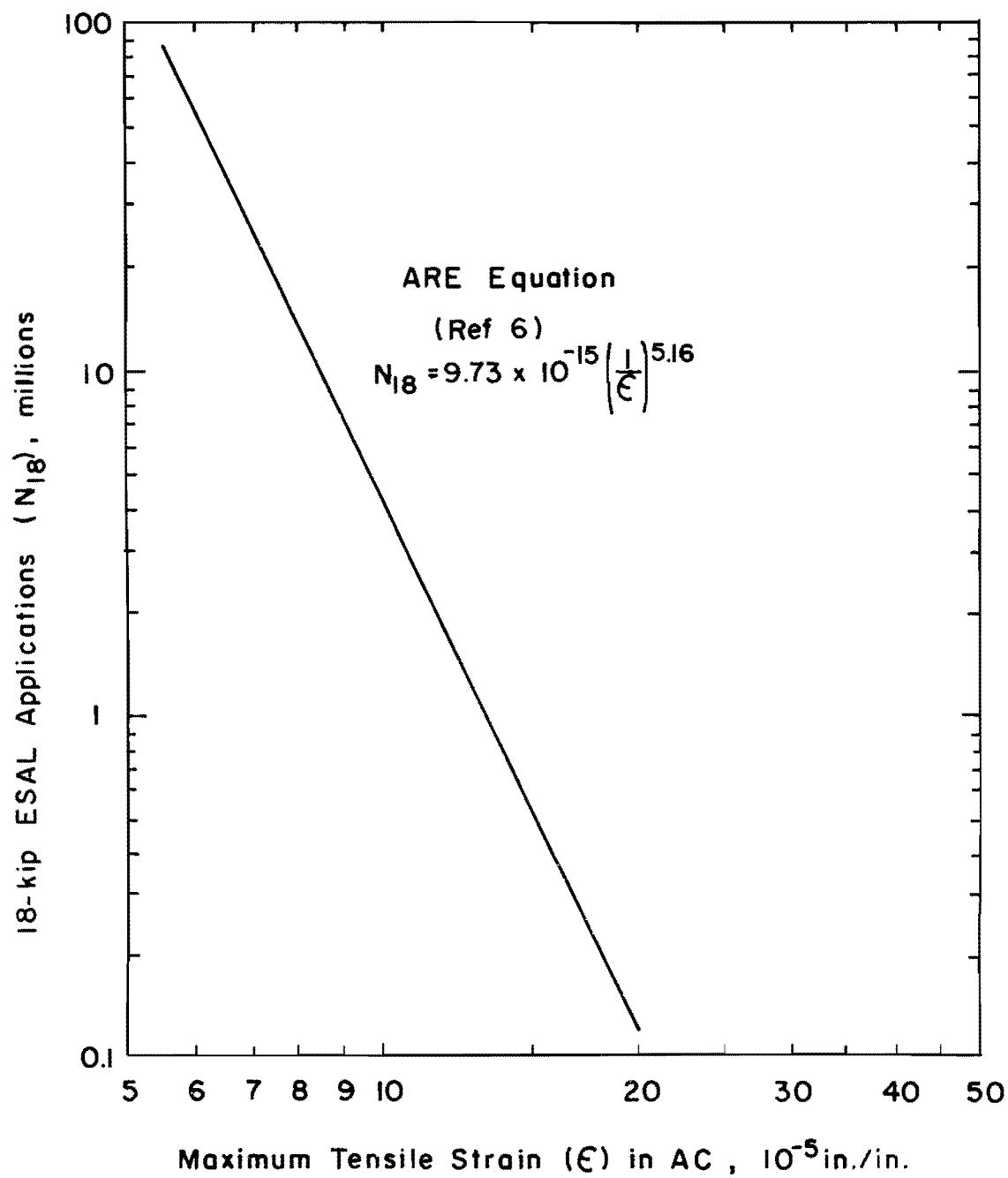


Fig 4.9. AC fatigue equation used in RPRDS-1.

TABLE 4.1. CHARACTERISTICS OF THE AASHO ROAD TEST FLEXIBLE SECTIONS WHICH WERE USED IN THE DEVELOPMENT OF THE AC FATIGUE EQUATION

<u>Layer</u>	<u>Elastic Modulus, psi</u>	<u>Poisson's Ratio</u>	<u>Range of Thickness, in.</u>
AC Surface	460,000	.30	1 - 6
Base	40,000	.40	0 - 9
Subbase	20,000	.40	0 - 16
Subgrade	5,000	.45	Semi-infinite in all cases

There are several computer models which use finite-element theory to solve engineering problems and the one used in this study is similar to most. It is called SAP-2 (Static Analysis Program - Version 2) and was developed at the University of California at Berkeley (Ref 40). Some thought was also given to using the discrete-element method incorporated into SLAB49 (Refs 41 and 42) as used in the development of the original design procedure (Ref 1), but it was rejected since SLAB49 is basically for a single slab PCC pavement and can not consider multiple overlays.

The approach used to develop a set of adjustment factors to account for pavement discontinuities was to (1) run SAP-2 to determine the response for an interior slab condition (this is similar to the elastic layer response due to differences in modelling the load and the subgrade), then (2) run SAP-2 for the critical loading condition (near the pavement edge or corner) to determine the critical response, and finally, (3) calculate the adjustment factor by taking the ratio of the critical response to the interior response. This adjustment factor was then used to adjust the interior response predicted by elastic layer theory.

Figure 4.10 illustrates these different stresses in an unbonded PCC overlay on an existing PCC pavement. Figure 4.10a shows the interior tensile stresses developed in the overlay and existing pavement due to a simulated 18-kip axle load. Figure 4.10b illustrates the edge stresses in both PCC layers for the case when there is a PCC shoulder. The critical stress factors for both PCC layers, in this case, are simply the ratio of the edge stress to the interior stress:

For the original PCC pavement,

$$C_P = \sigma_{P_e} / \sigma_{P_i}, \quad (4.7)$$

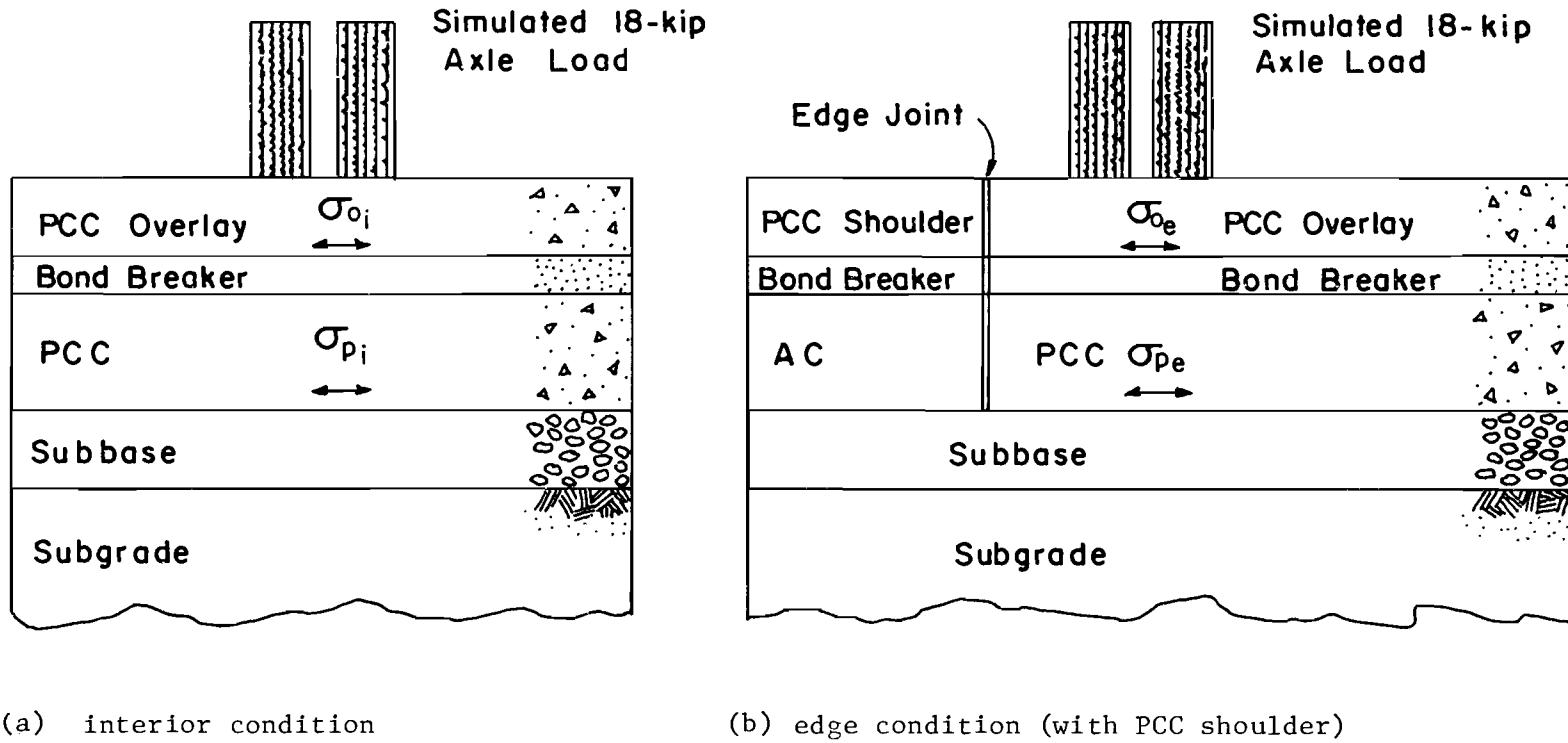


Fig 4.10. Illustration of interior and edge stress conditions for one of the overlay strategies considered in RPRDS-1 (an existing PCC pavement with an unbonded PCC overlay with PCC shoulders). The ratio of edge to interior stress is used for adjusting stresses predicted by elastic layer theory.

and for the PCC overlay,

$$C_o = \sigma_{o_e} / \sigma_{o_i} . \quad (4.8)$$

Figure 4.11 shows how the pavement structure in Fig 4.10b is modelled in SAP-2 to determine the interior and edge stresses. The figure also shows typical plan, front, and side views of the modal frame as well as the elements, loads, and boundary conditions which make up the model. It should be pointed out, also, that every advantage of symmetry is taken in modelling the structure. This is illustrated particularly in the side view of Fig 4.11 which represents half of the longitudinal profile of the structure. The other half is modelled without the additional elements and nodes (which increase computation time dramatically) by (1) fixing movement in or out of a transverse vertical plane in the structure under the load and (2) fixing the rotation about the transverse axes in the transverse vertical plane. Rotations are also fixed about vertical axes in the transverse vertical plane, as shown in Fig 4.11.

By varying some of the variables which affect the ratio of the critical to interior stresses the most (such as concrete, subgrade, and subbase stiffness), a range of critical to interior stress ratios can be determined. A summary of these ranges (as developed in this study) is provided in Table 6.3 of the RPRDS-1 User's Manual for all possible overlay combinations considered by RPRDS-1. Some guidelines for selecting the appropriate stress factors are also provided in the User's Manual.

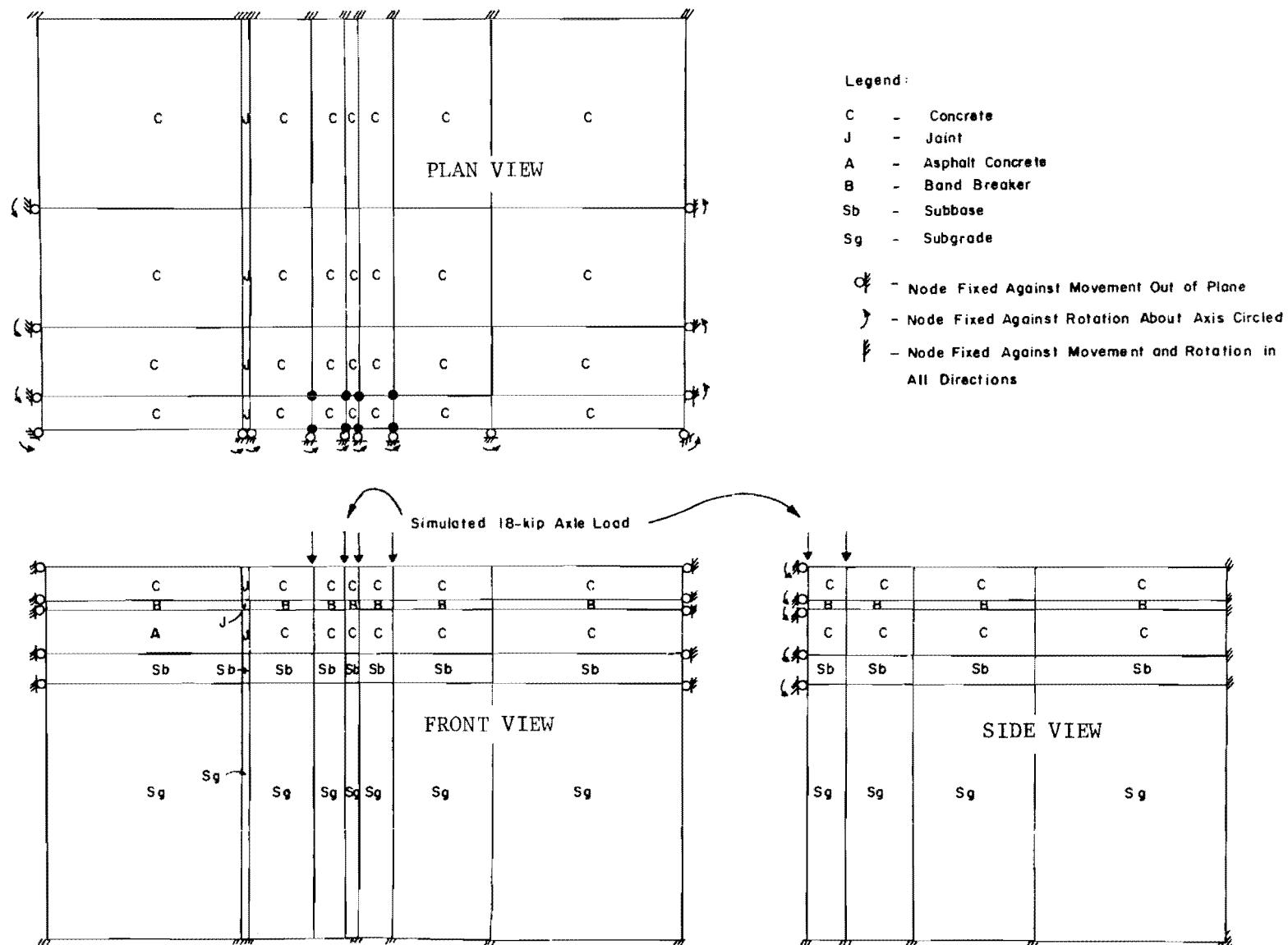


Fig 4.11. Illustration of pavement model used in SAP-2 to predict stresses for the pavement structure shown in Fig 4.10.

Year Corresponding to Cumulative Traffic

This section describes how RPRDS-1 computes the year (relative to year zero of the analysis period) corresponding to some cumulative 18-kip ESAL traffic. This model is used to estimate the approximate year of overlay placement and the year in which a strategy will "fail." This model is contained within the YEAR routine in RPRDS-1 and is illustrated in Fig 4.12.

Basically, the equation used by the Texas State Department of Highways and Public Transportation to compute the average daily traffic (ADT) at some future year is used here to compute the future year given the cumulative traffic. The equation for the future traffic is

$$W_i = W_0 (1 + iG) \quad (4.9)$$

where

$W_i$  = yearly traffic in  $i^{\text{th}}$  year,

$W_0$  = initial yearly traffic,

$i$  = future year, and

$G$  = traffic growth rate (expressed as a fraction).

The total cumulative traffic,  $W$ , in year  $i$ , may be expressed by the summation of  $W_j$  as  $j$  goes from 1 to  $i$ . Then by replacing the summation with an equivalent mathematical expression, Eq 4.9 can be rearranged to give the year corresponding to the cumulative traffic:

$$i = \frac{-2 - G + \sqrt{(2 + G)^2 + 8GW/W_0}}{2G} \quad (4.10)$$

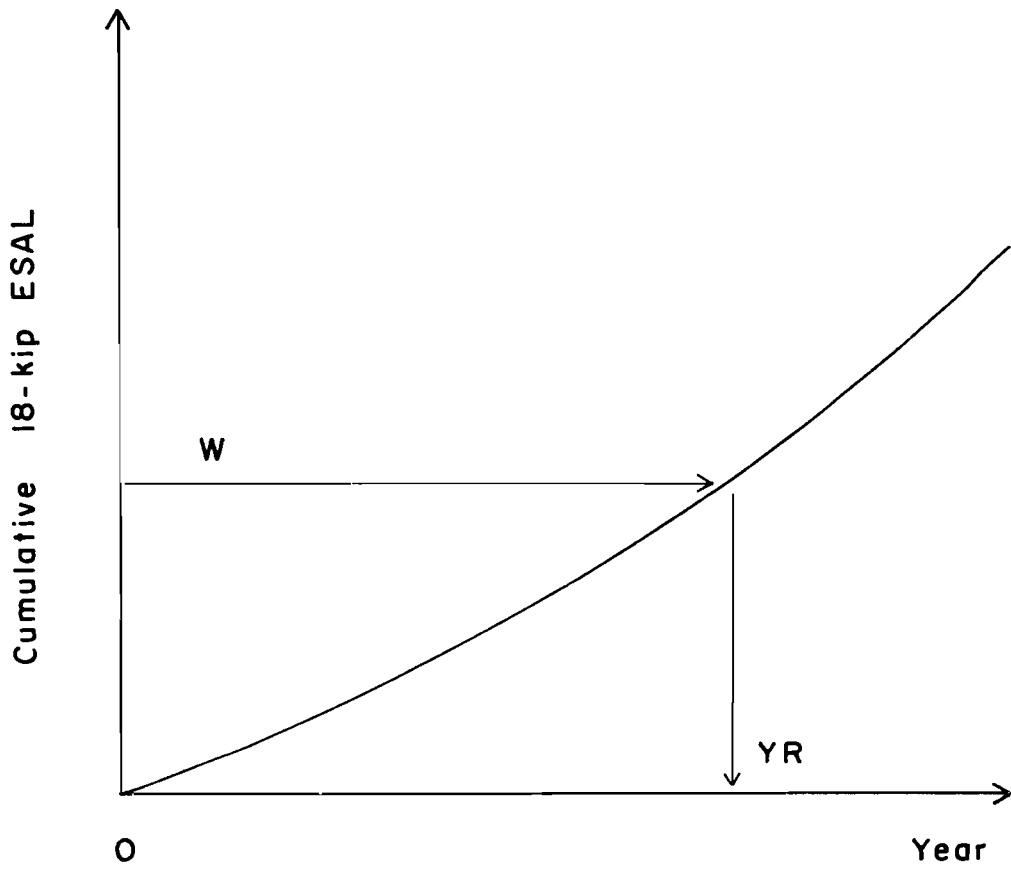


Fig 4.12. Illustration of how the year (YR) corresponding to some future cumulative 18-kip ESAL traffic (W) is determined.

This equation cannot be solved, however, if the traffic growth rate,  $G$ , is equal to zero. In this case, the following equation is used:

$$i = W/W_0 \quad (4.11)$$

## SUMMARY

As pointed out earlier, the purpose of this chapter is to describe how feasible overlay design strategies are generated in RPRDS-1. Now that the components of the routine (STRATEGY) used to generate these feasible strategies have been discussed, it is useful to provide a brief summary of how these components fit together.

First of all, it is necessary to generate a candidate strategy, keeping in mind some of the constraints on overlay thickness. To do this, certain cumulative 18-kip ESAL applications must be obtained: (1) the traffic from year zero to the time of overlay placement and (2) the traffic from year zero to the time of overlay failure. These 18-kip ESAL traffic values are determined by first combining the results of layer theory and the finite element analyses to predict the required critical responses. These critical responses are then used in conjunction with the fatigue equations and the fatigue life prediction models to obtain the 18-kip ESAL traffic values.

Next, the years corresponding to these 18-kip ESAL traffic values are determined (using the YEAR routine), so that a check for feasibility can be made using the remaining time constraints. If the candidate strategy meets these remaining constraints, it is stored as a feasible strategy for later cost analysis and optimization.

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## CHAPTER 5. COST ANALYSIS OF EACH FEASIBLE STRATEGY

The purpose of this chapter is to provide a description of how the individual and total costs for each feasible overlay design strategy are determined. The structure of the routine, COSTRY, within the RPRDS-1 program which performs this analysis is so simple that a detailed flowchart of the routine is not warranted. Figure 2.2 and 5.1 should provide the reader a good idea of what the individual costs are as well as the order in which they are determined.

Inspection of Fig 5.1 shows that there are several different cost submodels required to estimate the component costs of each strategy. These components include traffic delay cost (associated with overlay construction), overlay construction cost, distress/maintenance cost, value of extended life (beyond the end of the analysis period), and salvage value. The latter two are actually negative costs since they represent a future return on the investment made in a particular rehabilitation strategy.

Each of these cost submodels, along with the method for determining net present value and the method of optimization, is discussed below.

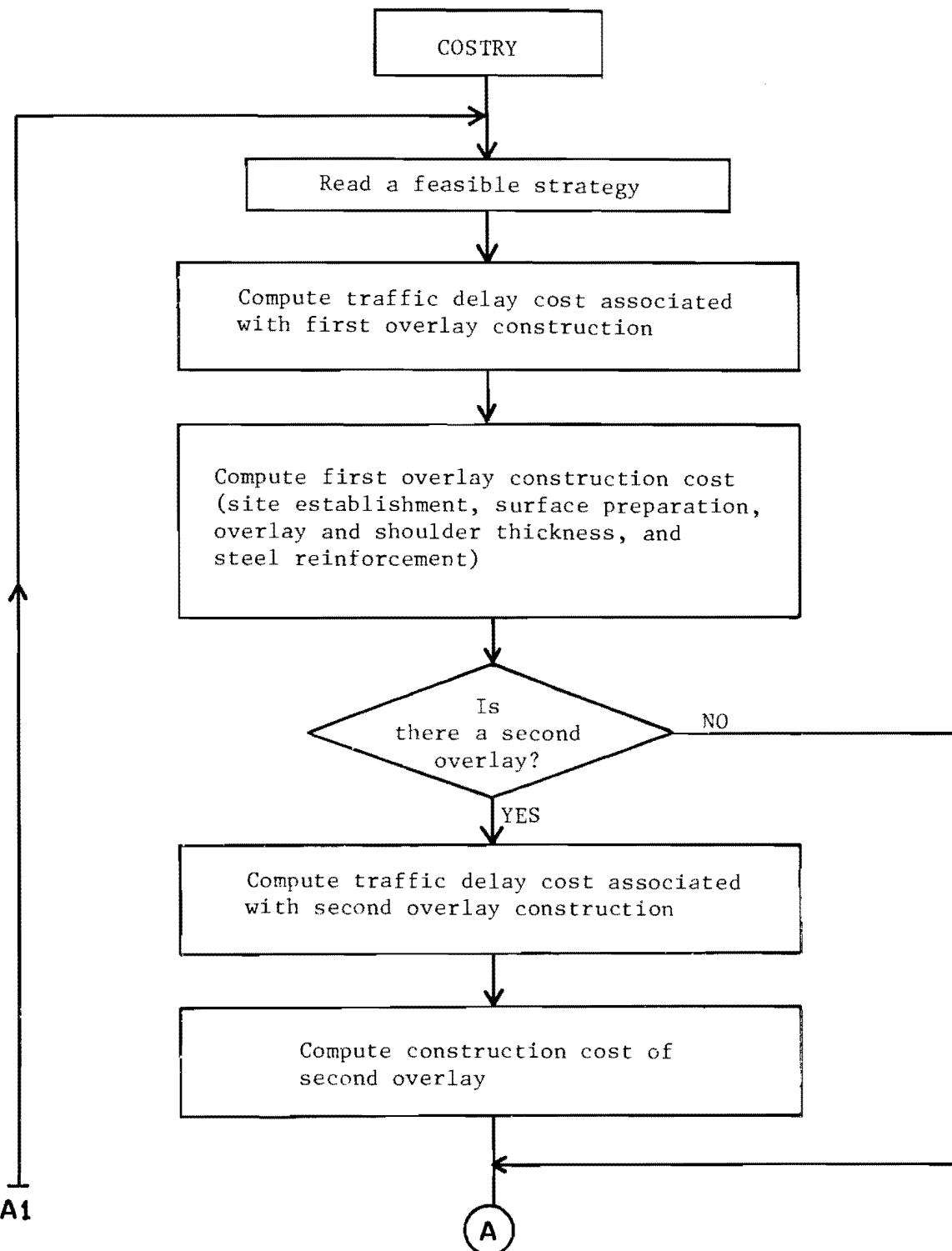


Fig 5.1. General flowchart of the cost analysis, COSTRY, routine.

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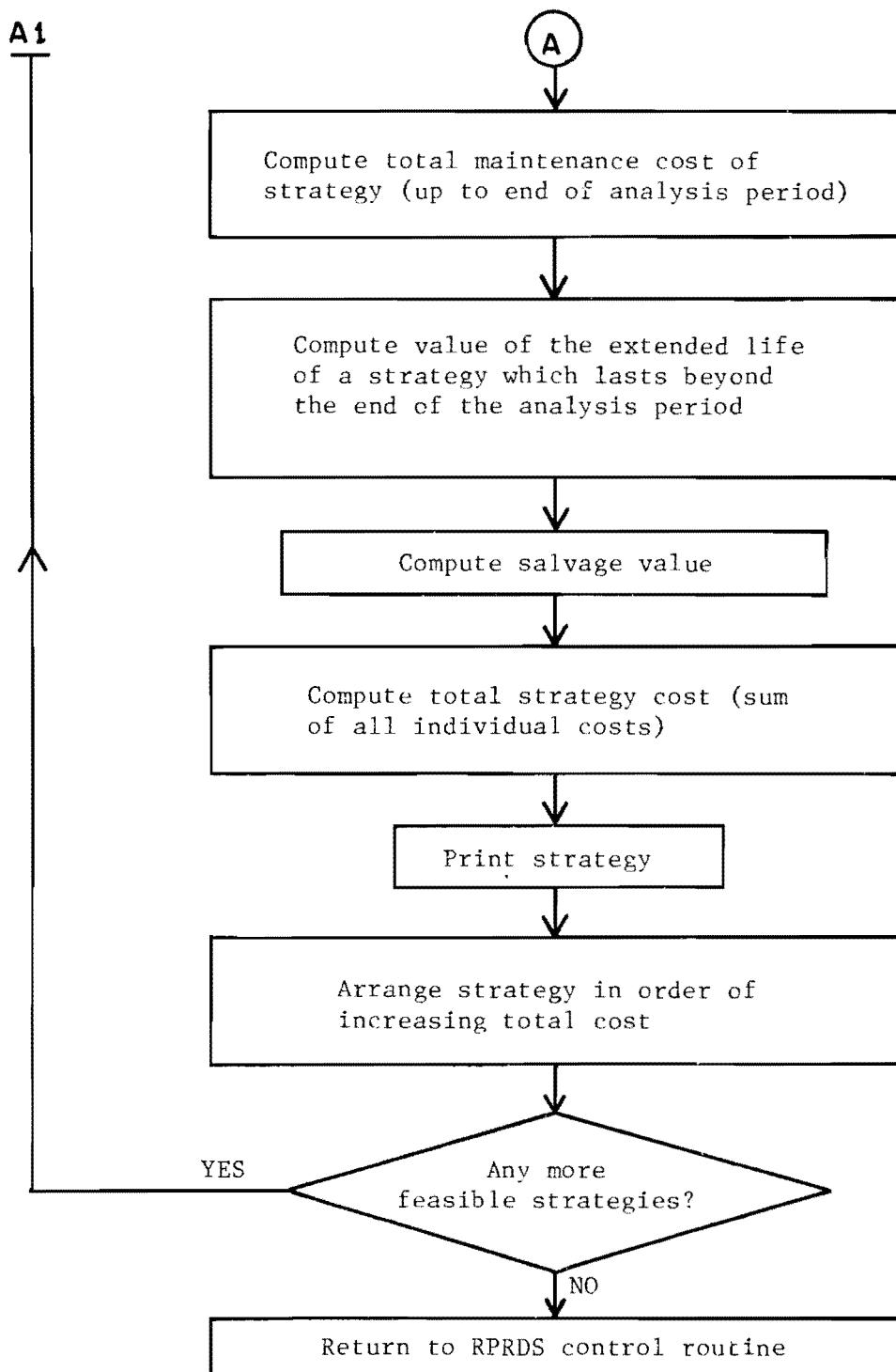


Fig 5.1. (Continued).

## TRAFFIC DELAY COST SUBMODEL

This model was originally developed by Scrivner, Moore, McFarland, and Carey (Ref 12). It has been continually updated and modified with each version of the Rigid Pavement System, RPS. Carmichael (Ref 7) made the most significant improvement, in 1974, while Daniel (Ref 43) has provided the most up-to-date user delay costs (1978) for Texas conditions. With the exception of some minor changes to incorporate the routine into the framework of RPRDS-1, the traffic delay cost routine (TDCSY) is the same as that used by Daniel. Since the development of this routine is well documented in these previous studies, only a cursory description of its method of predicting costs is presented here. A detailed description of the inputs required by the model is, however, provided in Chapter 6, the RPRDS-1 User's Manual.

Basically, the model first predicts the delay times incurred by each vehicle as it passes through the restricted overlay zone. Daily distributions of traffic for rural and urban areas of Texas, as well as the incremental user delay costs per unit time, are built into the routine. These, along with the user-specified traffic volumes and periods during which the delays will occur, are used to determine the total overall traffic delay cost. The cost is then converted to a per square yard basis and is brought back to net present value using the PRVAL routine discussed later in this chapter.

It should be pointed out, also, that the routine is capable of predicting what the vehicle delay times are, so long as the user provides information regarding traffic volume, overlay construction rate, detour models, and traffic speed profiles through the restricted zone. Once again,

Chapter 6 discusses in detail the selection of these inputs required by the model.

#### OVERLAY CONSTRUCTION COST SUBMODEL

The cost of overlay construction can be broken down further into four categories, site establishment cost, pavement surface preparation cost, overlay and shoulder thickness, and steel reinforcement. Each is determined on a per square yard basis and numerically summed to give the total overlay construction cost. The submodel which estimates these costs is incorporated directly into the COSTRY routine. A description of how each of these costs is determined is provided next.

##### Site-Establishment Cost

This refers to the cost of mobilizing the men and equipment necessary to perform the overlay construction. It does not include the cost of right-of-way or any other cost which is not dependent on the type of overlay to be constructed. Since RPRDS-1 predicts costs on a per square yard basis, the value of this cost is divided by the total pavement area in the project before summation.

##### Surface-Preparation Cost

This refers to the cost of any cleaning and milling which must be performed on an existing surface prior to overlay. It is entered on a per square yard basis and is therefore ready for immediate summation.

### Overlay and Shoulder Thickness Cost

First of all, the cost of shoulder construction is included in RPRDS-1 since the capability exists for considering the effect of a PCC shoulder (in lieu of a flexible or ACP shoulder) on the overlay strategy's fatigue life. The calculation of the shoulder construction cost is handled in the same way as that of the overlay thickness cost; that is, the cost of a certain thickness of overlay (or shoulder) consists of a fixed cost (dollars per square yard) and a variable cost (dollars per square yard per inch of thickness).

The fixed cost takes care of the cost of any traffic detour arrangements which need to be made and the cost of machinery and manpower required to perform the actual construction. Examples of the latter include the cost of vibrating and surface finishing for PCC overlays, and compaction, rolling, and surface finishing for ACP overlays. The units of fixed cost are dollars per square yard.

The variable cost accounts for the differences in thickness between different overlay strategies. Consequently, the units of variable cost are dollars per square yard per inch.

In addition to the thickness cost, the construction cost submodel also considers the increased volume of material required for level-up and the cost of bond breaker placement for unbonded PCC overlay strategies.

### Steel Reinforcement Cost Submodel

Unlike the Rigid Pavement System, RPS (discussed earlier), RPRDS-1 does not use a sophisticated model for the prediction of the steel reinforcement percentages required by PCC pavements. Instead, it must rely on the

designer's empirical estimates of the steel percentages required for the different overlay types.

There are two reasons why RPRDS-1 must use this simple method. The first is that the design here is for PCC overlays, a case where the method used in RPS (for new PCC pavements) is not applicable. The second, and more important, reason is that existing models for the design of reinforcement in PCC overlays are not at the stage where they can be easily incorporated into a design system. In any case, the method used here is more than adequate for use in the cost estimates. It is the responsibility of the user or designer to determine the required steel design in the event that a PCC overlay strategy is selected.

Basically, the steel percentages selected by the user (which should include transverse as well as longitudinal steel) are used to estimate the volume and weight of steel in a square yard of overlay. The cost per square yard is then calculated by multiplying the weight of steel per square yard by the cost per pound of steel, another user input.

#### DISTRESS/MAINTENANCE COST SUBMODEL

The purpose of this section is to describe how maintenance costs are predicted in RPRDS-1. Due to the interaction between the occurrence of pavement distress and the need for maintenance, some discussion is also provided on distress prediction. Also, since distress and maintenance are so confounded, it should be pointed out that the two are combined and considered simultaneously in RPRDS-1 in the MNTCST routine.

This submodel was developed in this study on the basis of an analysis by Taute (Ref 31) of a statewide condition survey of CRC pavements in Texas (Ref 44). As a result, it is largely exogenous and requires a lot of user input on the rates of distress occurrence during different stages of a pavement's life. Fortunately, however, this approach is general enough to allow for future improvements in the areas of distress prediction.

#### Method for Calculating Maintenance Costs

The mechanics of the model are simple. The user first defines the rate of distress occurrence and the cost for a single repair on the existing pavement. Then for each overlay type considered the user must specify (1) the cost of repairing a typical distress manifestation (or defect) which may occur, (2) the rates at which these defects occur during two stages of the fatigue life of the overlay, and (3) the rates of defect occurrence for any number of years (after the end of the fatigue life) the user wishes to consider to extend the life of a given overlay strategy (these additional years considered represent a period of heavy maintenance). With this information, the program will increment its way through the life of a strategy, multiplying the number of defects which occur during a given year by the cost of repairing them and then bringing them back to net present value. Then, when the end of the analysis period is reached, these yearly costs are accumulated to give the maintenance costs for the existing pavement and overlay(s), as well as the total maintenance cost of the strategy. Note here that, since the costs are computed after every year, there is an inherent assumption that maintenance will occur after every year. This is not a bad assumption, however, since it is only used to compute the present

value of any future maintenance costs. If maintenance does occur less often, the error may be considered negligible, especially in view of the fact that the error in distress prediction may be much more significant.

#### Distress Prediction

As pointed out earlier, the basis of the distress/maintenance cost submodel is a statewide condition survey of CRC pavements in Texas (Ref 44). In an analysis of this data performed by Taute (Ref 31), a pattern of distress development in these CRC pavements was observed. This pattern is illustrated in the graph shown in Fig 5.2. The vertical axis represents the total number of defects (i.e., punchouts or patches) which may occur in a typical mile of CRCP and the horizontal axis represents a normalized scale of the predicted fatigue life of that CRCP. As can be seen, no defects occur between 0 and 20 percent of the fatigue life, while they occur at a rate of one per mile per year between 20 and 60 percent and at a rate of 2 per mile per year between 60 and 100 percent of the pavement's fatigue life. Obviously, since these distress levels are low, the corresponding maintenance costs will be low. But, as the pavement is subjected to traffic beyond the end of its predicted fatigue life, its distress will increase dramatically. The geometric progression which was observed in the survey data is also shown in Fig 5.2. This section of the CRCP distress curve corresponds to a period of heavy maintenance which the user may want to consider to allow a certain design strategy to last the analysis period.

Before concluding this discussion of distress and maintenance, there is one important point which should be considered by the user when using the model; the data obtained from the Texas condition survey were from existing

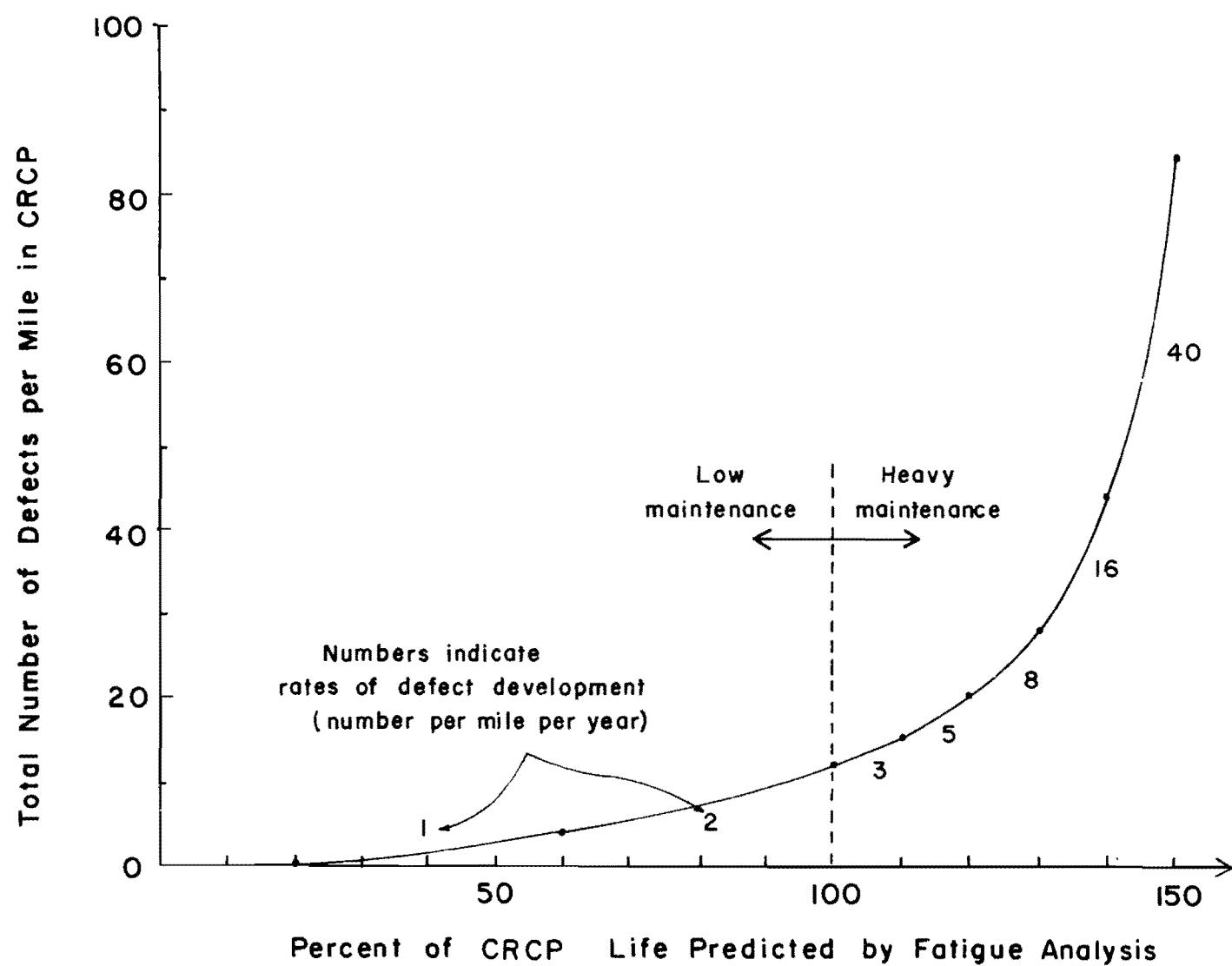


Fig 5.2. Normalized graph of the development of CRCP defects in Texas.

CRC pavements only. This means that there is some question as to the validity of applying these results to CRCP overlays of rigid pavements. Hopefully, this and the two other reports (Refs 31 and 44) will provide the user enough background to aid in the selection of appropriate values for both CRCP overlays and ACP overlays on CRCP. Unfortunately, no background can be provided here for JCP overlays or ACP overlays on JCP.

#### VALUE OF EXTENDED LIFE

This quantity represents a future return (negative cost) resulting from the additional years of service past the end of the analysis period that some strategies will provide due to the fact that they are "over-designs." This is different from salvage value and comes about because of the nature of the input thicknesses in RPRDS-1. While one overlay thickness strategy may not last the analysis period, the next overlay strategy, which may be only one inch thicker, may last an additional five to ten years depending on the traffic. Obviously, it is not reasonable to eliminate these strategies from consideration (since the cost of the additional inch of thickness may be small) nor is it fair not to consider the value of these additional years of service.

Consequently, provision is made in RPRDS-1 for the user to assign some value (on a per square yard basis) to each additional year of service. These values are brought back to present value using the combined interest and inflation rate model discussed later.

The RPRDS-1 User's Manual in Chapter 6 will provide the user some guidance in the selection of the value of extended life. It should be noted

here, however, that some consideration should be given to (1) the fact that there is greater uncertainty in costs and traffic in the years past the analysis period, (2) the fact that maintenance costs were not computed for these additional years of service, and (3) the fact that salvage value is computed at the year the pavement reaches the end of its life and not at the end of the analysis period.

#### SALVAGE VALUE

This is another quantity that represents future return (negative cost). It accounts for the value of the overlay structure after it reaches the end of its life. Note (as pointed out earlier) that this does not necessarily correspond to the end of the analysis period since some strategies may last significantly longer.

Salvage value is computed by multiplying the total cost of overlay construction (in dollars per square yard) by a percentage specified by the user and once again returning this value to net present value. Note here that only the value of overlay construction cost is considered. (Original pavement construction cost need not be considered since it would be the same for all strategies.)

#### NET PRESENT VALUE

This submodel is used to account for the time value of money, namely, inflation and the opportunity cost of capital (prime interest). Ideally, the present value of some inflated future cost can be determined by first

determining what the future cost would be due to inflation and then calculating the amount of money that should be invested now to accrue interest and pay for that future cost. This can be done using specified values of interest and inflation, but, since these tend to fluctuate over the years, a better approach would be to use the difference between the two rates to compute net present value. There seems to be a little more stability in this value and the mathematical error in using it is negligible (a second order term is not considered). The expression for computing net present value using this method is shown below:

$$NPV = PC / (1 + d)^n \quad . \quad (5.1)$$

where

NPV = net present value,

PC = present cost,

d = difference between interest and inflation (expressed as a fraction), and

n = year in which the future cost is incurred.

Generally, the opportunity cost of capital (prime interest) is greater than inflation. Therefore, the net present value of a future cost for some item is less than today's cost for the same item. Consequently, there is a tendency for future rehabilitation strategies to be more optimal than early strategies when there is a large difference between prime interest rate and the rate of inflation. The offsetting factor for overlay construction, however, is that the overlay required at some future date may be considerably

thicker and, therefore, much more expensive than an overlay constructed at an earlier date.

#### METHOD OF OPTIMIZATION

The method of optimization used in RPRDS-1 is very simple and the same as that used in other pavement design systems. Basically, RPRDS-1 will order the top 20 strategies (ORDER routine) in order of increasing net present value. Then after all feasible strategies are printed, these top 20 are printed in an easily readable form (OUT20 routine).

#### SUMMARY

This chapter was intended to provide a brief but concise description of how the individual and total costs for each strategy are determined. Hopefully, this has been accomplished. Summarizing, each individual cost is computed on a per square yard basis and brought back to net present value before summing to get total strategy cost. Then, each of the strategy's individual costs is printed in the program's output to give the user an idea of what the major constituents of the total costs are.

## CHAPTER 6. RPRDS-1 USER'S MANUAL

The overall objective of this report is to develop a design system for rigid pavement rehabilitation by combining the Texas SDHPT Rigid Pavement Overlay Design (RPOD) procedure (Refs 9 and 31) developed initially for the Federal Highway Administration by Austin Research Engineers, Inc. (Ref 1) and some other design and cost models into a computer program, RPRDS-1, which could economically analyze a large number of feasible overlay design strategies. Chapters 1 through 5 have discussed in detail, the individual models and their development, improvement and incorporation into the first version of the rigid pavement rehabilitation design system, RPRDS-1. The purpose of Chapter 6, then, is to provide the user of the RPRDS-1 computer program a detailed description of how to use the program and how to interpret its results. Accordingly, guidelines for the selection of the inputs required (as well as some description of how the inputs are treated) will be presented. Then, in order to both illustrate the capabilities of the program and to discuss its output, a sample problem (complete with output from a single run) is presented.

Before beginning the description of the inputs, however, it is first useful to briefly discuss the most recent version of Texas SDHPT RPOD procedure since many of the same inputs are required by RPRDS-1.

## TEXAS SDHPT RPOD PROCEDURE

The significant steps of this procedure are illustrated in the flow diagram shown in Fig 6.1. A short discussion of each of these is provided below. They are not, however, intended to replace the reports referenced earlier.

- Step 1: Select the design criteria. This includes 18-kip equivalent single axle load (ESAL) traffic estimates (past and projected), lane and directional distribution factors, overlay and shoulder types to be considered, available aggregates, bond breaker criteria, construction methods, geometric constraints, and any other criteria which constrain the overlay design.
- Step 2: Conduct condition survey of the pavement in order to classify and quantify the cracking and other distress modes observed. The soil type in the area should also be inspected and classified.
- Step 3: Gather Dynaflect deflection data at approximately 100-foot intervals along the length of the project. Readings should be taken from all five sensors and the data should distinguish between measurements made at midslab and those made at discontinuities such as joints or cracks.
- Step 4: Select design sections. This is done by analyzing the Dynaflect deflection profiles where the sensor 5 and the difference between sensor 1 and sensor 5 are plotted for each longitudinal Dynaflect measurement. Figure 6.2 provides an

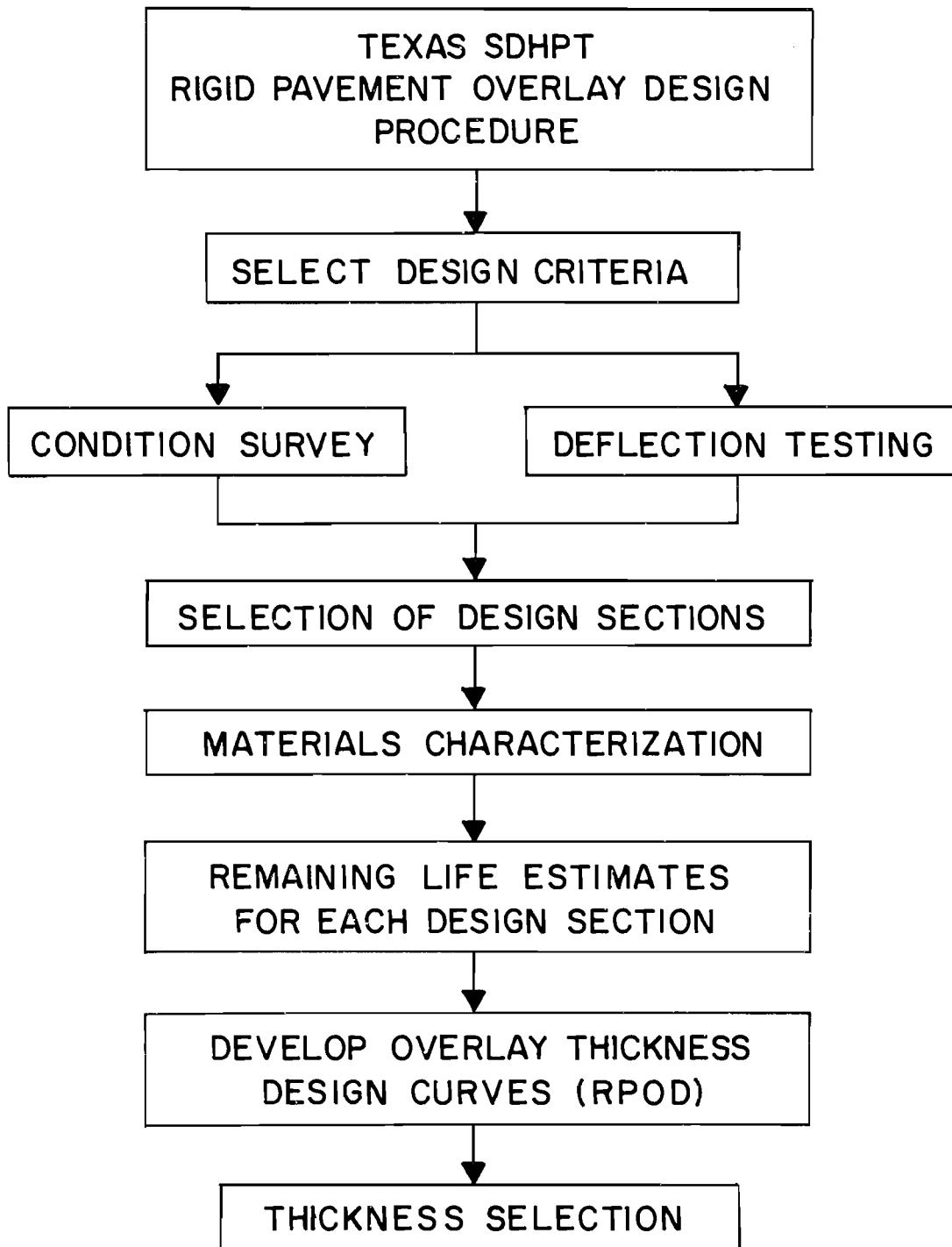


Fig 6.1. Flowchart of the Texas SDHPT Rigid Pavement Overlay Design procedure (Ref 31).

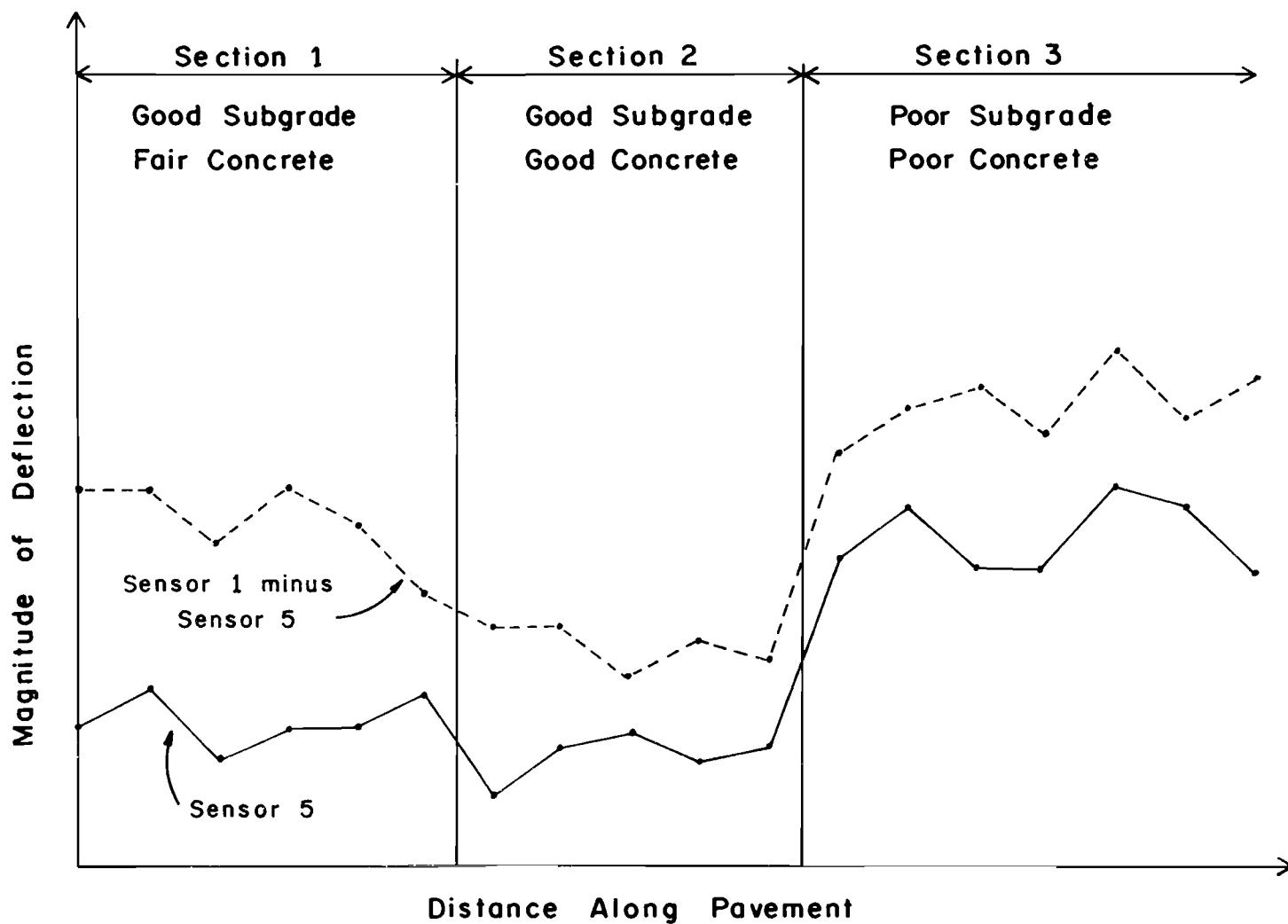


Fig 6.2. Deflection profile illustrating the procedure for selecting overlay design sections.

ideal illustration of how the sections are divided. Keep in mind that the sensor 5 reading is indicative of the variation of subgrade stiffness while sensor 1 minus sensor 5 indicates the variation of stiffness in the stronger pavement layers (particularly the concrete).

Step 5: Characterize the material properties of the pavement and subgrade, i.e., concrete flexural strength and the elastic properties for all layers in each section. This should be done by a combination of lab testing (i.e., indirect tensile tests on portland cement concrete and other bound layers and resilient modulus tests on subgrade and base materials) and Dynaflect deflection basin fitting (e.g., for a design Dynaflect deflection basin in each section, select elastic material properties of each layer which correspond to the best "fitted" basin predicted by elastic layer theory. Results of the lab tests should be used to home in on the solution). Adjustments to these layer moduli should then be made for stress sensitivity (since the design axle load is much heavier than the Dynaflect load) and predicted temperature conditions.

Step 6: Estimate the fraction of remaining life left in the existing pavement for each design section. This is obtained from estimates of the life of the existing pavement, past traffic estimates (Step 1), existing pavement condition (Step 2), and subgrade strength (Step 5).

Step 7: Use the rigid pavement overlay design (RPOD-2) computer model to generate overlay thickness designs for each design section. Note that several design curves may be generated for a

particular design section due to the range in acceptable design criteria.

Step 8: Select the overlay thickness required for each design section using the design future traffic and the design curves generated in Step 7. If alternative designs exist, the optimum should be selected based on projected cost and performance comparisons.

Note that the last sentence in Step 8 describes the need to compare alternative overlay design strategies, which is the purpose of RPRDS-1.

#### DESCRIPTION OF RPRDS-1 INPUT VARIABLES

The inputs to RPRDS-1 have been divided into 11 broad categories for ease of description. These eleven categories include

- (1) Project Description,
- (2) Original Pavement,
- (3) Traffic Variables,
- (4) Time Constraints,
- (5) Remaining Life Variables,
- (6) Overlay Characteristics,
- (7) Overlay Construction Cost Variables,
- (8) Traffic Delay Cost Variables,
- (9) Distress/Maintenance Cost Variables,
- (10) Cost Returns, and
- (11) Combined Interest and Inflation Rate.

For each of these headings, one or more data cards is required. Each separate input variable is assigned a number which corresponds to the order of the card on which it is placed and its order on the card. For example, the directional distribution factor, which falls under the category of Traffic Variables, is the fifth variable on the ninth card in the data, and, therefore, it is identified by the number 9.5. This method of classification will be adhered to in the later discussion of each variable.

The inputs required for a single problem are contained within 60 data cards (plus one to terminate program execution). The input guide which identifies the input field and the location of each variable in the data set is presented in Appendix D. It does not provide the detailed description of each variable that is presented here.

#### Project Description

1.1 Title Card. This card should provide information regarding the type, location, and date of the project, as well as the name or initials of the program user.

#### Original Pavement

The following cards are for the identification and description of the original pavement structure.

2.1 Surface Type. This variable identifies the type of existing pavement surface, either CRCP or JCP. This variable is used as part of a check which keeps a bonded CRCP overlay from being placed on an existing JCP or a bonded JCP overlay from being placed on an existing CRCP. Note also

that the program cannot handle an existing overlay unless it is considered as part of an overlay design strategy. In other words, the variable must define the type of original concrete surface.

2.2 Concrete Shoulder. This variable acts as a switch on which PCC fatigue equation (see Chapter 4) to use to predict the fatigue life (number of 18-kip ESAL cycles to loss of pavement load-carrying capacity) of the existing pavement. An existing rigid pavement with a concrete shoulder is in a much better moisture environment than one without a concrete shoulder. The specification of an existing concrete shoulder, then, allows the program to account for its lower rate of deterioration by using the PCC fatigue equation developed for these conditions.

2.3 Number of Pavement Lanes. This variable identifies the number of existing pavement lanes (in one direction). It is used primarily for estimating the quantity and area of overlay. It is also used in estimating traffic delay costs during overlay construction.

2.4 Number of Pavement Layers. This variable identifies the number of separate pavement layers (including subgrade) in the original pavement structure. For each layer, thicknesses and elastic properties (elastic modulus and Poisson's ratio) will be required for estimating pavement responses. A maximum of five existing layers may be considered.

3.1 Project Length. This variable defines the length of the project. It is used mainly to compute overlay quantities. Depending on the trade-offs between long and short projects, the project length may range from a one-half-mile section selected from Dynaflect profiles (see Step 4 of Texas SDHPT RPOD procedure) up to a 10-mile section which will require an overlay

which is thicker overall (due to larger variations in the design data) but more consistent.

3.2 Lane Width. This variable defines the average width of the existing pavement lanes. It is also used to compute overlay quantities.

3.3 Total Shoulder Width. This variable is used primarily to compare the cost of flexible shoulder versus concrete shoulder construction at the time of overlay. Consequently, the total width refers to the width of shoulder (inside and out) which may be constructed with portland cement concrete in lieu of asphaltic concrete.

4.0 Pavement Thicknesses. This card may contain up to five values which represent the thicknesses of each pavement layer, including the subgrade. The thickness of the bottom layer is always assumed to be semi-infinite, and, therefore, it may be left blank. Note, too, that the bottom layer does not necessarily have to be subgrade; it can be some type of rigid base or bedrock below the subgrade. Bedrock should not normally be considered, however, since it has very little effect on the stresses and strains carried by the load-carrying layer.

The thicknesses of each layer should be determined from measurements of cores taken in the field. If this is not possible, initial construction specifications may be used.

5.0 Elastic Moduli. This card contains the elastic moduli of each of the layers which make up the pavement structure. Taut, McCullough, and Hudson (Ref 31) recommend a method of materials characterization which is a combination of lab testing and Dynaflect deflection basin fitting for estimating the elastic moduli of each layer. This was described briefly in

Step 5 of the Texas RPOD procedure earlier in this chapter, but the user should still refer to the reference for further detail.

These values are used to compute the remaining life of the existing pavement. Consequently, they should be representative of the pavement in an uncracked condition, (i.e., concrete modulus should be greater than 3,000,000 psi).

6.0 Poisson's Ratios. Like the elastic moduli, this value should be defined for each existing layer, including the subgrade. Since the variation of Poisson's ratio has little effect on the predicted responses, however, Table 6.1 may be used to select appropriate values according to material type.

7.1 Concrete Flexural Strength. This value should be representative of the existing pavement's flexural strength over the remaining years of its service life. Accordingly, it should be estimated from correlations with the concrete tensile strength determined from the indirect tensile test (Ref 9). Alternatively, it may be estimated from correlations with the concrete stiffness and aggregate type (Refs 37 and 38) or even from past records of the strength at construction.

The flexural strength entered is used in the PCC fatigue equations (Chapter 4) to estimate the additional number of 18-kip cycles that can be carried by the existing concrete pavement. This value should always be specified, but a value of 500 psi may be used if the existing pavement has less than 10 percent remaining life.

7.2 Critical Stress Factors. This value is also used in the PCC fatigue equations to estimate the additional life left in the existing pavement. It

TABLE 6.1 RECOMMENDED VALUES OF POISSON'S RATIO  
FOR DIFFERENT PAVEMENT MATERIALS

<u>Material Type</u>	<u>Range of Poisson's Ratio</u>
Portland cement concrete	.15 - .20
Asphaltic concrete	.25 - .35
Cement stabilized base	.20 - .30
Asphalt stabilized base	.25 - .35
Unbound granular base	.40
Granular subgrade	.40
Clayey or silty subgrades	.45

TABLE 6.2 EXISTING PAVEMENT CRITICAL STRESS FACTORS

<u>Existing Pavement Type</u>	<u>Existing PCC Shoulders</u>	<u>Range of Critical Stress Factor</u>
CRCP	No	1.20 - 1.25
	Yes	1.05 - 1.10
JCP (with load transfer)	No	1.25 - 1.30
	Yes	1.10 - 1.20
JCP (without load transfer)	No	1.50 - 1.60
	Yes	1.40 - 1.50

represents the ratio of the critical stress to the interior stress in the existing pavement (Chapter 4). This value should always be specified, even if the existing pavement has no remaining life. Table 6.2 provides ranges of this value for different types of existing pavement. The low level for each category should be used if the results of the condition survey indicate that the existing pavement has performed well. Likewise, a high level should be used if poor performance has been observed.

7.3 Concrete Stiffness After Cracking. This value represents the elastic modulus of the existing PCC after it loses its load-carrying capacity. A value of 800,000 psi is recommended if the existing pavement is CRCP. A range of 300,000 to 500,000 psi is recommended for jointed pavements. The high level should be used normally, unless there is excessive pumping or a high joint to interior deflection ratio (greater than 1.5). It may also be necessary to use a lower value if severely distressed areas will not be repaired prior to overlay. This variable should not be left blank.

8.1 Number of Defects. This value is the number of defects (per mile) which are present in the existing pavement. This number is used to estimate the cost of repairs which are to be performed on the existing pavement prior to overlay. This number is not required if these repairs will not be performed or if they are not to be considered.

8.2 Repair Cost. This value should be the total cost for repairing a defect in the existing pavement. It is not required if repairs will not be made prior to overlay.

8.3 Rate of Defect Development. This value represents the rate of development of defects over the remainder of the service life of the existing

pavement. It is used to compute the cost of repairs that will be performed to the existing pavement prior to some future overlay. A value recommended for CRC existing pavements is 2 per year per mile. Due to a lack of data, no recommendation is made for jointed pavements (see Chapter 5). This value is not required if no repairs are to be made prior to overlay.

#### Traffic Variables

The data on the following card relate to the traffic, both vehicle and truck, that is to be carried by the facility over the analysis period.

9.1 Average Daily Traffic. This value (ADT) should be the present average number of vehicles per day carried by the facility. It is used to predict the user delay cost associated with construction of some future overlay (see Chapter 5).

9.2 ADT Growth Rates. This value represents the yearly rate of growth of ADT. Note that a linear type growth is assumed, which is commensurate with Texas SDHPT practice.

9.3 Initial Yearly 18-kip ESAL. This value is the number of yearly 18-kip equivalent single axle loads (18-kip ESAL) presently being carried by the facility in both directions. This quantity is used to predict the life (in years) of a given rehabilitation strategy and is, therefore, always required.

9.4 18-kip ESAL Growth Rate. Like the ADT growth rate, this value is used to estimate traffic growth over the analysis period. In this case, however, it is used to project the growth of 18-kip ESAL, which may be

different from the growth of ADT. Note, too, that if this value is left blank, zero growth is assumed.

9.5 Directional Distribution Factor. Certain highways, such as those near a seaport, have shown a marked difference in distribution of traffic in one direction from the other. Even though the vehicle distribution may be split evenly, there may be heavier trucks and, therefore, greater 18-kip equivalencies moving in one direction. The directional distribution factor, expressed as a percent of the total 18-kip ESAL traffic in both directions, is used to account for this possibility. Note that if this value is not 50 percent, then the optimum designs generated by RPRDS are only for the direction being considered.

9.6 Lane Distribution Factor. This factor accounts for the distribution of truck traffic across the facility (in one direction). Since most of the heavy traffic is carried by the inside lane, it is generally the "design" lane. The lane distribution factor then defines what percent of the 18-kip ESAL traffic is carried by the design lane. This factor usually has a value of 90 to 95 percent for four-lane facilities and may be as low as 70 percent for eight-lane facilities.

#### Time Constraints

10.1 Analysis Period. This constraint defines how many years (from the present) the user desires the facility to last (See Chapter 4). This value is generally 20 years.

10.2 Minimum Time Between Overlays. This constraint specifies the minimum number of years that can be allowed between two overlays. This value

should not be greater than the analysis period. Also, if a second overlay will not be considered, this value is not required.

10.3 Maximum Number of Years of Heavy Maintenance. According to the relationship between the fatigue life and the rate of distress occurrence developed by Taute (Ref 31) and discussed in Chapter 4, it may be feasible to consider strategies which may require a period of heavy maintenance to last the analysis period. Accordingly, this value defines the maximum number of years of heavy maintenance (maximum of 10 years) the user may wish to consider to allow a strategy to last the analysis period. Note that for each additional year, distress increases rapidly, and therefore maintenance costs will increase correspondingly. It should also be noted that the user must provide data on these distress rates (in the Distress/Maintenance Cost Variables Section) for each additional year considered. Since, at this time, very little reliable data exist, the user may not consider this option until more data become available.

#### Remaining Life Variables

The remaining life data on these two cards are used to define specific times at which an overlay may be placed. Recall that remaining life corresponds to some level of damage in the surface (load-carrying) layer, and, consequently, remaining life is related to accumulated 18-kip ESAL traffic and a corresponding future year (see Chapter 4).

11.1 Number of Original Pavement Remaining Life Values. This number defines how many different values of remaining life of the original pavement at which the first overlay may be placed. This number should be at least one

(otherwise an overlay will never be placed). This maximum limit on this number is 10.

11.2 Minimum Existing Pavement Remaining Life. Since it is not practical to bond a PCC overlay to an existing PCC pavement which has a very low level of remaining life (due to problems with reflection cracking), this constraint is provided. For user-specified values of remaining life below this value, bonded PCC overlays will not be considered. It does not affect ACP or unbonded PCC overlays. A practical range for this value is between 10 and 20 percent.

11.3 Original Pavement Remaining Life Values. These values of remaining life of the existing pavement identify points during the life of the original pavement at which the first overlay may be placed. Variable 11.1 defined how many of these values will be entered. They must be entered in order of decreasing magnitude and the first is assumed to correspond to year zero of the analysis period (Taute, Ref 31, provides some information on the relationship between remaining life and the level of distress observed in the existing pavement). It is suggested that these values be entered in increments of no less than 10 percent, with the last value equal to zero.

12.1 Number of First Overlay Remaining Life Values. This number is similar to that used in variable 11.1. It defines how many different values of remaining life in the first overlay at which the second overlay may be placed. The maximum limit is 10. This value should be zero if two-overlay strategies are not desired.

12.2 First Overlay Remaining Life Values. These values of remaining life of the first overlay identify points during the life of the pavement

structure at which a second overlay may be placed. Variable 12.1 defines how many of these values will be entered. As in 11.3, they must be entered in order of decreasing magnitude. It is suggested that, for practical design problems where a second overlay is to be considered, the list of these values should begin with 70 percent and decrease in 10 percent increments. This card may be left blank if no two-overlay strategies are to be considered.

#### Overlay Characteristics

The information required for the following cards and variables is used to identify what types of overlay strategies are to be considered and to define the pertinent properties for each alternative (see Chapter 4).

13.0 Types of First Overlay. This card identifies the types of first overlay that are to be considered. Five different types are available: (1) ACP, (2) bonded CRCP, (3) unbonded CRCP, (4) bonded JCP, and (5) unbonded JCP. It should be pointed out that any or all may be considered in a single run.

In cases where the user is interested in comparing various type overlays where there is some uncertainty about the relative costs between the two, it is recommended that separate RPRDS-1 runs be made for the different overlay types. This will allow the user to compare optimum overlay strategies of the various types considered, keeping in mind their cost uncertainty.

14.0 Types of Second Overlay. This card identifies the types of second overlay that are to be considered. There are three different types available: (1) ACP, (2) CRCP, and (3) JCP. Note that for strategies where the second overlay is CRCP or JCP, the first overlay will always be ACP since

RPRDS-1 can only consider one PCC overlay during the analysis period. Also, this card may be left blank if no two-overlay strategies are to be considered.

15.1 Number of ACP First Overlay Thicknesses. This value defines how many different ACP first overlay thicknesses are due to be considered. A maximum of eight is allowed.

15.2 Number of ACP Second Overlay Thicknesses. RPRDS-1 allows the user to select a different set of thicknesses to use for the second ACP overlay. (This is useful, since the user may be constrained to one thickness for the first overlay). This value defines how many second ACP overlay thicknesses are to be considered. A maximum of eight is allowed.

15.3 Number of PCC Overlay Thicknesses. This value defines how many PCC thicknesses are to be considered. The thicknesses apply to both CRCP and JCP overlays, whether they make up the first overlay or the second overlay. A maximum of eight is allowed.

16.0 ACP First Overlay Thicknesses. This card identifies what ACP thicknesses (in inches) to use for the first overlay. The number of these different thicknesses is set in variable 15.1. These thicknesses should be entered in order of increasing magnitude. The first should be no less than 2 inches (a minimum for structural rehabilitation) and the largest thickness should be no greater than 8 inches. This card may be left blank if an ACP first overlay is not to be considered.

17.0 ACP Second Overlay Thicknesses. This card identifies what ACP thicknesses (in inches) to use for the second overlay. The number of these

different thicknesses is set in variable 15.2. Once again, these thicknesses should be entered in order of increasing magnitude with the first no less than 2 inches and the last no greater than 8 inches. This card may be left blank if an ACP second overlay is not to be considered.

18.0 PCC Overlay Thicknesses. This card identifies what CRCP and/or JCP thicknesses (in inches) to use for either the first or second PCC overlay. The number of these different thicknesses is set in variable 15.3. These thicknesses should be entered in order of increasing magnitude, with the first no less than 5 inches (a minimum practical construction thickness). The maximum practical thickness is left up to the designer.

19.1 Allowable Total Overlay Thickness. This variable acts as a constraint on those two-overlay strategies in which the combined thickness of both overlays may be too large for bridge clearance (or some other similar factor). Consequently, those strategies in which the combined thickness is greater than this allowable will not be considered. This value should not be left blank if two-overlay strategies are to be considered.

19.2 Average Level-up Thickness. This value is used to compute the cost of the additional overlay thickness required for level-up. It has no effect on the fatigue life calculations or the constraint on total overlay thickness. Also, it is assumed that this value applies to both first and second overlays, regardless of type.

19.3 Bond Breaker Thickness. This variable is used in the fatigue life calculations for unbonded PCC overlays. A value of one inch is recommended. This value should not be left blank if an unbonded PCC overlay strategy is to be considered.

20.1 ACP Overlay Design Stiffness. This variable defines the ACP elastic modulus to use for pavement response calculations. Various methods are available for predicting what this value should be for given environmental conditions. Kasianchuk's traffic-weighted mean stiffness method (Ref 25) is recommended. The range on this value should be between 300,000 and 500,000 psi. A value of 400,000 psi is recommended for Texas conditions if no other data are available.

20.2 Poisson's Ratio, ACP Overlay. This variable is also used to predict pavement response. Its variation has very little effect on the predicted responses; however, it cannot be ignored. A value of 0.30 is recommended (see Table 6.2).

20.3 PCC Overlay Design Stiffness. This variable defines the elastic modulus of the portland cement concrete for both CRCP and JCP overlays. The variation of this value has a significant effect on the prediction of pavement response, and, therefore, it should be estimated with a good degree of accuracy. The factor which most affects this value is the type of aggregate used in the mix. If a crushed stone aggregate is used, this value is generally in the range of 4,000,000 to 5,000,000 psi. If a siliceous river gravel is used, this value will probably be in the range of 5,000,000 to 7,000,000 psi (Refs 37 and 38). The ACI equation (Ref 39),

$$E_c = 57000 \sqrt{f'_c}$$

where

$E_c$  = concrete elastic modulus, psi, and

$f'c$  = concrete compressive strength, psi,

may also be used to estimate the stiffness (elastic modulus) of the concrete if concrete compressive strengths are available.

20.4 Poisson's Ratio, PCC Overlay. This value is also used to predict pavement response. Like the Poisson's ratio for the ACP overlay, its variation has little effect on pavement response. Therefore, a value of 0.15 is recommended.

20.5 Bond Breaker Stiffness. A bond breaker is used for unbonded PCC overlays to help prevent reflection cracking. Consequently, a low stiffness asphaltic concrete layer is recommended for design (a value of 100,000 psi or lower).

20.6 Poisson's Ratio, Bond Breaker. Since this layer consists of a low stiffness asphaltic concrete, a value of 0.35 is recommended. Once again, its variation has little effect on the predicted pavement responses.

21.1 Number of Overlay Flexural Strengths. RPRDS-1 allows the designer to consider up to five different concrete flexural strengths in the various PCC overlay design strategies. An increased flexural strength may make a significant difference in the predicted life of a strategy, and, therefore, it may be worthy of consideration. It should be realized, however, that the concrete fatigue equations are based on a mean value measured at the AASHO Road Test, 690 psi, which limits the range of inference to between 600 and 800 psi. Also, since an increased cement content is necessary to achieve a

higher flexural strength, the designer must later input the cost associated with these different concrete strengths.

21.2 Number of Flexural Strength for Bonded PCC Overlays. Since the flexural strength of bonded PCC overlays has no effect on the fatigue life of those strategies, only one strength need be considered. Consequently, this number identifies which flexural strength in the list (of those to be considered in card 22.0) is to be used for a bonded PCC overlay. For example, if three flexural strengths are to be considered and the strength which would normally be used for a bonded PCC overlay is the second in the list, the user should enter a 2 for this variable.

22.0 PCC Overlay Flexural Strengths. These values should be entered in increasing order (in psi). As discussed under variable 21.1, the limits of flexural strength that may be considered is 600 to 800 psi. This card may be left blank if no PCC overlays are to be considered.

#### Pavement Stress Factors After Overlay

This section of overlay characteristics deals with the selection of stress factors (ratios of critical stress to interior slab stress) for all possible overlay combinations selected by the user. Though there may be several of these combinations, the selection of the appropriate stress factors for each is simple. Basically, all the user must do is refer to Table 6.3, which identifies the inputs required for cards 23 through 40. Each card represents a particular overlay combination where the critical stress to be computed is located in either the existing pavement or the PCC overlay. Most of these cards also allow the specification of a second stress

TABLE 6.3 CRITICAL STRESS FACTORS FOR THE VARIOUS EXISTING PAVEMENT-OVERLAY-SHOULDER COMBINATIONS CONSIDERED IN RPRDS-1.

Card/ Variable No.	First Overlay Type	Second Overlay Type	Location of Critical Stress	Overlay Shoulder Type	Ratio of Critical to Interior Stress	
					CRCP Existing Pavement	JCP Existing Pavement
23.1	ACP	none	Exist. Pavt.	ACP	1.20 - 1.30	1.40 - 1.50
24.1	ACP	CAP	Exist. Pavt.	ACP		
25.1	ACP	CRCP	Exist. Pavt.	ACP		
25.2	ACP	CRCP	Exist. Pavt.	CRCP		
26.1	ACP	CRCP	CRCP Overlay	ACP		
26.2	ACP	CRCP	CRCP Overlay	CRCP		
27.1	ACP	JCP	Exist. Pavt.	ACP		
27.2	ACP	JCF	Exist. Pavt.	JCP		
28.1	ACP	JCP	JCP Overlay	ACP		
28.2	ACP	JCP	JCP Overlay	JCP		
29.1	Bonded CRCP	none	Exist. Pavt.	ACP		
29.2	Bonded CRCP	none	Exist. Pavt.	CRCP		
30.1	Bonded CRCP	ACP	Exist. Pavt.	ACP		
30.2	Bonded CRCP	ACP	Exist. Pavt.	CRCP		
31.1	Bonded JCP	none	Exist. Pavt.	ACP		
31.2	Bonded JCP	none	Exist. Pavt.	JCP		
32.1	Bonded JCP	ACP	Exist. Pavt.	ACP		
32.2	Bonded JCP	ACP	Exist. Pavt.	JCP		
33.1	Unbonded CRCP	none	Exist. Pavt.	ACP		
33.2	Unbonded CRCP	none	Exist. Pavt.	CRCP		
34.1	Unbonded CRCP	none	CRCP Overlay	ACP		
34.2	Unbonded CRCP	none	CRCP Overlay	CRCP		
35.1	Unbonded CRCP	ACP	Exist. Pavt.	ACP		
35.2	Unbonded CRCP	ACP	Exist. Pavt.	CRCP		
36.1	Unbonded CRCP	ACP	CRCP Overlay	ACP		
36.2	Unbonded CRCP	ACP	CRCP Overlay	CRCP		
37.1	Unbonded JCP	none	Exist. Pavt.	ACP		
37.2	Unbonded JCP	none	Exist. Pavt.	JCP		

(continued)

TABLE 6.3 (Continued).

Card/ Variable No.	First Overlay Type	Second Overlay Type	Location of Critical Stress	Overlay Shoulder Type	Ratio of Critical to Interior Stress	
					CRCP Existing Pavement	JCP Existing Pavement
38.1	Unbonded JCP	none	JCP Overlay			
38.2	Unbonded JCP	none	JCP Overlay			
39.1	Unbonded JCP	ACP	Exist. Pavt.			
39.2	Unbonded JCP	ACP	Exist. Pavt.			
40.1	Unbonded JCP	ACP	JCP Overlay			
40.2	Unbonded JCP	ACP	JCP Overlay			

factor (for the same overlay combination) to simulate the effect of a PCC shoulder constructed along with the PCC overlay.

The user should use Table 6.3 to select the stress ratio required from the column corresponding to the type of existing pavement. Any stress factor left blank or specified to be zero will keep RPRDS-1 from considering the corresponding overlay strategy. This is an important point because an error of this type will probably go unnoticed since these strategies will appear to be infeasible in the RPRDS-1 program output. It is recommended, then, that the user pay close attention to selecting and recording these variables.

For a detailed description of how these stress factors were developed, see Chapter 4.

41.1 Method of Response Prediction. This variable defines the method in which the pavement responses are to be determined either by the elastic layer submodel, LAYER, or the elastic layer regression submodel, REGRSP. Use of the REGRSP submodel allows the user to familiarize himself with the operation of the program and the particular overlay design problem using a minimum of computer time. However, the LAYER submodel should be used if the program is to be used for the selection of an optimal rehabilitation design strategy. See Chapter 3 for a detailed description of the LAYER and REGRSP submodels.

#### Overlay Construction Cost Variables

This begins the description of the inputs associated with the cost of an overlay strategy. None of the remaining inputs that will be discussed has any effect on the performance (i.e., fatigue life) prediction of an overlay strategy.

The next seven cards (numbers 42.0 through 49.0) define the variables associated with overlay construction cost.

42.0 Site Establishment Cost. This card identifies the cost associated with establishing the overlay site. This cost is considered because the cost of mobilizing manpower and equipment may differ according to overlay type. Consequently, there are five different costs that may be specified. Variables 42.1, 42.2, and 42.3 represent the costs for ACP, CRCP, and JCP equipment, respectively. In cases where both PCC and ACP construction equipment are required for a particular strategy, such as a CRCP overlay with an ACP bond breaker and ACP shoulder, variables 42.4 and 42.5 are provided. They may be used to reflect a lower equipment unit cost when the two types are required. It should be noted that each represents a total cost for the entire project, regardless of length.

43.0 Pavement Surface Preparation Cost. This cost should represent the cost of preparing the pavement surface (i.e., cleaning and milling) prior to overlay placement. Variable 43.1 applies to the existing pavement while variables 43.2, 43.3, and 43.4 apply to the first overlay prior to the second and may be neglected if no two-overlay strategies are to be considered. Note that the units on this cost are dollars per square yard of surface area.

44.1 Fixed Cost of ACP Overlay Construction. This input defines the fixed component of the ACP overlay placement cost. It is used along with the variable cost to predict the total placement cost. This method allows some flexibility to account for the sensitivity of placement cost to overlay thickness. The units of fixed cost are dollars per square yard while the units for variable cost are dollars per square yard per inch of thickness.

An example is to specify a fixed cost of 6.00 dollars per square yard and a variable cost of 0.50 dollar per square yard per inch, so that the cost of a 6-inch ACP overlay would be  $6.00 + (6 \times 0.50)$  or 9.00 dollars per square yard.

44.2 Variable Cost of ACP Overlay Construction. This variable, along with the fixed component (variable 44.1) is used to compute the total cost of ACP overlay placement. The units of variable cost are dollars per square yard per inch.

44.3 Fixed Cost of Flexible Shoulder Construction. This input defines the fixed component of flexible shoulder placement cost. The units are dollars per square yard and it is similar in application to variable 44.1.

44.4 Variable Cost of Flexible Shoulder Construction. This input defines the variable component of flexible shoulder construction. Its units are dollars per square yard per inch. See the description of variables 44.1 and 44.2 for further discussion on fixed and variable costs.

44.5 Cost of Bond Breaker Construction. Unlike ACP overlay and flexible shoulder placement cost, the cost for bond breaker placement has only one component since only one thickness (variable 19.3) is ever considered. Consequently, the units of this variable are dollars per square yard.

45.0 CRCP Fixed Costs. These inputs define the fixed component of CRCP overlay placement cost. They are similar in nature to variable 44.1, with one exception. The user must specify a fixed cost for each PCC flexural strength specified in card 22.0. Once again, the units are dollars per

square yard. This card should be left blank if no CRCP overlays are to be considered.

46.0 CRCP Variable Costs. These inputs define the variable component of CRCP overlay placement cost. They correspond to the fixed cost specified for each PCC flexural strength to be used for CRCP overlay construction. The units are dollars per square yard per inch. This card should be left blank if no CRCP overlays are to be considered.

47.0 JCP Fixed Costs. These inputs define the fixed component of JCP overlay placement cost. They are similar in nature to variable 44.1. The difference is that the user must specify a fixed cost for each PCC flexural strength specified in card 22.0. The units are dollars per square yard. This card should be left blank if no JCP overlays are to be considered.

48.0 JCP Variable Costs. These inputs define the variable component of JCP overlay placement cost. They correspond to the fixed cost specified for each PCC flexural strength to be used for JCP overlay construction. The units are dollars per square yard per inch. This card should be left blank if no JCP overlays are to be considered.

49.1 Total CRCP Overlay Steel Percentage. This variable defines the total percentage of steel, both longitudinal and transverse required in a CRCP overlay. Generally, this value ranges between 0.5 and 0.7 percent for CRCP overlays but may be left blank if no CRCP overlays are to be considered.

49.2 Total JCP Overlay Steel Percentage. This variable defines the total steel percentage, both longitudinal and transverse, required in a JCP overlay. Generally, this value ranges between zero and 0.4 percent for JCP

overlays. (The higher end represents a jointed reinforced concrete pavement, JRCP.) This variable may be left blank if no JCP overlays are to be considered.

49.3 Cost of Steel Reinforcement. This variable defines the cost per unit weight of steel used in a reinforced concrete overlay. The user need not consider the cost of placement if it was considered in the fixed cost of placement. The units of this variable are dollars per pound. Also, it may be left blank if no PCC overlays are to be considered.

#### Traffic Delay Cost Variables

This section describes the variables associated with user costs arising from traffic delay during overlay construction. The traffic delay cost model is discussed in Chapter 5. Basically, the model attempts to predict the length of delay as well as the number of vehicles that are delayed due to overlay construction. Then, built-in unit costs are used to estimate the total delay cost. To predict this total cost, the user must provide information on the size and length of the overlay project, its location, how traffic is to be handled, estimates of present traffic volumes, average vehicle speeds, and overlay construction rates. Each of the variables which make these up are described next.

50.1 Location of Project. The model uses "built-in" average daily distributions of traffic to predict the amounts of traffic which will be delayed during the periods when traffic is detoured or constricted. Since these average daily distributions are different in rural areas than in urban, the user must specify which of the two best applies to his conditions.

50.2 Model Number for Handling traffic. Since the delay duration and the number of vehicles delayed are dependent upon the method in which traffic is detoured, it is necessary for the user to specify which method will be used. The choices available are shown in Fig 6.3.

50.3 Number of Open Lanes, Overlay Direction. This variable specifies how many lanes are open to traffic in the overlay direction. This includes detour lanes, the lane provided by the shoulder (if it is used to carry traffic), and a lane which may be shared with traffic in the non-overlay direction. This variable should never be zero.

50.4 Number of Open Lanes, Non-Overlay Direction. This variable specifies how many lanes are open to traffic in the non-overlay direction. Unless it is necessary to close a lane in this direction due to encroachment of overlay construction equipment and personnel, this variable should be equal to variable 2.3.

51.1 Time of Day Overlay Construction Begins. This variable, along with the next, is used to define the period during the day during which traffic will be delayed. In the case of PCC overlays, where traffic may be detoured for two weeks or more, this period should cover the entire day. For ACP overlays, however, these variables may correspond to the beginning and ending of construction since the overlay lanes may be opened to traffic immediately after the hour that construction ends. Note that the hours are specified using military time where 4:00 a.m. is 0400 hours, 4:00 p.m. is 1600 hours, etc.

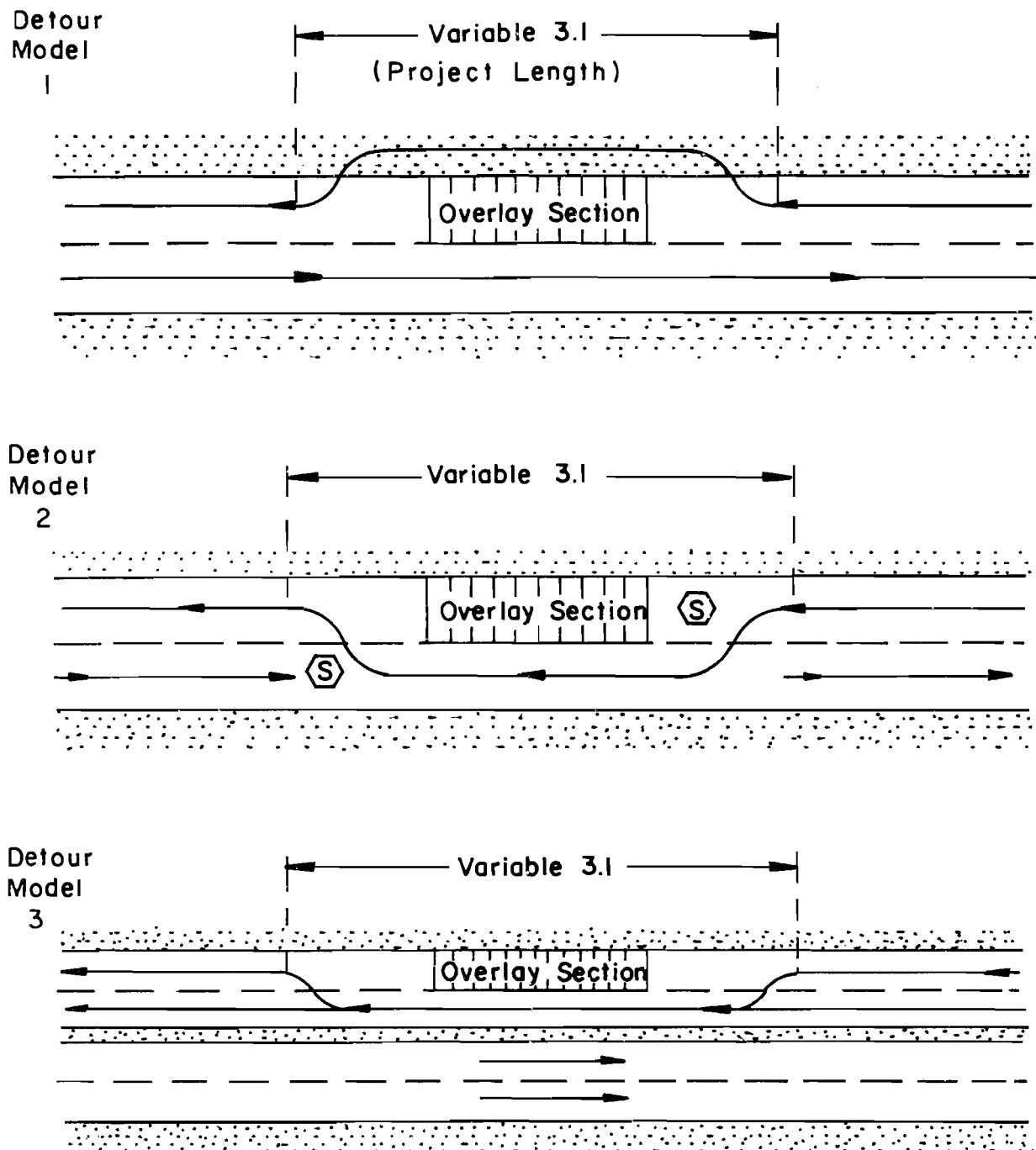


Fig 6.3. Illustration of the detour models available in RPRDS-1 for use in estimating traffic delay cost.

(Continued)

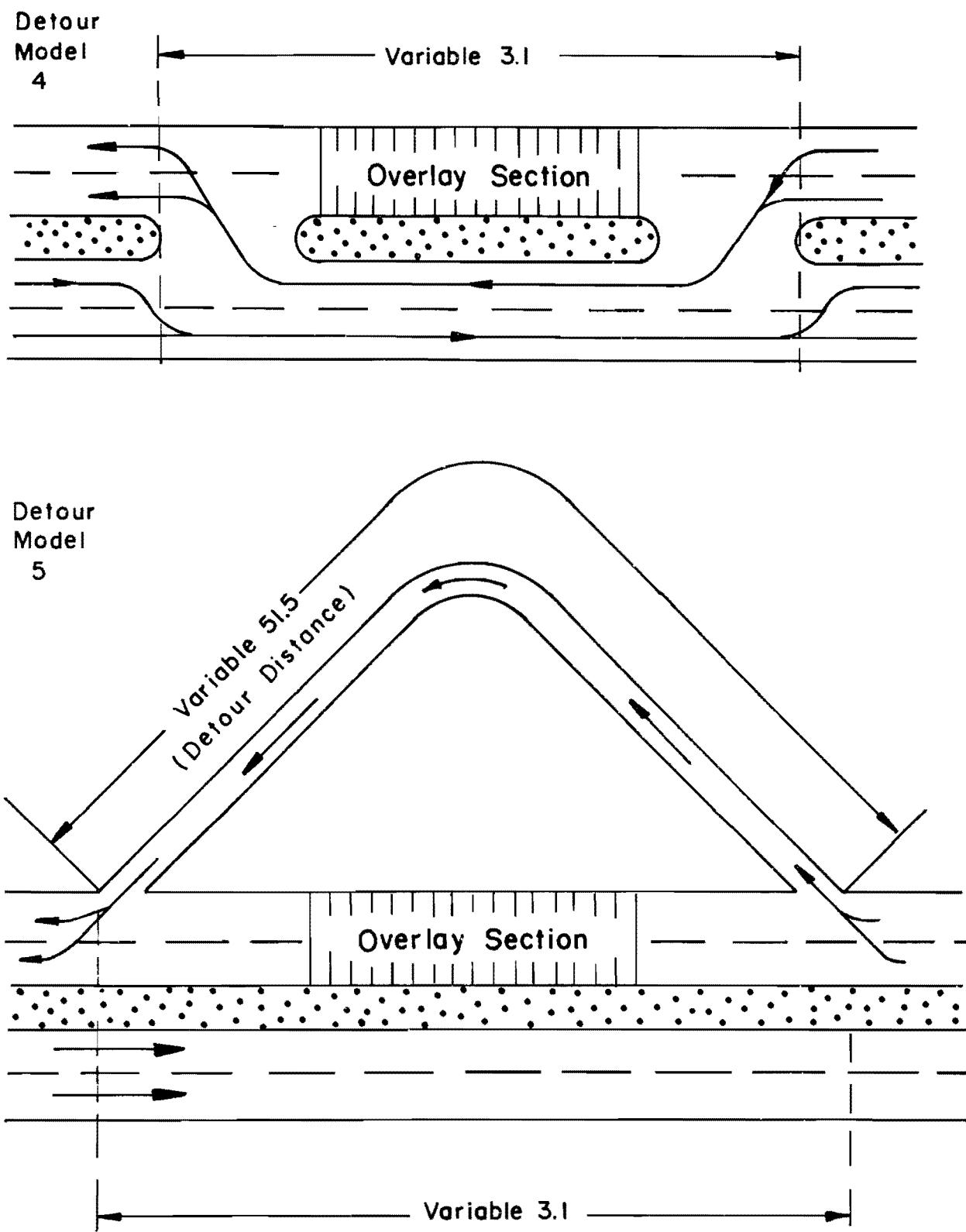


Fig 6.3.. (Continued).

51.2 Time of Day Overlay Construction Ends. This variable and the preceding one are used to specify a total daily traffic delay period. Its units are also in military time (see variable 51.1).

51.3 Hours Per Day Overlay Construction Occurs. This variable is used to determine how many days it will take to complete overlay construction. This variable is not necessarily the difference (in standard hours) between variables 51.2 and 51.1, since they define the period during the day during which traffic will be delayed. The value of this variable must be greater than zero.

51.4 Number of Days Concrete Is Allowed to Cure. This variable is used to account for the additional period of traffic delay after PCC overlay construction for concrete curing.

51.5 Detour Distance. This variable defines a length over which traffic will be detoured. It applies to model 5 only (see Fig 6.3).

52.1 Average Approach Speed. This variable, along with the others on card 52, is used to calculate how much time each vehicle will be delayed due to the reduction of speed through the overlay zone. This variable is basically the average speed of traffic under unrestricted conditions.

52.2 Average Speed, Overlay Direction. This variable defines the average speed of vehicles traveling through the restricted zone in the overlay direction. It is used with variable 52.1 to calculate the vehicle delay due to reduced speed.

52.3 Average Speed, Non-Overlay Direction. This variable defines the average speed of vehicles traveling through the restricted zone in the

non-overlay direction. It is used with variable 52.1 to calculate the vehicle delay due to reduced speed and may be equal to variable 52.1 if traffic in the non-overlay direction is not disturbed.

53.1 Distance Traffic Is Slowed, Overlay Direction. This variable accounts for the length over which traffic is slowed in the overlay direction during overlay construction. Its value is not necessarily the length of the project since the restricted zone may be much shorter.

53.2 Distance Traffic Is Slowed, Non-Overlay Direction. This variable is similar to variable 53.1 except that it is for traffic in the non-overlay direction. In many cases where traffic is not disturbed in the non-overlay direction, this variable will have a value of zero.

53.3 Percent of Vehicles Stopped, Overlay Direction. In some cases where traffic is heavy or forced to share a traffic lane (such as in detour model 2, Fig 6.3), the closing of a single lane for overlay construction may force many vehicles to slow down and stop. This variable attempts to account for the percentage of these vehicles which are stopped, due to either traffic or overlay construction equipment and personnel.

53.4 Percent of Vehicles Stopped, Non-Overlay Direction. This variable is the same as variable 53.3 except that it is for the non-overlay direction. Depending on the detour model, the value may vary from zero to the value for the overlay direction.

53.5 Average Vehicle Delay, Overlay Direction. This variable defines the average amount of delay incurred by stopped vehicles (during the stopped period only). This variable, along with variable 53.3, defines the total

amount of vehicle stop time during overlay construction in the overlay direction. This value is then added to the time lost due to slowing down, to get the total vehicle delay time in the overlay direction.

53.6 Average Vehicle Delay, Non-Overlay Direction. This variable is the same as variable 53.5 except that it is for the non-overlay direction. This value may be zero if no delay occurs in the non-overlay direction.

54.1 Asphaltic Concrete Production Rate. This variable along with the overlay thickness and length of construction day is used to compute the total number of days required to complete overlay construction. It is assumed, then, that this calculated number of days is the period over which the traffic delays will occur. Note that the units of this variable are in cubic yards per hour so that a thick overlay will require more construction time than a thin overlay.

54.2 CRCP Production Rate. This variable is the same as variable 54.1 except that it is for a CRCP overlay. Note that the placement of steel reinforcement may have an effect on this value.

54.3 JCP Production Rate. This variable is the same as variable 54.1 and 54.2 except that it is for a JCP overlay. Also, some consideration should be given here to the time required for joint preparation as well as for the placement of steel reinforcement.

54.4 Bond Breaker Production Rate. This variable is similar to the production rates discussed previously. In fact, the value for this variable may be the same as that for an ACP overlay (variable 54.1). The difference

is that this variable will be used to estimate construction time required for a bond breaker used in an unbonded PCC overlay strategy.

#### Distress/Maintenance Cost Variables

This set of data is used to compute the maintenance cost of each feasible strategy. Basically, the data required on the next four cards (55 through 58) consist of the cost to repair a defect and the yearly rates of defect or distress development for different periods during the life of the strategy. These values are entered for four possible overlay combinations, (1) CRCP, (2) JCP, (3) ACP on CRCP, and (4) ACP on JCP, which correspond to the four cards required.

For use in this application, the life of a pavement overlay strategy is divided into several periods as a result of work done by Taute (Ref 31). The first is the zero distress rate period (between zero and 20 percent of the overlay life) where very few (if any) severe distress manifestations will occur. The second period (between 20 and 60 percent of the overlay life) is the initial distress rate period, where distress develops at a slow but significant rate. The third period (between 60 and 100 percent of the overlay life) represents a secondary rate of distress development, which will occur up to the end of the overlay fatigue life. From this point out to the maximum allowable number of years of heavy maintenance (variable 10.3), the periods consist of one year intervals, where distress development should increase geometrically. The user, then, must define values for the initial distress rate, the secondary distress rate and the distress rate, for each year up to the maximum allowable number of years of heavy maintenance.

Further detailed discussion of this is provided in Chapter 5, but some recommended values for CRCP overlays and ACP/CRCP overlays are provided below. Unfortunately, no recommendations are made for JCP overlays, due to the lack of field data. Also, it should be pointed out that all of these data (in cards 55 through 58) may be left blank if the user does not wish to consider maintenance cost.

55.1 CRCP Overlay Distress Repair Cost. This variable should represent the cost of repairing a severe distress manifestation such as a punchout in a CRCP overlay. This cost should reflect the manpower, material, and equipment required to repair a single severe defect.

55.2 Initial CRCP Overlay Distress Rate. This variable defines the initial CRCP distress rate that is exhibited during the period between 20 and 60 percent of the overlay life. Results of statewide condition surveys in Texas (Ref 31) indicate that this value is about one per mile per year.

55.3 Secondary CRCP Overlay Distress Rate. This variable defines the secondary CRCP distress rate that is exhibited during the period between 60 and 100 percent of the overlay fatigue life. Results of statewide condition surveys in Texas indicate that this value is about two per mile per year.

55.4 CRCP Overlay Distress Rate for Each Year After Loss of Pavement Load-Carrying Capacity. This actually consists of a set of CRCP distress rates, one for each year up to the maximum allowable number of years of heavy maintenance (variable 10.3). Once again, results of the statewide Texas condition survey indicate the following progression for each year after the loss of pavement load-carrying capacity: first year - 3 per mile, second - 5 per mile, third - 8 per mile, fourth - 16 per mile, and fifth year - 40 per

mile. (It is recommended that heavy maintenance of CRCP not be considered for more than five years.)

56.1 JCP Overlay Distress Repair Cost. This variable should represent the cost of repairing a distress manifestation, such as a defective joint or badly cracked slab in a JCP overlay. This cost should reflect the manpower, material, and equipment required to repair a single severe defect.

56.2 Initial JCP Overlay Distress Rate. This variable defines the initial JCP distress rate that is exhibited during the period between 20 and 60 percent of the overlay fatigue life. Due to a lack of field data and the fact that the definition of a JCP severe distress manifestation is highly subjective, no recommendation is made for this value. It is hoped that future research will provide better information on which to base a recommendation.

56.3 Secondary JCP Overlay Distress Rate. This variable defines the secondary JCP distress rate that is exhibited during the period between 60 and 100 percent of the overlay fatigue life. For the same reasons given in variable 56.2, no recommendation is made for this value.

56.4 JCP Overlay Distress Rate for Each Year After Loss of Pavement Load-Carrying Capacity. This actually consists of a set of JCP distress rates, one for each year up to the maximum allowable number of years of heavy maintenance (variable 10.3). For the same reasons given in variable 56.2, no recommendation is made for these values.

57.1 Distress Repair Cost, ACP Overlay on CRCP. This variable should represent the cost of repairing a distress manifestation in an ACP overlay

over a CRCP. Once again, this cost should reflect the manpower, material, and equipment required to repair a single defect. Examples of such defects include punchouts and potholes. The cost of ACP repairs, however, should be relatively low compared to PCC pavement repairs.

57.2 Initial ACP/CRCP Overlay Distress Rate. This variable defines the initial distress rate for an ACP overlay (on a CRCP) for the period between 20 and 60 percent of the overlay fatigue life. The results of an experimental CRCP with an ACP overlay on IH-45 in Walker County, Texas (Ref 31), have shown good ACP overlay performance with little distress. On the other hand, other ACP overlay projects in Texas have shown poor performance. Due to the fact that there is a large variation in field data, no recommendation is made here for this value. It should, however, be at least as high as the recommended initial CRCP distress rate (one per mile per year).

57.3 Secondary ACP/CRCP Overlay Distress Rate. This variable defines the secondary distress rate for an ACP overlay (on a CRCP) for the period between 60 and 100 percent of the overlay fatigue life. As discussed in variable 57.2, there is a lot of variation in the results of field observations of this overlay combination and, therefore, no recommendation is made here. The value of this variable, however, should be at least as high as the recommended secondary CRCP distress rate (two per mile per year).

57.4 ACP/CRCP Overlay Distress Rate for Each Year After Loss of Pavement Load-Carrying Capacity. This consists of a set of ACP/CRCP distress rates, one for each year up to the maximum allowable number of years of heavy maintenance (variable 10.3). For the same reasons discussed in variables

57.1 and 57.2, no recommendation is made for these values. They should, however, be at least as high as those distress rates for a CRCP (variable 55.4).

58.1 Distress Repair Cost, ACP Overlay on JCP. This variable should represent the cost of repairing a distress manifestation in an ACP overlay over a JCP. The cost should reflect the manpower, material, and equipment required to repair a single defect. An example of such a defect would be a pothole. Also, the cost of such a repair should be relatively low compared to PCC pavement repairs.

58.2 Initial ACP/JCP Overlay Distress Rate. This variable defines the initial distress rate for an ACP overlay (on a JCP) for the period between 20 and 60 percent of the overlay fatigue life. Due to the lack of information on ACP overlay performance on JCP, no recommendation is made for this value. This value should, however, be as least as high as that used for the initial JCP distress rate (variable 56.2).

58.3 Secondary ACP/JCP Overlay Distress Rate. This variable defines the secondary distress rate for an ACP overlay (on a JCP) for the period between 60 and 100 percent of the overlay fatigue life. Once again, this value should be at least as high as that used for the secondary JCP overlay distress rate (variable 56.3).

58.4 ACP/JCP Overlay Distress Rate for Each Year After Loss of Pavement Load-Carrying Capacity. This consists of a set of ACP/JCP distress rates, one for each year up to the maximum allowable number of years of heavy maintenance (variable 10.3). As before, no recommendation is made here, but

the values should be at least as high as those used for a JCP overlay (variable 56.4).

#### Cost Returns

There are two input variables that fall under the heading of cost returns. They are both included on card 59 and they are both used to estimate the return (a negative cost) from an overlay design strategy at the end of the analysis period (see Chapter 5).

59.1 Salvage Value. This variable refers to the value (expressed as a percent of the construction cost) an overlay structure has after it has reached the end of its life. Salvage value may refer to the value the pavement has as a base layer for some future overlay, or it may refer to the value the concrete and steel have for other uses. Note, however, that it refers to the value of the overlay only, and that the computed value for the future year is brought back to net present value.

59.2 Value of Each Year of Extended Life. Due to the nature of the method for generating overlay design strategies in RPRDS-1, all strategies do not last the same period of time. In fact, some may last well beyond the analysis period. Accordingly, the purpose of this variable is to account for the additional life so that feasible strategies with different lifetimes may be compared on a somewhat equal basis (see Chapter 5).

The selection of the value of the extended life should be based on the estimated cost of the optimum strategy and some other factors pointed out in Chapter 5: 1) the present availability of funds for initial construction, 2) the uncertainty in costs and traffic beyond the analysis period, 3) the fact

that RPRDS only computes maintenance costs up to the end of the analysis period, and 4) the fact that salvage value is computed at the end of the strategy life and not at the end of the analysis period.

Consider the following example. The analysis period is 20 years and the designer expects that the cost of the optimum strategy will be about ten dollars per square yard. Though the project is paid for at the time of initial construction, the average value for each year of service is fifty cents per square yard. Considering some of the factors listed above, the value of extended life may range from zero to 20 cents per square yard per year. Using a value of ten cents per square yard per year in the example, the cost of a strategy that lasts twenty-four years would be reduced by approximately forty cents per square yard, depending on interest and inflation factors. This may result in a favorable comparison with other strategies that last only 20 years.

If on the other hand, the user elects not to consider the value of extended life (especially in cases where construction funds are limited), he may do so by specifying a value of zero for this variable.

#### Combined Interest And Inflation Rate

60.1 Interest Rate Minus Inflation Rate. This variable is the numeric difference between the interest rate and inflation rate that may be expected during the analysis period (see Chapter 5). This variable is used to determine the net present value of some cost incurred at some future date.

The estimation of this value may be illustrated by the following example. If the average prime interest rate (or the opportunity cost of capital) anticipated during the analysis period is 18 percent and inflation

is 13 percent, then the value of this variable would be the difference between the two, or 5 percent.

It is important to note that a high value will favor stage (or delayed) overlay construction strategies while a low value will favor early overlay construction strategies.

#### DESCRIPTION OF RPRDS-1 PRINTOUT

The printout of the RPRDS-1 program can be divided into two parts, the input summary and the output. The input summary is, basically, an echo print of all the inputs specified by the user, complete with any error diagnostics detected by the INPUT routine. (Note here that any error in the data will cause the program to terminate execution, but only after it completes its error scan of the input data.)

The output of the program basically consists of a list of all the feasible strategies that were generated plus a full-page printout for each of the optimal 20 strategies. The list of feasible strategies (provided first) allows the user to inspect all of those that were generated. The full-page printouts of the optimal strategies provided afterwards, then, allow the user to inspect the best strategies and select one or two for use as his recommended design.

A sample of the RPRDS-1 printout for an example problem (discussed next) is provided in Appendices F (Input Summary) and G (Output).

## RPRDS-1 EXAMPLE PROBLEM

In order to give the user an idea of how to operate the RPRDS-1 program, an example problem was prepared using some design data from an overlay design project where the Texas SDHPT rigid pavement overlay design (RPOD) procedure was first used. The project is located at the northern intersection of IH-410 and IH-35 in San Antonio, Texas. This intersection is known as the Fratt Interchange and the section under consideration is a jointed concrete pavement just north of the interchange.

In the example problem, all the data were selected from either this design project or from information contained within this chapter. The RPRDS-1 input guide (Appendix D) was then used to code the data to run the program. The coded data are presented in Appendix E, and the input summary generated by the program (as discussed earlier) is presented in Appendix F. The user should be able to relate all the data used in this example problem back to the discussion of the RPRDS-1 inputs presented earlier in this chapter. However, it is useful to point out some of the significant aspects about the data:

- (1) Original pavement structure is JCP.
- (2) Layer moduli were determined using the Dynaflect basin fitting procedure, since no laboratory tests were available.
- (3) The projected 18-kip ESAL traffic estimates over the analysis period were very large.
- (4) The possibility of up to five years of heavy overlay maintenance to last the analysis period was considered.

- (5) Original pavement had carried a lot of traffic, and, therefore, its present remaining life was estimated to be quite low (30 percent).
- (6) Two first overlay types were considered, ACP and unbonded CRCP.
- (7) Two second overlay types were considered, ACP and CRCP.
- (8) Two levels of PCC flexural strength for the CRCP overlay strategies were considered.
- (9) All cost estimates were based on judgement. (Therefore, the user should be sure to use his own estimates.)
- (10) The CRCP steel reinforcement percentages were based on experience and engineering judgement. (The user should always use a reliable design method to predict the actual steel percentage required if a PCC overlay strategy is selected.)
- (11) Finally, salvage value and the value of each year of extended life (past the end of the analysis period) were considered.

#### RPRDS-1 Output

The output from the program for the example problem is presented in Appendix G. The first four pages of this output represent the list of all feasible strategies that were generated and considered. (The first page provides a description of each column in this list). Note that 183 feasible strategies were generated and that the total net present value (column 28) ranged from a minimum of \$13.56 per square yard (strategy 182) to a maximum of \$18.42 per square yard (strategy 152). Note also that all possible overlay combinations of those specified were generated and that the bulk of these required two overlays during the analysis period.

The last part of the output following this list of feasible strategies, is the 20 most optimum strategies (only the top ten are presented in Appendix G). Inspection of the most optimum strategy (that with the least total net present value) shows that it consists of a single six-inch unbonded CRCP overlay (with a PCC shoulder) that is placed at year two of the analysis period, i.e., when the original pavement has no remaining life. Note that the strategy is projected to last 30 years, where the value of the extended life (the additional ten years of service) is worth \$0.73 per square yard. (This value, along with the salvage value, \$0.50 per square yard, actually reduces the total net present value.)

Inspection of the next eight optimal strategies shows that all consist of the same 6-inch unbonded CRCP strategy as the first. The only basic differences are the remaining life at the time of overlay placement, the design PCC flexural strength, and the type of shoulder construction.

It isn't until the ninth optimal strategy that an ACP overlay strategy comes in. Inspection of this strategy shows that two ACP overlays are actually required, the first 6 inches (placed at year one) and the second 4 inches (placed at year eight). Note, finally, that in optimal strategy 10, (which is similar to 9), the predicted fatigue life is only 18 years. This means that this strategy would require two years of heavy maintenance near the end of the analysis period.

## SUMMARY

The purpose of this chapter is to provide the user with a detailed description of the use and application of the rigid pavement rehabilitation

design system computer program, RPRDS-1. Discussion was first provided on the Texas SDHPT rigid pavement overlay design (RPOL) procedure, which makes up the basic rehabilitation design method in RPRDS-1. This discussion was then used as a background for the next topic: the detailed description of the RPRDS-1 input variables, which discusses the restraints on the inputs, how the inputs are used in the program, and how they may be determined. Finally, an example problem was presented in order to illustrate the application of the program on an actual rehabilitation design project in Texas.

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## CHAPTER 7. SUMMARY, CONCLUSIONS, AND RECOMMENDATIONS FOR FURTHER RESEARCH

### SUMMARY

The main objective of this study was to develop a design system for rigid pavement rehabilitation using the systems methodology as a guide for the process of selecting, modifying, improving, and incorporating appropriate design and cost models into a comprehensive computer program (RPRDS-1) for the analysis of rigid pavement rehabilitation strategies. Accordingly, a summary of the significant aspects and accomplishments of this study is provided here.

A review of the practices followed by many highway and transportation agencies indicated several methods of rigid pavement rehabilitation which should be considered in a rigid pavement rehabilitation design system. These include undersealing joints or cracks, pressure grouting, conventional ACP and PCC overlay placement, new overlay types (sulfur-asphalt, rubber-asphalt, and sulflex), and replacement of worn-out sections by either cast-in-place or precast slabs. Unfortunately, none of these methods (with the exception of overlay placement) has a rational design method suitable for use in RPRDS-1. Consequently, at the present time, only overlay placement can be considered within the system framework of RPRDS-1. As a result of efforts by the Federal Highway Administration (FHWA) and the Texas State Department of Highways and Public Transportation (Texas SDHPT), much work has been

accomplished (Refs 1, 3, and 9) towards the development of a rigid pavement overlay design procedure (RPOD). This procedure forms the basis for the design model used within RPRDS-1.

Basically, the procedure in RPRDS-1 uses

- (1) a combination of layer theory and finite element theory to predict pavement response under load and
- (2) fatigue models based on pavement response and Miner's linear damage hypothesis to estimate the life of an overlay strategy.

These, in turn, allow for the consideration of several other factors associated with overlaying as a means for rehabilitation. These include

- (1) overlay type,
- (2) time of placement,
- (3) varying overlay thickness,
- (4) varying overlay strength,
- (5) concrete shoulder construction, and
- (6) multiple overlays.

With all these available options, a large number of pavement rehabilitation strategies can be generated. However, many of them may be eliminated from consideration if they do not meet the user-specified constraints.

Several cost models are incorporated into RPRDS-1 to analyze the economy of each feasible strategy and allow the user to select the optimum. Basically, these cost models include

- (1) overlay construction cost,
- (2) maintenance cost,

- (3) traffic delay cost (during overlay construction), and
- (4) salvage value.

Each of these was discussed in Chapter 5.

The output of the program is divided into three components (as discussed in Chapter 6):

- (1) a summary of all the user-specified inputs,
- (2) a list of all of the feasible strategies that were generated with both the design and cost components, and
- (3) a summary of the twenty most optimum rehabilitation strategies for inspection by the user.

The RPRDS-1 computer program was developed with the aid of The University of Texas CDC Cyber 170 computer. The program requires a field length of approximately 70,000 (octal) to compile and 102,000 (octal) to run. Furthermore, every effort was made to insure that the program would be transportable to other computer installations, including IBM.

## CONCLUSIONS

Based upon the main result of this study, i.e., the development of the rigid pavement rehabilitation design system, RPRDS-1, the following specific conclusions can be made:

- (1) It is possible to apply the systems approach to the design and analysis of rigid pavement rehabilitation. More specifically, it is possible to incorporate the Texas SDHPT RPOD procedure into a

comprehensive systems program to aid the highway engineer in the selection of optimum rigid pavement rehabilitation strategies.

- (2) Since the components which make up RPRDS-1 (a) consist of the latest in analytical methods for predicting pavement response and performance and (b) are based on observed field data, RPRDS-1 will provide practical and reliable solutions for a multitude of different overlay problems.

Since RPRDS-1 has only recently been completed, it is difficult at this time to make any other conclusions relative to how it will perform. Only time and extensive use of the program will provide a basis for any further conclusions.

#### RECOMMENDATIONS FOR FURTHER RESEARCH

Several areas of needed research were recognized during the development of RPRDS-1. Some of these represent uncertainty in some of the models which are based on little or questionable data. Others represent suggestions for detailed analysis of RPRDS-1 as well as extending its capabilities.

##### Improved Fatigue Models

First, it is recommended that an improved fatigue model be developed for ACP overlays since the existing model in RPRDS-1 is not based on observations of ACP overlays on rigid pavements. Perhaps the results of experimental overlay projects can be used to verify or improve it for rigid pavement application. Also, it should be recognized that the cracking in an ACP

overlay on a rigid pavement is probably the result of a combination of fatigue and reflection cracking.

Continued observation and surveys of rigid pavements are also recommended, so as to provide some verification of the PCC fatigue models developed thus far.

#### Distress Models for Overlays

Information on the rate of distress development over the life of an overlay strategy is used in RPRDS-1 to compute the maintenance cost of the strategy. Though the results of statewide condition surveys in Texas have provided some information on CRC pavements, it needs to be verified for CRCP overlays through the data feedback process. More importantly, data should be collected on the distress rates of JCP and ACP overlays to insure an equal comparison with CRCP overlay strategies. This again calls for a review of the data available from other states as well as continued observation of in-service pavements.

#### Additional Rehabilitation Methods

RPRDS-1 considers only one method of rehabilitation, overlay placement. In order to achieve a total comprehensive rehabilitation design system, other methods should be incorporated as more rational design models are developed.

#### Sensitivity Analysis

In order to identify the relative importance of each of the inputs to RPRDS-1 and to get an idea of their effect on the results, a sensitivity

analysis of the program should be conducted. Such a study would show which input variables require precise determination as well as those which may require less attention.

#### Reliability

It is also recommended that at some point, some measure of reliability be incorporated into the program. Such an improvement would allow the consideration of the inherent variability of many of the inputs on the predicted lifetimes and costs of each strategy. This, in turn, would emphasize the strategies which have a greater degree of certainty.

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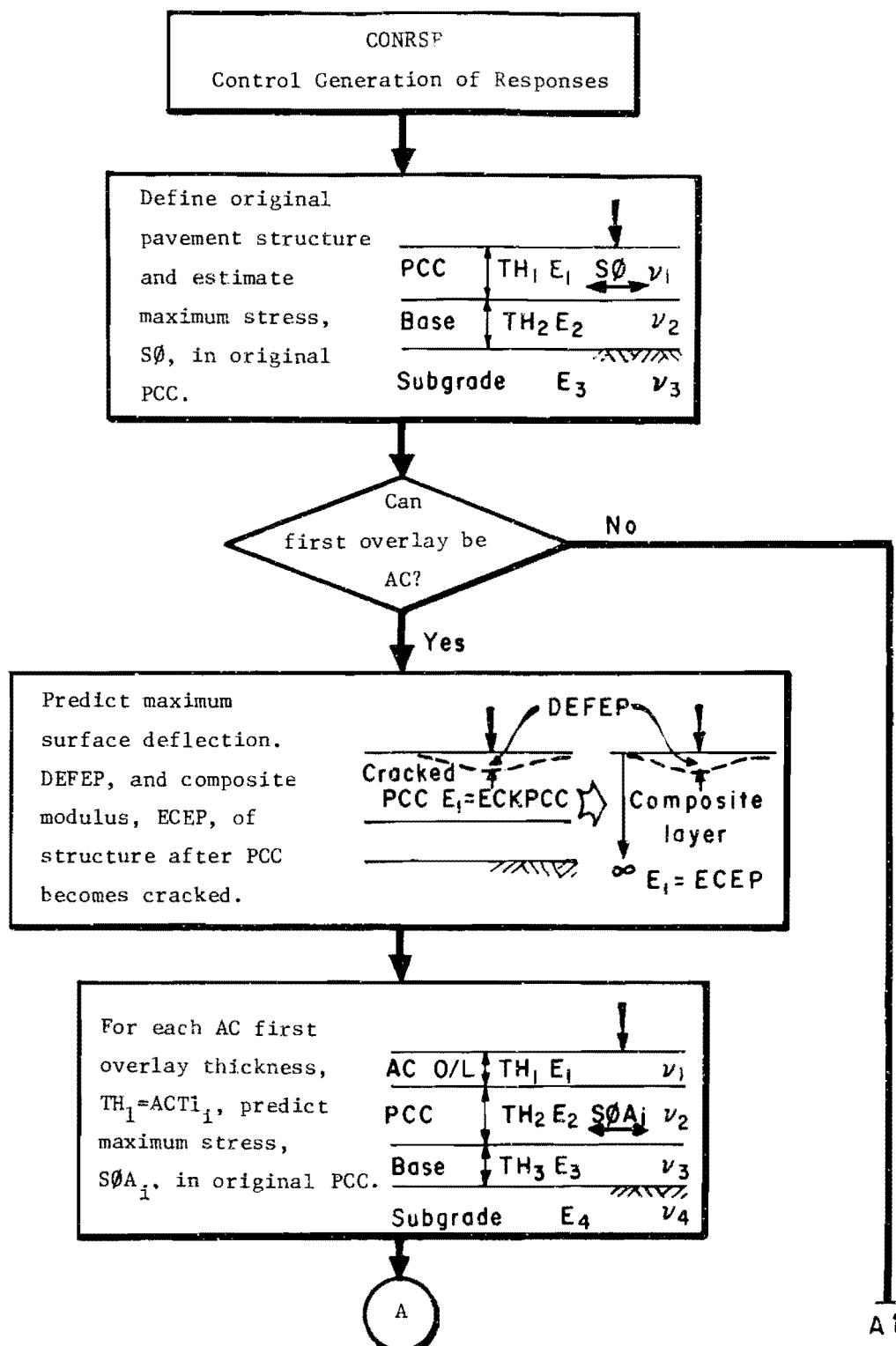
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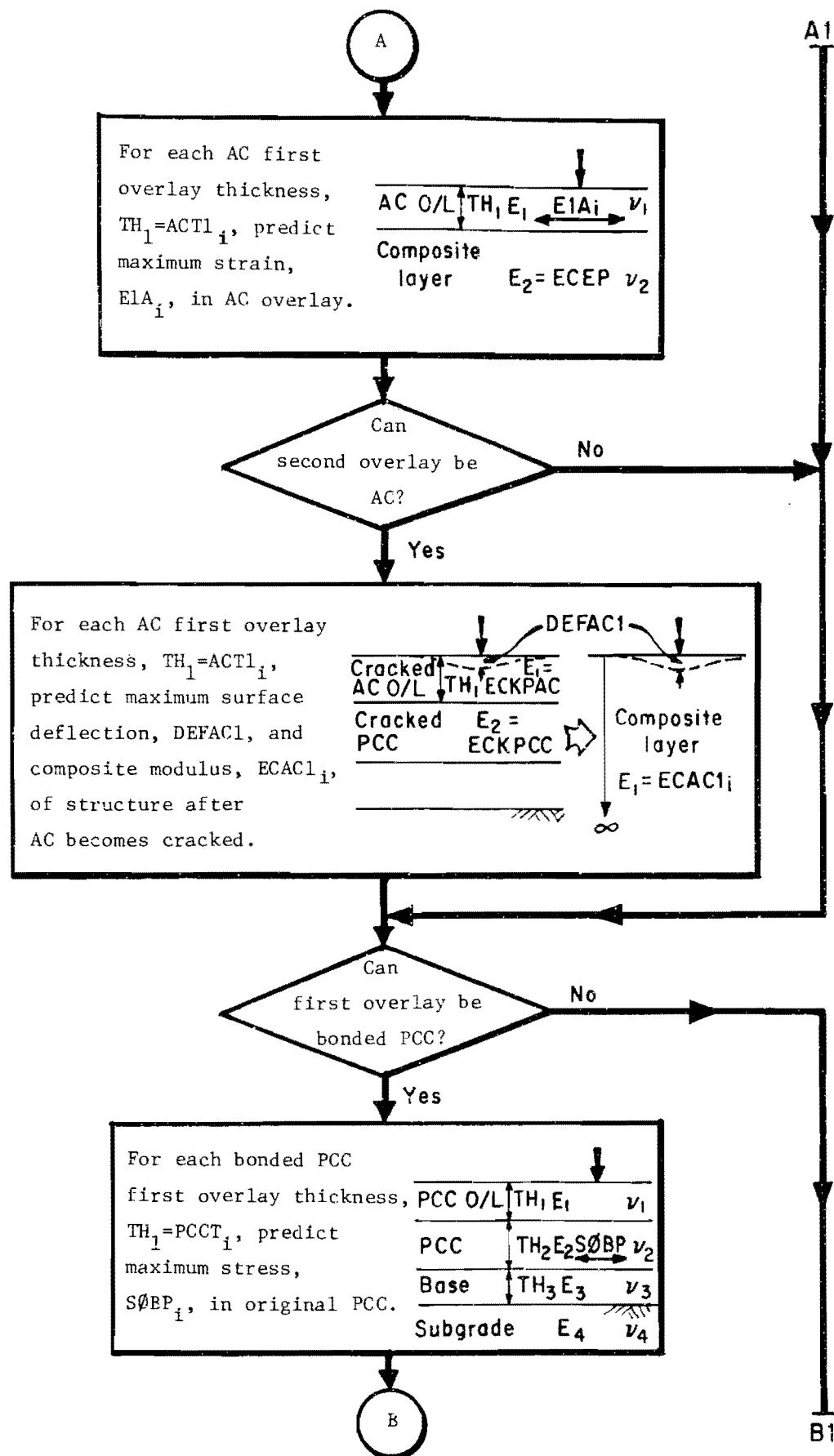
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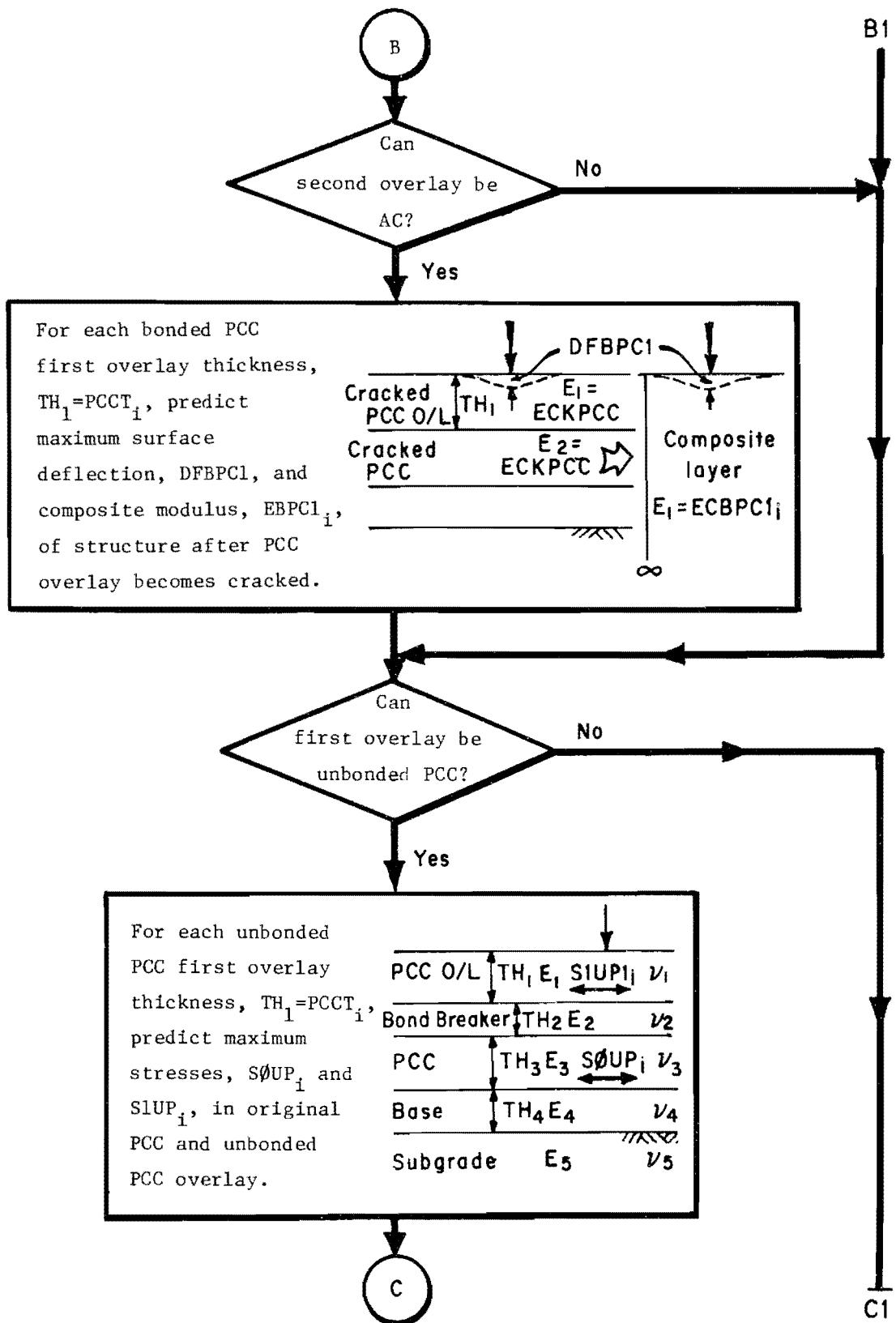
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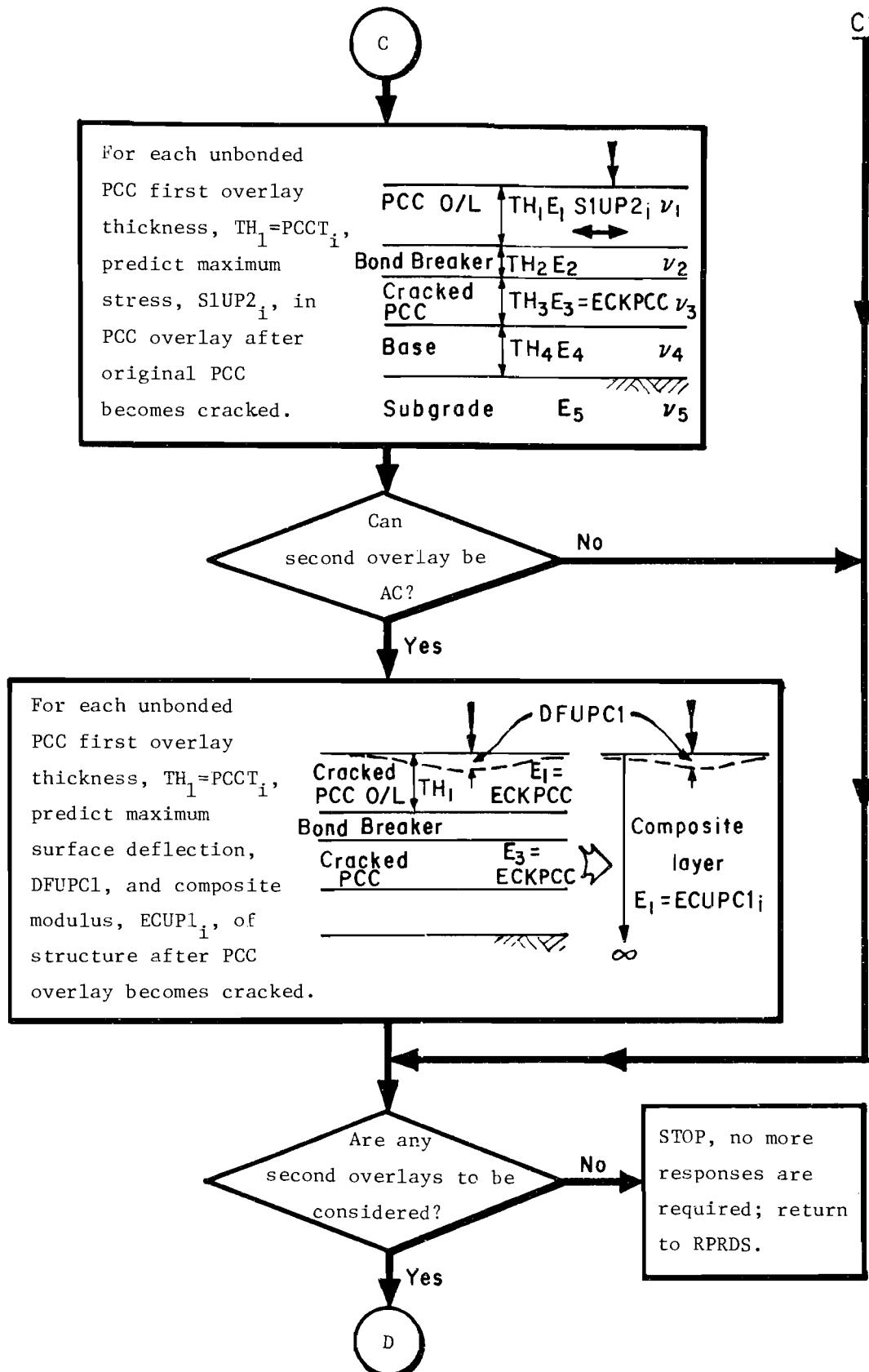
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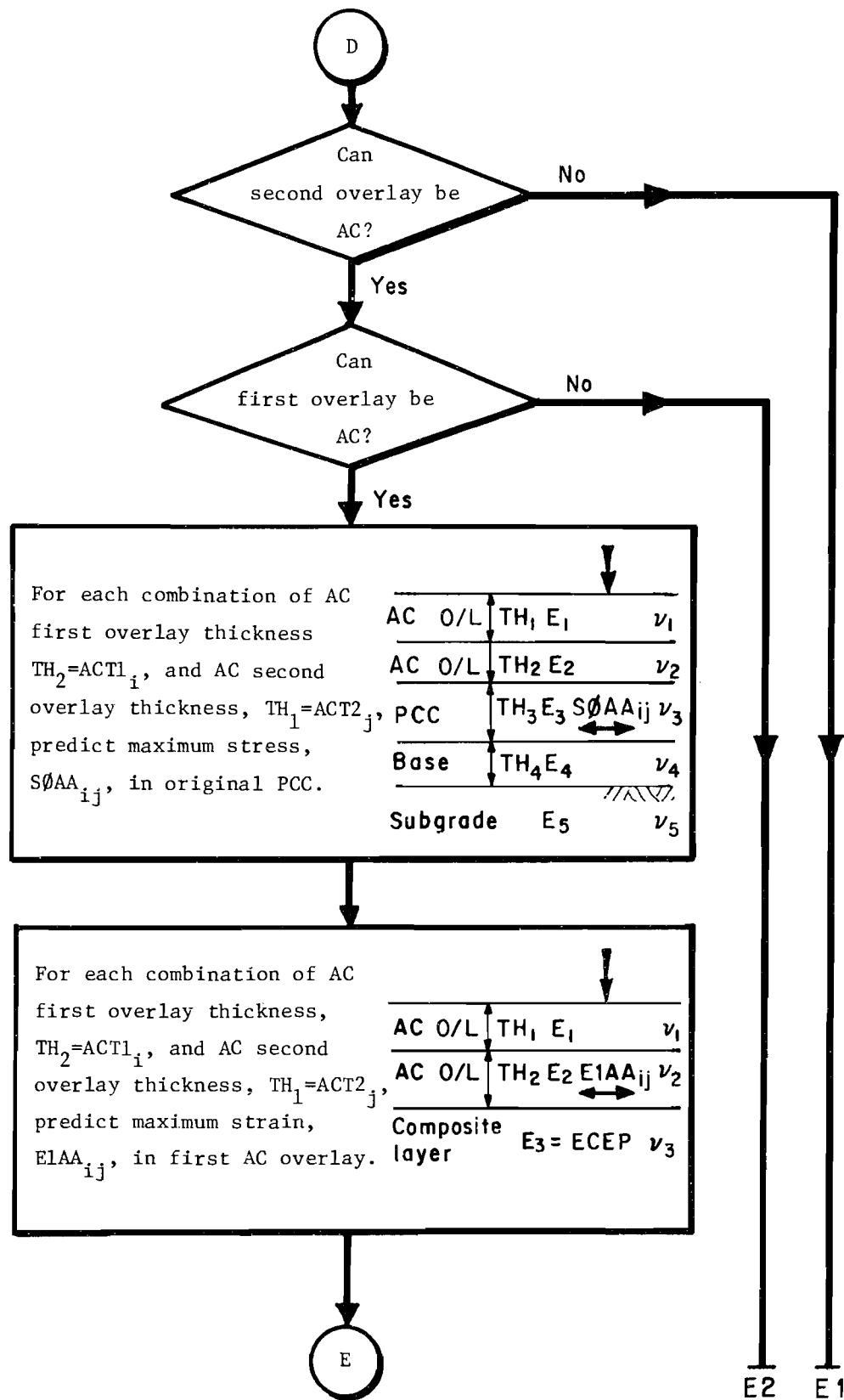
## APPENDIX A. FLOW DIAGRAM OF CONRSP ROUTINE

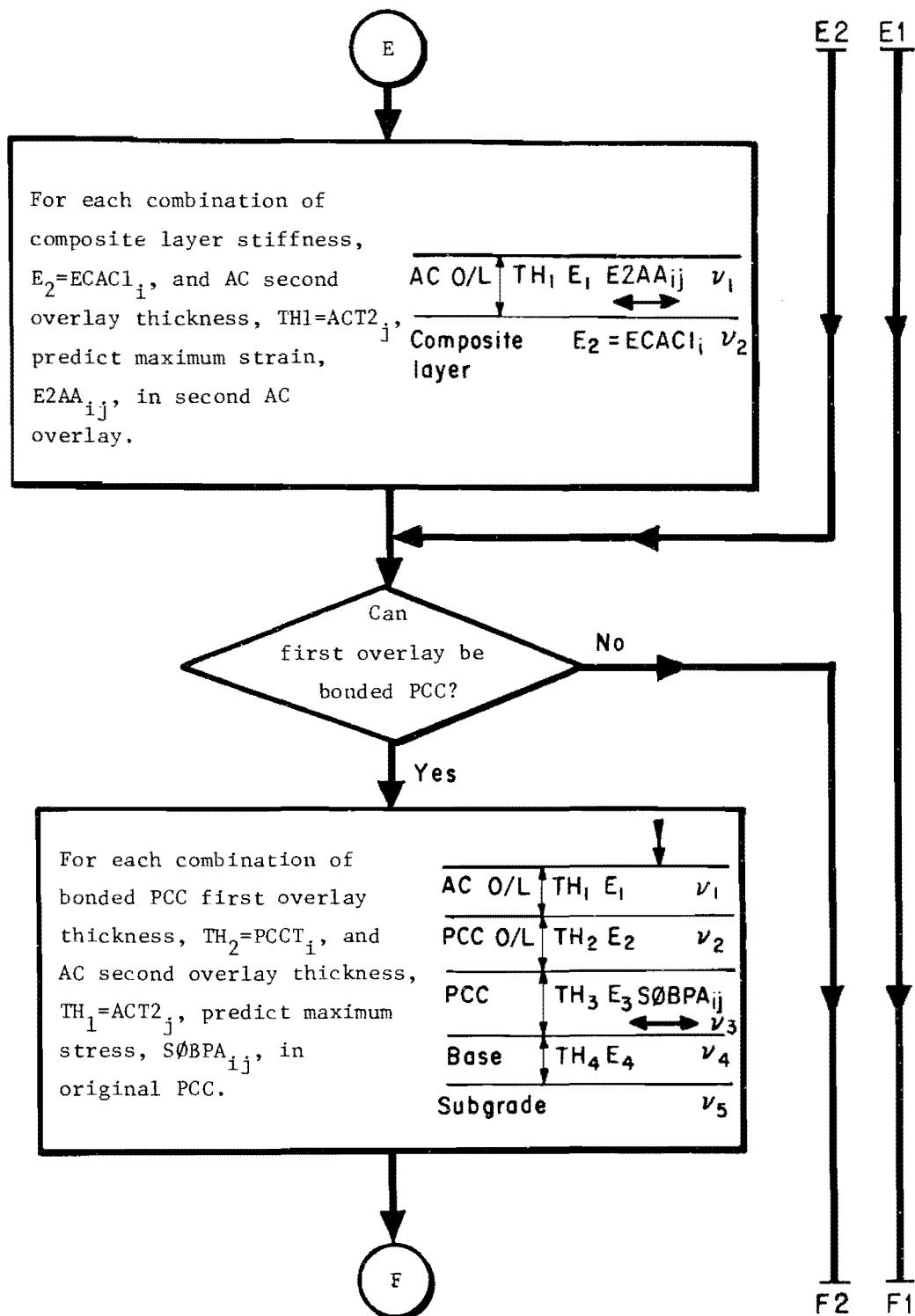


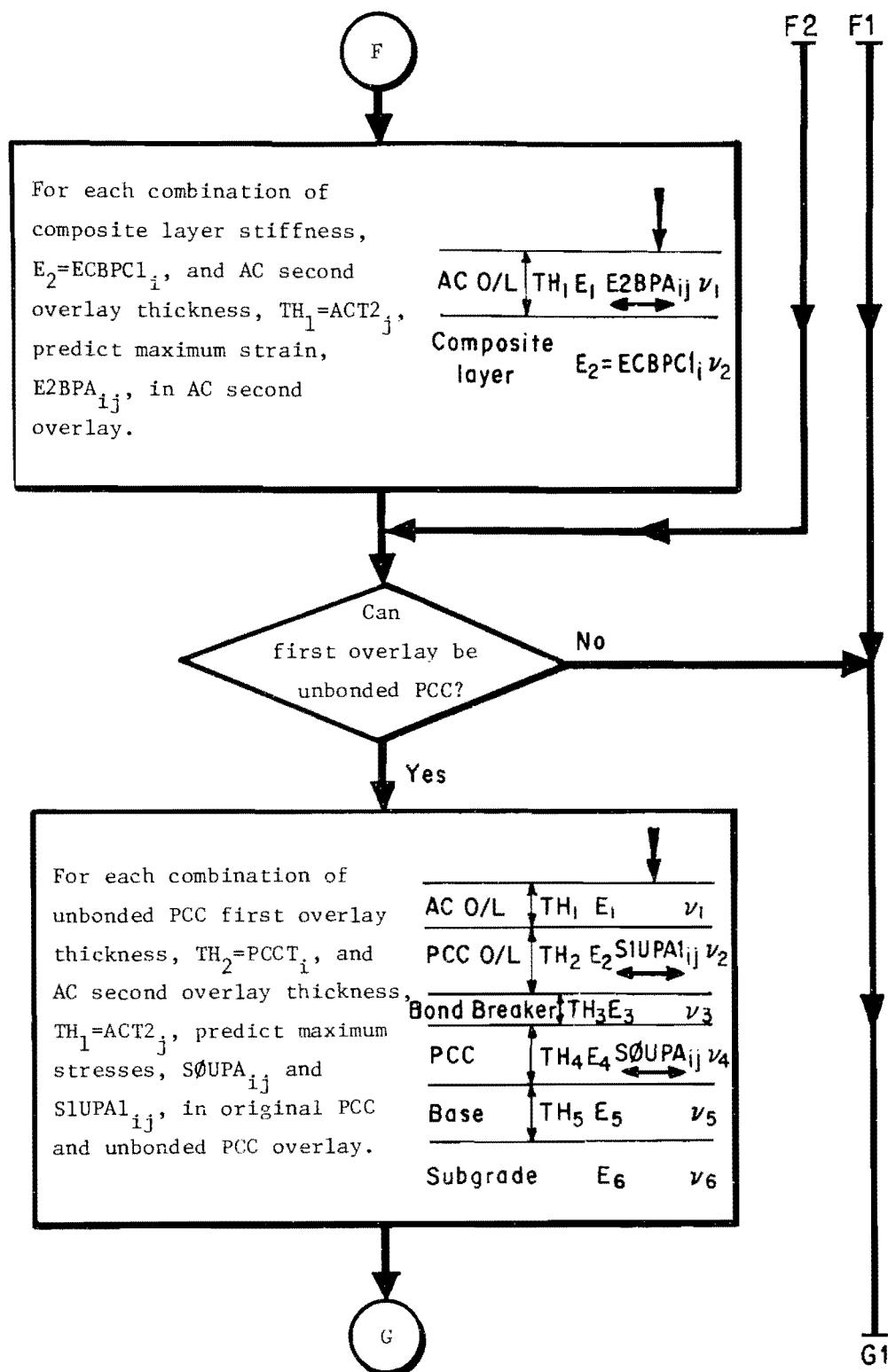


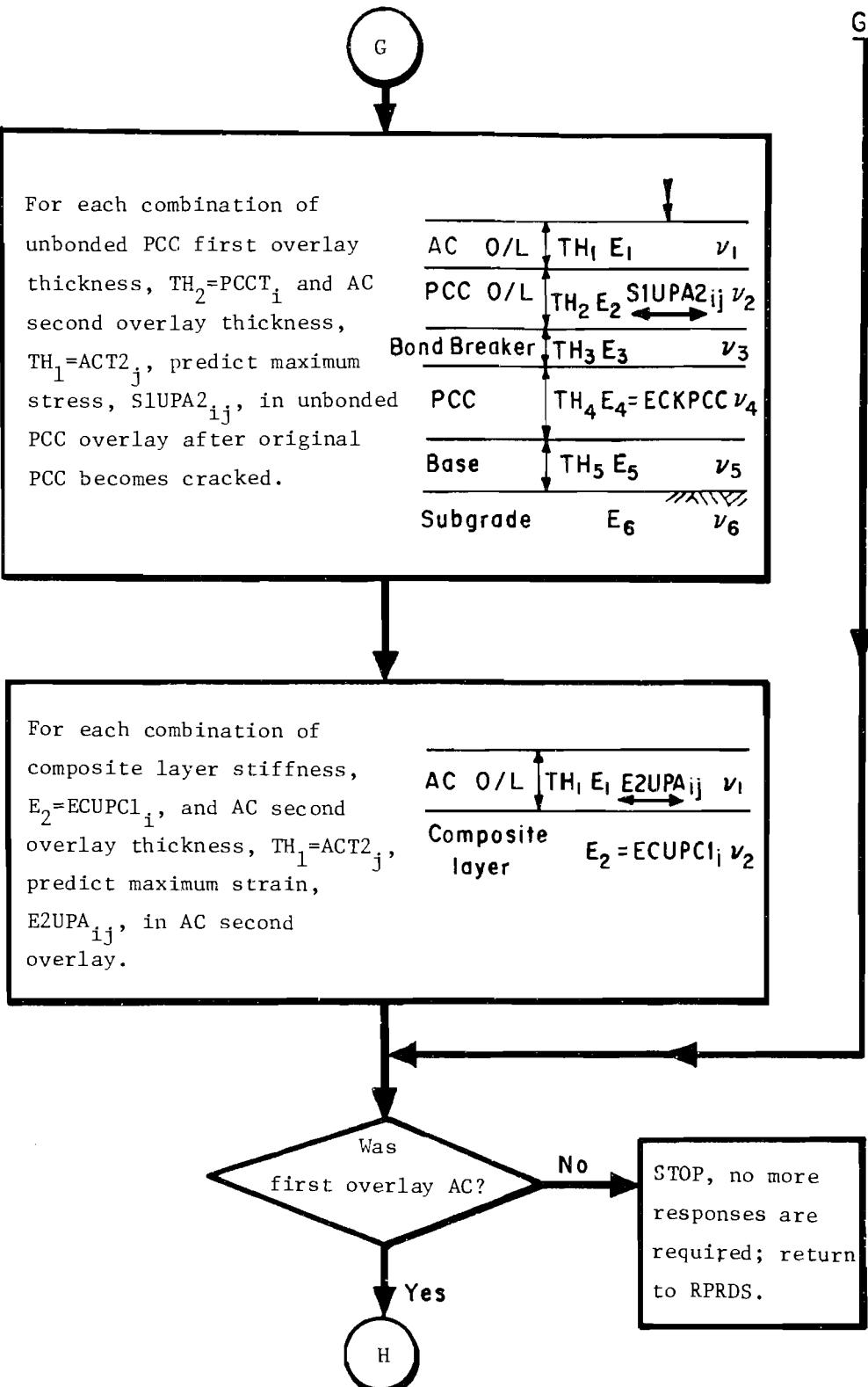


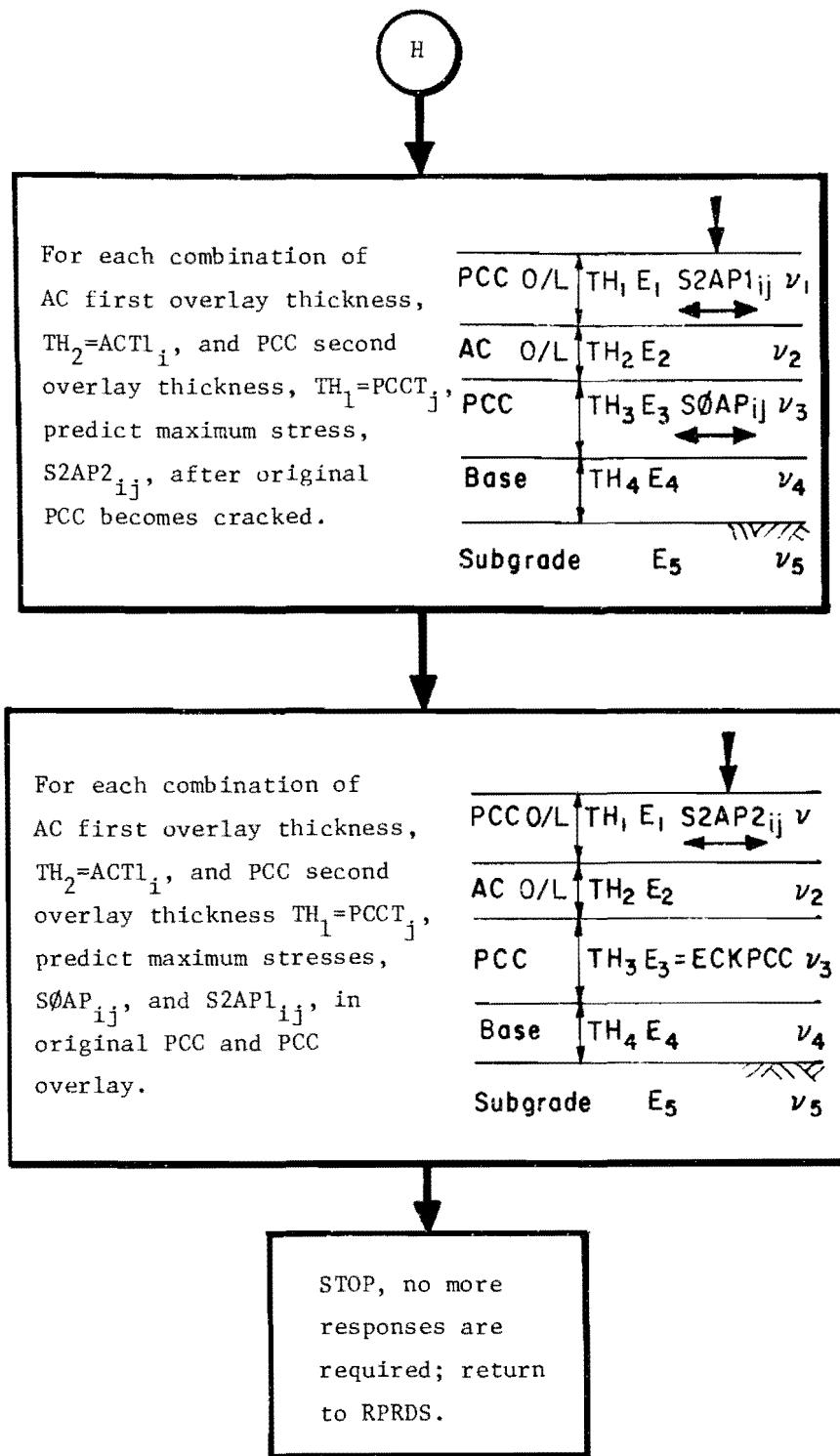












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## APPENDIX B

### REGRESSION MODELS FOR PREDICTING PAVEMENT RESPONSE

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## APPENDIX B. REGRESSION MODELS FOR PREDICTING PAVEMENT RESPONSES

This appendix provides all of the regression models developed as a part of this study to predict pavement response. Twelve models are presented and coded as follows:

- (1) E21
- (2) S31
- (3) S41
- (4) SB42
- (5) SU51
- (6) SU51C
- (7) SB52
- (8) SB53
- (9) SU53
- (10) SU62
- (11) SU62C
- (12) SU64

The first equation is for predicting strain in an asphalt concrete layer while the rest are for predicting stress in the concrete layers of various rigid pavement structures.

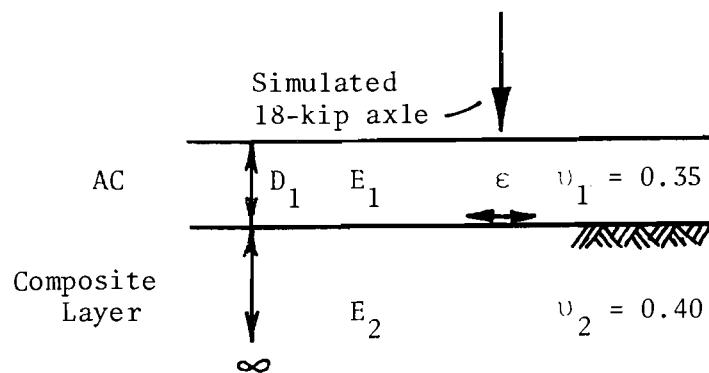
The following information is provided for each regression model:

- (1) an illustration of the pavement structure and the location of the predicted response,
- (2) the details of the experiment used to generate the equation, i.e., the inference space over which the equation may be applied,
- (3) the terms, coefficients and predictive accuracy of each equation, and
- (4) an illustration (from the experimental data), of the predictive accuracy of the equation.

Pavement Structure

and Response:

(Code: E21)



Details of the Experiment:

1. Full factorial, 3 factors, no. of observations =  $3^3 = 27$
2. Levels of the significant factors:

Factors	Levels		
	High	Medium	Low
$E_1$ (psi)	800,000	500,000	200,000
$E_2$ (psi)	60,000	40,000	20,000
$D_1$ (in)	10	7	4

Prediction Equation - E21:

$$\log_{10} \sigma = \sum (\text{Term} \times \text{Coefficient})$$

$$r^2 = 0.994$$

$$\text{std. error} = 0.0204$$

Term	Coefficient
Intercept	$-2.835 \times 10^0$
$E_1$	$-9.309 \times 10^{-7}$
$E_2$	$-7.530 \times 10^{-6}$
$D_1$	$-5.870 \times 10^{-2}$
$(E_1)^2$	$+4.108 \times 10^{-13}$
$E_1 \times E_2$	$+4.035 \times 10^{-12}$
$E_1 \times D_1$	$-2.356 \times 10^{-8}$

Fig B.1. E21 Regression model: for predicting tensile strain in an asphalt concrete surface layer.

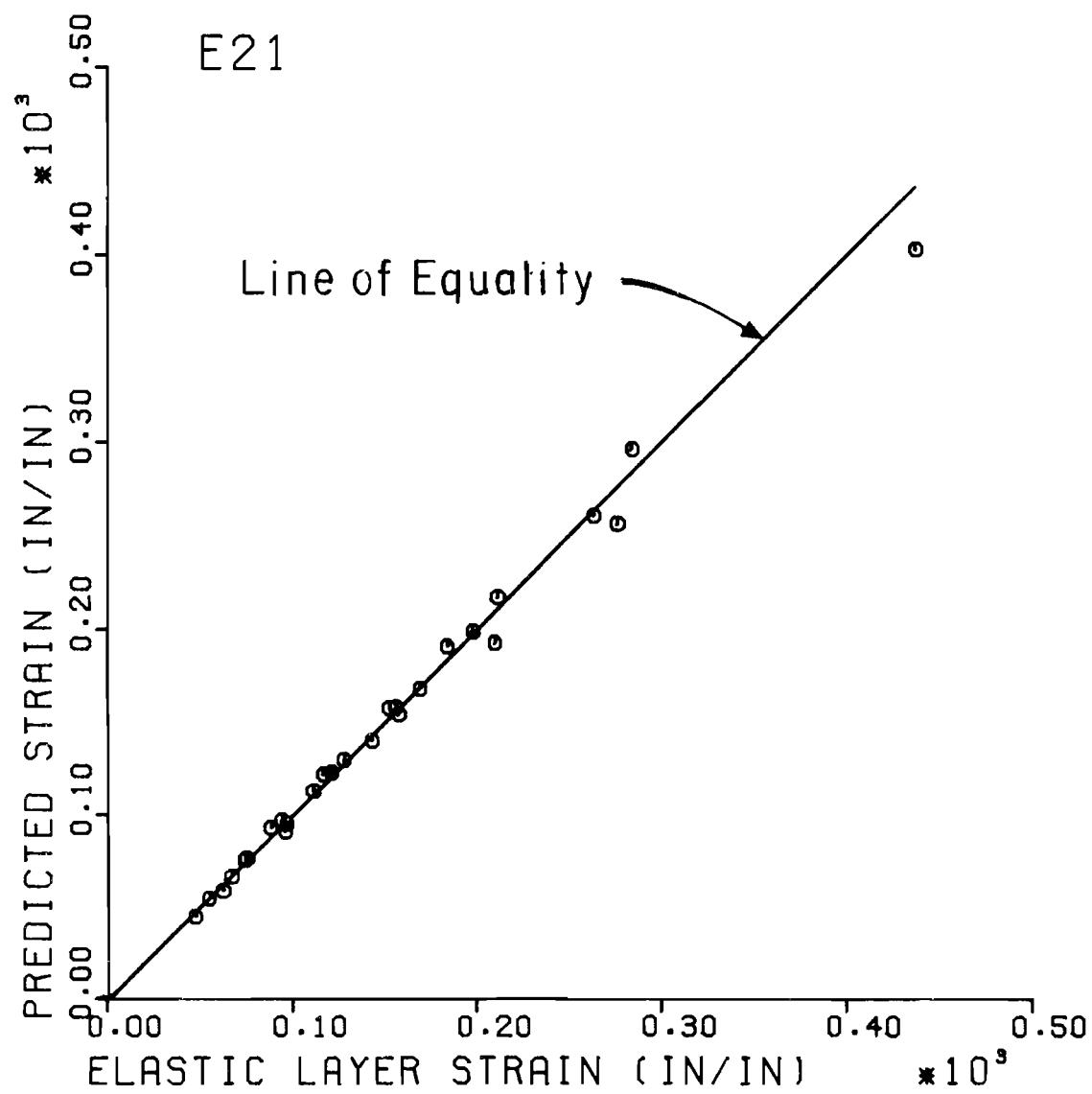
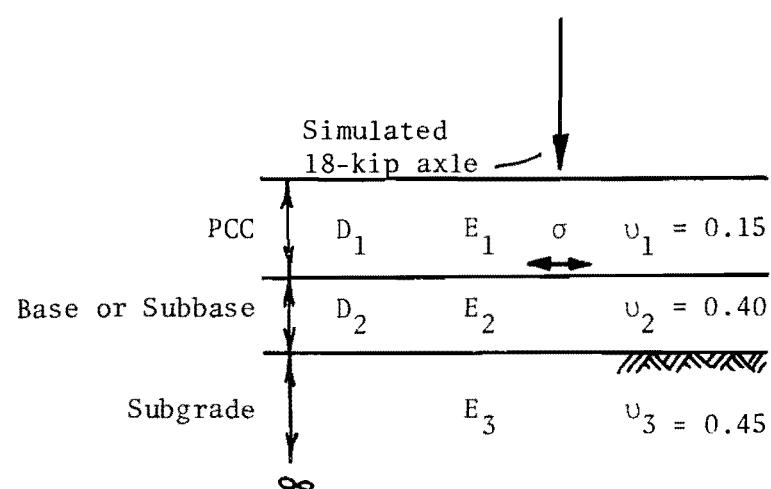


Fig B.2. Illustration of predictive accuracy of E21 Equation.

Pavement Structure

and Response:

(Code: S31)



Details of the Experiment:

1. Full factorial, 5 factors, no. of observations =  $3^5 = 243$
2. Levels of the significant factors:

Factors	Levels		
	High	Medium	Low
$E_1$ (psi)	6,500,000	5,000,000	3,500,000
$E_2$ (psi)	600,000	320,000	40,000
$E_3$ (psi)	20,000	11,000	2,000
$D_1$ (in)	10	8	6
$D_2$ (in)	12	9	6

(continued)

Fig B.3. S31 Regression model: for predicting concrete stress in a 3-layer concrete pavement.

Prediction Equation - S31:

	Term	Coefficient
$\log_{10} \sigma = \sum (\text{Term} \times \text{Coefficient})$		
$r^2 = 0.989$	Intercept	+ $2.880 \times 10^0$
std. error = 0.0202	$E_1$	+ $1.972 \times 10^{-8}$
	$E_2$	- $1.210 \times 10^{-6}$
	$E_3$	- $1.720 \times 10^{-5}$
	$D_1$	- $8.113 \times 10^{-2}$
	$E_2 \times D_2$	- $5.097 \times 10^{-8}$
	$E_2 \times D_1$	+ $6.121 \times 10^{-8}$
	$E_1 \times E_2$	+ $7.135 \times 10^{-14}$
	$(E_3)^2$	+ $3.818 \times 10^{-10}$
	$(E_2)^2$	+ $3.312 \times 10^{-13}$
	$E_2 \times E_3$	+ $5.034 \times 10^{-12}$

Fig B.3. (continued)

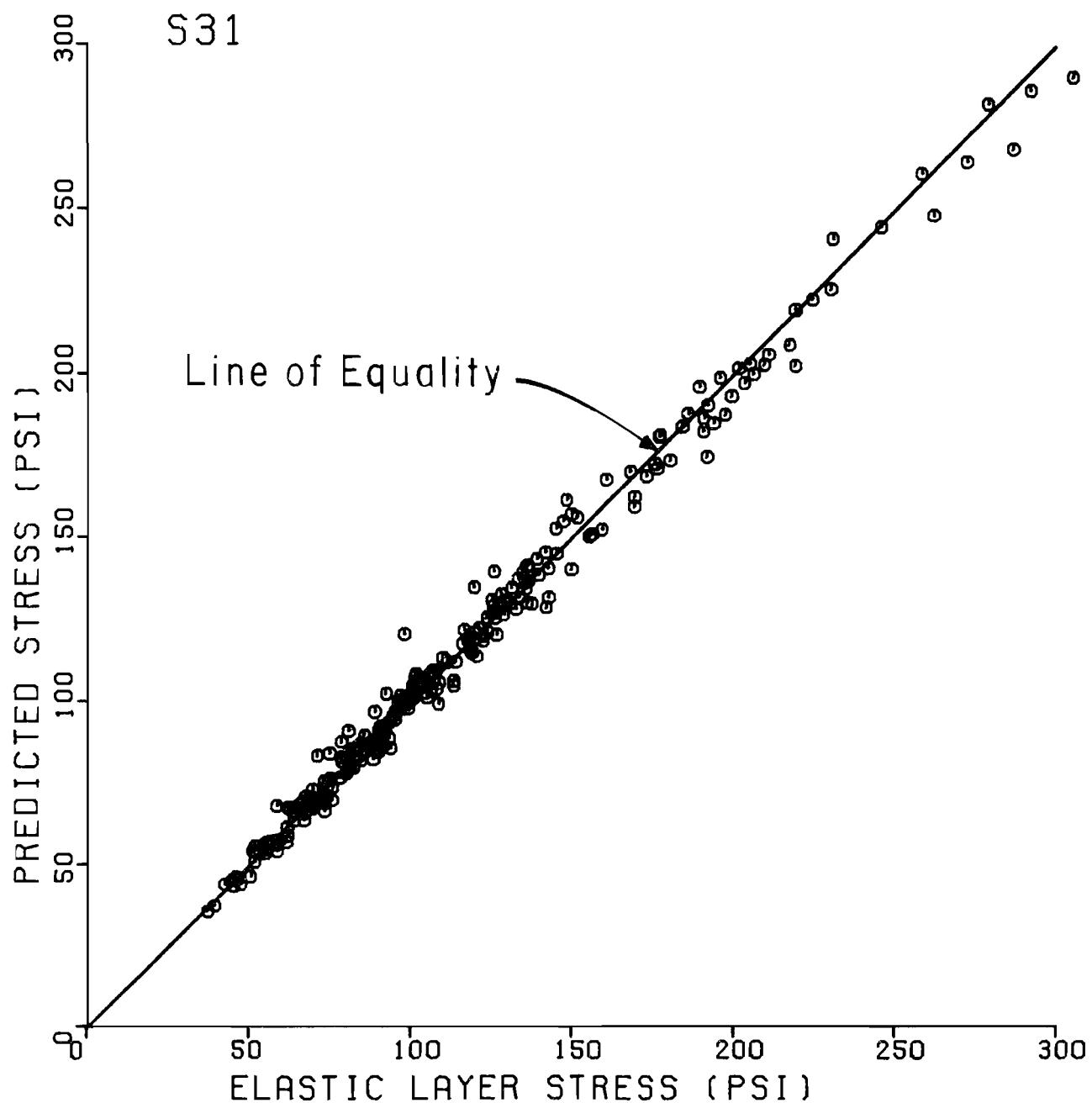
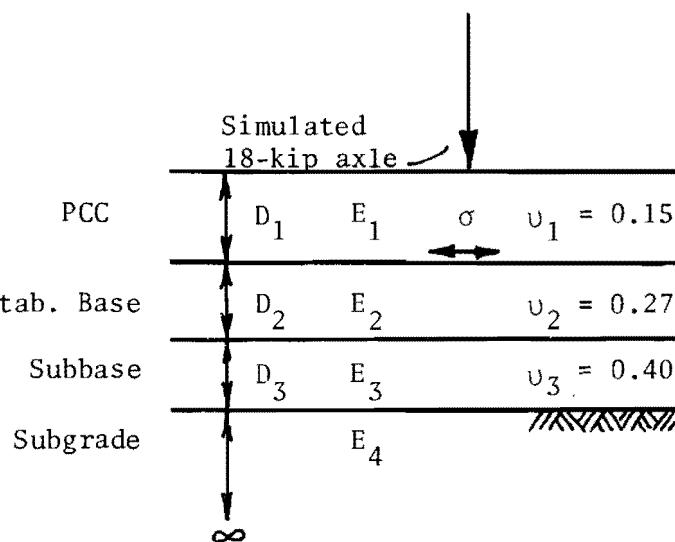


Fig B.4. Illustration of predictive accuracy of S31 equation.

## Pavement Structure

and Response:

(Code: S41)



## Details of the Experiment:

1. Fractional factorial, 7 factors, no. of observations =  $\frac{1}{9} \times 3^7 = 243$
2. Levels of the significant factors:

Factors	Levels		
	High	Medium	Low
$E_1$ (psi)	6,500,000	5,000,000	3,500,000
$E_2$ (psi)	800,000	500,000	200,000
$E_3$ (psi)	500,000	270,000	40,000
$E_4$ (psi)	20,000	11,000	2,000
$D_1$ (in)	10	8	6
$D_2$ (in)	10	8	6
$D_3$ (in)	12	9	6

(continued)

Fig B.5. S41 Regression Model: for predicting stress in 4-layer concrete pavement.

Prediction Equation - S41:

$$\log_{10} = (\text{Term} \times \text{Coefficient})$$

$$r^2 = 0.987$$

$$\text{std. error} = 0.0203$$

Term	Coefficient
Intercept	+ 2.660 x 10 <sup>0</sup>
E <sub>1</sub>	+ 3.326 x 10 <sup>-8</sup>
E <sub>2</sub>	- 9.386 x 10 <sup>-7</sup>
E <sub>3</sub>	- 6.715 x 10 <sup>-7</sup>
E <sub>4</sub>	- 5.279 x 10 <sup>-6</sup>
D <sub>1</sub>	- 5.911 x 10 <sup>-2</sup>
D <sub>2</sub>	- 1.153 x 10 <sup>-2</sup>
E <sub>1</sub> x E <sub>2</sub>	+ 5.406 x 10 <sup>-14</sup>
E <sub>2</sub> x D <sub>1</sub>	+ 3.909 x 10 <sup>-8</sup>
(E <sub>3</sub> ) <sup>2</sup>	+ 4.712 x 10 <sup>-13</sup>
E <sub>3</sub> x E <sub>4</sub>	+ 8.343 x 10 <sup>-12</sup>
E <sub>2</sub> x D <sub>2</sub>	- 3.106 x 10 <sup>-8</sup>
E <sub>3</sub> x D <sub>2</sub>	+ 3.016 x 10 <sup>-8</sup>
E <sub>3</sub> x D <sub>3</sub>	- 2.718 x 10 <sup>-8</sup>
E <sub>4</sub> x D <sub>1</sub>	- 6.465 x 10 <sup>-7</sup>
(E <sub>4</sub> ) <sup>2</sup>	+ 1.959 x 10 <sup>-10</sup>
(E <sub>2</sub> ) <sup>2</sup>	+ 1.826 x 10 <sup>-13</sup>

Fig B.5. (Continued)

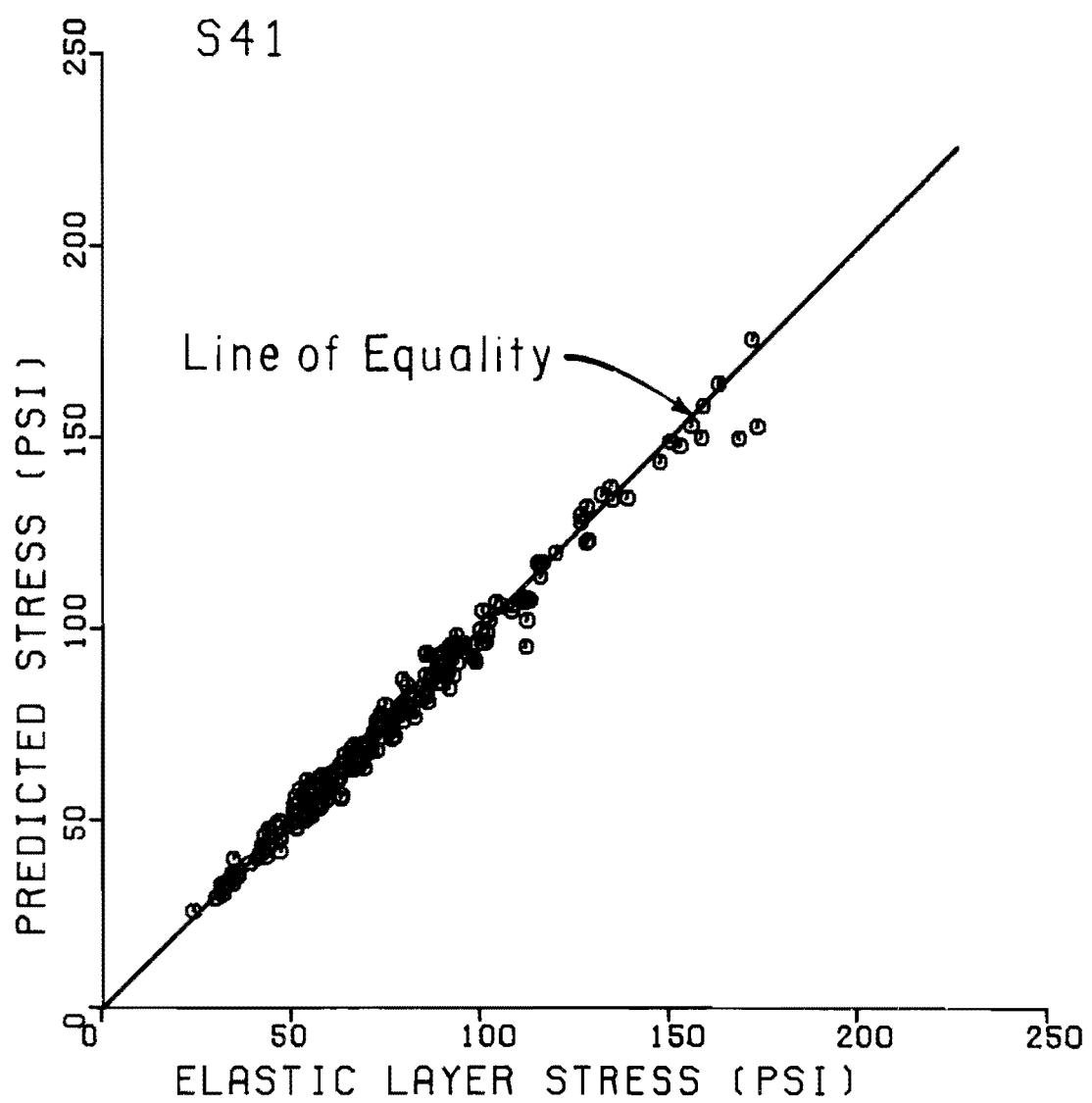
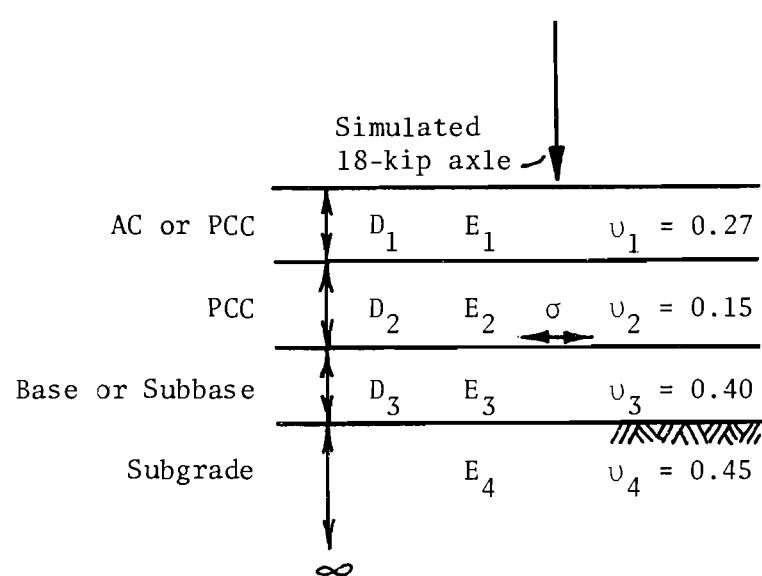


Fig B.6. Illustration of predictive accuracy of S41 equation.

Pavement Structure  
and Response:

(Code: SB42)



Details of the Experiment:

1. Fractional factorial, 7 factors, no. of observations =  $\frac{1}{9} \times 3^7 = 243$
2. Levels of the significant factors:

Factors	Levels		
	High	Medium	Low
$E_1$ (psi)	6,250,000	3,250,000	250,000
$E_2$ (psi)	6,500,000	5,000,000	3,500,000
$E_3$ (psi)	600,000	320,000	40,000
$E_4$ (psi)	20,000	11,000	2,000
$D_1$ (in)	8	6.5	5
$D_2$ (in)	10	8	6
$D_3$ (in)	12	9	6

(continued)

Fig B.7. 5B42 Regresion Model: for predicting stress in a 5-layer concrete pavement with a bonded overlay.

Prediction Equation - SB42:

$$\log_{10} \sigma = \Sigma (\text{Term} \times \text{Coefficient})$$

$$r^2 = 0.987$$

$$\text{std. error} = 0.0213$$

Term	Coefficient
Intercept	+ 2.667 x 10 <sup>0</sup>
$E_1$	- 9.509 x 10 <sup>-8</sup>
$E_2$	+ 3.368 x 10 <sup>-8</sup>
$E_3$	- 6.977 x 10 <sup>-7</sup>
$E_4$	- 1.644 x 10 <sup>-5</sup>
$D_1$	- 2.719 x 10 <sup>-2</sup>
$D_2$	- 5.441 x 10 <sup>-2</sup>
$D_3$	- 5.797 x 10 <sup>-3</sup>
$(E_1)^2$	+ 8.702 x 10 <sup>-15</sup>
$E_3 \times D_3$	- 3.814 x 10 <sup>-8</sup>
$E_1 \times E_3$	+ 9.055 x 10 <sup>-14</sup>
$(E_4)^2$	+ 3.764 x 10 <sup>-10</sup>
$E_2 \times E_3$	+ 4.602 x 10 <sup>-14</sup>
$E_3 \times D_2$	+ 3.225 x 10 <sup>-8</sup>
$E_1 \times D_1$	- 2.891 x 10 <sup>-9</sup>
$E_1 \times D_3$	+ 1.323 x 10 <sup>-9</sup>
$E_3 \times (E_1)^2$	- 8.115 x 10 <sup>-21</sup>

Fig B.7. (Continued)

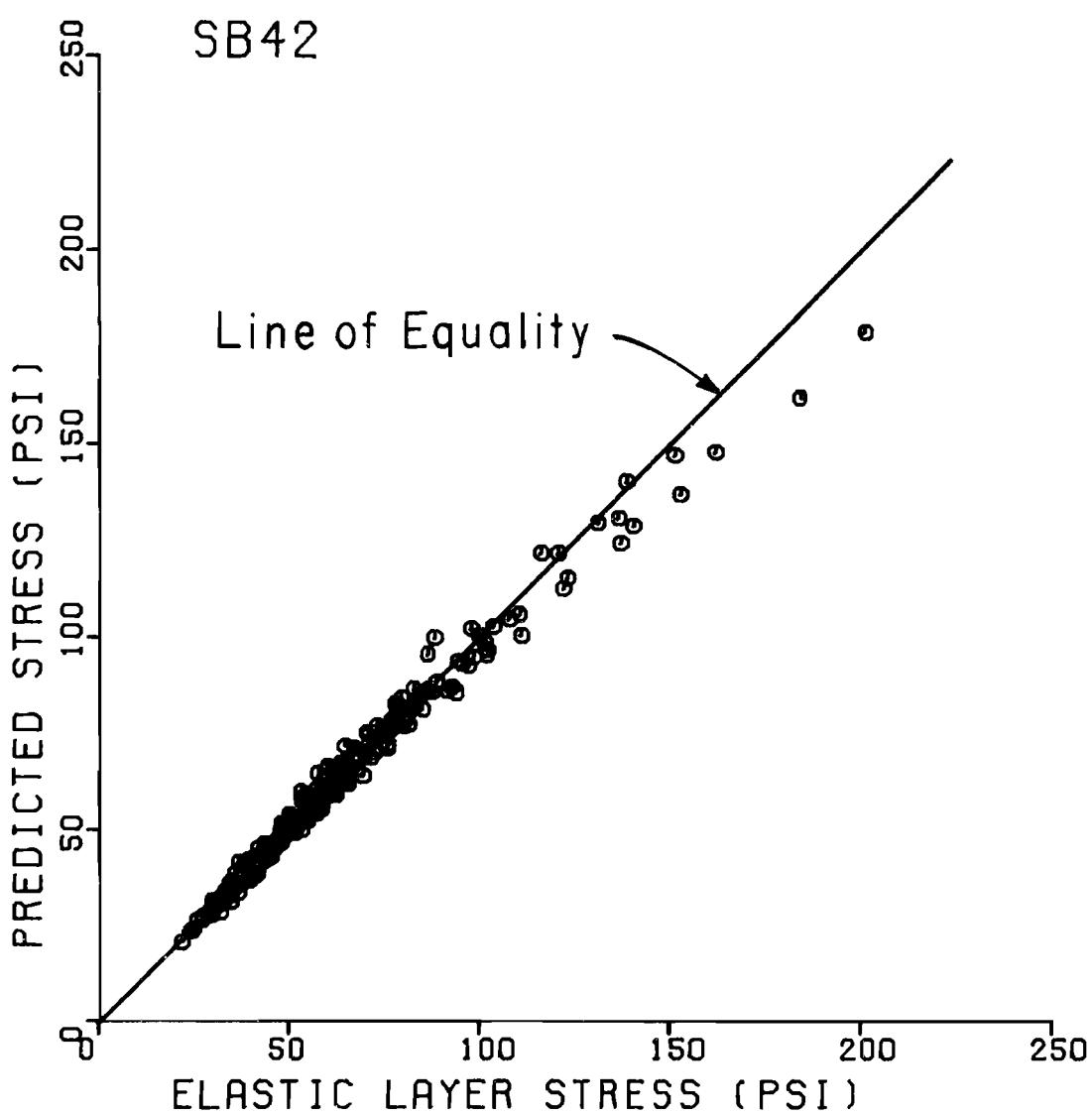
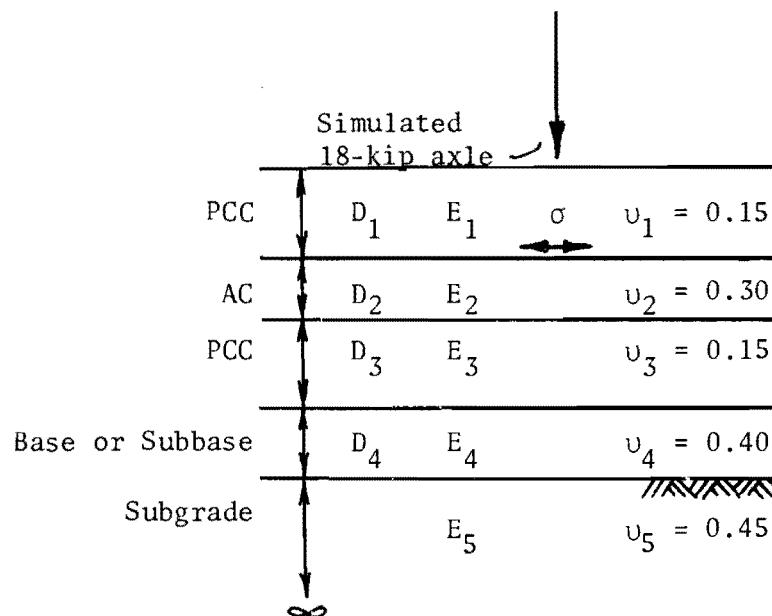


Fig B.8. Illustration of predictive accuracy of SB42 equation.

## Pavement Structure

and Response:

(Code: SU51)



## Details of the Experiment:

1. Fractional factorial, 9 factors, no. of observations =  $\frac{1}{81} \times 3^9 = 243$
2. Levels of the significant factor:

Factors	Levels		
	High	Medium	Low
$E_1$ (psi)	6,500,000	5,000,000	3,500,000
$E_2$ (psi)	550,000	300,000	50,000
$E_3$ (psi)	6,500,000	5,000,000	3,500,000
$E_4$ (psi)	600,000	320,000	40,000
$E_5$ (psi)	20,000	11,000	2,000
$D_1$ (in)	8	7	6
$D_2$ (in)	7	4	1
$D_3$ (in)	10	8	6
$D_4$ (in)	12	9	6

(continued)

Fig B.9. SU51 Regression Model: for predicting stress in unbonded concrete overlay of 5-layer concrete pavement.

Prediction Equation - SU51:

Term	Coefficient
$\log_{10} \sigma = \Sigma (\text{Term} \times \text{Coefficient})$	
Intercept	+ 2.461 x 10 <sup>0</sup>
$E_1$	+ 4.790 x 10 <sup>-8</sup>
$E_2$	- 2.780 x 10 <sup>-6</sup>
$E_3$	- 2.149 x 10 <sup>-8</sup>
$E_4$	- 5.871 x 10 <sup>-8</sup>
$D_1$	- 5.780 x 10 <sup>-2</sup>
$D_2$	+ 3.569 x 10 <sup>-2</sup>
$D_3$	- 3.495 x 10 <sup>-2</sup>
$(E_2)^2$	+ 1.161 x 10 <sup>-12</sup>
$E_1 \times E_2$	+ 1.093 x 10 <sup>-13</sup>
$E_2 \times D_2$	+ 1.583 x 10 <sup>-7</sup>
$D_2 \times D_3$	+ 4.019 x 10 <sup>-3</sup>
$E_3 \times D_2$	+ 4.103 x 10 <sup>-9</sup>
$E_2 \times (D_2)^2$	- 1.483 x 10 <sup>-8</sup>
$E_2 \times D_1$	+ 5.646 x 10 <sup>-8</sup>
$E_2 \times E_3$	- 3.550 x 10 <sup>-14</sup>
$D_1 \times D_2$	- 4.068 x 10 <sup>-3</sup>
$E_2 \times E_5$	+ 4.396 x 10 <sup>-12</sup>
$E_1 \times (D_2)^2$	- 7.478 x 10 <sup>-10</sup>

Fig B.9. (Continued)

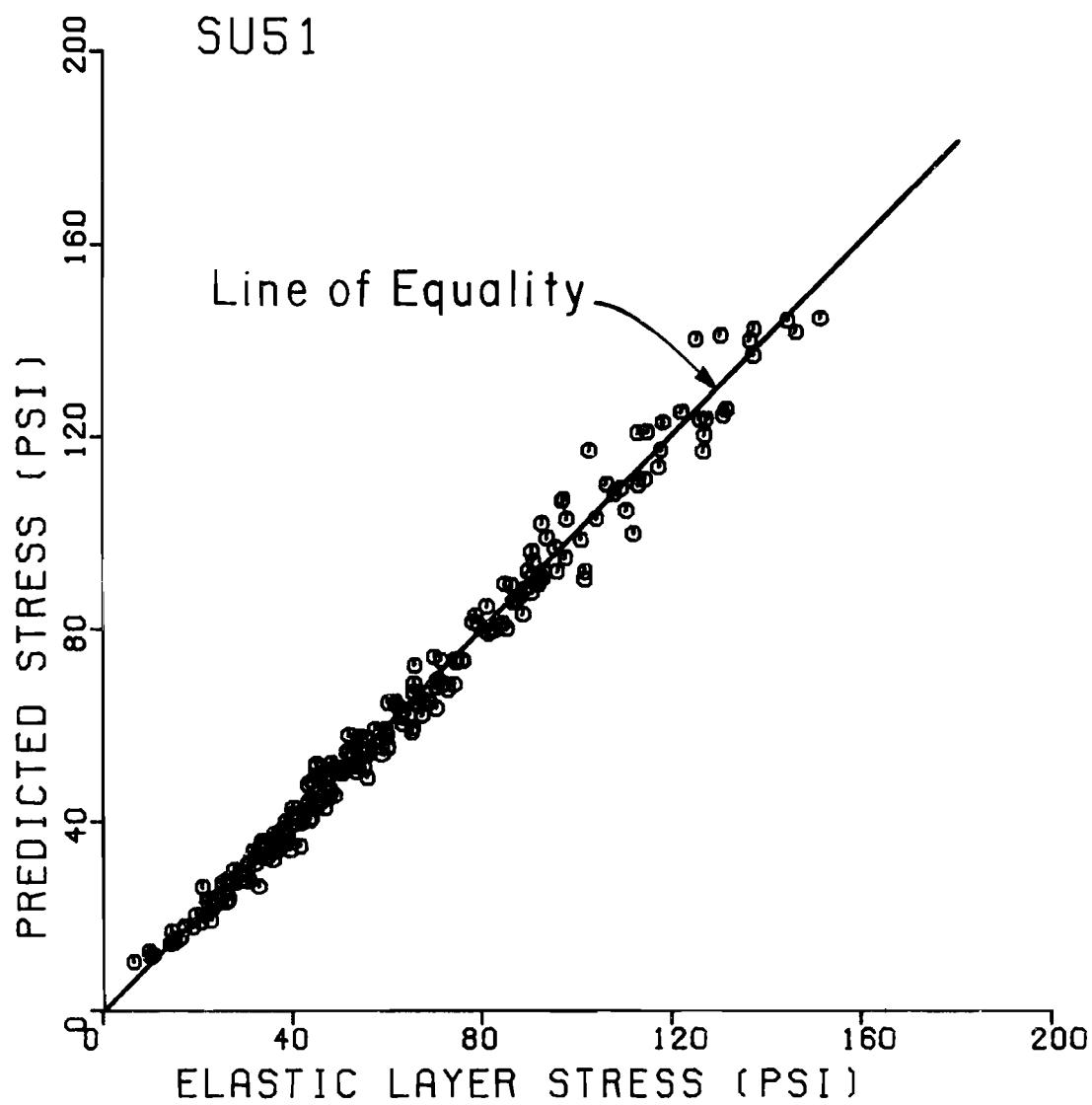
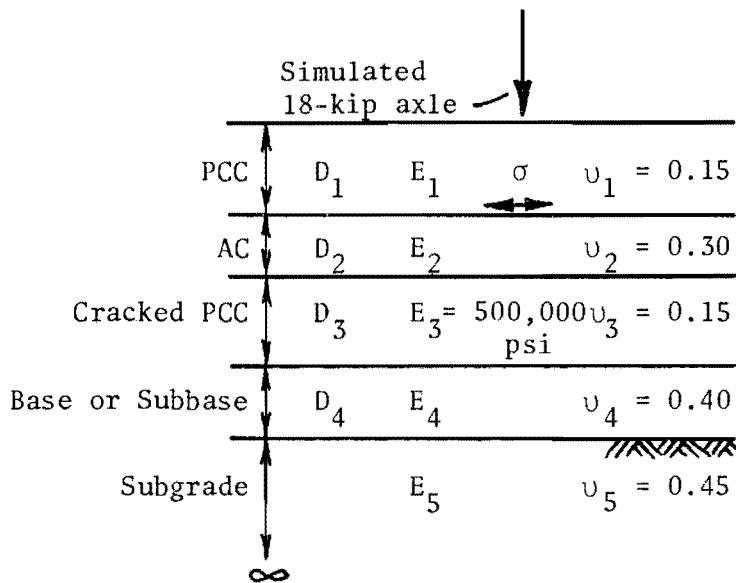


Fig B.10. Illustration of predictive accuracy of SU51 equation.

Pavement Structure  
and Response:

(Code: SU51C)



#### Details of the Experiment:

1. Fractional factorial, 8 factors, no. of observations =  $\frac{1}{27} \times 3^8 = 243$
2. Levels of the significant factors:

Factors	Levels		
	High	Medium	Low
E <sub>1</sub> (psi)	6,500,000	5,000,000	3,500,000
E <sub>2</sub> (psi)	550,000	300,000	50,000
E <sub>4</sub> (psi)	500,000	270,000	40,000
E <sub>5</sub> (psi)	20,000	11,000	2,000
D <sub>1</sub> (in)	8	7	6
D <sub>2</sub> (in)	7	4	1
D <sub>3</sub> (in)	10	8	6
D <sub>4</sub> (in)	12	9	6

Note: E<sub>3</sub> in experiment was fixed at 500,000 psi to simulate cracked PCC.

(continued)

Fig B.11. SU51C Regression Model: for predicting stress in unbonded concrete overlay of 5-layer concrete pavement (original PCC cracked).

Prediction Equation - SU51C:

$$\log_{10} \sigma = \sum (\text{Term} \times \text{Coefficient})$$

$$r^2 = 0.986$$

$$\text{std. error} = 0.0189$$

Term	Coefficient
Intercept	+ 2.696 x 10 <sup>0</sup>
E <sub>1</sub>	+ 3.354 x 10 <sup>-8</sup>
E <sub>2</sub>	- 1.455 x 10 <sup>-6</sup>
E <sub>4</sub>	- 5.530 x 10 <sup>-7</sup>
E <sub>5</sub>	- 4.660 x 10 <sup>-6</sup>
D <sub>1</sub>	- 7.299 x 10 <sup>-2</sup>
D <sub>3</sub>	- 2.170 x 10 <sup>-2</sup>
D <sub>4</sub>	- 1.899 x 10 <sup>-3</sup>
E <sub>2</sub> x D <sub>2</sub>	- 5.900 x 10 <sup>-8</sup>
(E <sub>2</sub> ) <sup>2</sup>	+ 8.141 x 10 <sup>-13</sup>
E <sub>1</sub> x E <sub>2</sub>	+ 6.601 x 10 <sup>-14</sup>
E <sub>4</sub> x D <sub>2</sub>	+ 2.420 x 10 <sup>-8</sup>
E <sub>2</sub> x D <sub>1</sub>	+ 5.436 x 10 <sup>-8</sup>
(E <sub>4</sub> ) <sup>2</sup>	+ 3.316 x 10 <sup>-13</sup>
E <sub>4</sub> x E <sub>5</sub>	+ 5.807 x 10 <sup>-12</sup>
D <sub>2</sub> x D <sub>3</sub>	+ 1.066 x 10 <sup>-3</sup>
E <sub>4</sub> x D <sub>4</sub>	- 1.267 x 10 <sup>-8</sup>
E <sub>4</sub> x D <sub>3</sub>	+ 1.869 x 10 <sup>-8</sup>
E <sub>5</sub> x D <sub>2</sub>	+ 2.859 x 10 <sup>-7</sup>
E <sub>2</sub> x E <sub>4</sub>	- 1.273 x 10 <sup>-13</sup>

Fig B.11. (Continued)

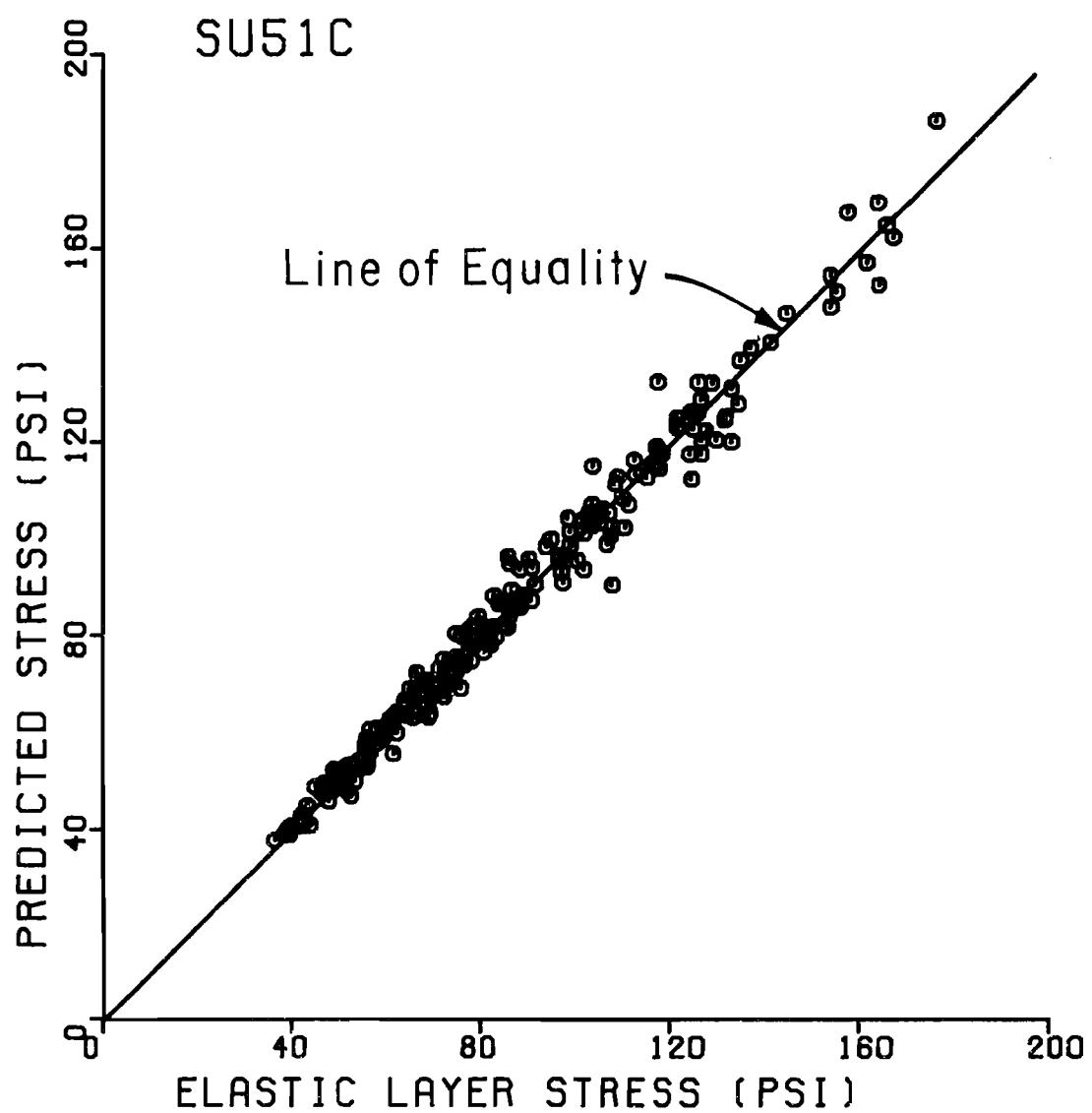
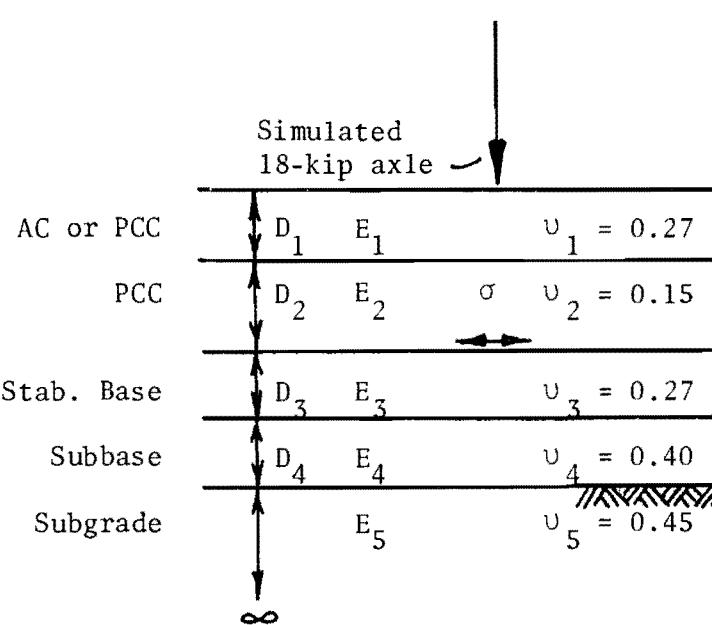


Fig B.12. Illustration of predictive accuracy of SU51C equation.

Pavement Structure  
and Response:

(Code: SB52)



Details of the Experiment:

1. Full factorial, 9 factors, no. of observations =  $\frac{1}{81} \times 3^9 = 243$
2. Levels of the significant factors:

Factors	Levels		
	High	Medium	Low
E <sub>1</sub> (psi)	6,250,000	3,250,000	250,000
E <sub>2</sub> (psi)	6,500,000	5,000,000	3,500,000
E <sub>3</sub> (psi)	800,000	650,000	500,000
E <sub>4</sub> (psi)	500,000	270,000	40,000
E <sub>5</sub> (psi)	20,000	11,000	2,000
D <sub>1</sub> (in)	8	6	4
D <sub>2</sub> (in)	8	7	6
D <sub>3</sub> (in)	10	8	6
D <sub>4</sub> (in)	12	9	6

(continued)

Fig B.13. SB52 Regression Model: for predicting stress in 5-layer concrete pavement with bonded overlay.

## Prediction Equation - SB52

Term	Coefficient
Intercept	+ 2.173 x 10 <sup>0</sup>
E <sub>1</sub>	- 3.538 x 10 <sup>-8</sup>
E <sub>2</sub>	+ 7.741 x 10 <sup>-8</sup>
E <sub>4</sub>	- 5.965 x 10 <sup>-7</sup>
E <sub>5</sub>	- 1.472 x 10 <sup>-5</sup>
D <sub>1</sub>	- 2.788 x 10 <sup>-2</sup>
D <sub>2</sub>	- 3.204 x 10 <sup>-2</sup>
D <sub>4</sub>	- 6.584 x 10 <sup>-3</sup>
(E <sub>4</sub> ) <sup>2</sup>	+ 3.372 x 10 <sup>-13</sup>
E <sub>4</sub> x E <sub>5</sub>	+ 7.174 x 10 <sup>-12</sup>
E <sub>4</sub> x D <sub>3</sub>	+ 1.787 x 10 <sup>-8</sup>
E <sub>1</sub> x E <sub>4</sub>	+ 2.296 x 10 <sup>-14</sup>
E <sub>4</sub> x D <sub>4</sub>	- 2.377 x 10 <sup>-8</sup>
E <sub>1</sub> x E <sub>2</sub>	- 2.750 x 10 <sup>-15</sup>
E <sub>1</sub> x E <sub>3</sub>	- 2.551 x 10 <sup>-14</sup>
E <sub>3</sub> x D <sub>3</sub>	- 4.774 x 10 <sup>-8</sup>
E <sub>1</sub> x D <sub>3</sub>	+ 1.195 x 10 <sup>-9</sup>
E <sub>1</sub> x D <sub>1</sub>	- 1.399 x 10 <sup>-9</sup>
(E <sub>1</sub> ) <sup>2</sup>	+ 2.168 x 10 <sup>-15</sup>
E <sub>1</sub> x E <sub>5</sub>	- 2.598 x 10 <sup>-13</sup>
(E <sub>5</sub> ) <sup>2</sup>	+ 2.346 x 10 <sup>-10</sup>
E <sub>5</sub> x D <sub>4</sub>	+ 3.573 x 10 <sup>-7</sup>

Fig B.13. (Continued)

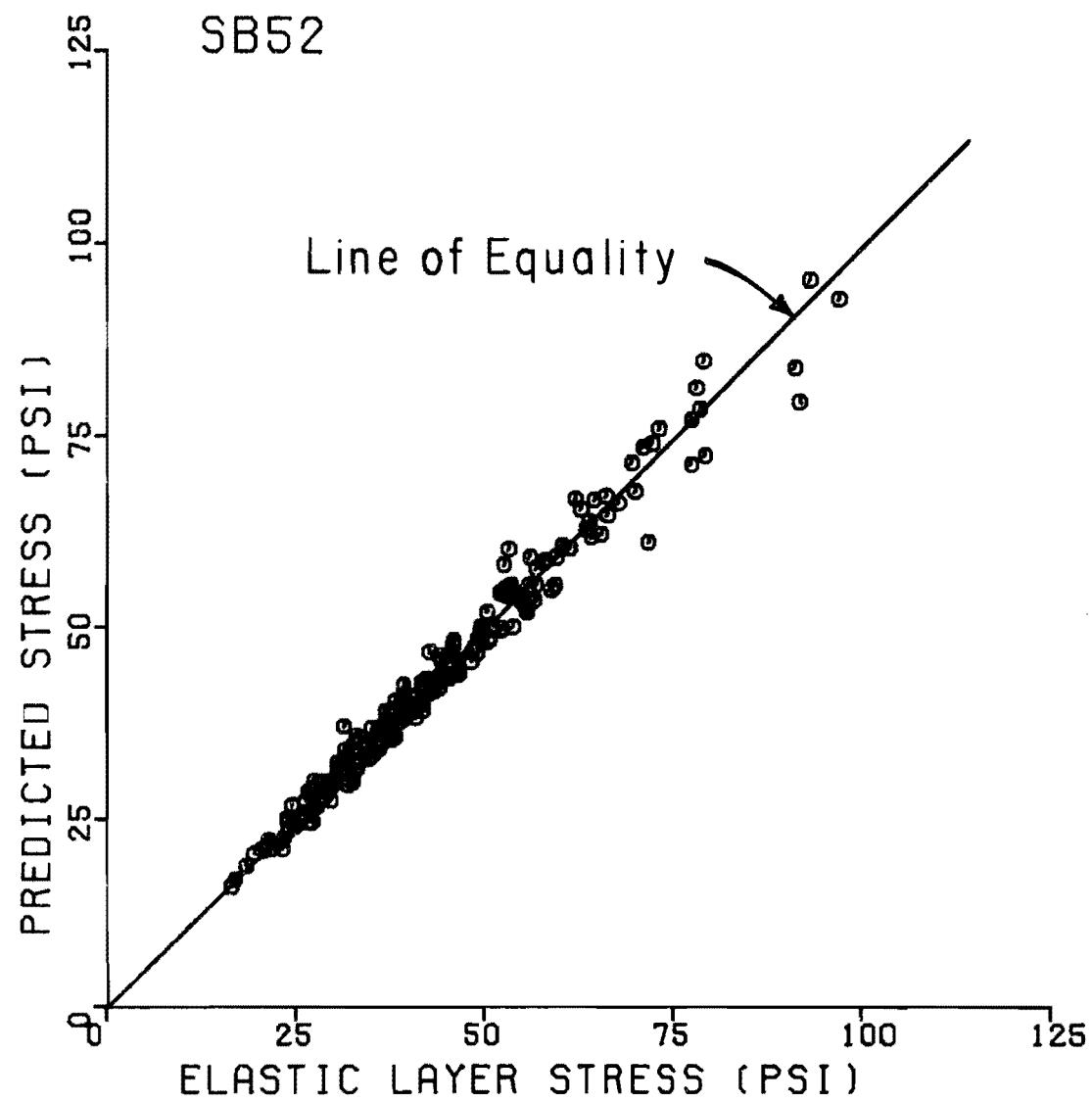
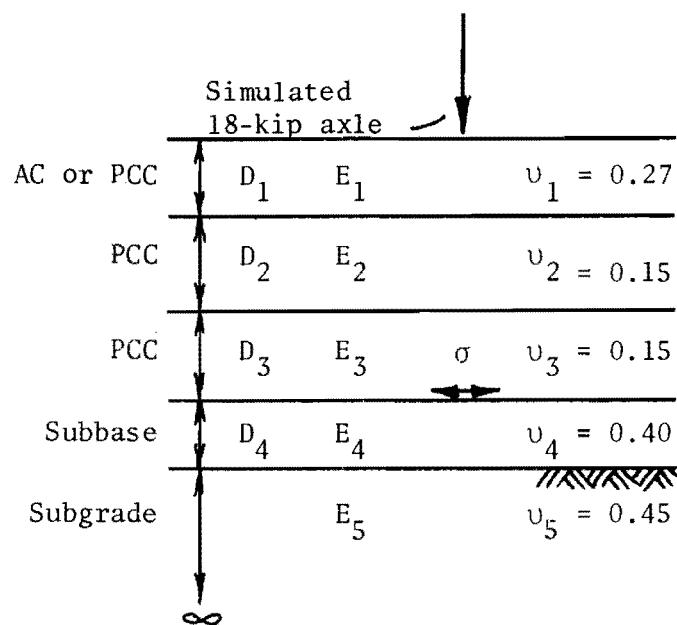


Fig B.14. Illustration of predictive accuracy of SB52 equation.

Pavement Structure  
and Response:

(Code: SB53)



Details of the Experiment:

1. Fractional factorial, 9 factors, no. of observations =  $\frac{1}{81} \times 3^9 = 243$
2. Levels of the significant factors:

Factors	Levels		
	High	Medium	Low
$E_1$ (psi)	6,250,000	3,250,000	250,000
$E_2$ (psi)	6,500,000	5,000,000	3,500,000
$E_3$ (psi)	6,500,000	5,000,000	3,500,000
$E_4$ (psi)	600,000	320,000	40,000
$E_5$ (psi)	20,000	11,000	2,000
$D_1$ (in)	8	6	4
$D_2$ (in)	8	7	6
$D_3$ (in)	10	8	6
$D_4$ (in)	12	9	6

(continued)

Fig B.15. SB53 Regression Model: for predicting stress in original PCC of 5-layer concrete pavement.

Prediction Equation - SB53:

	Term	Coefficient
$\log_{10} \sigma = \Sigma (\text{Term} \times \text{Coefficient})$		
	Intercept	$+ 2.256 \times 10^0$
$r^2 = 0.988$	$E_1$	$- 4.030 \times 10^{-8}$
std. error = 0.0167	$E_2$	$- 6.979 \times 10^{-9}$
	$E_3$	$+ 3.705 \times 10^{-8}$
	$E_4$	$- 1.970 \times 10^{-7}$
	$E_5$	$- 1.464 \times 10^{-5}$
	$D_1$	$- 1.614 \times 10^{-2}$
	$D_2$	$- 3.452 \times 10^{-2}$
	$D_3$	$- 3.388 \times 10^{-2}$
	$(E_1)^2$	$+ 4.159 \times 10^{-15}$
	$E_4 \times D_4$	$- 2.820 \times 10^{-8}$
	$E_1 \times D_1$	$- 3.127 \times 10^{-9}$
	$(E_5)^2$	$+ 3.159 \times 10^{-10}$
	$E_3 \times E_4$	$+ 2.993 \times 10^{-14}$
	$E_1 \times E_4$	$+ 1.410 \times 10^{-14}$

Fig B.15. (Continued)

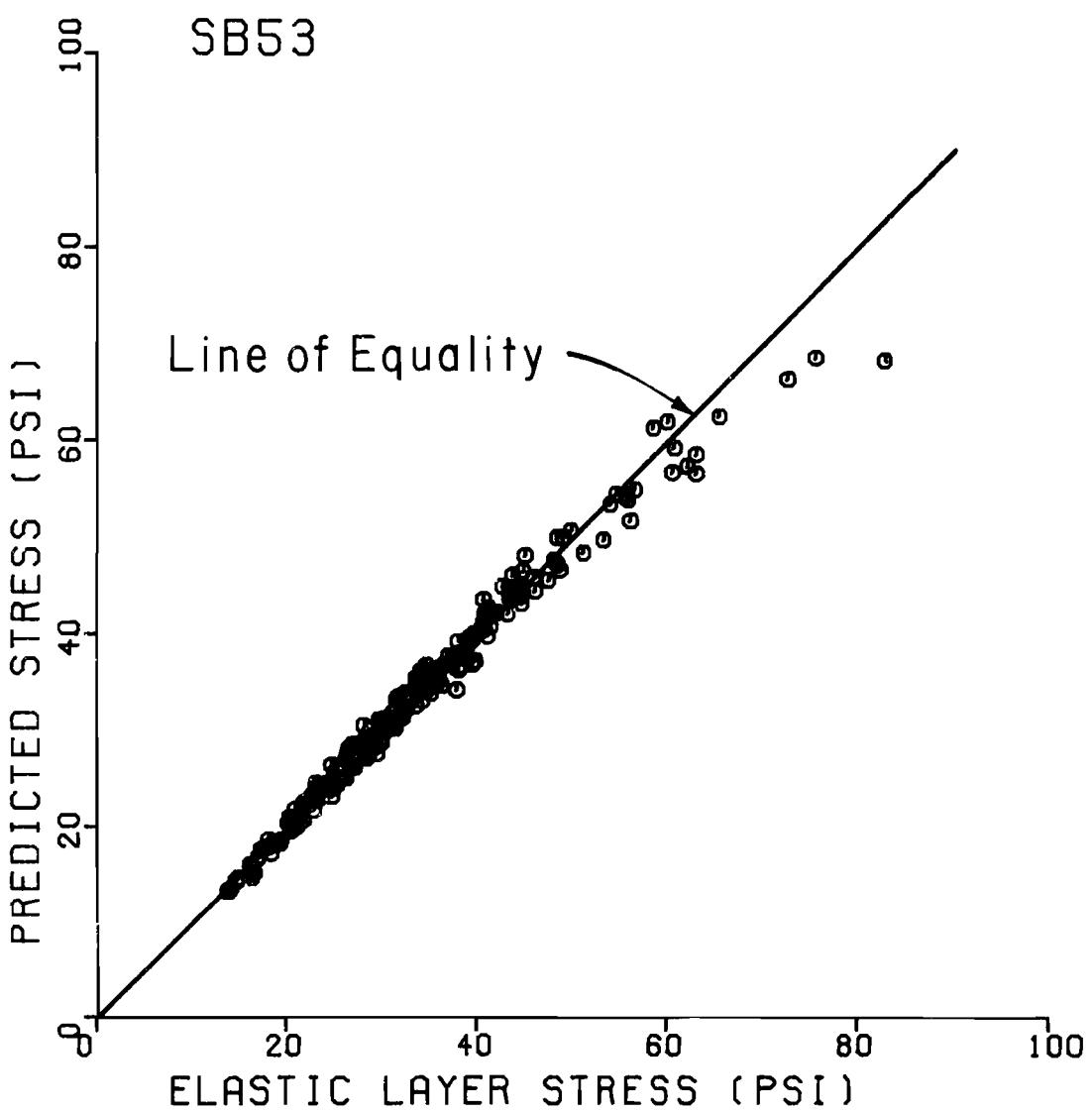
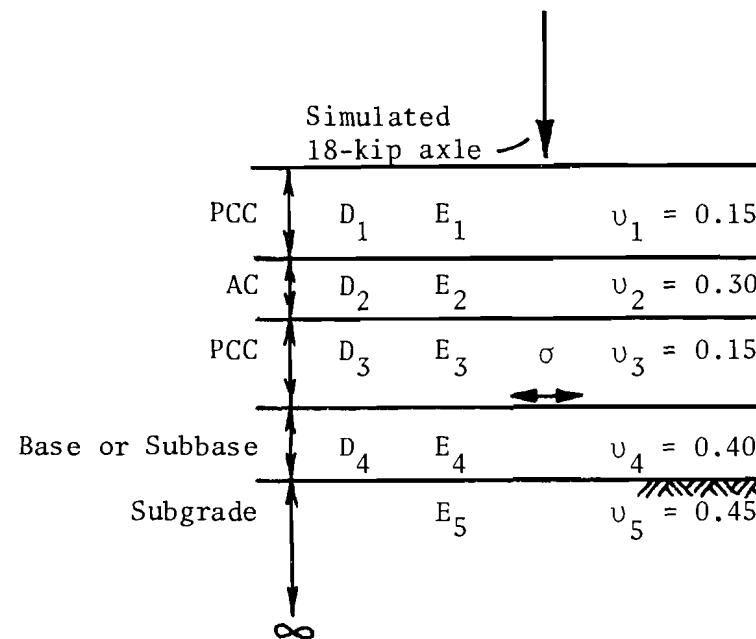


Fig B.16. Illustration of predictive accuracy of SB53 equation.

## Pavement Structure

and Response:

(Code: SU53)



## Details of the Experiment:

1. Fractional factorial, 9 factors, no. of observations =  $\frac{1}{81} \times 3^9 = 243$
2. Levels of the significant factors:

Factors	Levels		
	High	Medium	Low
E <sub>1</sub> (psi)	6,500,000	5,000,000	3,500,000
E <sub>2</sub> (psi)	550,000	300,000	50,000
E <sub>3</sub> (psi)	6,500,000	5,000,000	3,500,000
E <sub>4</sub> (psi)	600,000	320,000	40,000
E <sub>5</sub> (psi)	20,000	11,000	2,000
D <sub>1</sub> (in)	8	7	6
D <sub>2</sub> (in)	7	4	1
D <sub>3</sub> (in)	10	8	6
D <sub>4</sub> (in)	12	9	6

(continued)

Fig B.17. SU53 Regression Model: for predicting stress in original PCC of 5-layer concrete pavement with an unbonded PCC overlay.

Prediction Equation - SU53:

$$\log_{10} \sigma = \Sigma (\text{Term} \times \text{Coefficient})$$

$$r^2 = 0.983$$

$$\text{std. error} = 0.0215$$

Term	Coefficient
Intercept	+ 2.453 x 10 <sup>0</sup>
E <sub>1</sub>	- 1.730 x 10 <sup>-8</sup>
E <sub>3</sub>	+ 4.018 x 10 <sup>-8</sup>
E <sub>4</sub>	- 5.075 x 10 <sup>-7</sup>
E <sub>5</sub>	- 1.566 x 10 <sup>-5</sup>
D <sub>1</sub>	- 4.548 x 10 <sup>-2</sup>
D <sub>2</sub>	- 4.037 x 10 <sup>-2</sup>
D <sub>3</sub>	- 3.535 x 10 <sup>-2</sup>
D <sub>4</sub>	- 3.833 x 10 <sup>-3</sup>
E <sub>4</sub> x D <sub>4</sub>	- 3.892 x 10 <sup>-8</sup>
E <sub>2</sub> x E <sub>4</sub>	+ 2.597 x 10 <sup>-13</sup>
(E <sub>5</sub> ) <sup>2</sup>	+ 3.087 x 10 <sup>-10</sup>
E <sub>3</sub> x E <sub>4</sub>	+ 4.087 x 10 <sup>-14</sup>
E <sub>4</sub> x D <sub>3</sub>	+ 2.717 x 10 <sup>-8</sup>
E <sub>2</sub> x D <sub>3</sub>	- 2.861 x 10 <sup>-8</sup>
D <sub>2</sub> x D <sub>3</sub>	+ 1.739 x 10 <sup>-3</sup>
E <sub>2</sub> x D <sub>4</sub>	+ 1.071 x 10 <sup>-8</sup>
E <sub>2</sub> x E <sub>5</sub>	+ 3.848 x 10 <sup>-12</sup>

Fig B.17. (Continued)

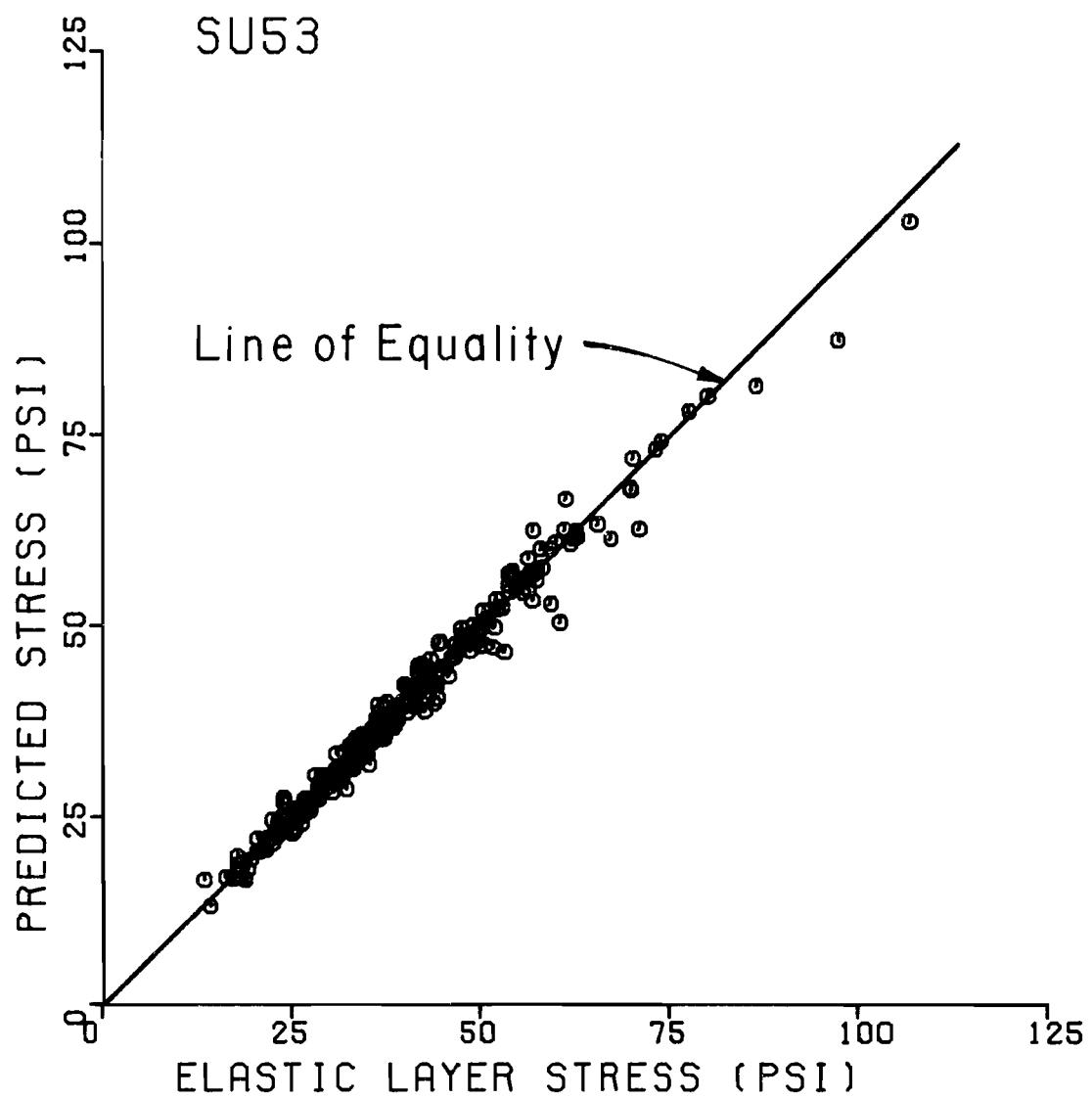
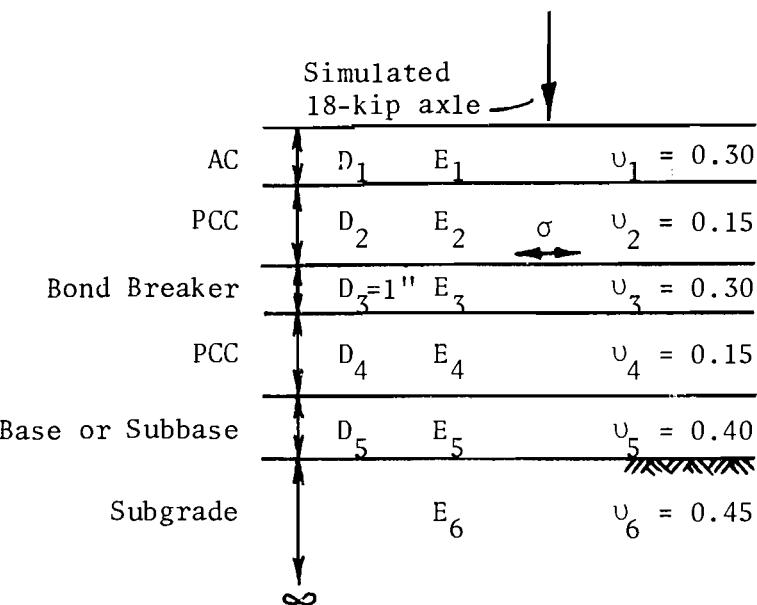


Fig B.18. Illustration of predictive accuracy of SU53 equation.

Pavement Structure  
and Response:

(Code: SU62)



Details of the Experiment:

1. Fractional factorial, 10 factors, no. of observations =  $\frac{1}{243} \times 3^{10} = 243$
2. Levels of the significant factors:

Factors	Levels		
	High	Medium	Low
$E_1$ (psi)	800,000	500,000	200,000
$E_2$ (psi)	6,500,000	5,000,000	3,500,000
$E_3$ (psi)	200,000	110,000	20,000
$E_4$ (psi)	6,500,000	5,000,000	3,500,000
$E_5$ (psi)	600,000	320,000	40,000
$E_6$ (psi)	20,000	11,000	2,000
$D_1$ (in)	8	6	4
$D_2$ (in)	8	7	6
$D_4$ (in)	10	8	6
$D_5$ (in)	12	9	6

(continued)

Note:  $D_3$  in experiment was fixed at 1" to simulate a thin bond breaker.

Fig B.19. SU62 Regression Model: for predicting stress in concrete overlay of 6-layer concrete pavement.

Prediction Equation - SU62:

$$\log_{10} \sigma = \sum (\text{Term} \times \text{Coefficient})$$

$$r^2 = 0.987$$

$$\text{std. error} = 0.0260$$

Term	Coefficient
Intercept	+ 2.471 x 10 <sup>0</sup>
$E_1$	- 9.153 x 10 <sup>-8</sup>
$E_2$	+ 4.652 x 10 <sup>-8</sup>
$E_3$	- 4.790 x 10 <sup>-6</sup>
$E_5$	- 1.098 x 10 <sup>-7</sup>
$D_1$	- 3.761 x 10 <sup>-2</sup>
$D_2$	- 5.153 x 10 <sup>-2</sup>
$D_4$	- 1.926 x 10 <sup>-2</sup>
$D_5$	- 3.928 x 10 <sup>-3</sup>
$(E_3)^2$	+ 8.508 x 10 <sup>-12</sup>
$E_2 \times E_3$	+ 2.205 x 10 <sup>-13</sup>
$E_3 \times D_4$	- 1.166 x 10 <sup>-7</sup>
$E_3 \times E_4$	- 1.620 x 10 <sup>-13</sup>
$E_3 \times D_2$	+ 1.440 x 10 <sup>-7</sup>
$E_1 \times E_3$	+ 4.716 x 10 <sup>-13</sup>

Fig B.19. (Continued)

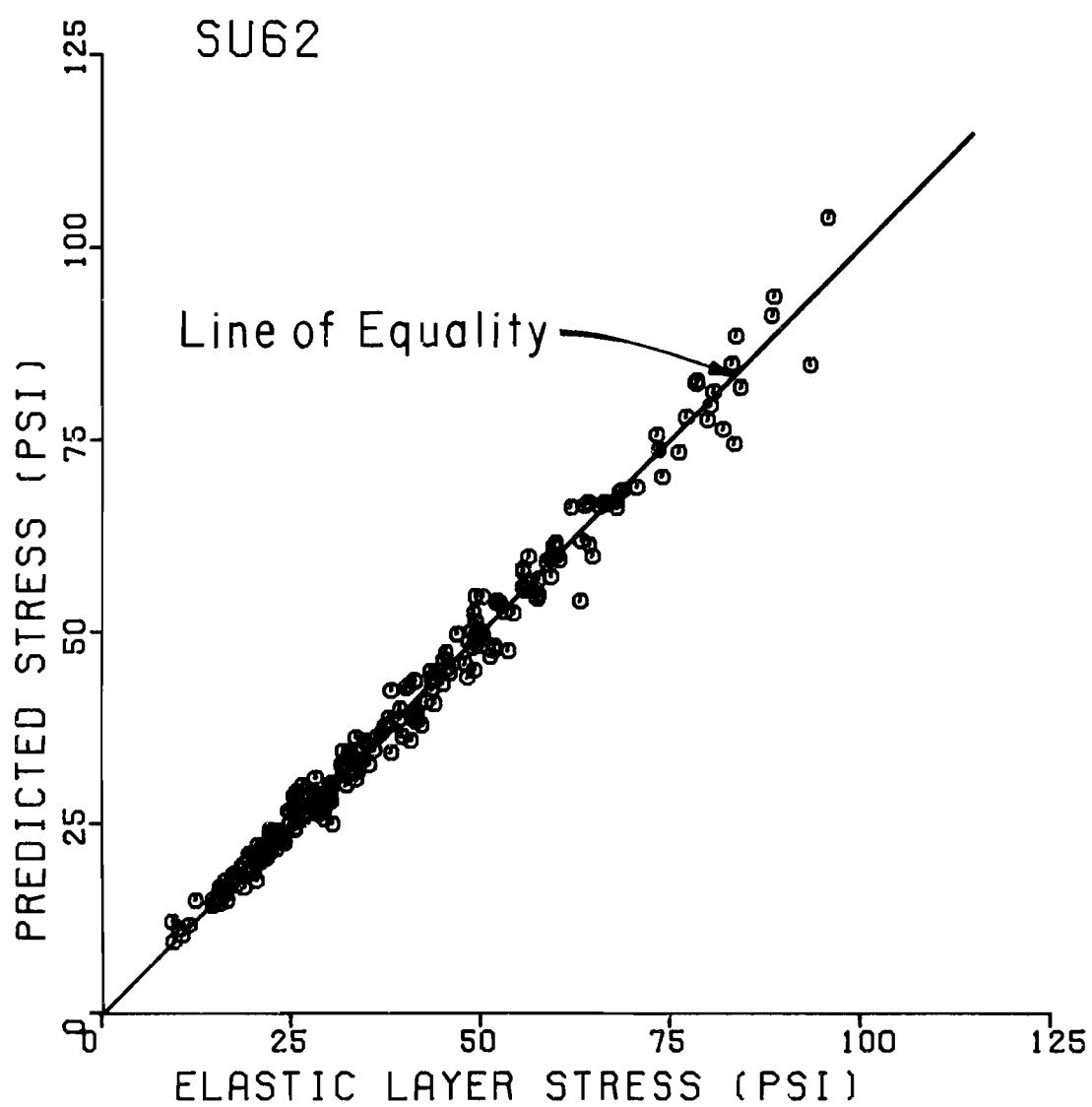
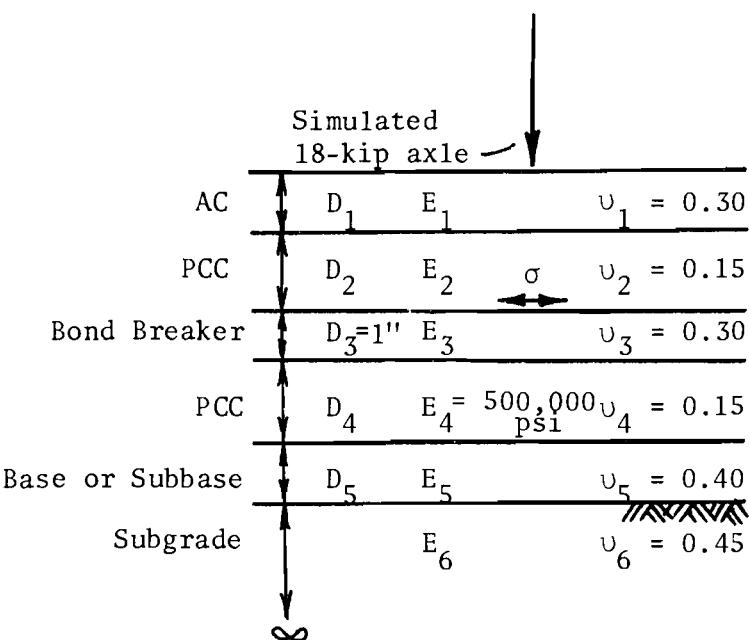


Fig B.20. Illustration of predictive accuracy of SU62 equation.

## Pavement Structure

and Response:

(Code: SU62C)



## Details of the Experiment:

1. Fractional factorial, 9 factors, no. of observation =  $\frac{1}{81} \times 3^9 = 243$
2. Levels of the significant factors:

		Levels		
Factors		High	Medium	Low
$E_1$	(psi)	800,000	500,000	200,000
$E_2$	(psi)	6,500,000	5,000,000	3,500,000
$E_3$	(psi)	200,000	110,000	20,000
$E_5$	(psi)	500,000	270,000	40,000
$E_6$	(psi)	20,000	11,000	2,000
$D_1$	(in)	8	6	4
$D_2$	(in)	8	7	6
$D_4$	(in)	10	8	6
$D_5$	(in)	12	9	6

(continued)

Note:  $D_3$  in this experiment was fixed at 1" to simulate a thin bond breaker.  
 $E_4$  was fixed at 500,000 psi to simulate cracked PCC.

Fig B.21. SU62C Regression Model: for predicting stress in concrete overlay of 6-layer concrete pavement (original PCC cracked).

Prediction Equation - SU62C:

$$\log_{10} \sigma = \sum (\text{Term} \times \text{Coefficient})$$

$$r^2 = 0.988$$

$$\text{std. error} = 0.0167$$

Term	Coefficient
Intercept	+ 2.686 x 10 <sup>0</sup>
E <sub>1</sub>	- 1.034 x 10 <sup>-7</sup>
E <sub>2</sub>	+ 4.675 x 10 <sup>-8</sup>
E <sub>3</sub>	- 2.873 x 10 <sup>-6</sup>
E <sub>5</sub>	- 5.247 x 10 <sup>-7</sup>
E <sub>6</sub>	- 1.705 x 10 <sup>-5</sup>
D <sub>1</sub>	- 3.231 x 10 <sup>-2</sup>
D <sub>2</sub>	- 5.267 x 10 <sup>-2</sup>
D <sub>4</sub>	- 2.267 x 10 <sup>-2</sup>
D <sub>5</sub>	- 6.684 x 10 <sup>-3</sup>
(E <sub>3</sub> ) <sup>2</sup>	+ 5.357 x 10 <sup>-12</sup>
E <sub>5</sub> x E <sub>6</sub>	+ 8.304 x 10 <sup>-12</sup>
(E <sub>5</sub> ) <sup>2</sup>	+ 4.216 x 10 <sup>-13</sup>
E <sub>3</sub> x E <sub>5</sub>	- 6.900 x 10 <sup>-13</sup>
E <sub>2</sub> x E <sub>3</sub>	+ 1.037 x 10 <sup>-13</sup>
E <sub>5</sub> x D <sub>5</sub>	- 2.004 x 10 <sup>-8</sup>
(E <sub>6</sub> ) <sup>2</sup>	+ 1.903 x 10 <sup>-10</sup>
E <sub>6</sub> x D <sub>5</sub>	+ 3.434 x 10 <sup>-7</sup>
E <sub>5</sub> x D <sub>4</sub>	+ 1.987 x 10 <sup>-8</sup>
E <sub>3</sub> x D <sub>2</sub>	+ 9.607 x 10 <sup>-8</sup>
E <sub>6</sub> x D <sub>4</sub>	+ 4.388 x 10 <sup>-7</sup>
E <sub>3</sub> x D <sub>4</sub>	- 4.152 x 10 <sup>-8</sup>
E <sub>1</sub> x E <sub>3</sub>	+ 2.548 x 10 <sup>-13</sup>

Fig B.21. (Continued)

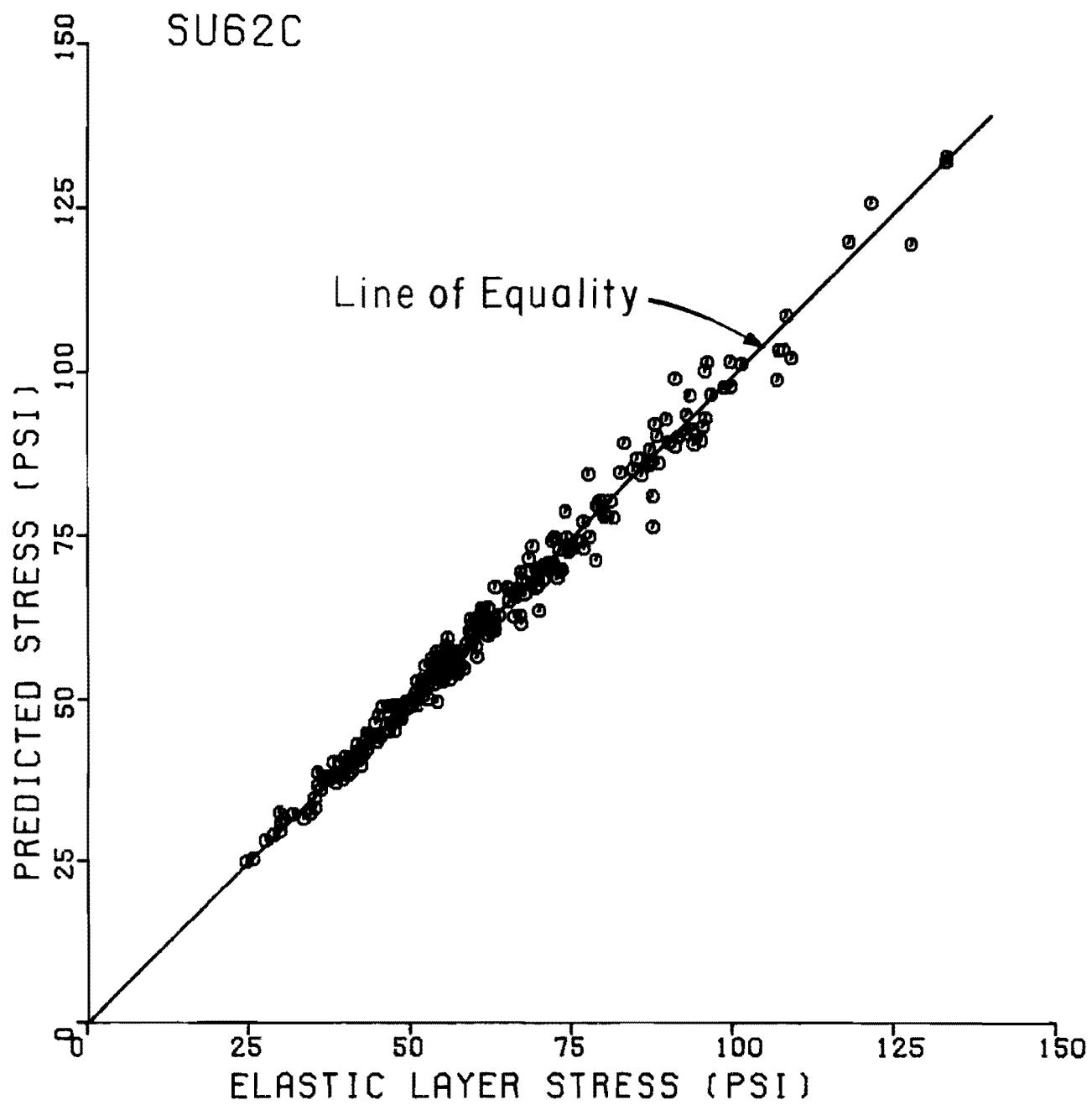
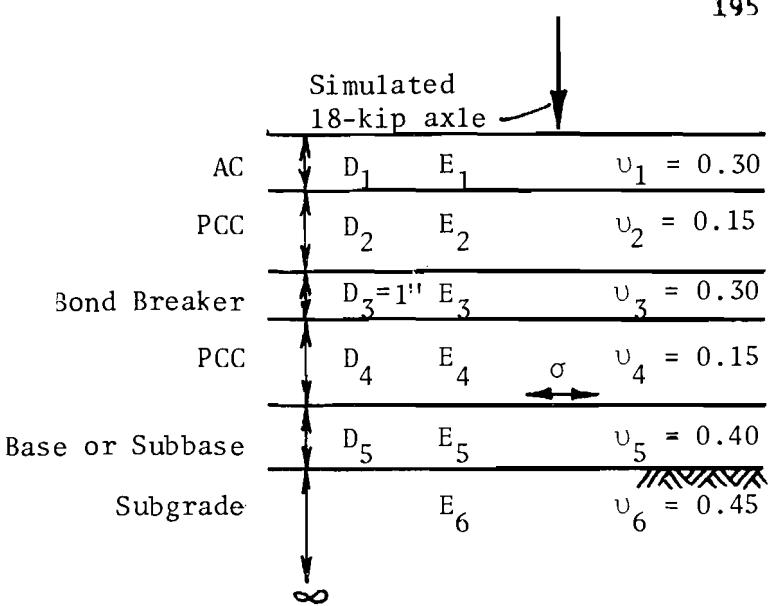


Fig B.22. Illustration of predictive accuracy of SU62C equation.

Pavement Structure  
and Response:

(Code: SU64)



Details of the Experiment:

1. Fractional factorial, 10 factors, no. of observations =  $\frac{1}{243} \times 3^{10} = 243$
2. Levels of the significant factors:

Factors	Levels		
	High	Medium	Low
E <sub>1</sub> (psi)	800,000	500,000	200,000
E <sub>2</sub> (psi)	6,500,000	5,000,000	3,500,000
E <sub>3</sub> (psi)	200,000	110,000	20,000
E <sub>4</sub> (psi)	6,500,000	5,000,000	3,500,000
E <sub>5</sub> (psi)	600,000	320,000	40,000
E <sub>6</sub> (psi)	20,000	11,000	2,000
D <sub>1</sub> (in)	8	6	4
D <sub>2</sub> (in)	8	7	6
D <sub>4</sub> (in)	10	8	6
D <sub>5</sub> (in)	12	9	6

Note: D<sub>3</sub> in experiment was fixed at 1" to simulate a thin bond breaker.

(continued)

Fig B.23. SU64 Regression Model: for predicting stress in original PCC of 6-layer concrete pavement.

Prediction Equation - SU64:

$$\log_{10} \sigma = \sum (\text{Term} \times \text{Coefficient})$$

$$r^2 = 0.983$$

$$\text{std. error} = 0.0204$$

Term	Coefficient
Intercept	+ 2.257 x 10 <sup>0</sup>
$E_2$	- 1.226 x 10 <sup>-8</sup>
$E_3$	+ 7.180 x 10 <sup>-7</sup>
$E_4$	+ 4.318 x 10 <sup>-8</sup>
$E_5$	- 4.756 x 10 <sup>-7</sup>
$E_6$	- 1.776 x 10 <sup>-5</sup>
$D_1$	- 1.155 x 10 <sup>-2</sup>
$D_2$	- 4.257 x 10 <sup>-2</sup>
$D_4$	- 2.253 x 10 <sup>-2</sup>
$D_5$	- 4.381 x 10 <sup>-3</sup>
$E_5 \times D_5$	- 4.004 x 10 <sup>-8</sup>
$(E_6)^2$	+ 3.490 x 10 <sup>-10</sup>
$E_4 \times E_5$	+ 3.949 x 10 <sup>-14</sup>
$E_5 \times D_4$	+ 2.659 x 10 <sup>-8</sup>
$E_3 \times E_5$	+ 5.826 x 10 <sup>-13</sup>
$E_3 \times D_4$	- 7.963 x 10 <sup>-8</sup>
$(E_3)^2$	- 2.212 x 10 <sup>-12</sup>
$E_3 \times E_6$	+ 1.148 x 10 <sup>-11</sup>
$E_1 \times D_1$	- 1.533 x 10 <sup>-8</sup>
$E_3 \times D_5$	+ 3.088 x 10 <sup>-8</sup>

Fig B.23. (Continued)

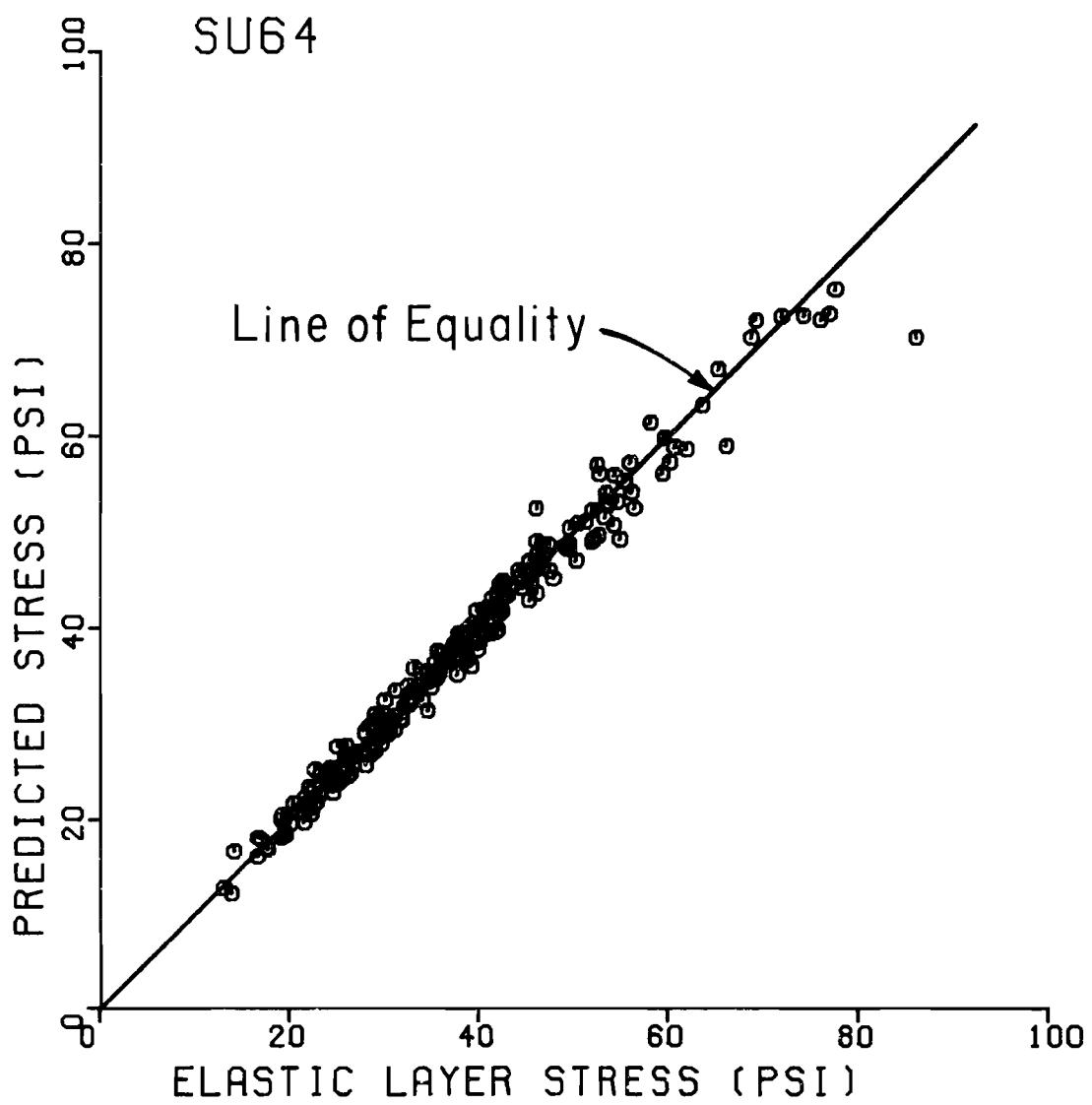


Fig B.24. Illustration of predictive accuracy of SU64 equation.

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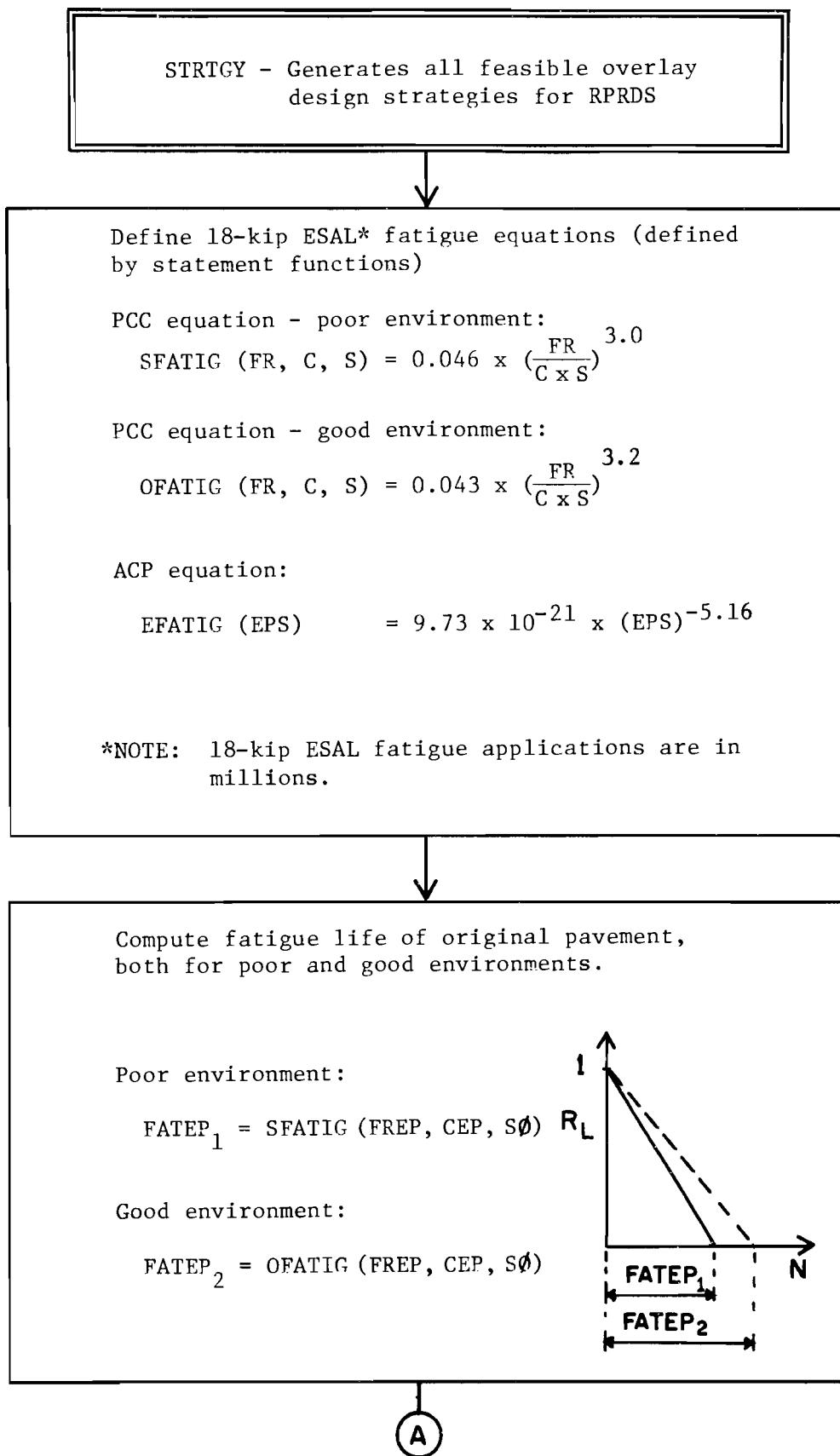
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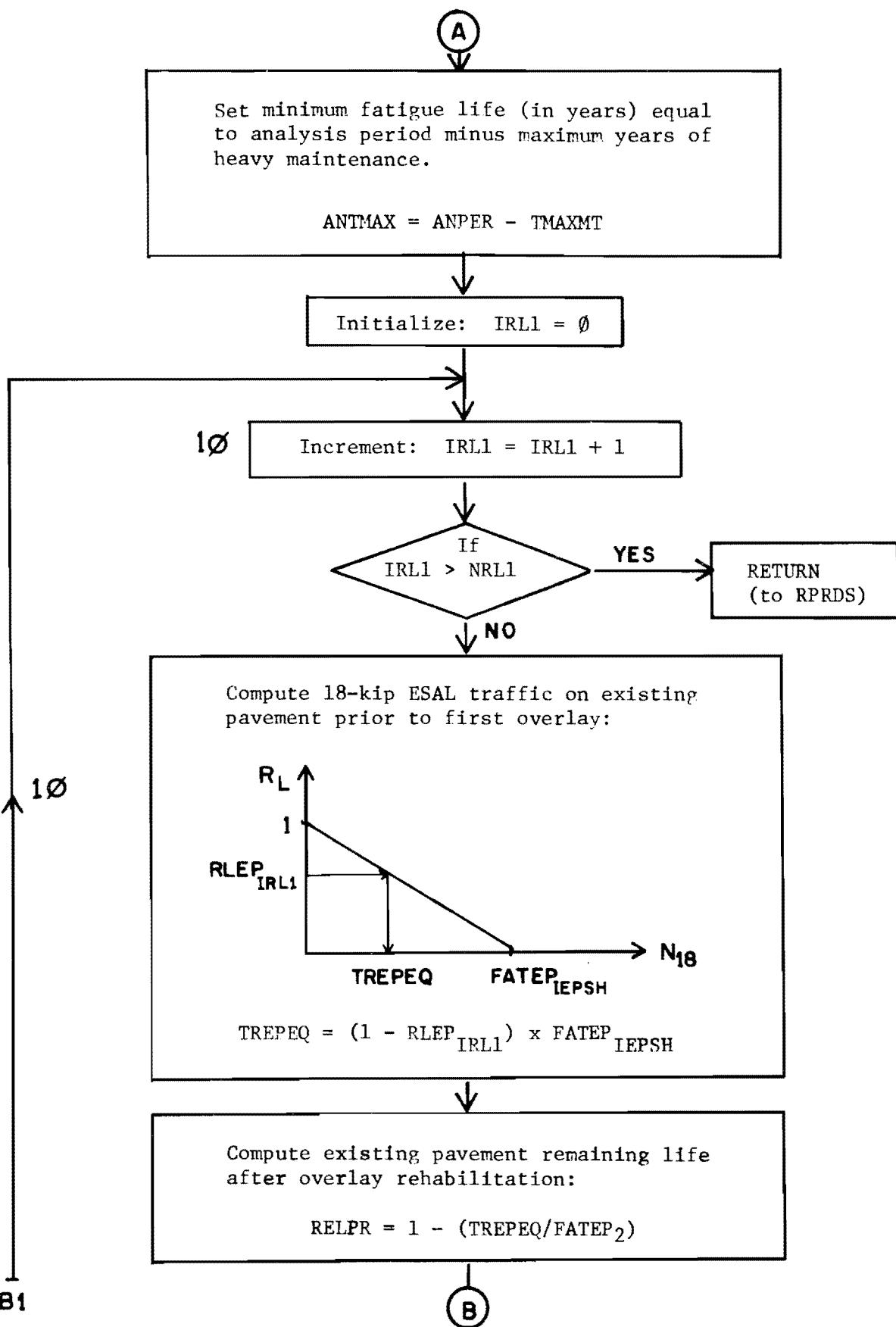
APPENDIX C  
FLOW DIAGRAM FOR STRGY ROUTINE

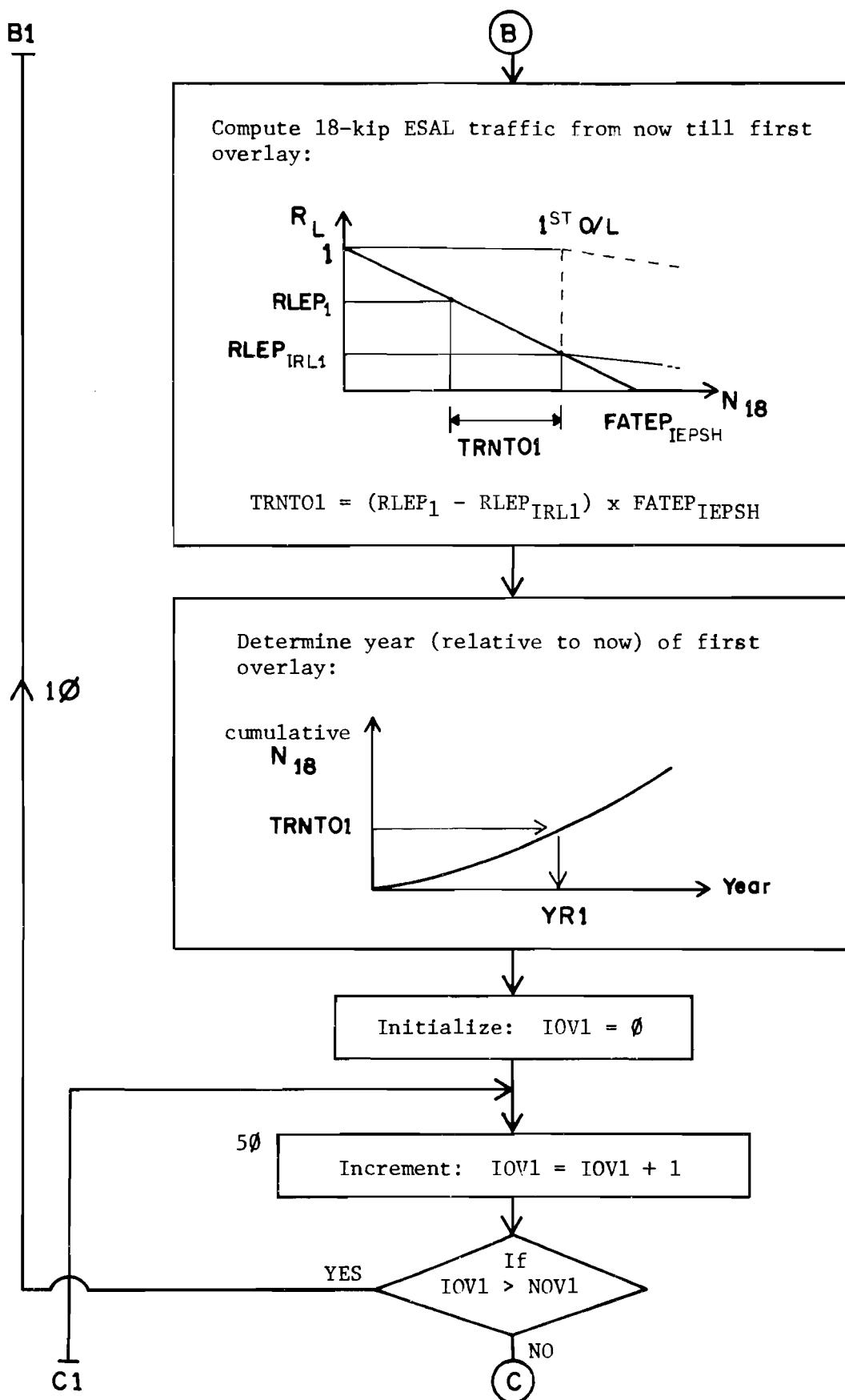
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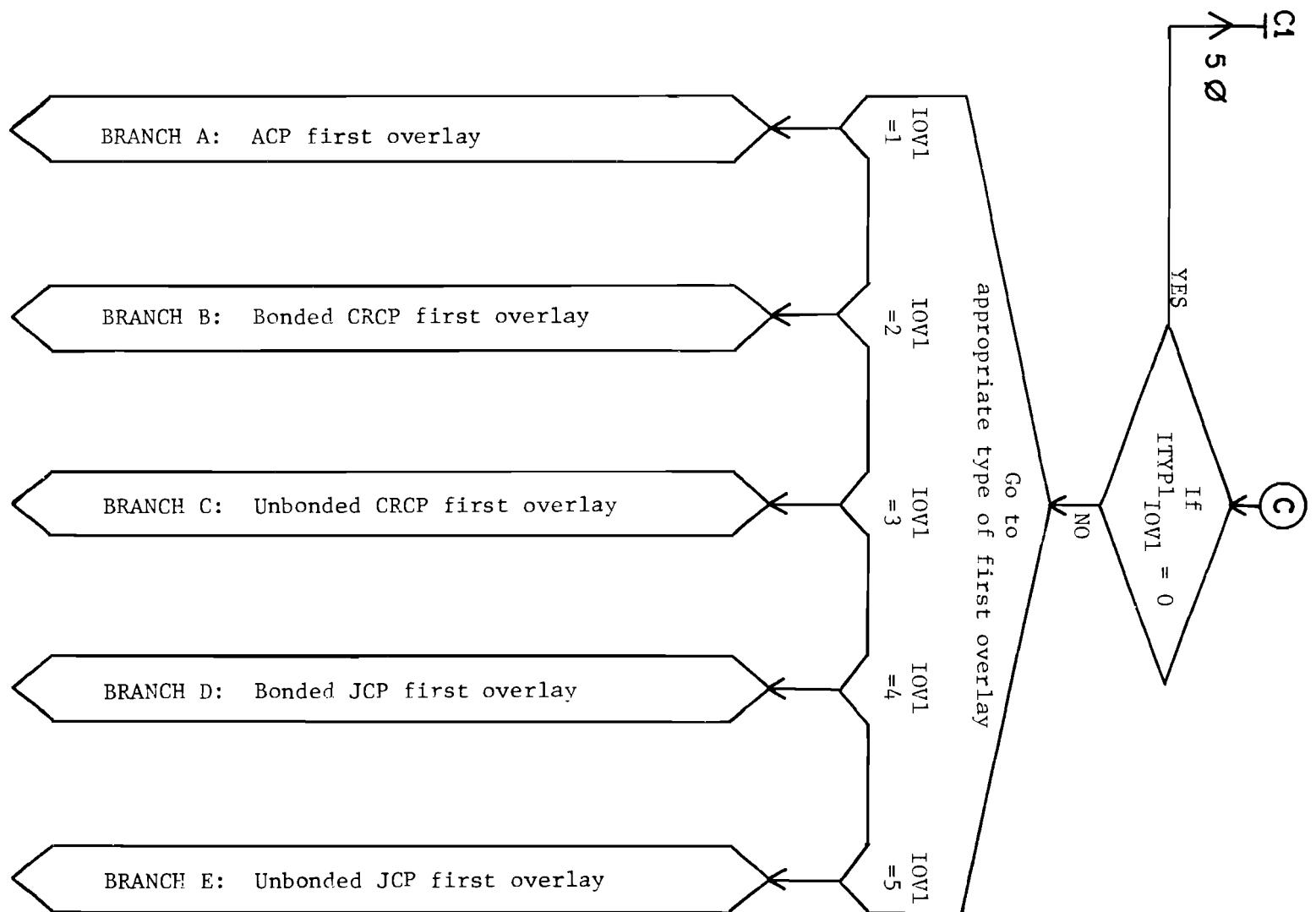
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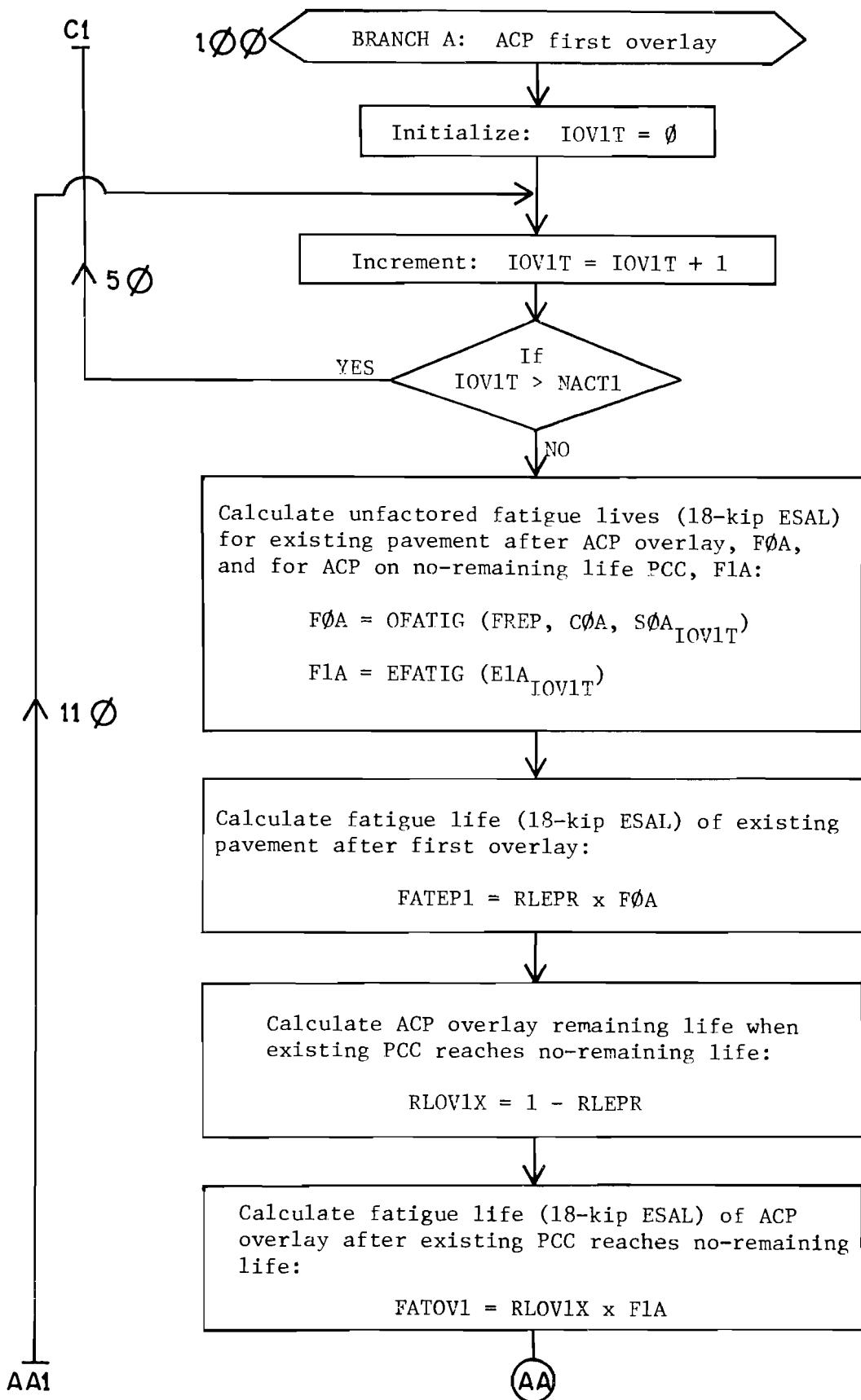
## APPENDIX C. FLOW DIAGRAM OF STRGY ROUTINE

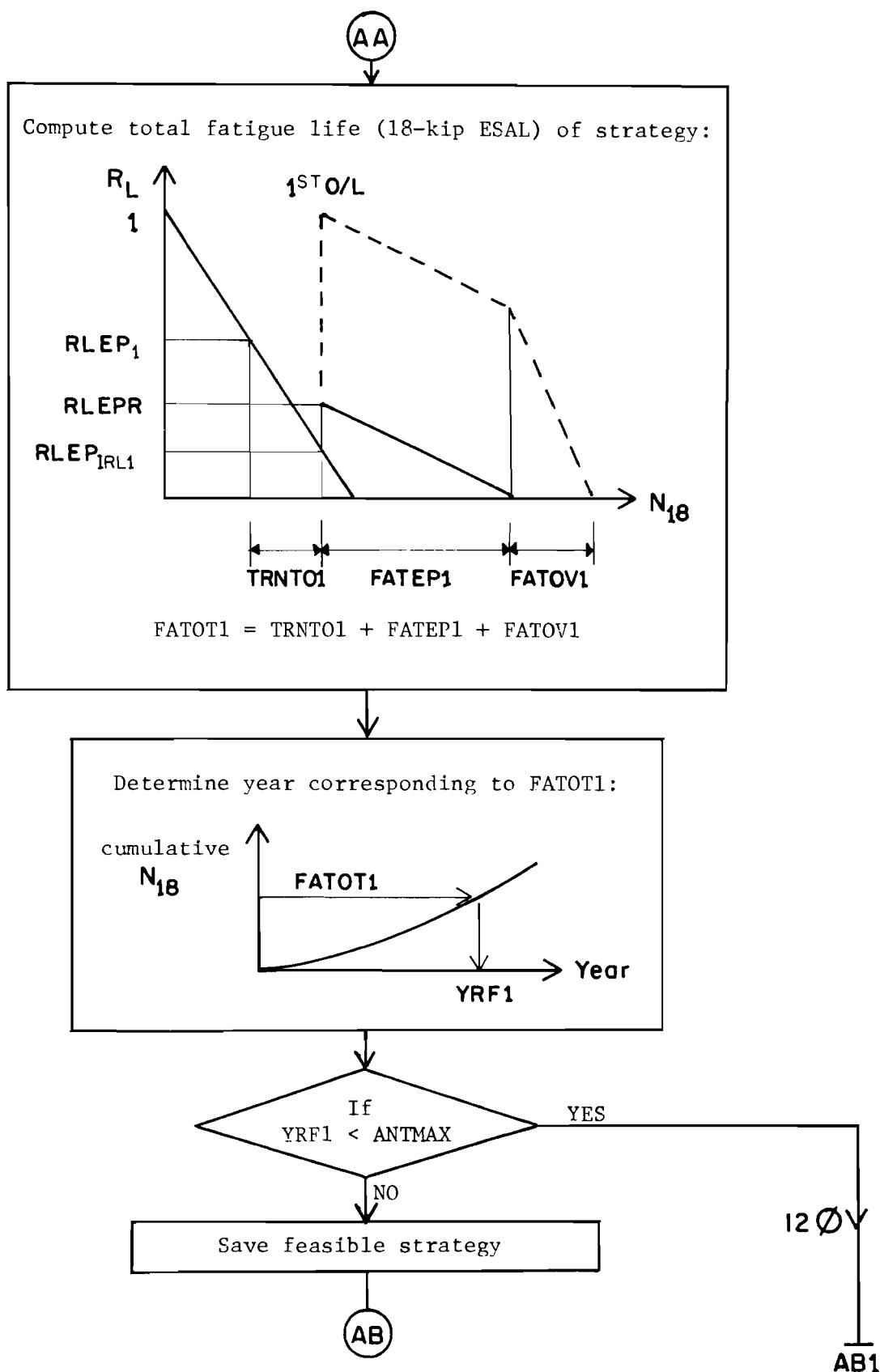


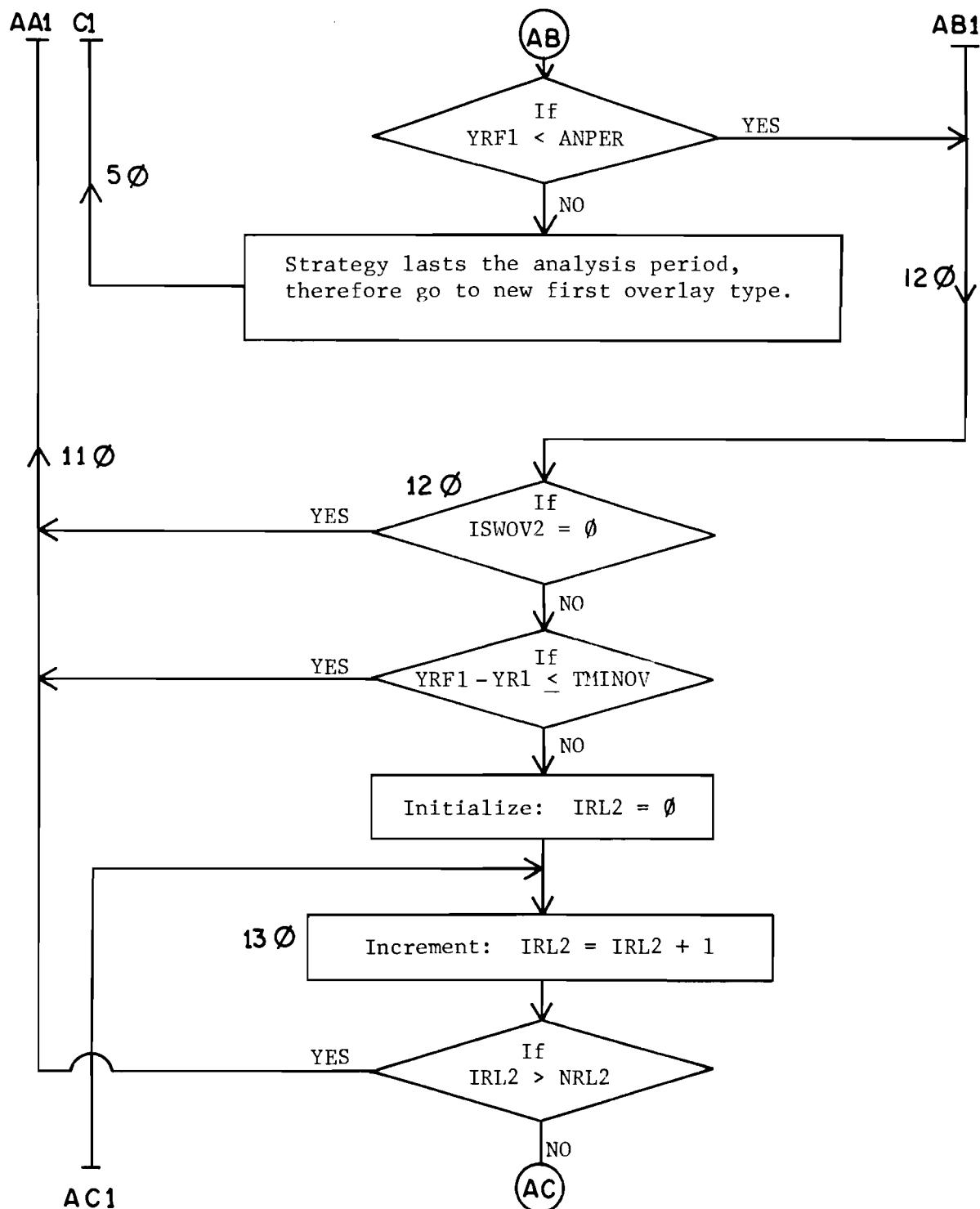


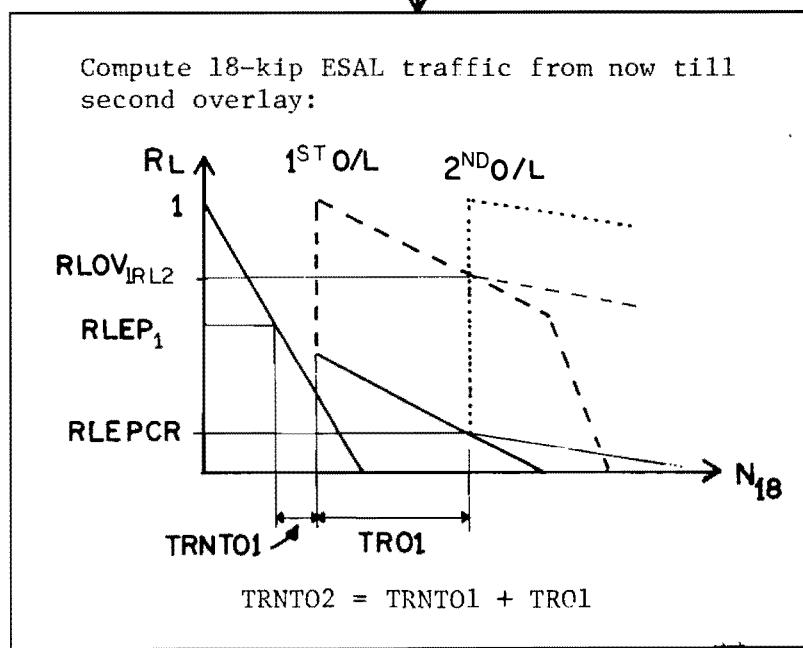
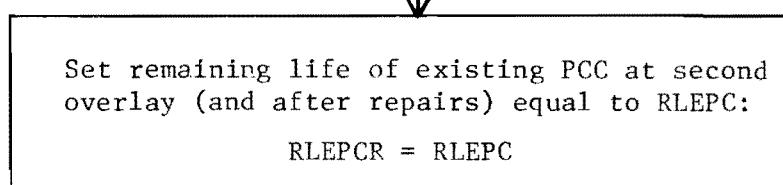
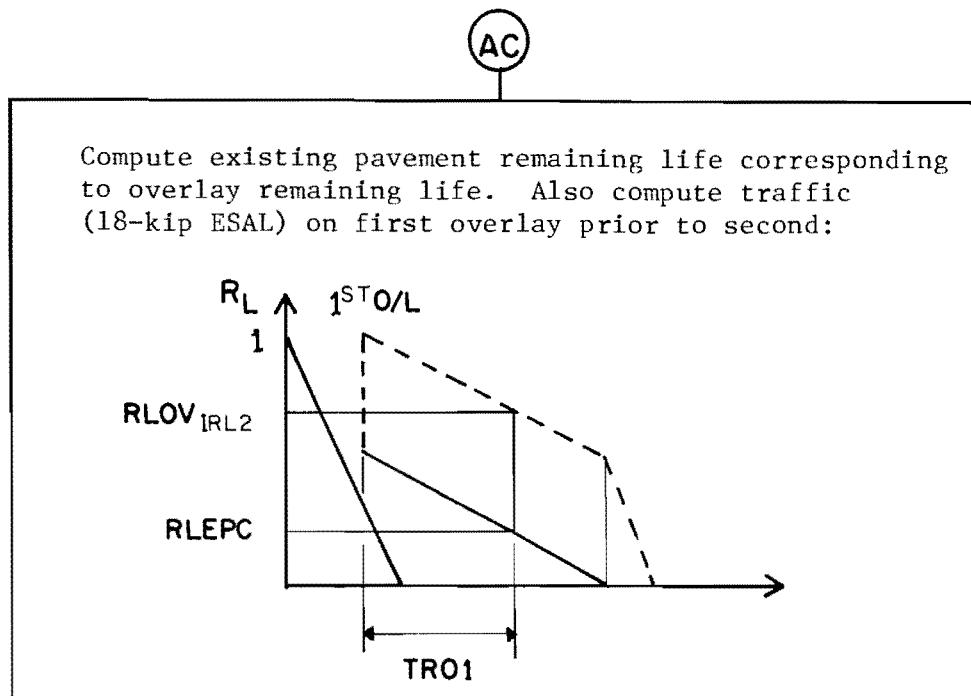


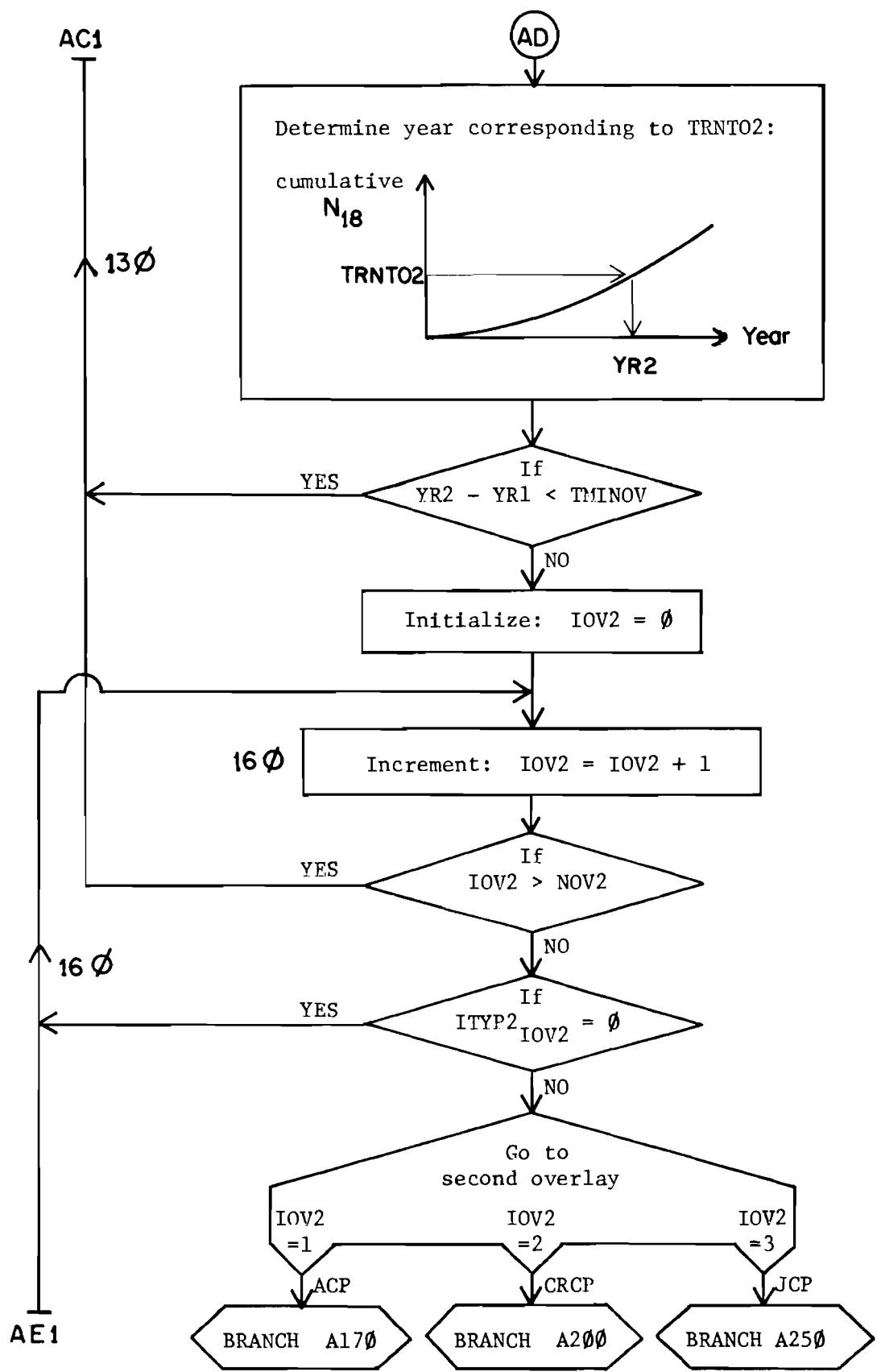


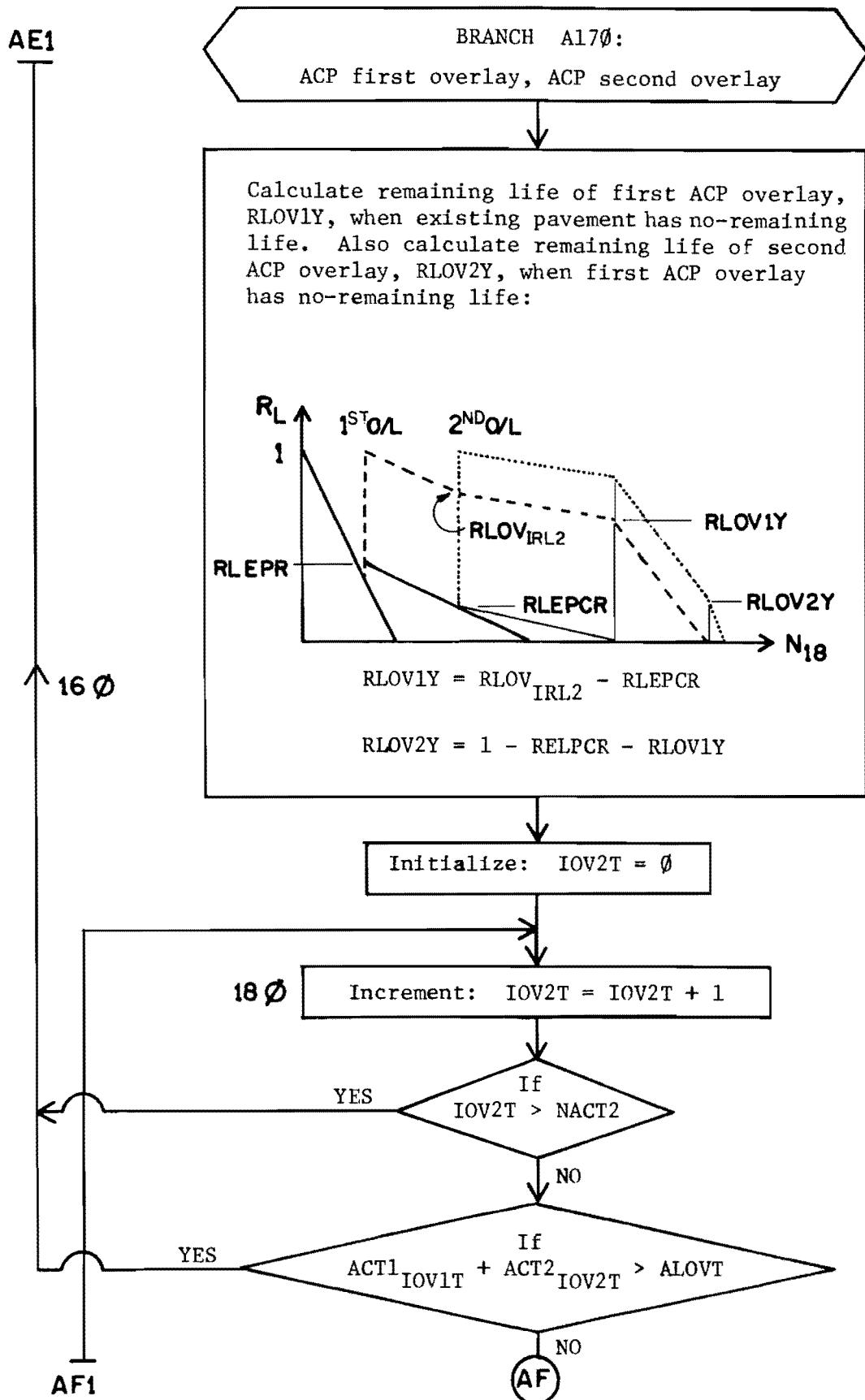


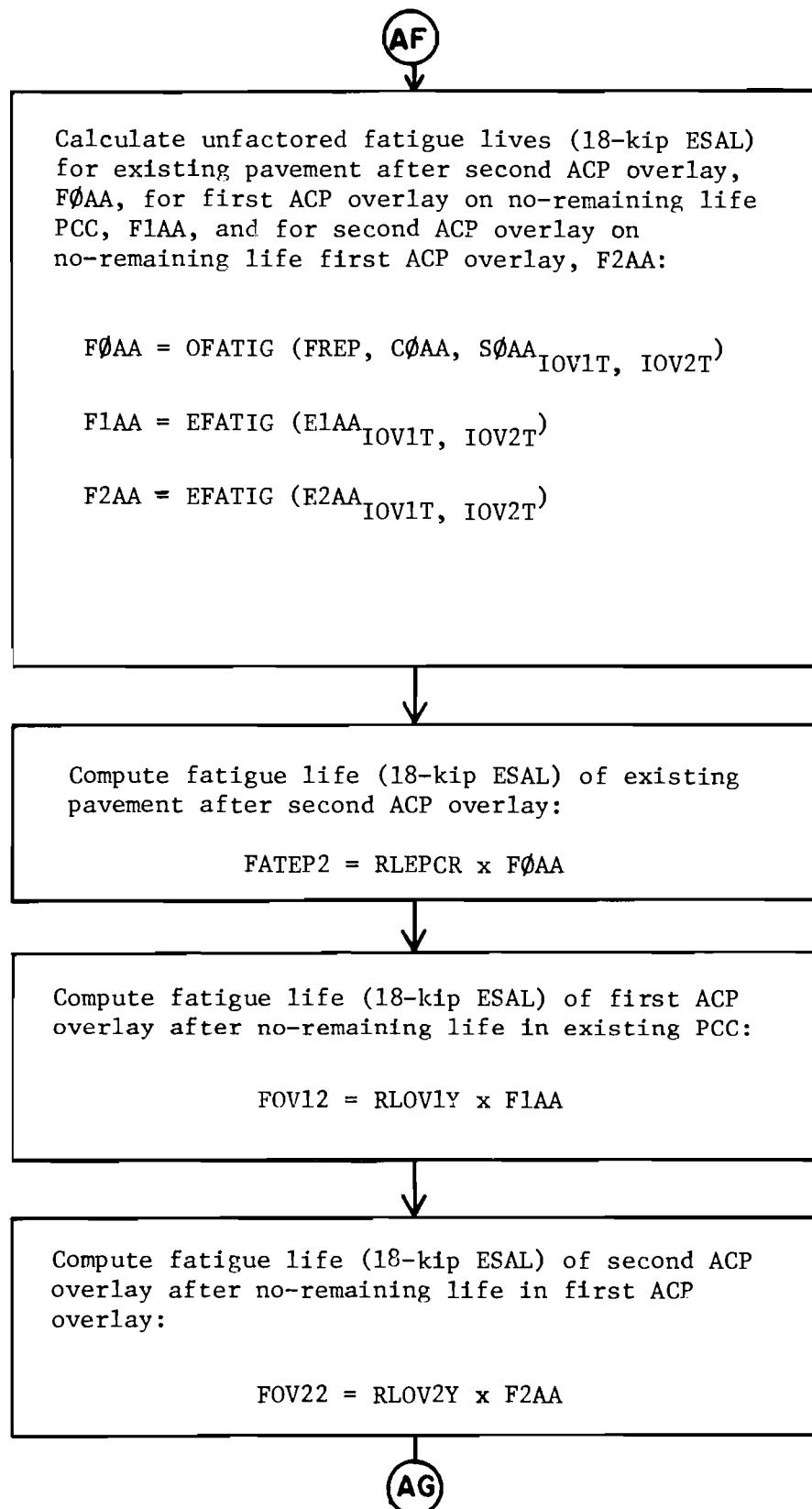


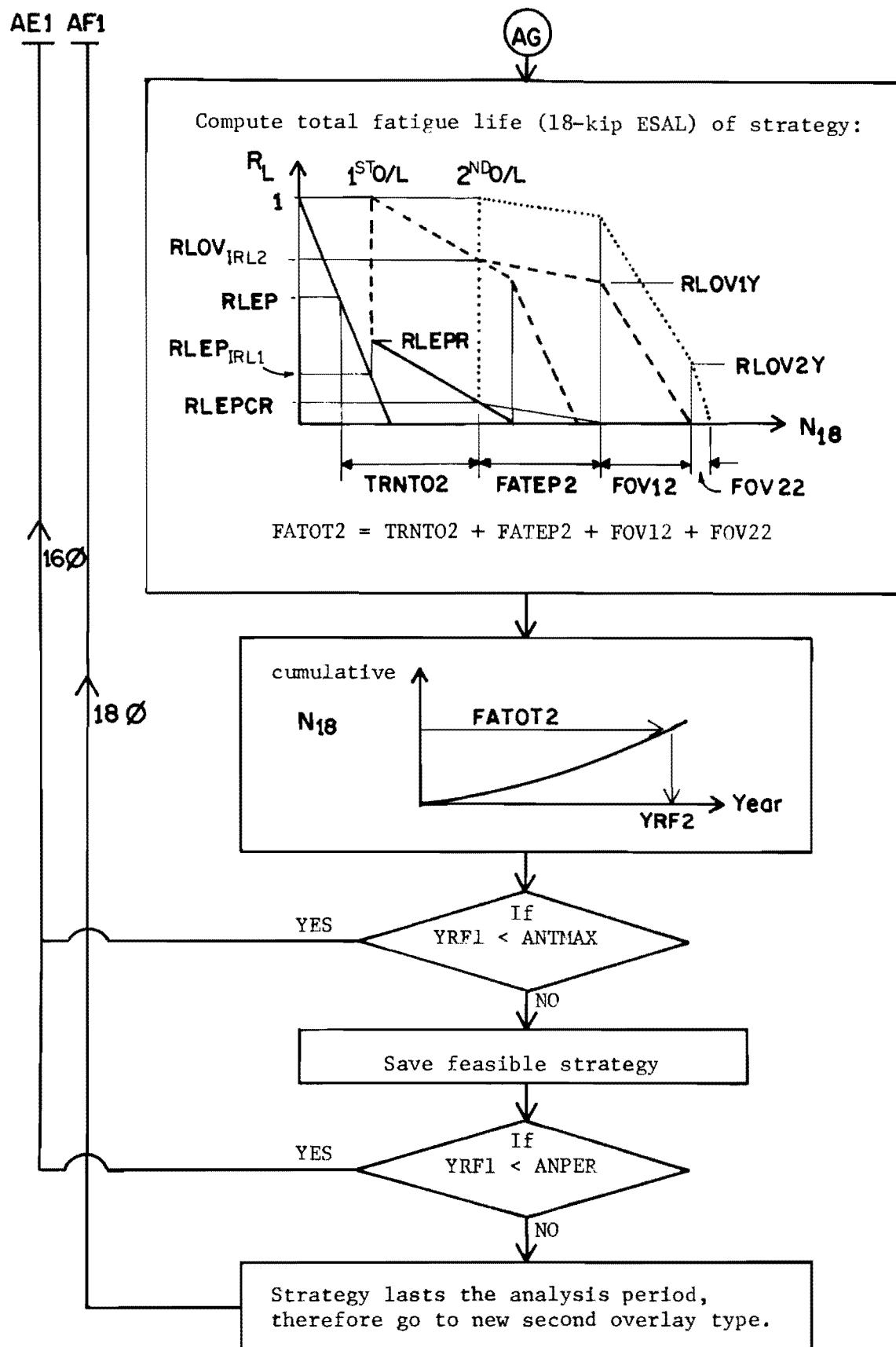


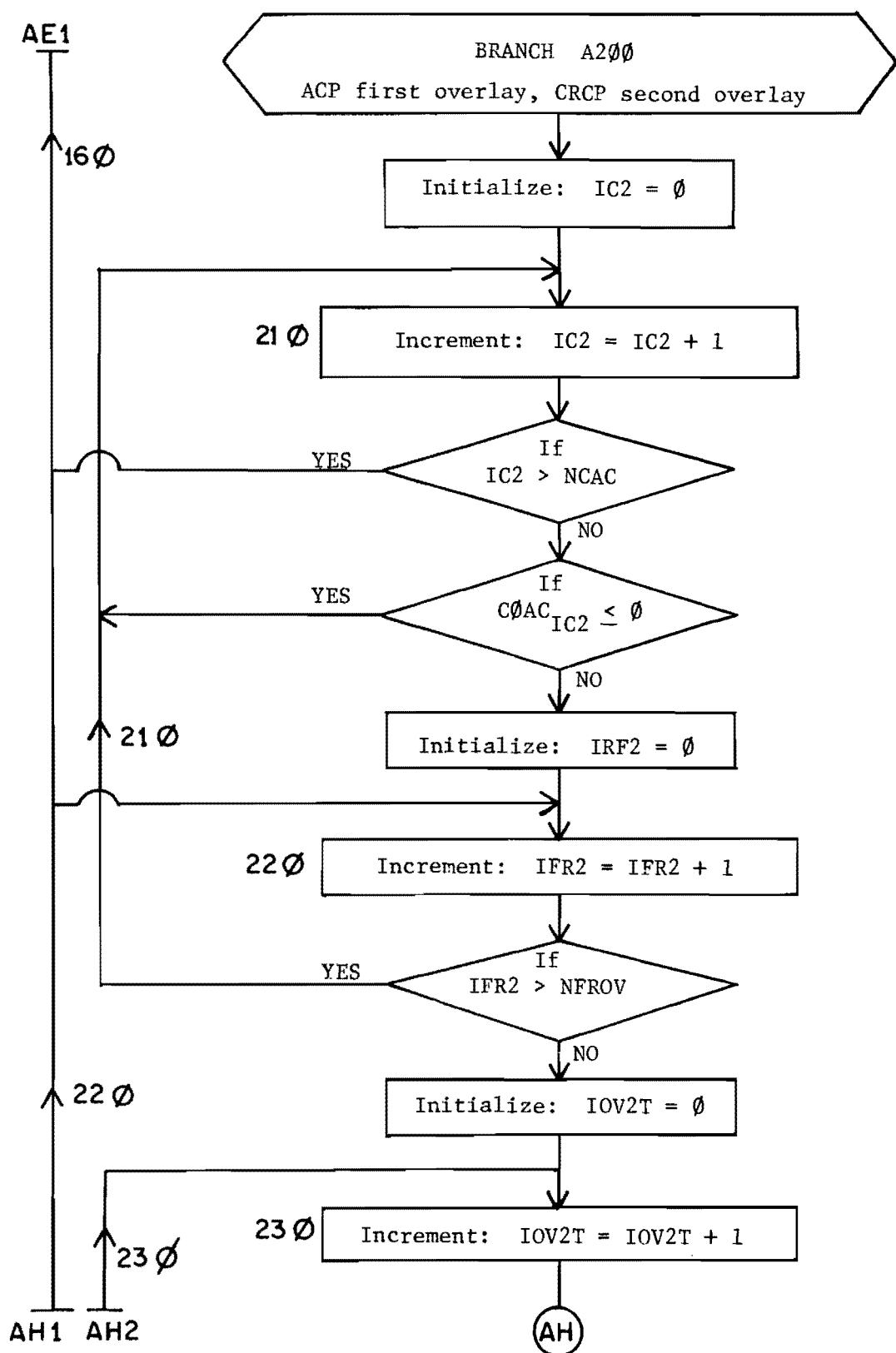


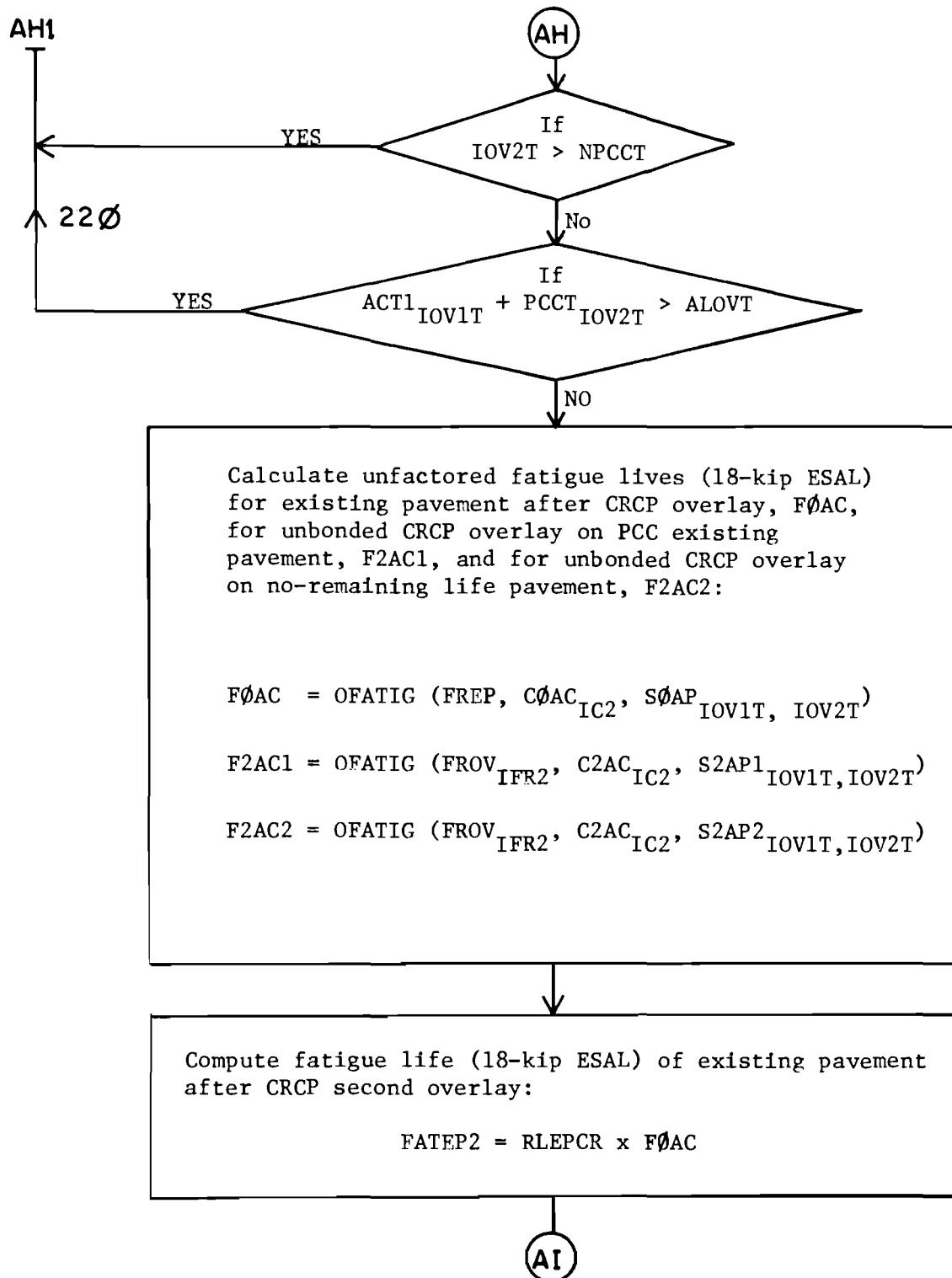


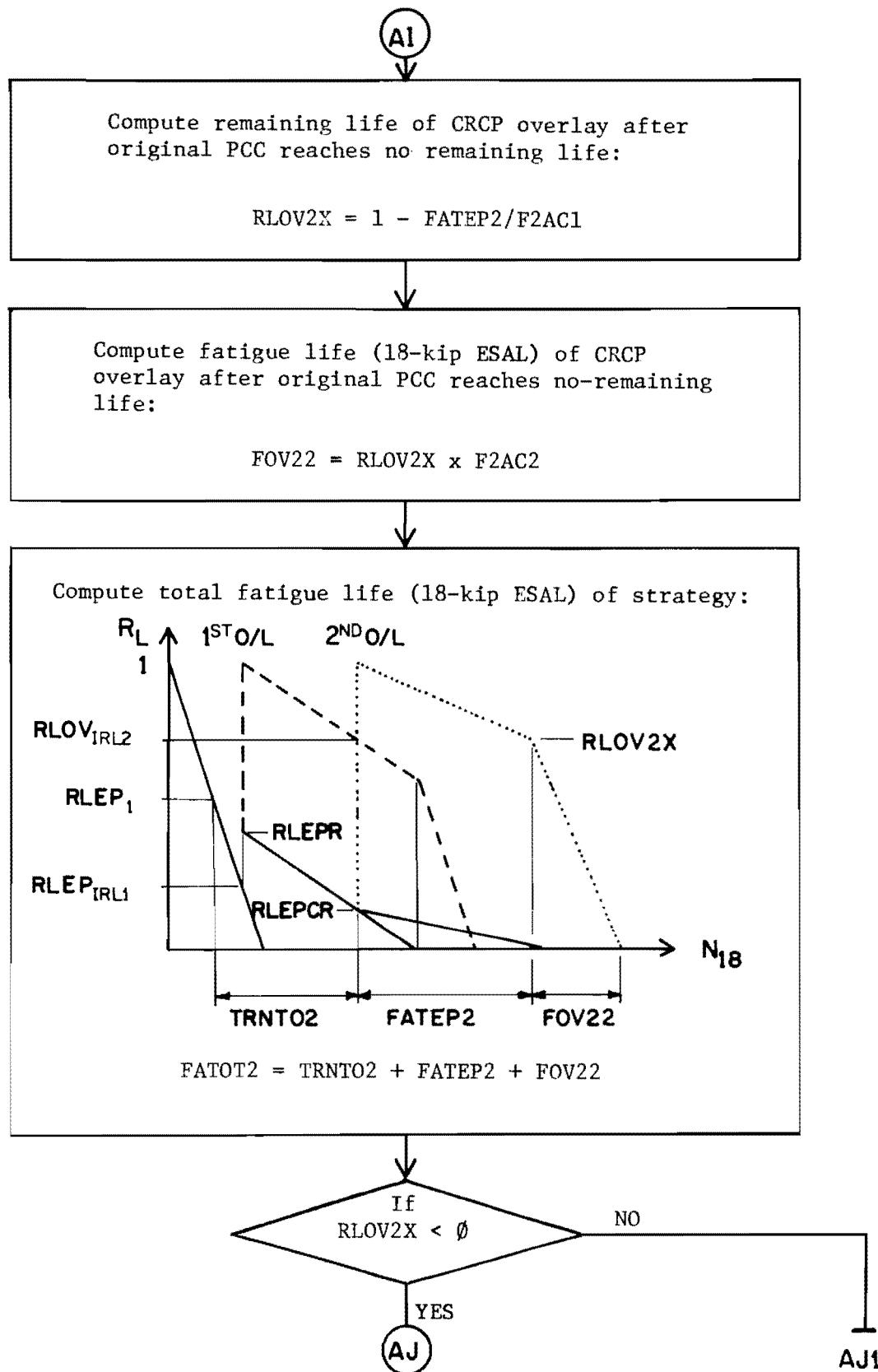


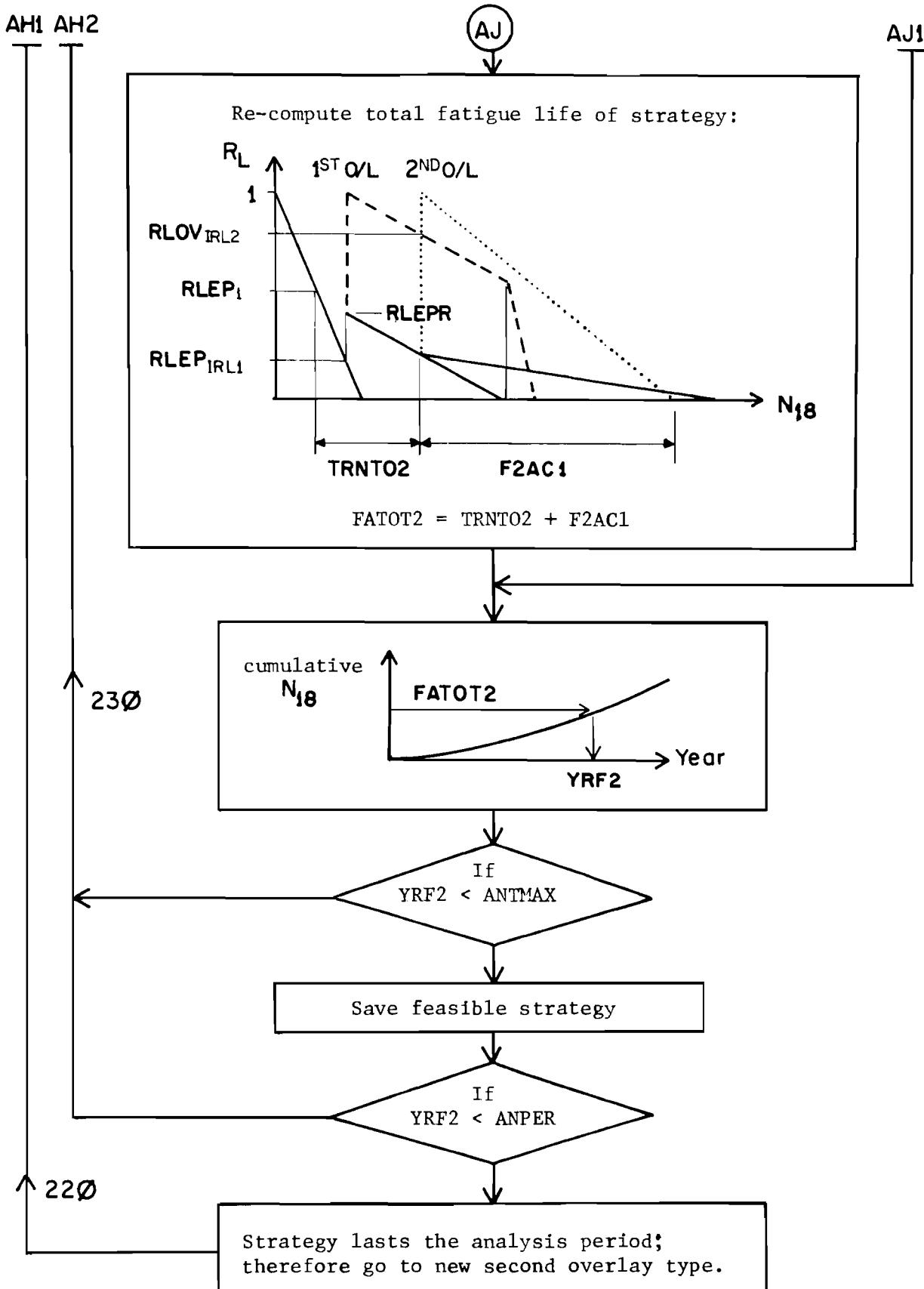


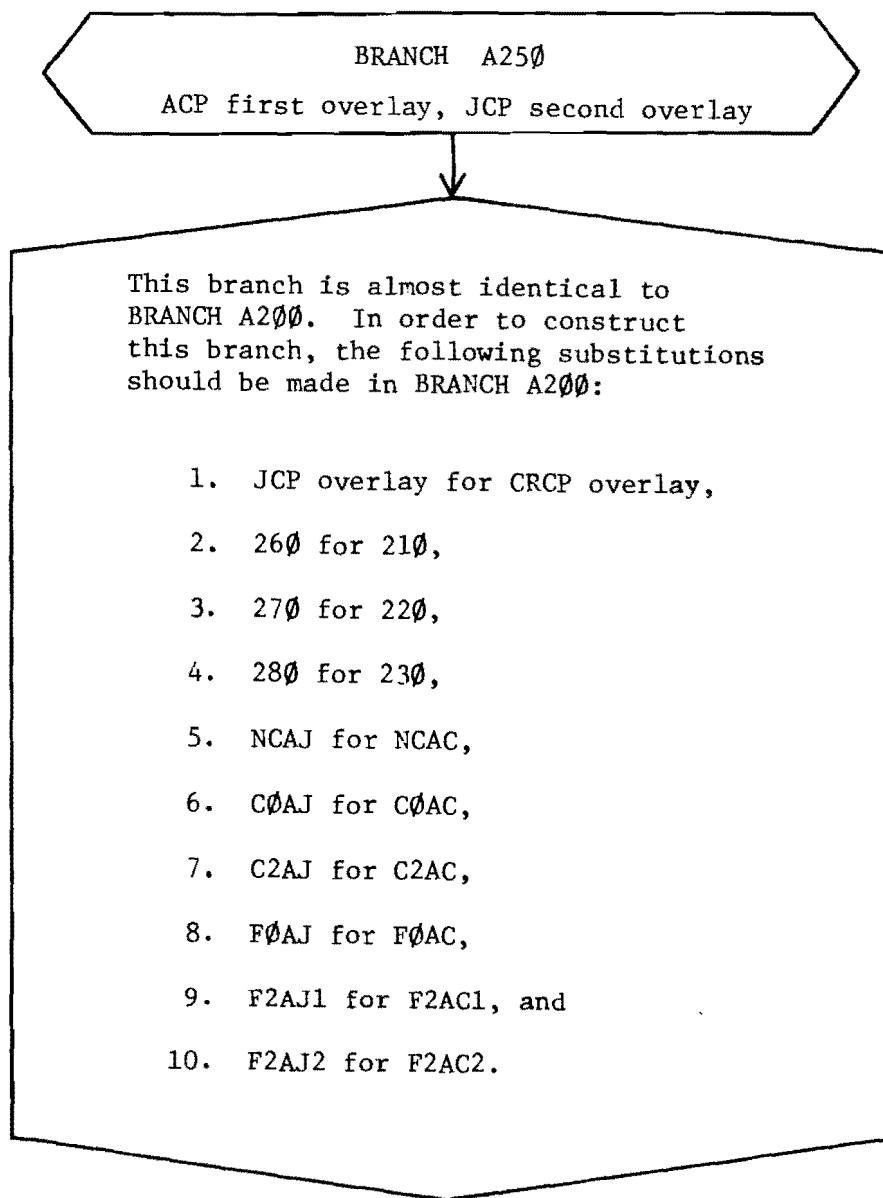


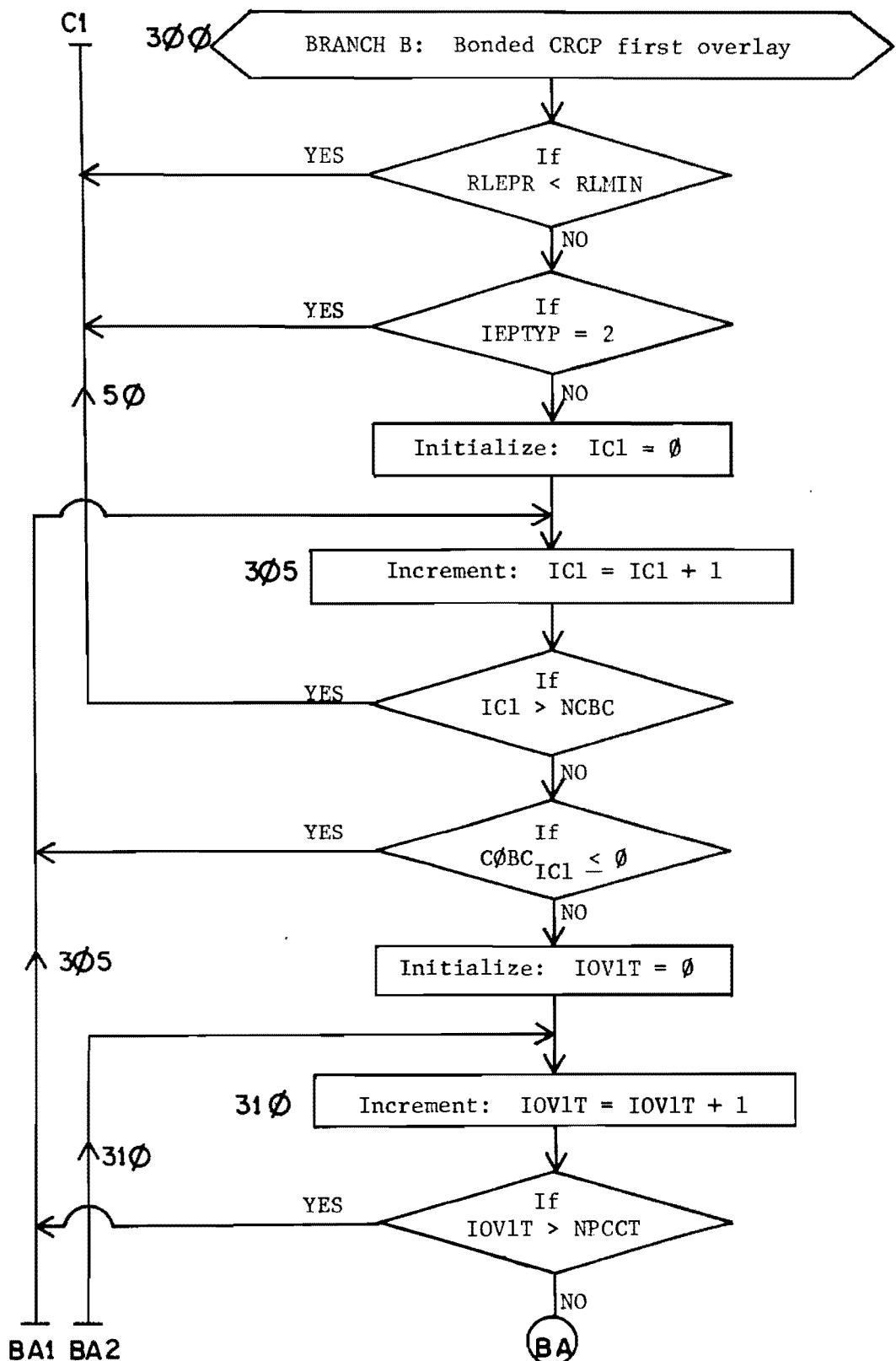


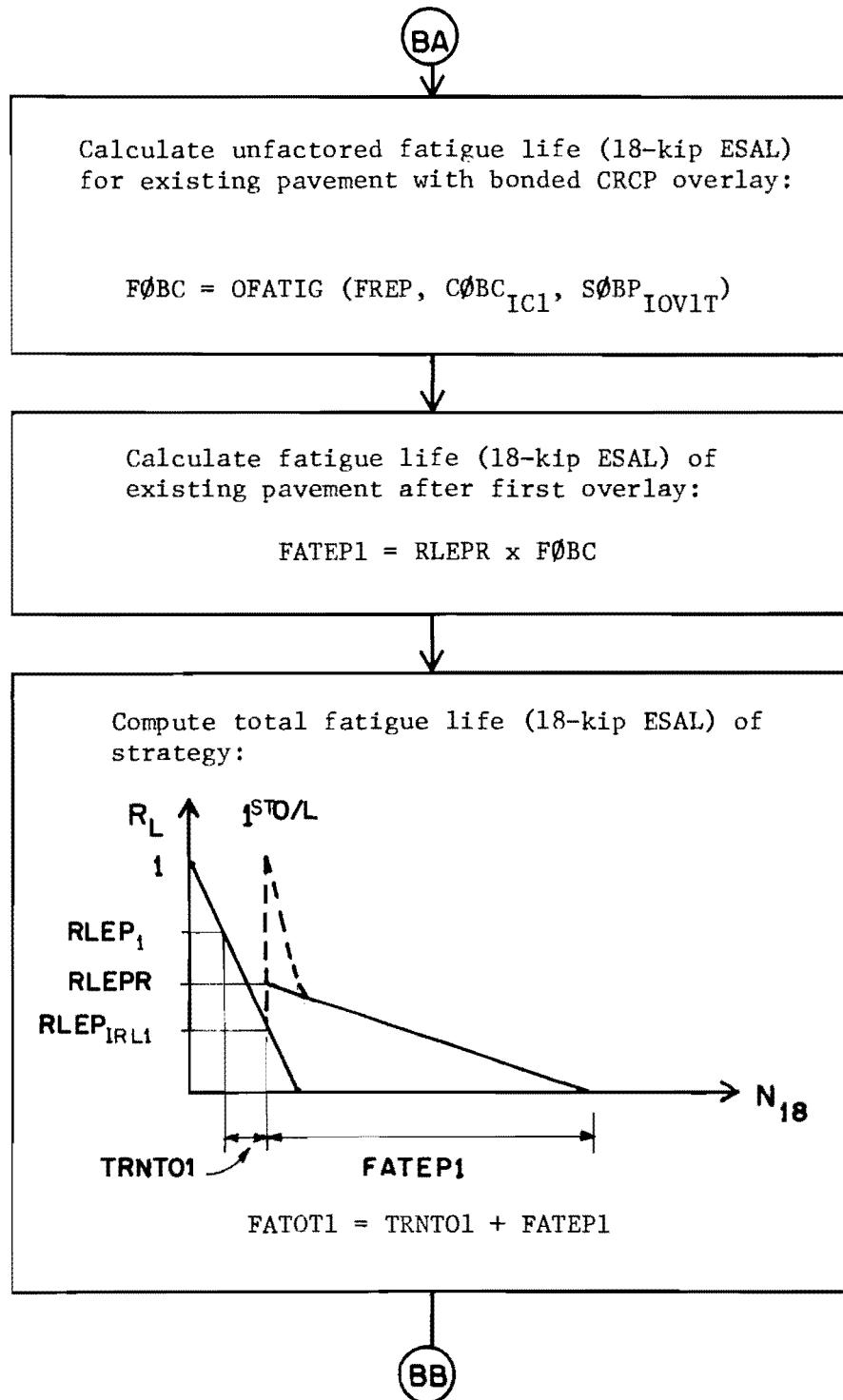


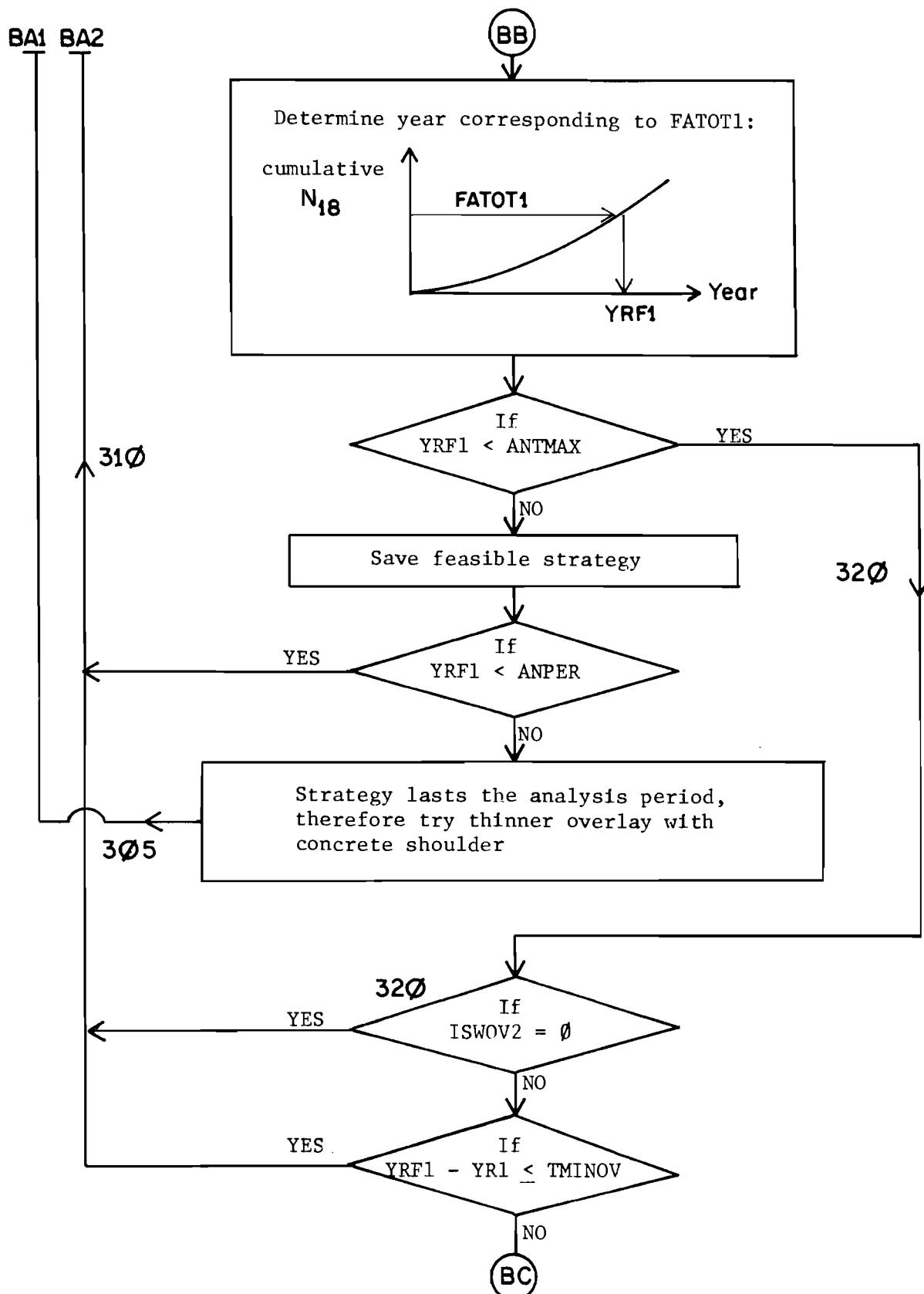


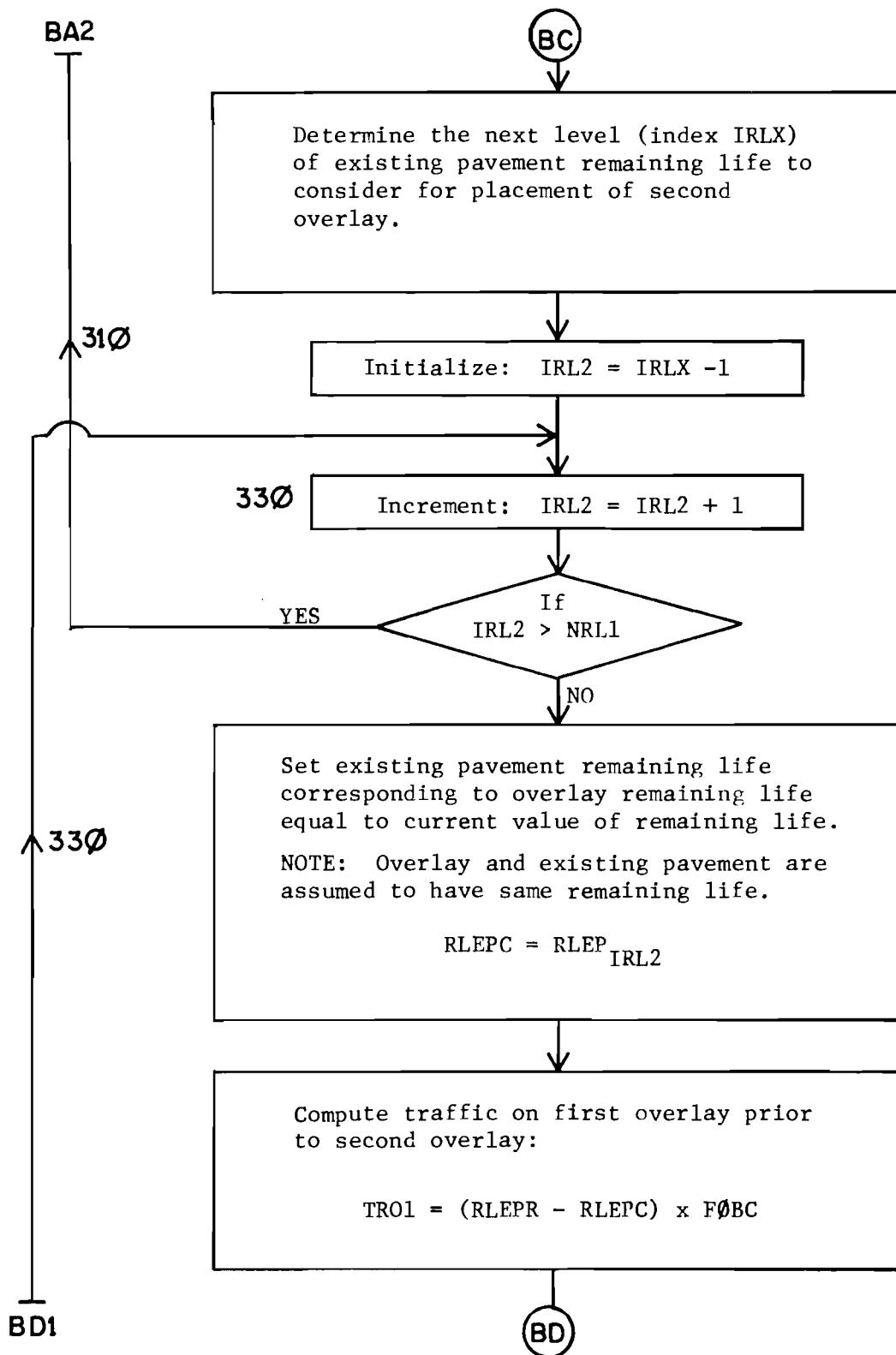


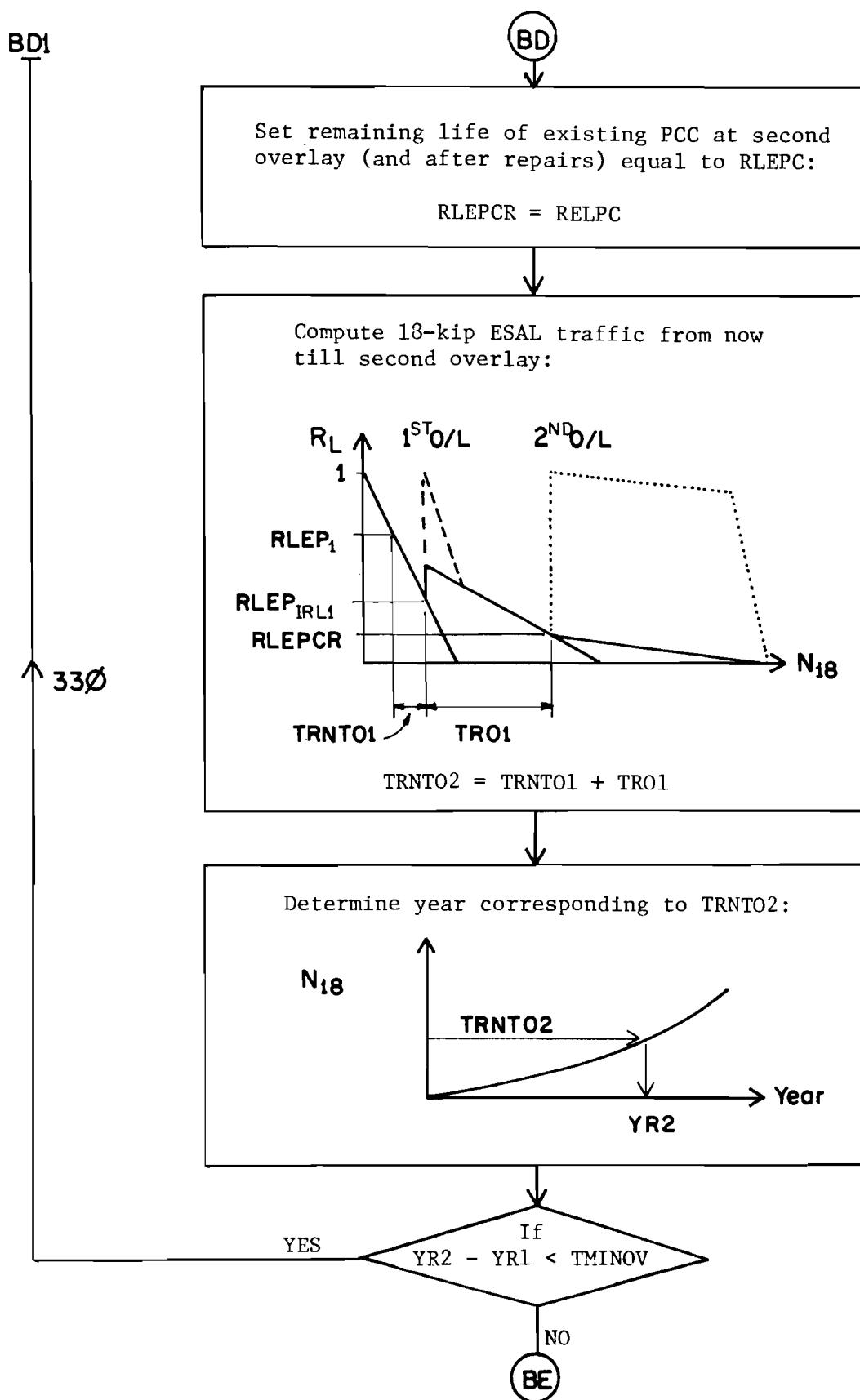


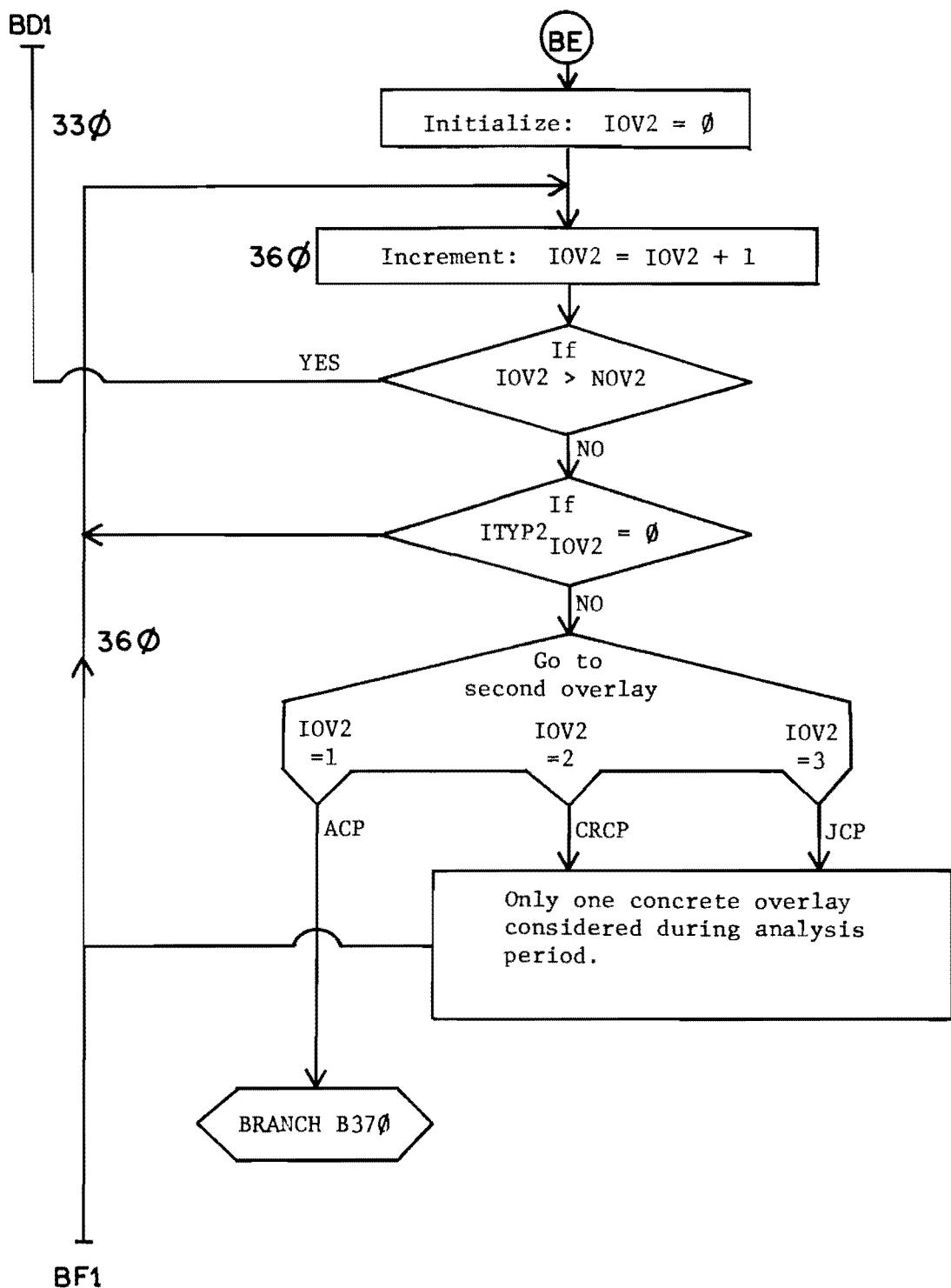


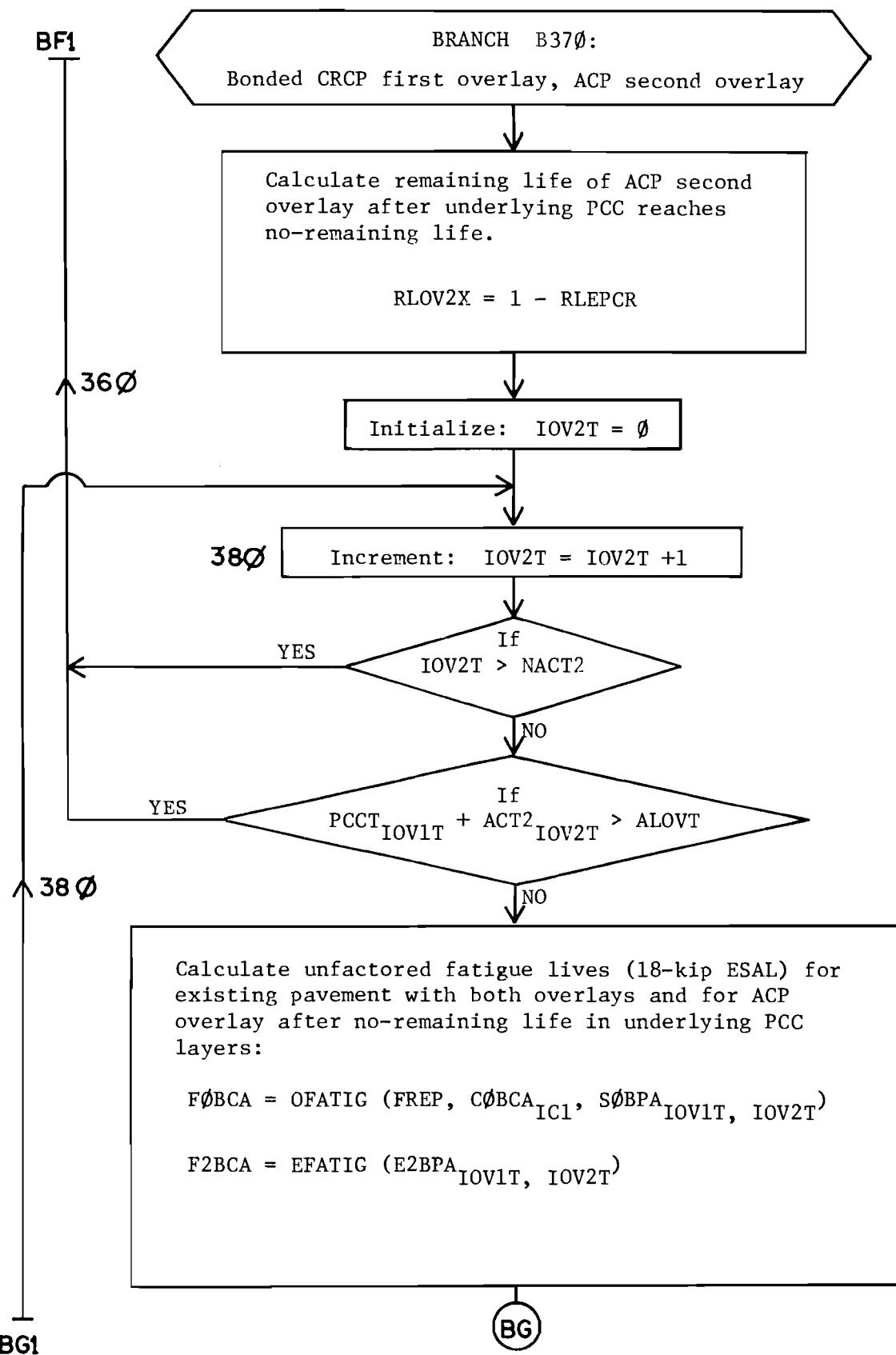


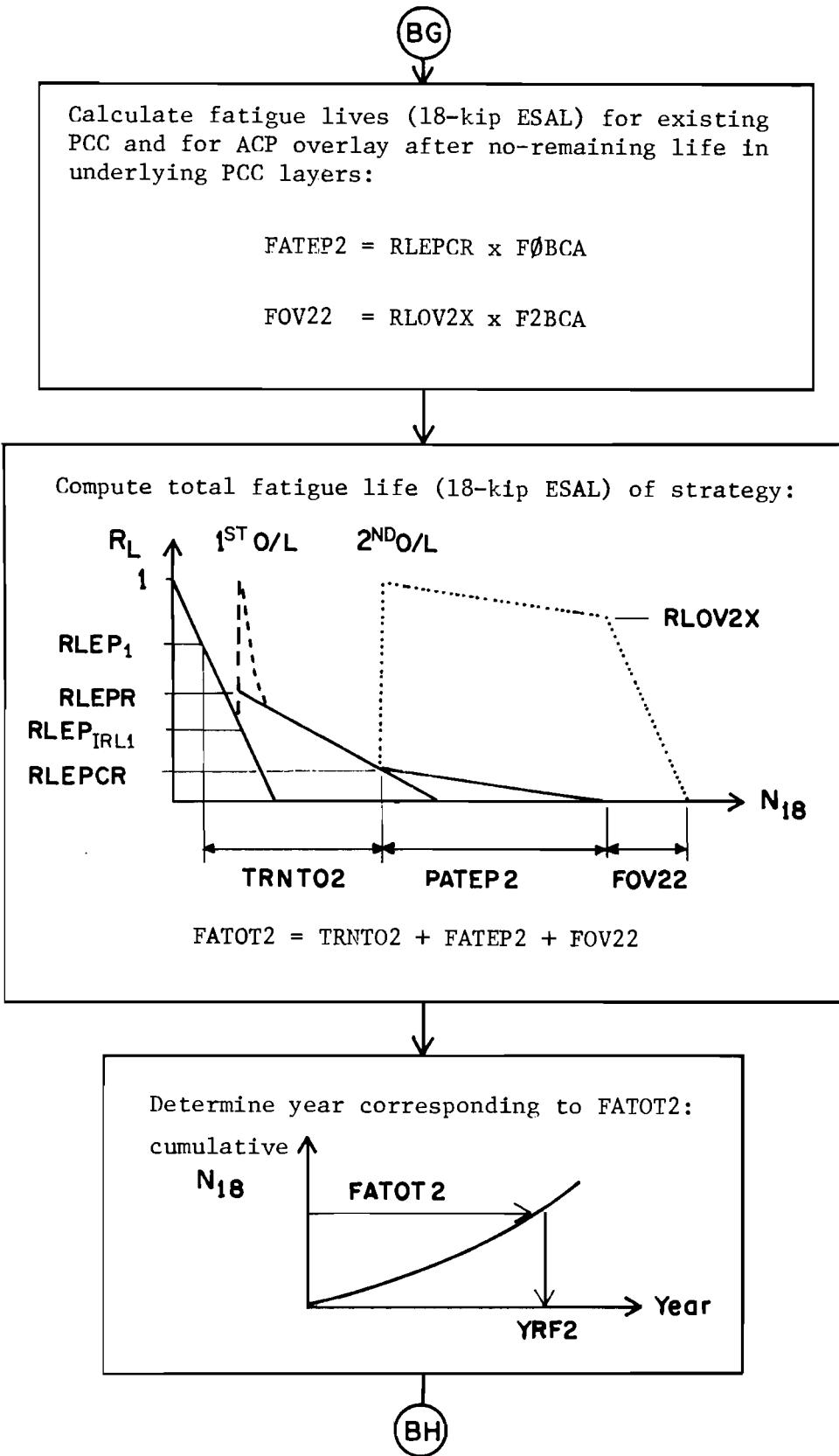


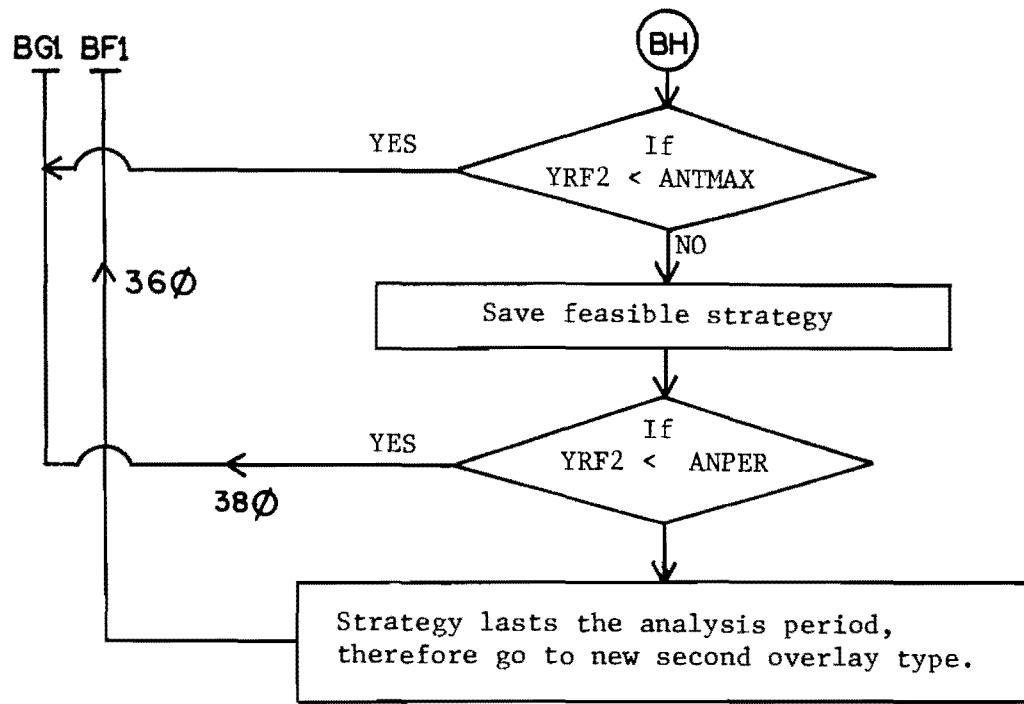


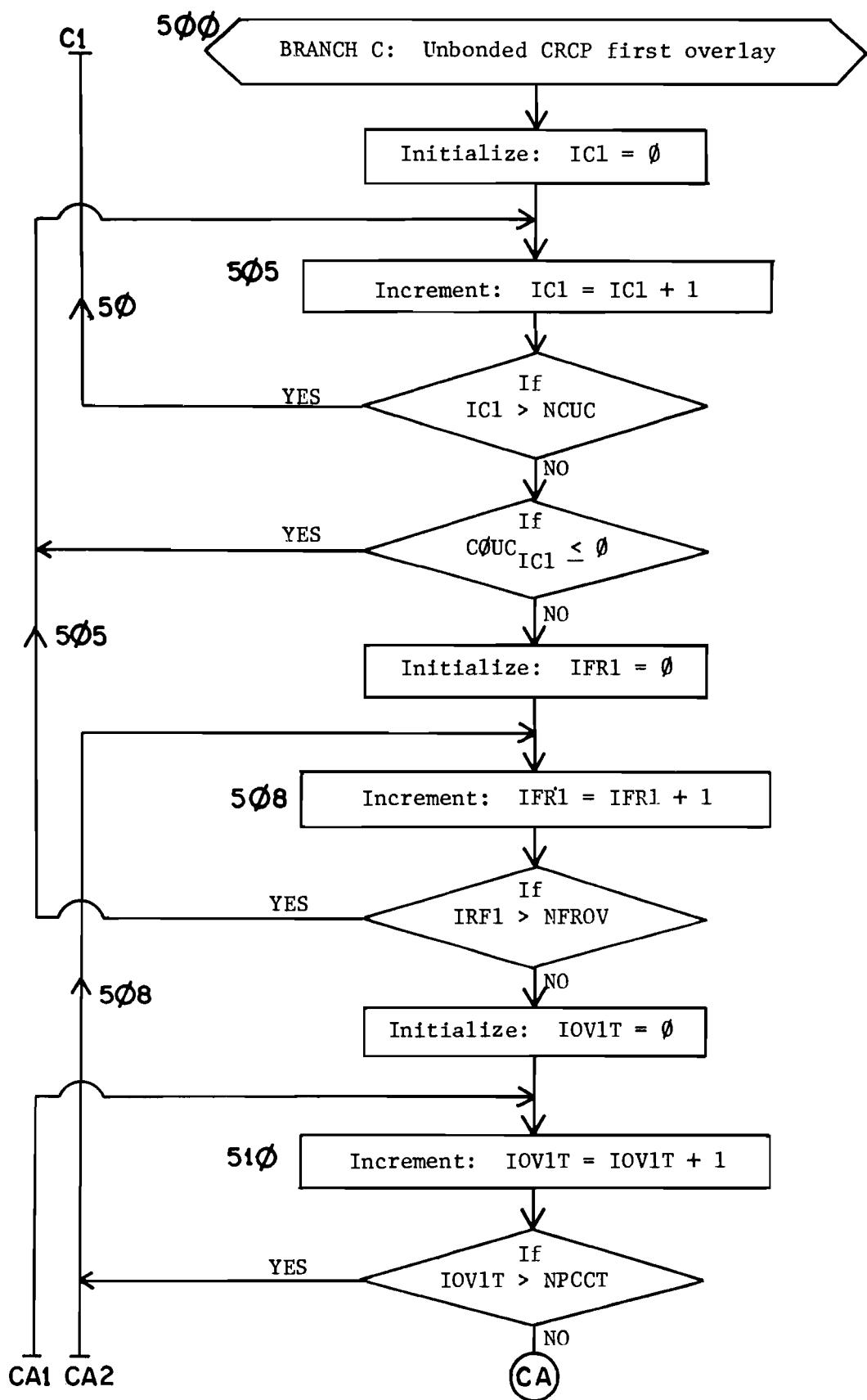


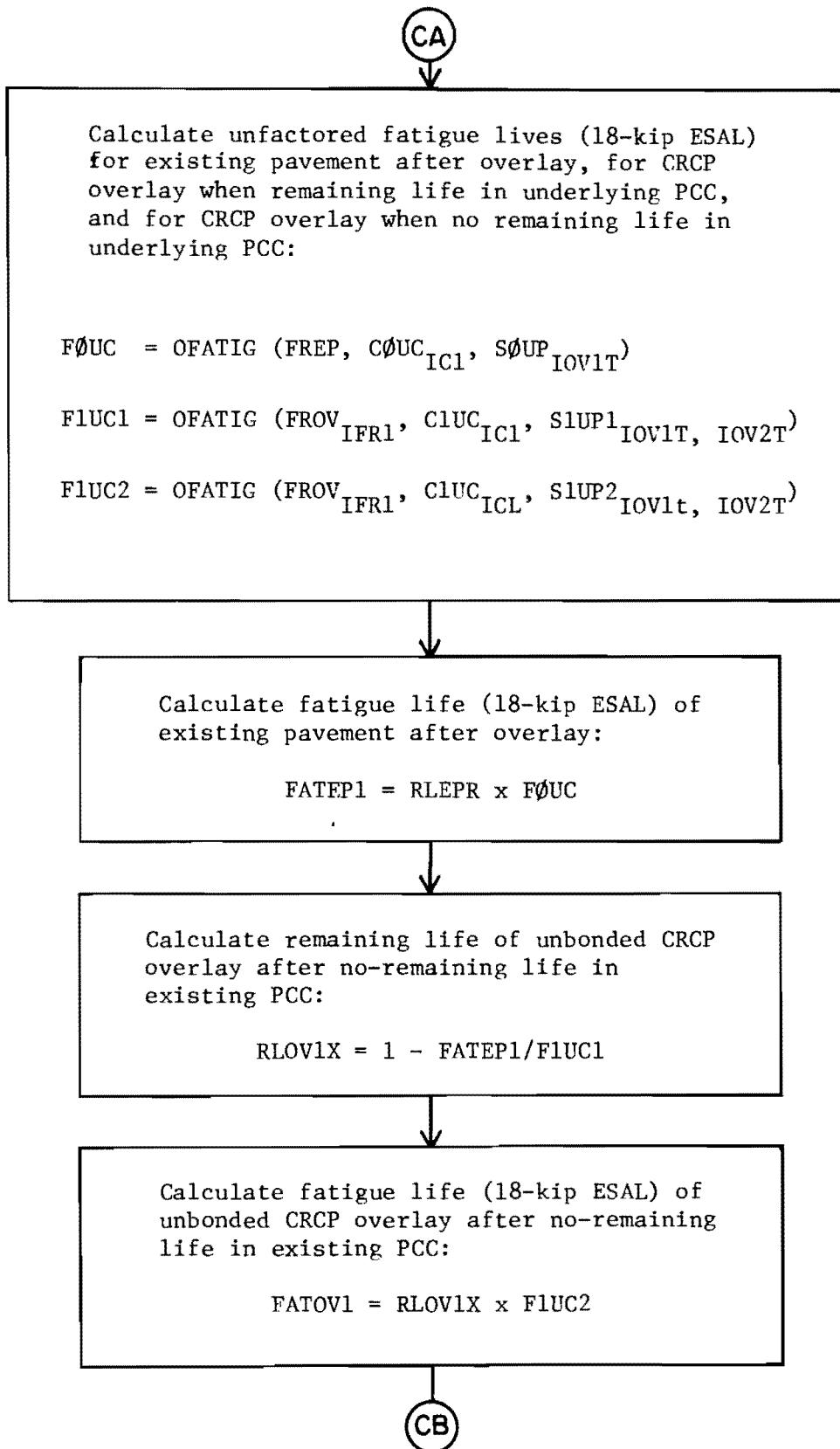


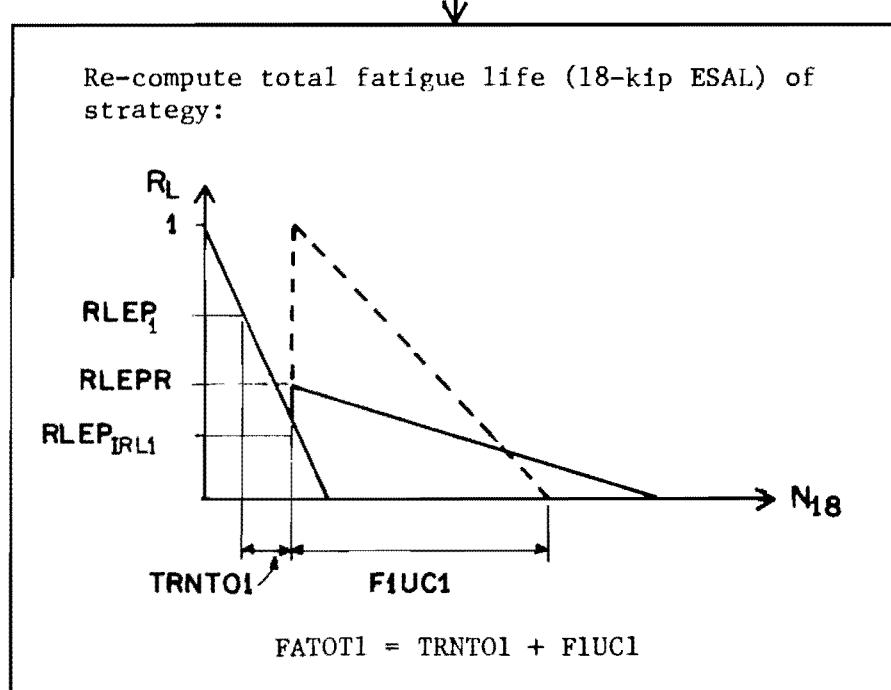
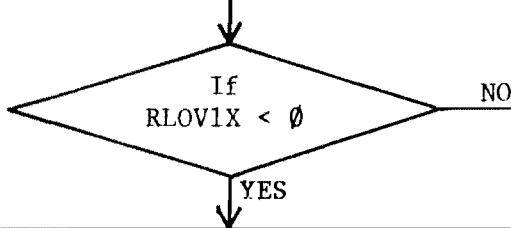
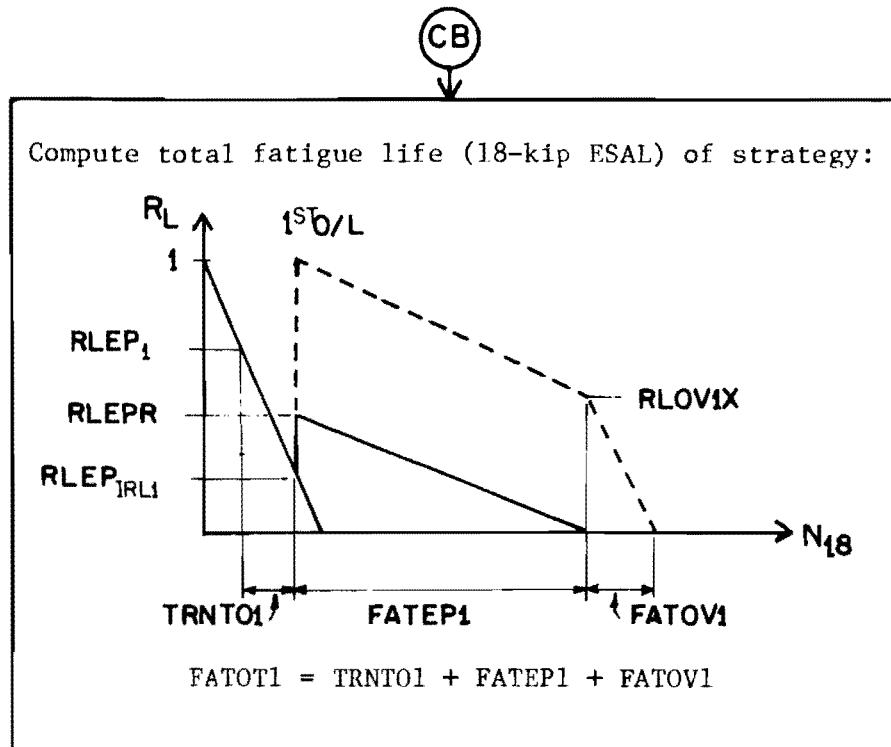






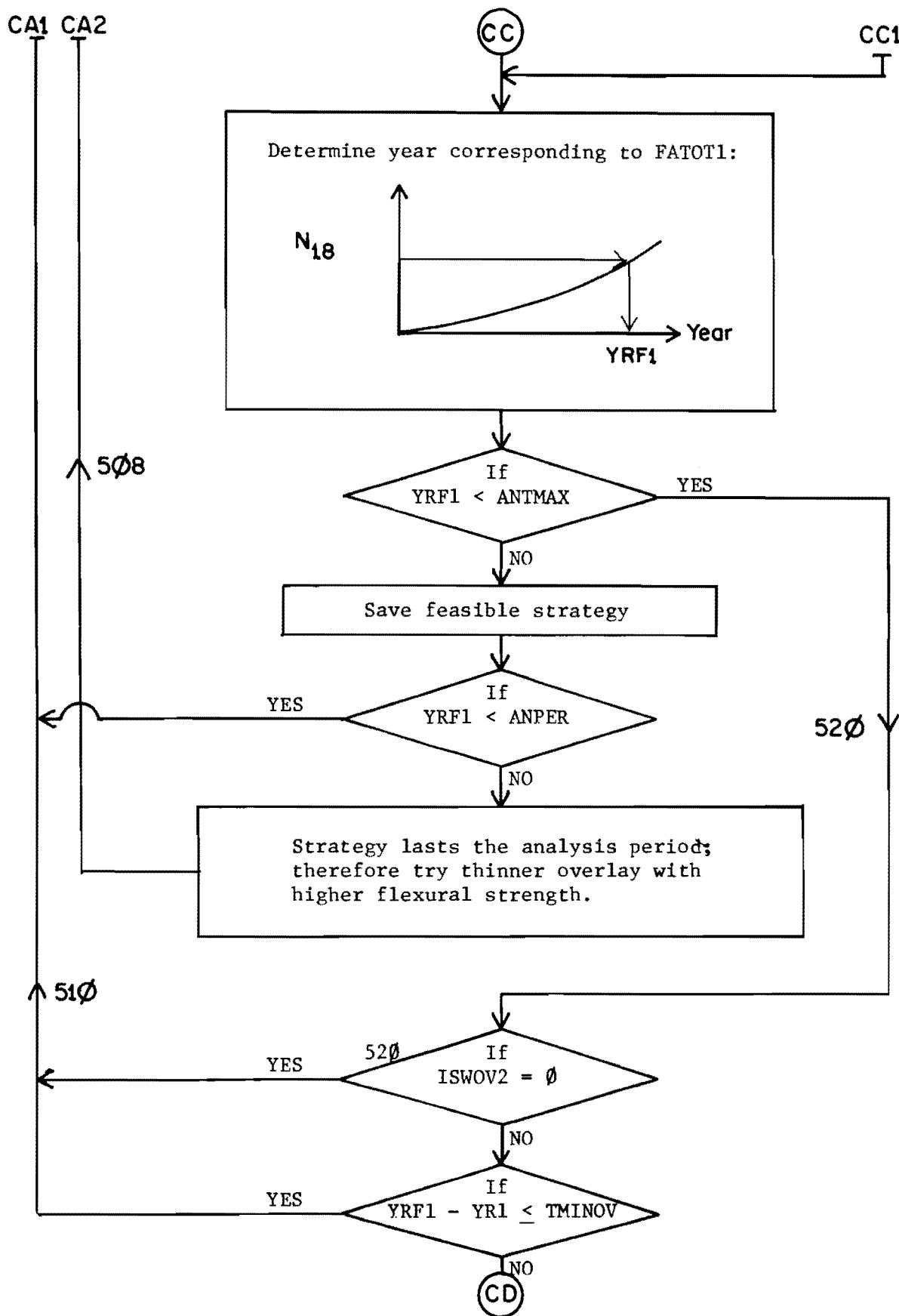


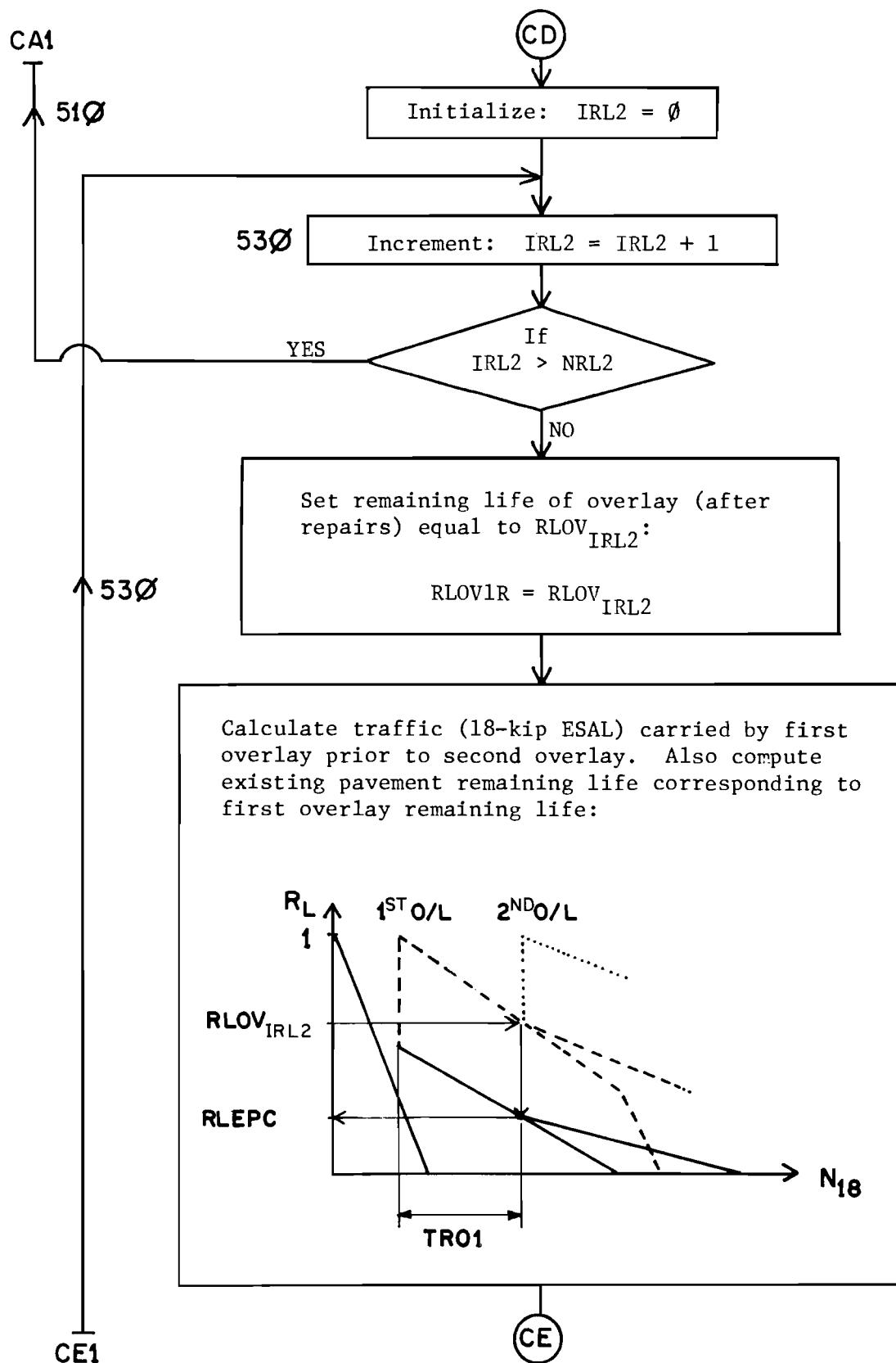


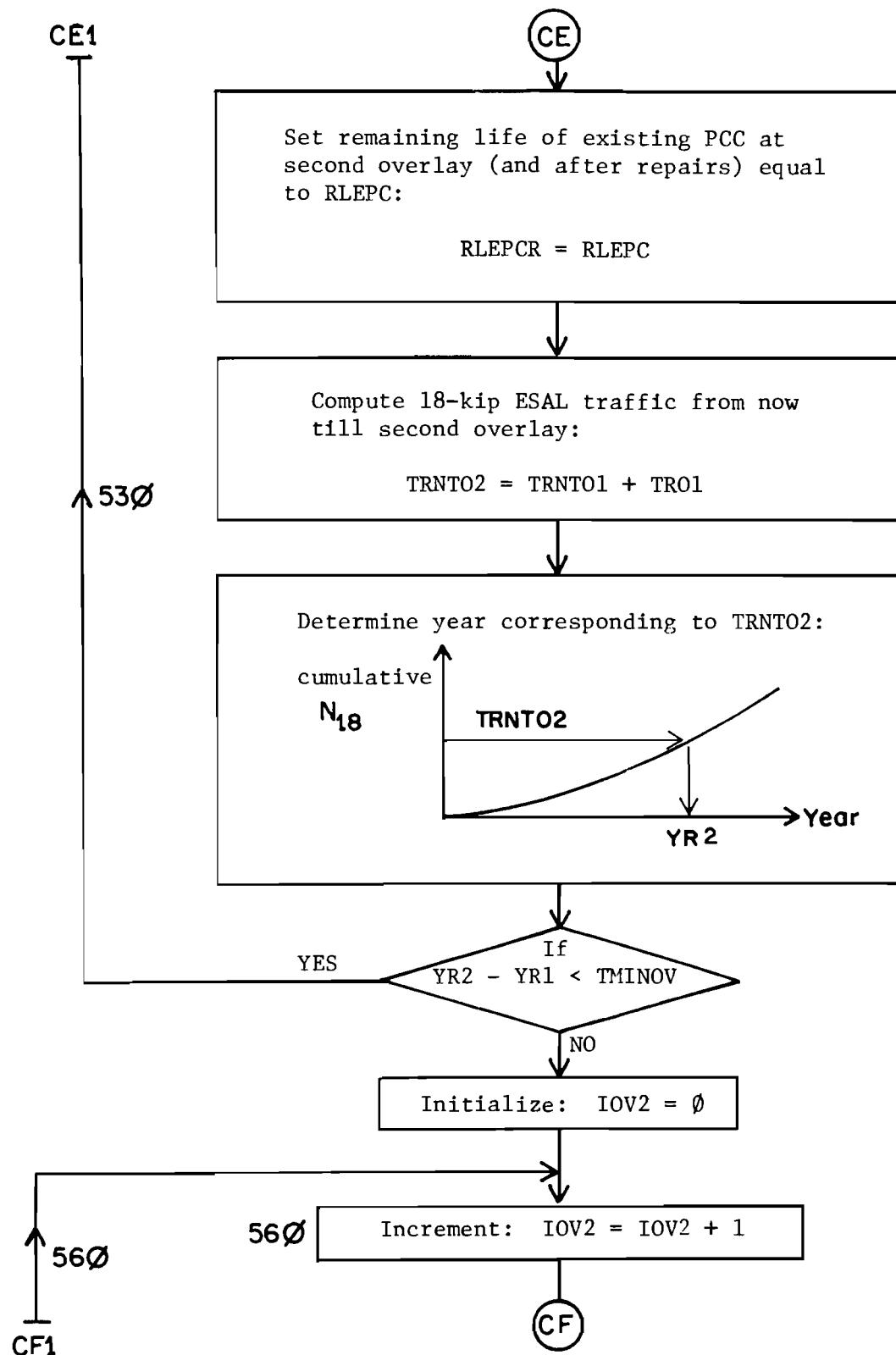


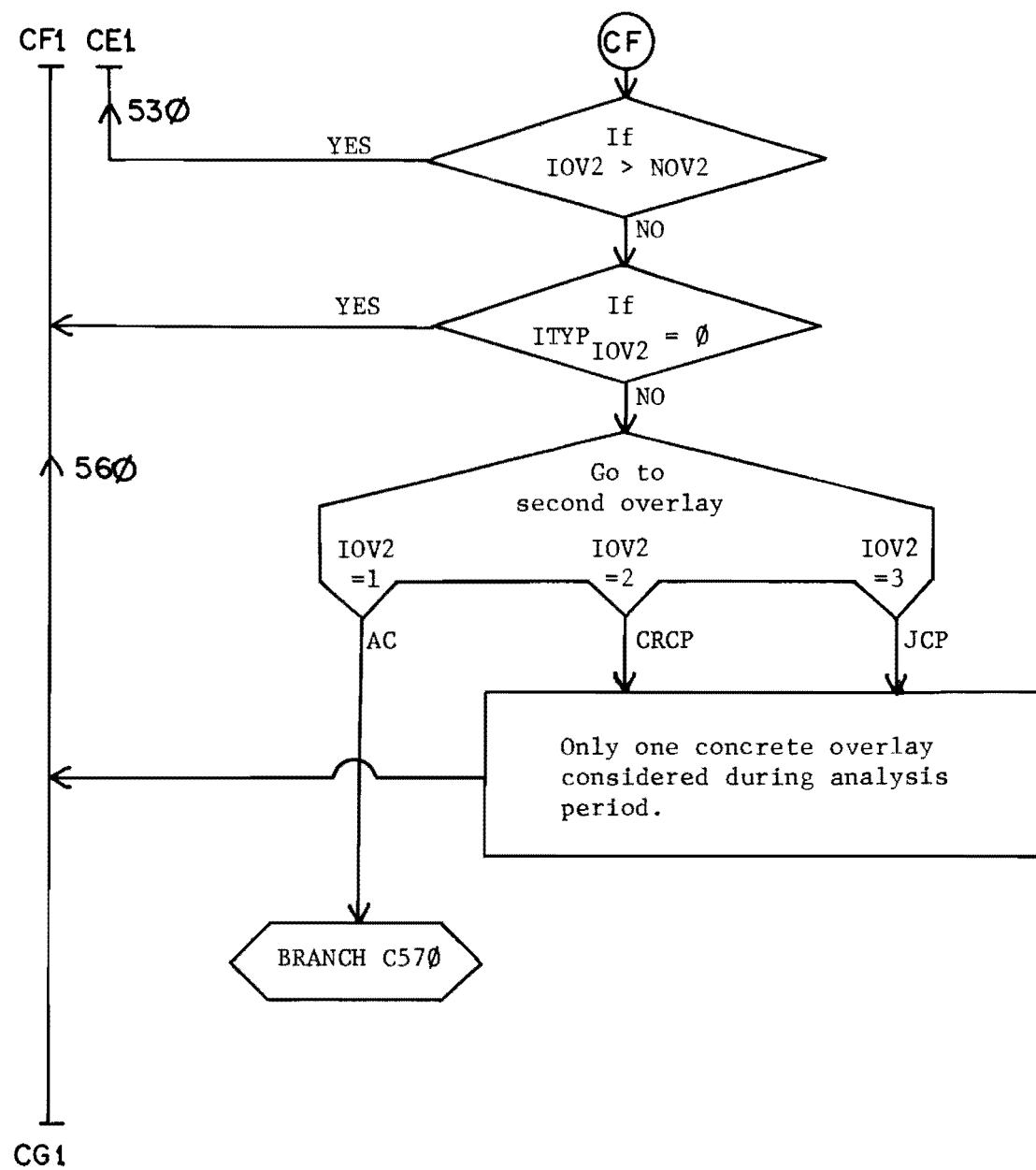
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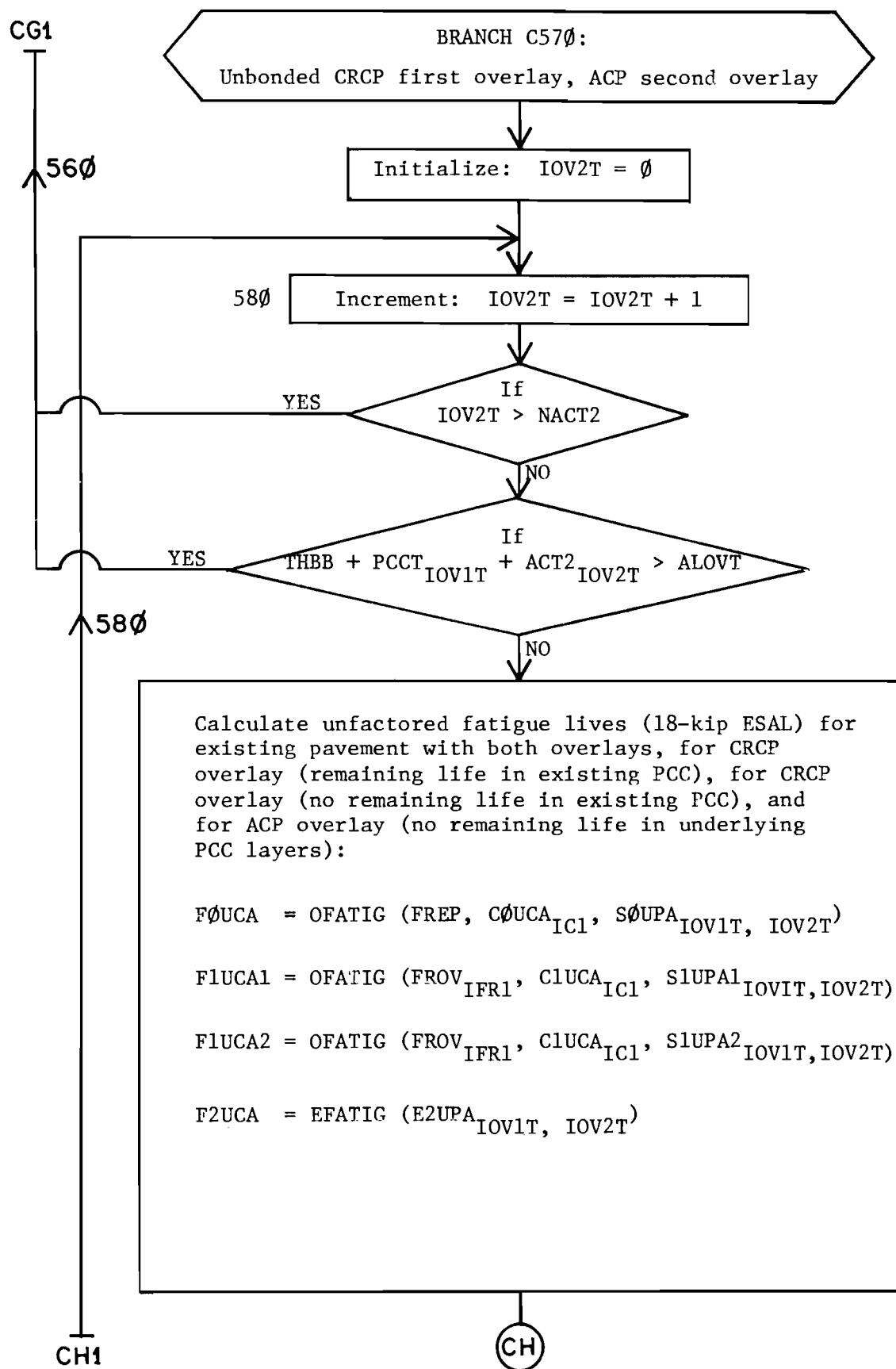
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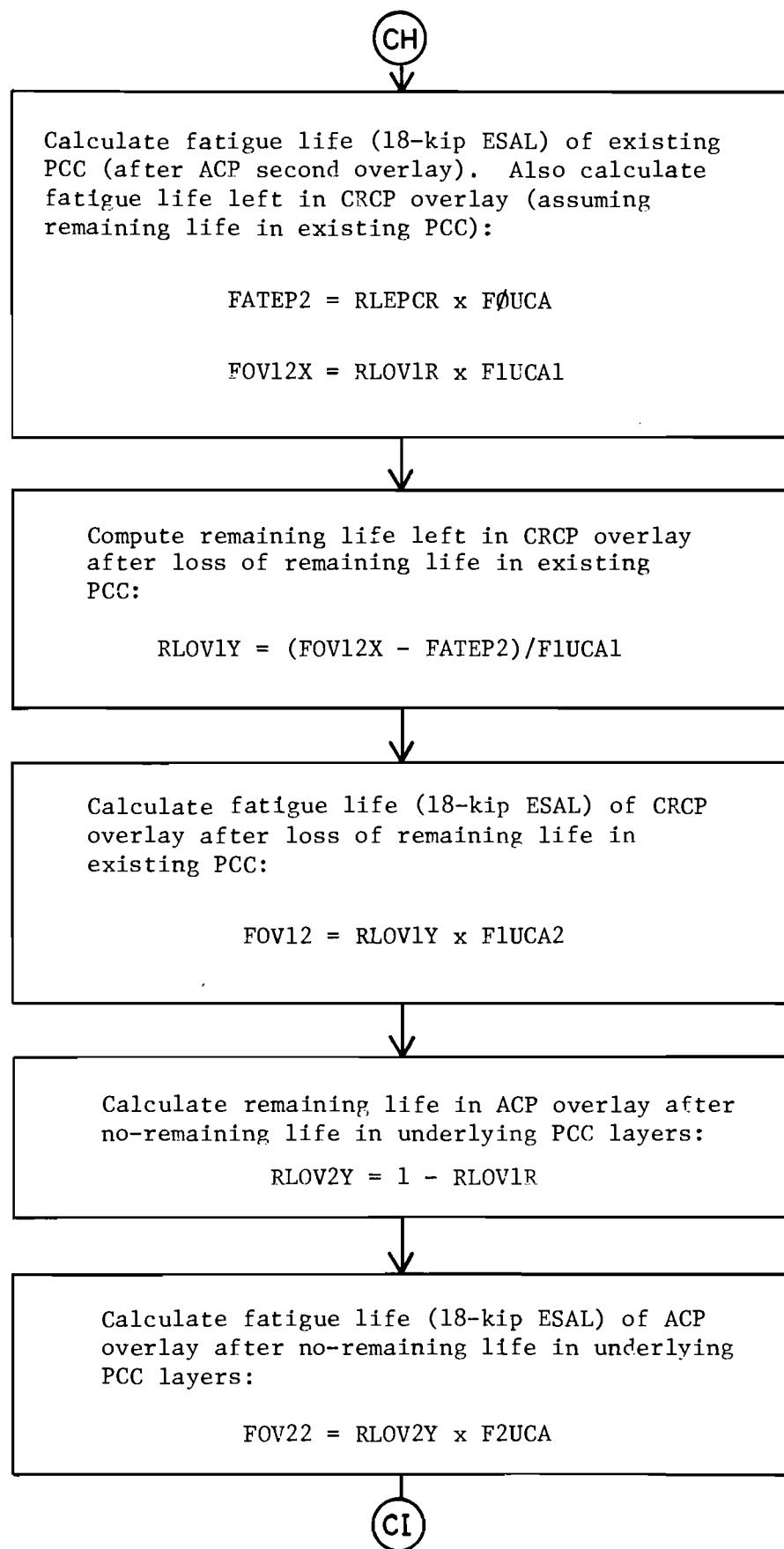


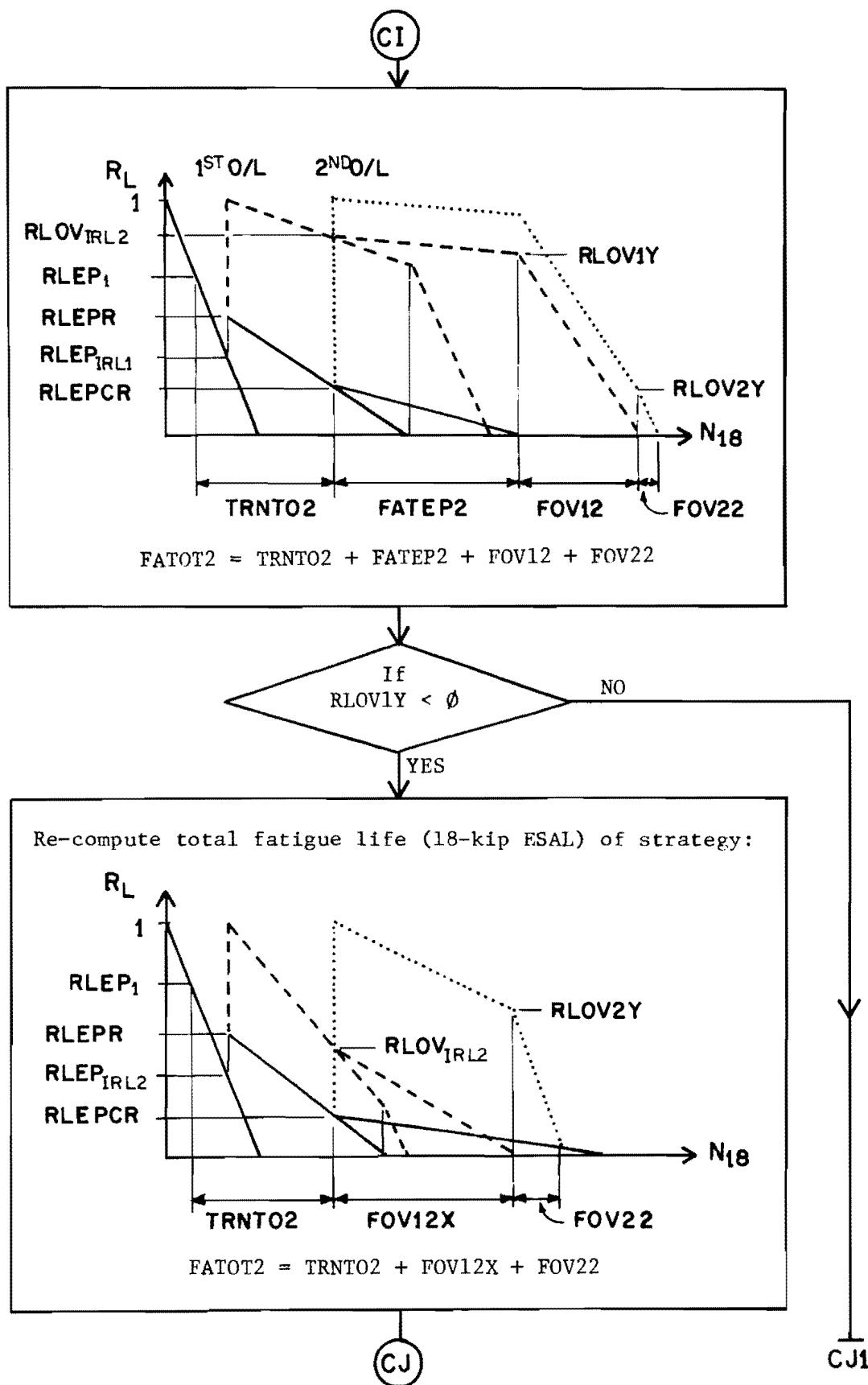


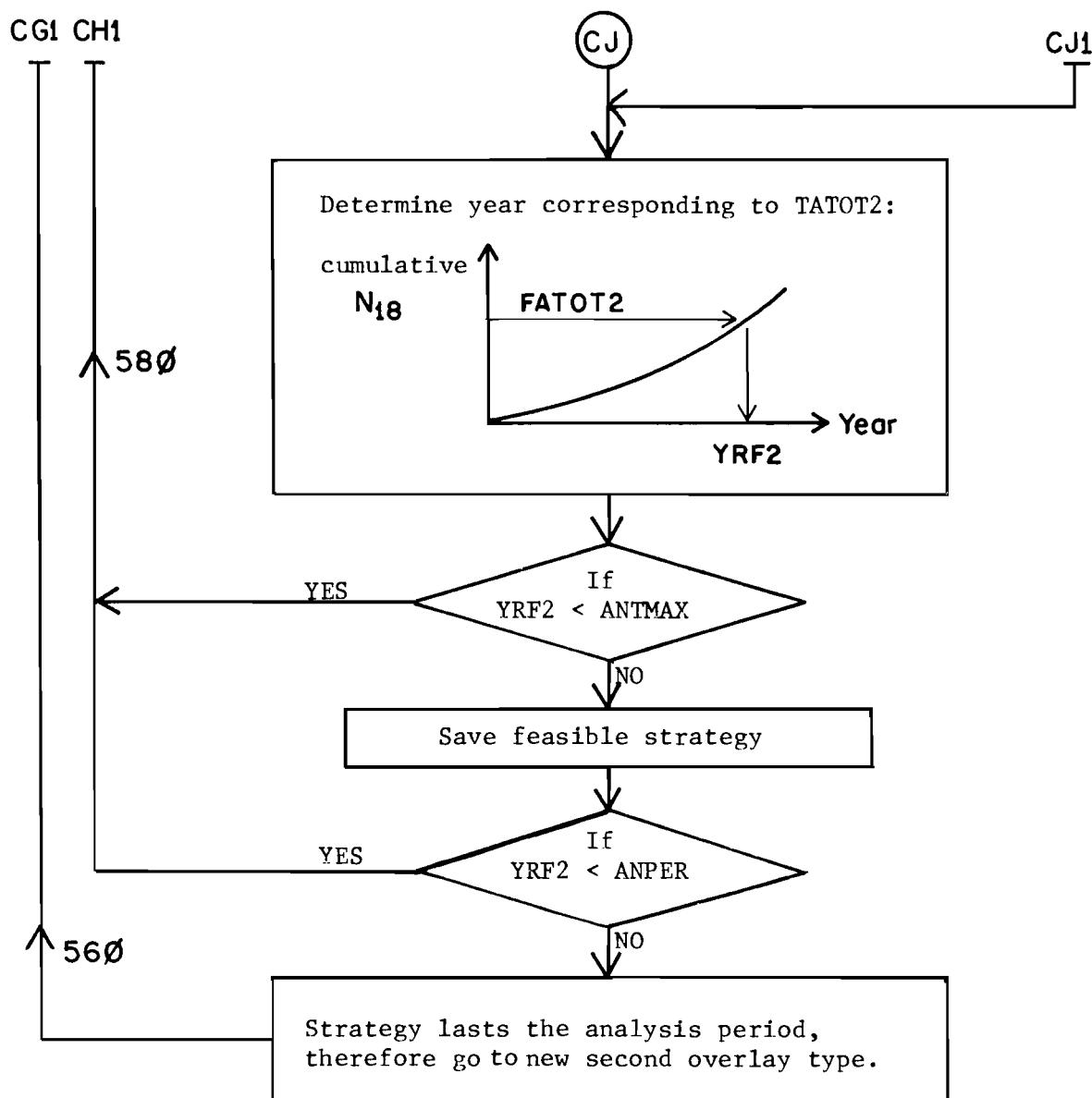












900

## BRANCH D: Bonded JCP first overlay



This branch is almost identical to BRANCH B.  
In order to construct this branch, the  
following substitutions should be made in  
BRANCH B (and its accompanying BRANCH B370):

1. JCP overlay for CRCP overlay,
2. a 1 for the 2 in second diamond,
3. 700 for 300,
4. 705 for 305,
5. 710 for 310,
6. 720 for 320,
7. 730 for 330,
8. 760 for 360,
9. BRANCH D770 for BRANCH B370,
10. 780 for 380,
11. NCBJ for NCBC,
12. CØBJ for COBC,
13. CØBJA for COBCA,
14. FØBJ for FØBC,
15. FØBJA for FØBCA, and
16. F2BJA for F2BCA.

BRANCH E: Unbonded JCP first overlay

This branch is almost identical to BRANCH C.  
In order to construct this branch, the following  
substitutions should be made in BRANCH C (and  
its accompanying BRANCH C570):

1. JCP overlay for CRCP overlay
2. 900 for 500,
3. 905 for 505,
4. 908 for 508,
5. 910 for 510,
6. 920 for 520,
7. 930 for 530
8. 960 for 560,
9. BRANCH E970 for BRANCH C570,
10. 980 for 580,
11. NCUJ for NCUC,
12. C0UJ for C0UJ,
13. C1UJ for C1UC,
14. C0UJA for C0UCA,
15. C1UJA for C1UCA,
16. F0UJ for F0UC,
17. F1UJI for F1UC1,
18. F1UJ2 for F1UC2,
19. F0UJA for F0UCA,
20. F1UJA1 for F1UCA1,
21. F1UJA2 for F1UCA2, and
22. F2UJA for F2UCA.

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**APPENDIX D**  
**RPRDS-1 INPUT GUIDE**

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## APPENDIX D. RPRDS-1 INPUT GUIDE

This input guide represents a summary of the input data required for RPRDS-1 and a guide for recording it on cards (or card images) for use by the program. This section is not intended to provide a detailed description of each input variable (see RPRDS-1 User's Manual, Chapter 6), but merely show how the data should be organized for running one or several rigid pavement rehabilitation design problems.

The data for a single problem are divided into eleven categories for ease of input:

- (1) Project Description,
- (2) Original Pavement,
- (3) Traffic Variables,
- (4) Time Constraints,
- (5) Remaining Life Variables,
- (6) Overlay Characteristics,
- (7) Overlay Construction Cost Variables,
- (8) Traffic Delay Cost Variables,
- (9) Distress/Maintenance Cost Variables
- (10) Cost Returns, and
- (11) Combined Interest and Inflation Rate.

Each variable within these categories is assigned a variable number according to the number of the card it appears on and its order on the card. This assigned number makes it easy to locate the variable, both in the program output and in the User's Manual (Chapter 6), where it is discussed in great detail.

In order to generate a card deck to run the RPRDS-1 program, the user should follow the guide, provided next, which defines each input variable. There are three important things to note, however, when following the guide.

The first is that each variable (except for the title) is entered in five or ten-column fields within each card.

The second is that each variable (except for the title) should be entered as either a real or integer value. If a variable is real, it should be entered with a decimal point and may be entered anywhere in its field. If the variable is an integer, it must be entered without the decimal point and must also be right-justified (furthest to the right) in its field.

The third item to note is that a format summary for all the data (which illustrates the relative location of each input variable) is provided at the end of this section as an aid in coding the data.

#### Project Description

##### Card No. 1:

1.1 Title card, alphanumeric, col. 1-80.

#### Original Pavement

##### Card No. 2:

2.1 Surface type, integer, col. 1-5. (1=CRCP, 2=JCP)  
2.2 Concrete shoulder, integer, col. 6-10. (1=No, 2=Yes)  
2.3 No. of lanes in one direction, integer, col. 11-15.  
2.4 No. of pavement layers, integer, col. 16-20. (maximum of 5)

##### Card No. 3:

3.1 Project length (miles), real, col. 1-10.

3.2 Lane width (feet), real, col. 11-20.  
 3.3 Total shoulder width (feet), real, col. 21-30.

## Card No. 4:

4.0 Thicknesses of existing layers (inches):  
 4.1 Concrete surface layer, real, col. 1-10.  
 4.2 Second layer, real, col. 11-20.  
 4.3 Third layer, real, col. 21-30.  
 4.4 Fourth layer, real, col. 31-40.  
 4.5 Fifth layer, real, col. 41-50.

## Card No. 5:

5.0 Elastic moduli of existing layers (psi):  
 5.1 Concrete surface layer (psi), real, col. 1-10.  
 5.2 Second layer, real, col. 11-20.  
 5.3 Third layer, real, col. 21-30.  
 5.4 Fourth layer, real, col. 31-40.  
 5.5 Fifth layer, real, col. 41-50.

## Card No. 6:

6.0 Poisson's ratios for existing layers:  
 6.1 Concrete surface layer, real, col. 1-10.  
 6.2 Second layer, real, col. 11-20.  
 6.3 Third layer, real, col. 21-30.  
 6.4 Fourth layer, real, col. 31-40.  
 6.5 Fifth layer, real, col. 41-50.

## Card No. 7:

7.1 Concrete flexural strength (psi), real, col. 1-10.  
 7.2 Critical stress factor, real, col. 11-20.  
 7.3 Concrete stiffness after cracking (psi), real, col. 21-30.

## Card No. 8:

8.1 Number of existing defects per mile, real, col. 1-10.  
 8.2 Cost of repairing a defect (dollars), real, col. 11-20.  
 8.3 Rate of defect development (number per year per mile),  
     real, col. 21-30.

Traffic Variables

## Card No. 9:

9.1 Average daily traffic (vehicles per day), real, col. 1-10.  
 9.2 Average daily traffic growth rate (percent), real, col.  
     11-20.  
 9.3 Initial yearly 18-kip equivalent single axle loads  
     (millions), real, col. 21-30.  
 9.4 18-kip ESAL growth rate (percent), real, col. 31-40.  
 9.5 Directional distribution factor (percent), real, col.  
     41-50.  
 9.6 Lane distribution factor (percent), real, col. 51-60.

Time Constraints

Card No. 10:

- 10.1 Analysis period (years), real, col. 1-10.  
 10.2 Minimum time between overlays (years), real, col. 11-20.  
 10.3 Maximum allowable years of heavy maintenance after loss of structural load-carrying capacity, real, col. 21-30.  
 (Maximum of 10 years)

Remaining Life Variables

Card No. 11:

- 11.1 Number of original pavement remaining life values to consider, integer, col. 1-5. (Maximum of 10)  
 11.2 Minimum existing pavement remaining life at which bonded PCC overlay may be placed (percent), real, col. 6-10.  
 11.3 Values of original pavement remaining life (percent) at which first overlay may be placed (in descending order):  
 1 first remaining life, real, col. 11-15.  
 2 second remaining life, real, col. 16-20.  
 3 third remaining life, real, col. 21-25.  
 4 fourth remaining life, real, col. 26-30.  
 5 fifth remaining life, real, col. 31-35.  
 6 sixth remaining life, real, col. 36-40.  
 7 seventh remaining life, real, col. 41-45.  
 8 eighth remaining life, real, col. 46-50.  
 9 ninth remaining life, real, col. 51-55.  
 10 tenth remaining life, real, col. 56-60.

Card No. 12:

- 12.1 Number of first overlay remaining life values to consider, integer, col. 1-5. (Maximum of 10)  
 12.2 Values of first overlay remaining life (percent) at which second overlay may be placed (in descending order):  
 1 first remaining life, real, col. 11-15.  
 2 second remaining life, real, col. 16-20.  
 3 third remaining life, real, col. 21-25.  
 4 fourth remaining life, real, col. 26-30.  
 5 fifth remaining life, real, col. 31-35.  
 6 sixth remaining life, real, col. 36-40.  
 7 seventh remaining life, real, col. 41-45.  
 8 eighth remaining life, real, col. 46-50.  
 9 ninth remaining life, real, col. 51-55.  
 10 tenth remaining life, real, col. 56-60.

Overlay Characteristics

Card No. 13:

- 13.0 Types of first overlay to consider (0=No, 1=Yes):  
 13.1 ACP, integer, col. 1-5.  
 13.2 Bonded CRCP, integer, col. 6-10.  
 13.3 Unbonded CRCP, integer, col. 11-15.

13.4 Bonded JCP, integer, col. 16-20.  
13.5 Unbonded JCP, integer, col. 21-25.

Card No. 14:

14.0 Types of second overlay to consider (0=No, 1=Yes):  
14.1 ACP, integer, col. 1-5.  
14.2 CRCP, integer, col. 6-10.  
14.3 JCP, integer, col. 11-15.

Card No. 15:

15.1 Number of ACP first overlay thicknesses to consider,  
integer, col. 1-5. (Maximum of 8)  
15.2 Number of ACP second overlay thinckesses to consider,  
integer, col. 6-10. (Maximum of 8)  
15.3 Number of PCC overlay thicknesses to consider, integer,  
col. 11-15. (Maximum of 8)

Card No. 16:

16.0 ACP first overlay thicknesses (inches) in ascending order:  
16.1 first thickness, real, col. 1-10.  
16.2 second thickness, real, col. 11-20.  
16.3 third thickness, real, col. 21-30.  
16.4 fourth thickness, real, col. 31-40.  
16.5 fifth thickness, real, col. 41-50.  
16.6 sixth thickness, real, col. 51-60.  
16.7 seventh thickness, real, col. 61-70.  
16.8 eighth thickness, real, col. 71-80.

Card No. 17:

17.0 ACP second overlay thicknesses (inches) in ascending order:  
17.1 first thickness, real, col. 1-10.  
17.2 second thickness, real, col. 11-20.  
17.3 third thickness, real, col. 21-30.  
17.4 fourth thickness, real, col. 31-40.  
17.5 fifth thickness, real, col. 41-50.  
17.6 sixth thickness, real, col. 51-60.  
17.7 seventh thickness, real, col. 61-70.  
17.8 eighth thickness, real, col. 71-80.

Card No. 18:

18.0 PCC overlay thicknesses (inches) in ascending order:  
18.1 first thickness, real, col. 1-10.  
18.2 second thickness, real, col. 11-20.  
18.3 third thickness, real, col. 21-30.  
18.4 fourth thickness, real, col. 31-40.  
18.5 fifth thickness, real, col. 41-50.  
18.6 sixth thickness, real, col. 51-60.  
18.7 seventh thickness, real, col. 61-70.  
18.8 eighth thickness, real, col. 71-80.

Card No. 19:

19.1 Allowable total overlay thickness (inches), real, col.  
1-10.

- 19.2 Average level-up thickness (inches), real, col. 11-20.  
 19.3 Bond breaker thickness (inches), real, col. 21-30.

Card No. 20:

- 20.1 ACP overlay design stiffness (psi), real, col. 1-10.  
 20.2 Poisson's ratio, ACP overlay, real, col. 11-20.  
 20.3 PCC overlay design stiffness (psi), real, col. 21-30.  
 20.4 Poisson's ratio, PCC overlay, real, col. 31-40.  
 20.5 Bond breaker stiffness (psi), real, col. 41-50.  
 20.6 Poisson's ratio, bond breaker, real, col. 51-60.

Card No. 21:

- 21.1 Number of overlay flexural strengths to consider, integer, col. 1-5. (Maximum of 5)  
 21.2 Number which identifies which flexural strength in the list to use for bonded PCC overlay, integer, col. 6-10.

Card No. 22:

- 22.0 PCC overlay flexural strengths (psi) in ascending order:  
 22.1 first flexural strength, real, col. 1-10.  
 22.2 second flexural strength, real, col. 11-20.  
 22.3 third flexural strength, real, col. 21-30.  
 22.4 fourth flexural strength, real, col. 31-40.  
 22.5 fifth flexural strength, real, col. 41-50.

Card Numbers 23 through 40:

These cards define critical stress factors (ratios of critical stress to interior stress) for various overlay and shoulder combinations. These factors also depend on which concrete layer in the structure they apply to, therefore, in the descriptions below, the first term provided represents the layer to which the stress factor applies. The second term describes the overlay combination and the third term describes the shoulder type.

- 23.1 Existing pavement, single ACP overlay, ACP shoulder, real, col. 1-10.
- 24.1 Existing pavement, two ACP overlays, ACP shoulder, real, col. 1-10.
- 25.1 Existing pavement, first overlay-ACP and second-CRCP, ACP shoulder, real, col. 1-10.
- 25.2 Existing pavement, first overlay-ACP and second-CRCP, CRCP shoulder, real, col. 11-20.
- 26.1 CRCP overlay, first overlay-ACP and second-CRCP, ACP shoulder, real, col. 1-10.
- 26.2 CRCP overlay, first overlay-ACP and second-CRCP, CRCP shoulder, real, col. 11-20.

- 27.1 Existing pavement, first overlay-ACP and second-JCP, ACP shoulder, real, col. 1-10.
- 27.2 Existing pavement, first overlay-ACP and second-JCP, JCP shoulder, real, col. 11-20.
- 28.1 JCP overlay, first overlay-ACP second-JCP, ACP shoulder, real, col. 1-10.
- 28.2 JCP overlay, first overlay-ACP second-JCP, JCP shoulder, real, col. 11-20.
- 29.1 Existing pavement, single bonded CRCP overlay, ACP shoulder, real, col. 1-10.
- 29.2 Existing pavement, single bonded CRCP overlay, CRCP shoulder, real, col. 11-20.
- 30.1 Existing pavement, first overlay-bonded CRCP and second-ACP, ACP shoulder, real, col. 1-10.
- 30.2 Existing pavement, first overlay-bonded CRCP and second-ACP, CRCP shoulder, real, col. 11-20.
- 31.1 Existing pavement, single bonded JCP overlay, ACP shoulder, real, col. 1-10.
- 31.2 Existing pavement, single bonded JCP overlay, JCP shoulder, real, col. 11-20.
- 32.1 Existing pavement, first overlay-bonded JCP and second ACP, ACP shoulder, real, col. 1-10.
- 32.2 Existing pavement, first overlay-bonded JCP and second ACP, JCP shoulder, real, col. 11-20.
- 33.1 Existing pavement, single unbonded CRCP overlay, ACP shoulder, real, col. 1-10.
- 33.2 Existing pavement, single unbonded CRCP overlay, CRCP shoulder, real, col. 11-20.
- 34.1 CRCP overlay, single unbonded CRCP overlay, ACP shoulder, real, col. 1-10.
- 34.2 CRCP overlay, single unbonded CRCP overlay, CRCP shoulder, real, col. 11-20.
- 35.1 Existing pavement, first overlay-unbonded CRCP and second-ACP, ACP shoulder, real, col. 1-10.
- 35.2 Existing pavement, first overlay-unbonded CRCP and second-ACP, CRCP shoulder, real, col. 11-20.

- 36.1 CRCP overlay, first overlay-unbonded CRCP and second-ACP, ACP shoulder, real, col. 1-10.
- 36.2 CRCP overlay, first overlay-unbonded CRCP and second-ACP, CRCP shoulder, real, col. 11-20.
- 37.1 Existing pavement, single unbonded JCP overlay, ACP shoulder, real, col. 1-10.
- 37.2 Existing pavement, single unbonded JCP overlay, JCP shoulder, real, col. 11-20.
- 38.1 JCP overlay, single unbonded JCP overlay, ACP shoulder, real, col. 1-10.
- 38.2 JCP overlay, single unbonded JCP overlay, JCP shoulder, real, col. 11-20.
- 39.1 Existing pavement, first overlay-unbonded JCP and second-ACP, ACP shoulder, real, col. 1-10.
- 39.2 Existing pavement, first overlay-unbonded JCP and second-ACP, JCP shoulder, real, col. 11-20.
- 40.1 JCP overlay, first overlay-unbonded JCP and second-ACP, ACP shoulder, real, col. 1-10.
- 40.2 JCP overlay, first overlay-unbonded JCP and second-ACP, JCP shoulder, real, col. 11-20.

## Card No. 41:

- 41.1 Switch on method of response predicton, integer, col. 1-5. (1=LAYER submodel, 2=LAYER regression submodel)

Overlay Construction Cost Variables

## Card No. 42:

- 42.0 Site establishment costs (dollars):
- 42.1 ACP equipment, real, col. 1-10.
- 42.2 CRCP equipment, real, col. 11-20.
- 42.3 JCP equipment, real, col. 21-30.
- 42.4 ACP and CRCP equipment combined, real, col. 31-40.
- 42.5 ACP and JCP equipment combined, real, col. 41-50.

## Card No. 43:

- 43.0 Pavement surface preparation costs (dollars per square yard):
- 43.1 Existing pavement, real, col. 1-10.
- 43.2 ACP overlay, real, col. 11-20.
- 43.3 CRCP overlay, real, col. 21-30.
- 43.4 JCP overlay, real, col. 31-40.

## Card No. 44:

- 44.1 Fixed cost of ACP overlay construction (dollars per square yard), real, col. 1-10.
- 44.2 Variable cost of ACP overlay construction (dollars per square yard per inch), real, col. 11-20.
- 44.3 Fixed cost of flexible shoulder construction (dollars per square yard), real, col. 21-30.
- 44.4 Variable cost of flexible shoulder construction (dollars per square yard per inch), real, col. 31-40.
- 44.5 Cost of bond breaker construction (dollars per square yard), real, col. 41-50.

## Card No. 45:

- 45.0 CRCP fixed cost for each flexural strength (dollars per square yard):
  - 45.1 first, real, col. 1-10.
  - 45.2 second, real, col. 11-20.
  - 45.3 third, real, col. 21-30.
  - 45.4 fourth, real, col. 31-40.
  - 45.5 fifth, real, col. 41-50.

## Card No. 46:

- 46.0 CRCP variable cost for each flexural strength (dollars per square yard per inch):
  - 46.1 first, real, col. 1-10.
  - 46.2 second, real, col. 11-20.
  - 46.3 third, real, col. 21-30.
  - 46.4 fourth, real, col. 31-40.
  - 46.5 fifth, real, col. 41-50.

## Card No. 47:

- 47.0 JCP fixed cost for each flexural strength (dollars per square yard):
  - 47.1 first, real, col. 1-10.
  - 47.2 second, real, col. 11-20.
  - 47.3 third, real, col. 21-30.
  - 47.4 fourth, real, col. 31-40.
  - 47.5 fifth, real, col. 41-50.

## Card No. 48:

- 48.0 JCP variable cost for each flexural strength (dollars per square yard per inch):
  - 48.1 first, real, col. 1-10.
  - 48.2 second, real, col. 11-20.
  - 48.3 third, real, col. 21-30.
  - 48.4 fourth, real, col. 31-40.
  - 48.5 fifth, real, col. 41-50.

## Card No. 49:

- 49.1 Total steel percentage required in CRCP overlays, real, col. 1-10.
- 49.2 Total steel percentage required in JCP overlays, real, col. 11-20.

49.3 Cost of steel reinforcement (dollars per pound), real,  
col. 21.30.

Traffic Delay Cost Variables

Card No. 50:

- 50.1 Location of project, integer, col. 1-5. (1=rural,  
2=urban)
- 50.2 Model number for handling traffic, integer, col. 6-10.  
(See User's Manual, Chapter 6)
- 50.3 Number of open lanes, overlay direction, integer, col.  
11-15.
- 50.4 Number of open lanes, non-overlay direction, integer,  
col. 16-20.

Card No. 51:

- 51.1 Military time of day overlay construction begins, real,  
col. 1-10. (e.g. 900. for 9:00 am)
- 51.2 Military time of day overlay construction ends, real,  
col. 11-20. (e.g. 1600. for 4:00 pm)
- 51.3 Hours per day overlay construction occurs, real, col.  
21-30.
- 51.4 Number of days concrete is allowed to cure, real, col.  
31-40.
- 51.5 Detour distance for detour model number 5 (miles), real,  
col. 41-50.

Card No. 52:

- 52.1 Average approach speed (mph), real, col. 1-10.
- 52.2 Average speed in overlay direction (mph), real, col.  
11-20.
- 52.3 Average speed in non-overlay direction (mph), real, col.  
21-30.

Card No. 53:

- 53.1 Distance traffic is slowed in overlay direction (miles),  
real, col. 1-10.
- 53.2 Distance traffic is slowed in non-overlay direction  
(miles), real, col. 11-20.
- 53.3 Percent of vehicles stopped in overlay direction, real,  
col. 21-30.
- 53.4 Percent of vehicles stopped in non-overlay direction,  
real, col. 31-40.
- 53.5 Average vehicle delay in overlay direction (hours),  
real, col. 41-50.
- 53.6 Average vehicle delay in non-overlay direction (hours),  
real, col. 51-60.

Card No. 54:

- 54.1 ACP production rate (cubic yards per hour), real, col.  
1-10.
- 54.2 CRCP production rate (cubic yards per hour), real, col.  
11-20.

- 54.3 JCP production rate (cubic yards per hour), real, col. 21-30.
- 54.4 Bond breaker production rate (cubic yards per hour), real, col. 31-40.

#### Distress/Maintenance Cost Variables

Card No. 55:

- 55.1 CRCP overlay distress repair cost (dollars), real, col. 1-5.
- 55.2 Initial CRCP overlay distress rate (number per mile per year), real, col. 6-10.
- 55.3 Secondary CRCP overlay distress rate (number per mile per year), real, col. 11-15.
- 55.4 CRCP overlay distress rate (number per mile) for each year after loss of pavement load-carrying capacity:
- 1 first year after, real, col. 16-20.
  - 2 second year after, real, col. 21-25.
  - 3 third year after, real, col. 26-30.
  - 4 fourth year after, real, col. 31-35.
  - 5 fifth year after, real, col. 36-40.
  - 6 sixth year after, real, col. 41-45.
  - 7 seventh year after, real, col. 46-50.
  - 8 eighth year after, real, col. 51-55.
  - 9 ninth year after, real, col. 56-60.
  - 10 tenth year after, real, col. 61-65.

Card No. 56:

- 56.1 JCP overlay distress repair cost (dollars), real, col. 1-5.
- 56.2 Initial JCP overlay distress rate (number per mile per year), real, col. 6-10.
- 56.3 Secondary JCP overlay distress rate (number per mile per year), real, col. 11-15.
- 56.4 JCP overlay distress rate (number per mile) for each year after loss of pavement load-carrying capacity:
- 1 first year after, real, col. 16-20.
  - 2 second year after, real, col. 21-25.
  - 3 third year after, real, col. 26-30.
  - 4 fourth year after, real, col. 31-35.
  - 5 fifth year after, real, col. 36-40.
  - 6 sixth year after, real, col. 41-45.
  - 7 seventh year after, real, col. 46-50.
  - 8 eighth year after, real, col. 51-55.
  - 9 ninth year after, real, col. 56-60.
  - 10 tenth year after, real, col. 61-65.

Card No. 57:

- 57.1 Distress repair cost (dollars) for an ACP overlay on CRCP, real, col. 1-5.
- 57.2 Initial ACP/CRCP distress rate (number per mile per year), real, col. 6-10.

- 57.3 Secondary ACP/CRPC distress rate (number per mile per year), real, col. 11-15.
- 57.4 ACP/CRPC distress rate (number per mile) for each year after loss of pavement load-carrying capacity:
- 1 first year after, real, col. 16-20.
  - 2 second year after, real, col. 21-25.
  - 3 third year after, real, col. 26-30.
  - 4 fourth year after, real, col. 31-35.
  - 5 fifth year after, real, col. 36-40.
  - 6 sixth year after, real, col. 41-45.
  - 7 seventh year after, real, col. 46-50.
  - 8 eighth year after, real, col. 51-55.
  - 9 ninth year after, real, col. 56-60.
  - 10 tenth year after, real, col. 61-65.

**Card No. 58:**

- 58.1 Distress repair cost (dollars) for an ACP overlay on JCP, real, col. 1-5.
- 58.2 Initial ACP/JCP distress rate (number per mile per year), real, col. 6-10.
- 58.3 Secondary ACP/JCP distress rate (number per mile per year), real, col. 11-15.
- 58.4 ACP/JCP distress rate (number per mile) for each year after loss of pavement load-carrying capacity:
- 1 first year after, real, col. 16-20.
  - 2 second year after, real, col. 21-25.
  - 3 third year after, real, col. 26-30.
  - 4 fourth year after, real, col. 31-35.
  - 5 fifth year after, real, col. 36-40.
  - 6 sixth year after, real, col. 41-45.
  - 7 seventh year after, real, col. 46-50.
  - 8 eighth year after, real, col. 51-55.
  - 9 ninth year after, real, col. 56-60.
  - 10 tenth year after, real, col. 61-65.

**Cost Returns**

**Card No. 59:**

- 59.1 Salvage value, percent of overlay construction cost, real, col. 1-10.
- 59.2 Value of each year of extended life (dollars per square yard per year), real, col. 11-20.

**Combined Interest and Inflation Rate**

**Card No. 60:**

- 60.1 Interest rate minus inflation rate (percent), real, col. 1-10.

This concludes the input of data for a single problem. For an additional problem, the user should begin again with card no. 1, otherwise the last card should have STOP in columns 1 through 4.

Format for RPRDS-1 data input:

CARD No.	COLUMN NUMBERS											
	1	10	20	30	40	50	60	70	80			
1	1.1											
2	2.1	2.2	2.3	2.4								
3	3.1			3.2			3.3					
4	4.1			4.2			4.3		4.4		4.5	
5	5.1			5.2			5.3		5.4		5.5	
6	6.1			6.2			6.3		6.4		6.5	
7	7.1			7.2			7.3					
8	8.1			8.2			8.3					
9	9.1			9.2			9.3		9.4		9.5	9.6
10	10.1			10.2			10.3					
11	11.1	11.2	11.31	11.32	11.33	11.34	11.35	11.36	11.37	11.38	11.39	11.310
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13	13.1	13.2	13.3	13.4	13.5							
14	14.1	14.2	14.3									
15	15.1	15.2	15.3									

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CARD No.	COLUMN NUMBERS							
	10	20	30	40	50	60	70	80
16	16.1	16.2	16.3	16.4	16.5	16.6	16.7	16.8
17	17.1	17.2	17.3	17.4	17.5	17.6	17.7	17.8
18	18.1	18.2	18.3	18.4	18.5	18.6	18.7	18.8
19	19.1	19.2	19.3					
20	20.1	20.2	20.3	20.4	20.5	20.6		
21	21.1	21.2						
22	22.1	22.2	22.3	22.4	22.5			
23	23.1							
24	24.1							
25	25.1	25.2						
26	26.1	26.2						
27	27.1	27.2						
28	28.1	28.2						
29	29.1	29.2						
30	30.1	30.2						
31	31.1	31.2						
32	32.1	32.2						

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CARD No.	COLUMN NUMBERS							
	1	10	20	30	40	50	60	70
33	33.1	33.2						
34	34.1	34.2						
35	35.1	35.2						
36	36.1	36.2						
37	37.1	37.2						
38	38.1	38.2						
39	39.1	39.2						
40	40.1	40.2						
41	41.1							
42	42.1	42.2	42.3	42.4	42.5			
43	43.1	43.2	43.3	43.4				
44	44.1	44.2	44.3	44.4	44.5			
45	45.1	45.2	45.3	45.4	45.5			
46	46.1	46.2	46.3	46.4	46.5			
47	47.1	47.2	47.3	47.4	47.5			
48	48.1	48.2	48.3	48.4	48.5			
49	49.1	49.2	49.3					

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CARD No.	COLUMN NUMBERS												
	1	10	20	30	40	50	60	70	80				
50	50.1	50.2	50.3	50.4									
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52	52.1		52.2		52.3								
53	53.1		53.2		53.3		53.4		53.5		53.6		
54	54.1		54.2		54.3		54.4						
55	55.1	55.2	55.3	55.41	55.42	55.43	55.44	55.45	55.46	55.47	55.48	55.49	55.410
56	56.1	56.2	56.3	56.41	56.42	56.43	56.44	56.45	56.46	56.47	56.48	56.49	56.410
57	57.1	57.2	57.3	57.41	57.42	57.43	57.44	57.45	57.46	57.47	57.48	57.49	57.410
58	58.1	58.2	58.3	58.41	58.42	58.43	58.44	58.45	58.46	58.47	58.48	58.49	58.410
59	59.1		59.2										
60	60.1												

This concludes the data input for a single problem. For an additional problem, the user should begin again with card no. 1; otherwise the following should be the last card entered:

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-- CTR Library Digitization Team

APPENDIX E

CODED DATA FOR RPRDS-1 EXAMPLE PROBLEM

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-- CTR Library Digitization Team

IDENTIFICATION	REF ID	TEST PLAN	CODED BY	DATE	NO. 280	PAGE 2 of 4
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APPENDIX E. CODED DATA FOR . . .

264

## RUN 21 TEST - REDESIGN FOR EASY INTEGRATION

IDENTIFICATION OVERLAP INDEX 21-1120  
CODED BY S. DATE Nov 1932 PAGE 1 OF 4

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DATE Nov. 1935 PAGE 3 OF 4

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**IDENTIFICATION —**



## APPENDIX F

RPRDS-1 EXAMPLE PROBLEM- INPUT SUMMARY

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APPENDIX F. RPRDS-1 SAMPLE PROBLEM-INPUT SUMMARY

RPRDS1 - RIGID PAVEMENT REHABILITATION DESIGN SYSTEM - VERSION 1, NOV 1980  
 CENTER FOR TRANSPORTATION RESEARCH  
 UNIVERSITY OF TEXAS AT AUSTIN

\*\*\*\*\*  
 R P R D S   I N P U T   S U M M A R Y  
 \*\*\*\*\*

NOTE - VARIABLE NUMBERS CORRESPOND TO THOSE IN RPRDS USERS MANUAL

PROJECT DESCRIPTION

\*\*\*\*\*

1.1 TITLE  
 RPRDS1 TEST - REDESIGN FOR FRATT INTCHNG O/L PROJECT, S A TX, SBS/11/80

ORIGINAL PAVEMENT

\*\*\*\*\*

2.1	SURFACE TYPE	JCP
2.2	CONCRETE SHOULDER	NO
2.3	NO. OF LANES (ONE DIRECTION)	4
2.4	NO. OF PAVEMENT LAYERS	3
3.1	PROJECT LENGTH, MILES	2.50
3.2	LANE WIDTH, FEET	12.0
3.3	TOTAL SHOULDER WIDTH, FEET	3.

PAVEMENT STRUCTURE

LAYER NO.	THICKNESS (IN)	ELASTIC MODULUS (PSI)	Poissons Ratio
1	10.5	5000000	.15
2	14.0	5000000	.40
3	SEMI-INFINITE	6000000	.45

7.1	CONCRETE FLEXURAL STRENGTH, PSI	6000
7.2	CRITICAL STRESS FACTOR	1.40
7.3	CONCRETE STIFFNESS AFTER CRACKING, PSI	5000000
8.1	NO. OF EXISTING DEFECTS PER MILE	10
8.2	COST OF REPAIRING A DEFECT, DOL	20000
8.3	RATE OF DEFECT DEVELOPMENT, NO./YR/MILE	4.

## TRAFFIC VARTABLES

\*\*\*\*\*

9.1	AVERAGE DAILY TRAFFIC (ADT)	56000.
9.2	ADT GROWTH RATE, PERCENT	2.00
9.3	INITIAL YEARLY 18-KIP FSAL, MILLIONS	1.200
9.4	18-KIP FSAL GROWTH RATE, PERCENT	3.00
9.5	DIRECTIONAL DISTRIBUTION FACTOR, PERCENT	50.0
9.6	LANE DISTRIBUTION FACTOR, PERCENT	70.0

## TIME CONSTRAINTS

\*\*\*\*\*

10.1	ANALYSIS PERIOD, YEARS	20.0
10.2	MINIMUM TIME BETWEEN OVERLAYS, YEARS	5.0
10.3	MAXIMUM ALLOWABLE YEARS OF HEAVY MAINTENANCE AFTER LOSS OF STRUCTURAL LOAD-CARRYING CAPACITY	5.0

## REMAINING LIFE VARTABLES

\*\*\*\*\*

- 11.1 NO. OF ORIGINAL PAVEMENT REMAINING LIFE  
VALUES TO CONSIDER 4  
 11.2 MINIMUM EXISTING PAVEMENT REMAINING LIFE BELOW  
WHICH A BONDED PCC OVERLAY MAY NOT BE PLACED 10.  
 11.3 VALUES OF ORIGINAL PAVEMENT REMAINING LIFE AT WHICH  
FIRST OVERLAY MAY BE PLACED

NO.	REMAINING LIFE (PERCENT)
1	30.
2	24.
3	18.
4	0.

- 12.1 NO. OF FIRST OVERLAY REMAINING LIFE  
VALUES TO CONSIDER 5  
 12.2 VALUES OF FIRST OVERLAY REMAINING LIFE AT WHICH  
SECOND OVERLAY MAY BE PLACED

NO.	REMAINING LIFE (PERCENT)
1	84.
2	64.
3	44.
4	24.
5	0.

**OVERLAY CHARACTERISTICS**

\*\*\*\*\*

**13.I TYPES OF FIRST OVERLAY TO CONSIDER**

- .1 ACP = YES
- .2 BONDED CRCP = NO
- .3 UNBONDED CRCP = YES
- .4 BONDED JCP = NO
- .5 UNBONDED JCP = NO

**14.I TYPES OF SECOND OVERLAY TO CONSIDER**

- .1 ACP = YES
- .2 CRCP = YES
- .3 JCP = NO

**15.I NO. OF DIFFERENT OVERLAY THICKNESS TO CONSIDER**

- .1 ACP FIRST OVERLAY = 3
- .2 ACP SECOND OVERLAY = 4
- .3 PCC OVERLAY = 5

**16.I ACP FIRST OVERLAY THICKNESSES, INCHES**

- .1 4.0
- .2 5.0
- .3 6.0

**17.I ACP SECOND OVERLAY THICKNESSES, INCHES**

- .1 3.0
- .2 4.0
- .3 5.0
- .4 6.0

**18.I PCC OVERLAY THICKNESSES, INCHES**

- .1 6.0
- .2 6.5
- .3 7.0
- .4 7.5
- .5 8.0

19.1	ALLOWABLE TOTAL OVERLAY THICKNESS, INCHES	14.0
19.2	AVERAGE LEVEL-UP THICKNESS, INCHES	.5
19.3	BOND BREAKER THICKNESS, INCHES	1.0
20.1	ACP OVERLAY DESIGN STIFFNESS, PSI	3000000.
20.2	POISSONS RATIO, ACP OVERLAY	.30
20.3	PCC OVERLAY DESIGN STIFFNESS, PST	4500000.
20.4	POISSONS RATIO, PCC OVERLAY	.15
20.5	BOND BREAKER STIFFNESS, PST	50000.
20.6	POISSONS RATIO, BOND BREAKER	.30
21.1	NO. OF OVERLAY FLEXURAL STRENGTHS TO CONSIDER	2
21.2	NO. WHICH IDENTIFIES WHICH FLEXURAL STRENGTH IN THE LIST TO USE FOR A BONDED PCC OVERLAY	1
22.0	PCC OVERLAY FLEXURAL STRENGTH(S), PSI	
	.1 600.	
	.2 650.	

## \*\*\* PAVEMENT STRESS FACTORS AFTER OVERLAY \*\*\*

FIRST OVERLAY TYPE	SECOND OVERLAY TYPE	CRITICAL STRESS LOCATION	OVERLAY SHOULDER TYPE	CRIT./INTER. STRESS FACTOR
23.1	ACP	(NONE)	EX PAVT	ACP 1.40
24.1	ACP	ACP	EX PAVT	ACP 1.40
25.1	ACP	CRCP	EX PAVT	ACP 1.25
25.2	ACP	CRCP	EX PAVT	CRCP 1.05
26.1	ACP	CRCP	CRCP O/L	ACP 1.25
26.2	ACP	CRCP	CRCP O/L	CRCP 1.05
27.1	ACP	JCP	EX PAVT	ACP 0.00
27.2	ACP	JCP	EX PAVT	JCP 0.00
28.1	ACP	JCP	JCP O/L	ACP 0.00
28.2	ACP	JCP	JCP O/L	JCP 0.00
29.1	BOND CRC	(NONE)	EX PAVT	ACP 0.00
29.2	BOND CRC	(NONE)	EX PAVT	CRCP 0.00
30.1	BOND CRC	ACP	EX PAVT	ACP 0.00
30.2	BOND CRC	ACP	EX PAVT	CRCP 0.00
31.1	BOND JCP	(NONE)	EX PAVT	ACP 0.00
31.2	BOND JCP	(NONE)	EX PAVT	JCP 0.00
32.1	BOND JCP	ACP	EX PAVT	ACP 0.00
32.2	BOND JCP	ACP	EX PAVT	JCP 0.00
33.1	UNRD CRC	(NONE)	EX PAVT	ACP 1.25
33.2	UNRD CRC	(NONE)	EX PAVT	CRCP 1.05
34.1	UNRD CRC	(NONE)	CRCP O/L	ACP 1.25
34.2	UNRD CRC	(NONE)	CRCP O/L	CRCP 1.05
35.1	UNRD CRC	ACP	EX PAVT	ACP 1.25
35.2	UNRD CRC	ACP	EX PAVT	CRCP 1.05
36.1	UNRD CRC	ACP	CRCP O/L	ACP 1.25
36.2	UNRD CRC	ACP	CRCP O/L	CRCP 1.05
37.1	UNRD JCP	(NONE)	EX PAVT	ACP 0.00
37.2	UNRD JCP	(NONE)	EX PAVT	JCP 0.00
38.1	UNRD JCP	(NONE)	JCP O/L	ACP 0.00
38.2	UNRD JCP	(NONE)	JCP O/L	JCP 0.00
39.1	UNRD JCP	ACP	EX PAVT	ACP 0.00
39.2	UNRD JCP	ACP	EX PAVT	JCP 0.00
40.1	UNRD JCP	ACP	JCP O/L	ACP 0.00
40.2	UNRD JCP	ACP	JCP O/L	JCP 0.00

NOTE - STRATEGIES WITH A ZERO VALUE FOR THE CRITICAL TO INTERIOR STRESS FACTOR WILL NOT BE CONSIDERED.

## OVERLAY CONSTRUCTION COST VARIABLES

\*\*\*\*\*

## 42.M SITE ESTABLISHMENT COST, DOL

.1 ACP EQUIPMENT	10000.
.2 CRCP EQUIPMENT	20000.
.3 JCP EQUIPMENT	20000.
.4 ACP AND CRCP EQUIPMENT	25000.
.5 ACP AND JCP EQUIPMENT	25000.

## 43.M PAVEMENT SURFACE PREPARATION COSTS, DOL/SY

.1 EXISTING PAVEMENT	.20
.2 ACP OVERLAY	.20
.3 CRCP OVERLAY	.20
.4 JCP OVERLAY	.20

44.1 FIXED COST OF ACP OVERLAY CONSTRUCTION, DOL/SY	2.00
44.2 VARIABLE COST OF ACP OVERLAY CONSTR., DOL/SY/IN	1.00
44.3 FIXED COST OF FLEXIBLE SHOULDER CONSTR., DOL/SY	4.00
44.4 VARIABLE COST OF FLEX. SHOULDER CONSTR., DOL/SY/IN	.50
44.5 COST OF BOND BREAKER CONSTRUCTION, DOL/SY	2.00

## 45.M CRCP FIXED COST FOR EACH FLEXURAL STRENGTH

FLEXURAL STRENGTH (PSI)	FIXED COST (DOL/SY)
.1 680.	4.00
.2 654.	4.00

## 46.M CRCP VARIABLE COST FOR EACH FLEXURAL STRENGTH

FLEXURAL STRENGTH (PSI)	VARIABLE COST (DOL/SY/IN)
.1 680.	1.20
.2 654.	1.30

## 47.0 JCP FIXED COST FOR EACH FLEXURAL STRENGTH

FLEXURAL STRENGTH (PSI)	FIXED COST (DOL/SY)
.1 600.	2.00
.2 650.	2.00

## 48.0 JCP VARIABLE COST FOR EACH FLEXURAL STRENGTH

FLEXURAL STRENGTH (PSI)	VARIABLE COST (DOL/SY/TN)
.1 600.	0.00
.2 650.	0.00

49.1 TOTAL STEEL PERCENTAGE REQUIRED IN CRCP OVERLAYS	.60
49.2 TOTAL STEEL PERCENTAGE REQUIRED IN JCP OVERLAYS	0.00
49.3 COST OF STEEL REINFORCEMENT, DOL/LB	.50

## TRAFFIC DELAY COST VARIABLES

\*\*\*\*\*

50.1	LOCATION OF PROJECT (1=RURAL,2=URBAN)	2
50.2	MODEL NO. FOR HANDLING TRAFFIC	5
50.3	NO. OF OPEN LANES, OVERLAY DIRECTION	2
50.4	NO. OF OPEN LANES, NON-OVERLAY DIRECTION	4
51.1	MILITARY TIME OVERLAY CONSTRUCTION BEGINS	0000
51.2	MILITARY TIME OVERLAY CONSTRUCTION ENDS	1600
51.3	HOURS PER DAY OVERLAY CONSTRUCTION OCCURS	6.0
51.4	NO. OF DAYS CONCRETE IS ALLOWED TO CURE	14.
51.5	DETOUR DISTANCE TO USE IN MODEL 5, MILES	2.5
52.1	AVERAGE APPROACH SPEED, MPH	55,
52.2	AVERAGE SPEED, OVERLAY DIRECTION, MPH	40,
52.3	AVERAGE SPEED, NON-OVERLAY DIRECTION, MPH	55.
53.1	DISTANCE TRAFFIC IS SLOWED, OVERLAY DIRECTION, MILES	3.0
53.2	DISTANCE TRAFFIC IS SLOWED, NON-OVERLAY DIR., MILES	0.0
53.3	PERCENT OF VEHICLES STOPPED, OVERLAY DIRECTION	10.0
53.4	PERCENT OF VEHICLES STOPPED, NON-OVERLAY DIRECTION	0.0
53.5	AVERAGE VEHICLE DELAY, OVERLAY DIRECTION, HRS	.00200
53.6	AVERAGE VEHICLE DELAY, NON-OVERLAY DIRECTION, HRS	0.00000
54.1	ACR PRODUCTION RATE, CY/HR	42.
54.2	CRCR PRODUCTION RATE, CY/HR	60.
54.3	JCP PRODUCTION RATE, CY/HR	0.
54.4	BOND BREAKER PRODUCTION RATE, CY/HR	40.

## DISTRESS/MATNTENANCE COST VARTABLES

\*\*\*\*\*

55.1	DISTRESS REPAIR COST, CRCP OVERLAY, DOL	2000.00
55.2	INITIAL CRCP OVERLAY DISTRESS RATE, NO./MI/YR	1.0
55.3	SECONDARY CRCP OVERLAY DISTRESS RATE, NO./MI/YR	2.0
55.4	CRCP OVERLAY DISTRESS RATE FOR EACH YEAR AFTER LOSS OF PAVEMENT LOAD-CARRYING CAPACITY	

YEAR AFTER FAILURE	DISTRESS RATE (NO./MILE)
-----------------------	-----------------------------

-----	-----
1	3.0
2	5.0
3	8.0
4	16.0
5	40.0

56.1	DISTRESS REPAIR COST, JCP OVERLAY, DOL	0.00
56.2	INITIAL JCP OVERLAY DISTRESS RATE, NO./MI/YR	0.0
56.3	SECONDARY JCP OVERLAY DISTRESS RATE, NO./MI/YR	0.0
56.4	JCP OVERLAY DISTRESS RATE FOR EACH YEAR AFTER LOSS OF PAVEMENT LOAD CARRYNG CAPACITY	

YEAR AFTER FAILURE	DISTRESS RATE (NO./MILE)
-----------------------	-----------------------------

-----	-----
1	0.0
2	0.0
3	0.0
4	0.0
5	0.0

57.1	DISTRESS REPAIR COST, ACP OVERLAY ON CRCP, DOL	500.00
57.2	INITIAL ACP/CRCP DISTRESS RATE, NO./MI/YR	1.0
57.3	SECONDARY ACP/CRCP DISTRESS RATE, NO./MI/YR	2.0
57.4	ACP/CRCP DISTRESS RATE FOR EACH YEAR AFTER LOSS OF PAVEMENT LOAD-CARRYING CAPACITY	

YEAR AFTER FAILURE	DISTRESS RATE (NO./MILE)
1	3.0
2	5.0
3	8.0
4	16.0
5	40.0

58.1	DISTRESS REPAIR COST, ACP OVERLAY ON JCP, DOL	100.00
58.2	INITIAL ACP/JCP DISTRESS RATE, NO./MI/YR	5.0
58.3	SECONDARY ACP/JCP DISTRESS RATE, NO./MI/YR	10.0
58.4	ACP/JCP DISTRESS RATE FOR EACH YEAR AFTER LOSS OF PAVEMENT LOAD CARRYING CAPACITY	

YEAR AFTER FAILURE	DISTRESS RATE (NO./MILE)
1	20.0
2	40.0
3	80.0
4	160.0
5	400.0

## COST RETURNS

\*\*\*\*\*

59.1	SALVAGE VALUE, PERCENT OF OVERLAY CONSTRUCTION COST	10.0
59.2	VALUE OF EACH YEAR OF EXTENDED LIFE, DOL/SY/YR	.25

## COMBINED INTEREST AND INFLATION RATE

\*\*\*\*\*

60.1	INTEREST RATE MINUS INFLATION RATE, PERCENT	5.0
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APPENDIX G

RPRDS-1 EXAMPLE PROBLEM-OUTPUT

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## APPENDIX G. RPRDS-1 EXAMPLE PROBLEM-OUTPUT

\*\*\*\*\*  
 R P R D S   O U T P U T  
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THE FOLLOWING IS A LIST OF THE COMPONENTS WHICH MAKE UP A FEASIBLE OVERLAY DESIGN STRATEGY. THE COLUMN NUMBERS REFER TO THE COLUMN HEADINGS ON THE LIST OF FEASIBLE STRATEGIES WHICH BEGIN ON THE NEXT PAGE; THE DESCRIPTIONS IN THESE HEADING ALSO CORRESPOND TO THOSE IN THE LIST OF OPTIMAL STRATEGIES WHICH SUCCEED THE LIST OF FEASIBLE STRATEGIES.

COL NO.	COMPONENT OF STRATEGY
1.	STRATEGY NO.
1.	EXISTING PAVEMENT REMAINING LIFE AT TIME OF FIRST OVERLAY PLACEMENT (PERCENT)
2.	APPROXIMATE YEAR OF FIRST OVERLAY PLACEMENT
3.	TOTAL 18-KIP ESAL FATIGUE CYCLES BETWEEN YEAR ZERO AND YEAR OF FIRST OVERLAY PLACEMENT, MILLIONS
4.	PRESENT VALUE OF EXISTING PAVEMENT MAINTENANCE COST (DOL/SQ YD)
5.	FIRST OVERLAY TYPE
1	ASPHALTIC CONCRETE
2	BONDED CRCP
3	UNBONDED CRCP
4	BONDED JCP
5	UNBONDED JCP
	NOTE - A * AFTER NUMBER INDICATES PCC SHOULDER REQUIRED
7.	THICKNESS OF FIRST OVERLAY (INCHES)
8.	FLEXURAL STRENGTH OF FIRST OVERLAY (PSI)
9.	APPROXIMATE YEAR OF LOSS OF PAVEMENT LOAD-CARRYING CAPACITY AFTER FIRST OVERLAY
10.	TOTAL 18-KIP ESAL FATIGUE CYCLES BETWEEN YEAR ZERO AND YEAR OF FIRST OVERLAY FAILURE
11.	PRESENT VALUE OF COST OF FIRST OVERLAY CONSTRUCTION (DOL/SQ YD)
12.	PRESENT VALUE OF TRAFFIC DELAY COSTS DURING FIRST OVERLAY CONSTRUCTION (DOL/SQ YD)
13.	PRESENT VALUE OF FIRST OVERLAY MAINTENANCE COST (DOL/SQ YD)
14.	REMAINING LIFE OF FIRST OVERLAY AT TIME OF SECOND OVERLAY PLACEMENT (PERCENT)
15.	APPROXIMATE YEAR OF SECOND OVERLAY PLACEMENT
16.	TOTAL 18-KIP ESAL FATIGUE CYCLES BETWEEN YEAR ZERO AND YEAR OF SECOND OVERLAY PLACEMENT, MILLIONS
17.	SECOND OVERLAY TYPE
1	ASPHALTIC CONCRETE
2	CRCP
3	JCP
	NOTE - A * AFTER NUMBER INDICATES PCC SHOULDER REQUIRED
19.	THICKNESS OF SECOND OVERLAY (INCHES)
20.	FLEXURAL STRENGTH OF SECOND OVERLAY (PSI)
21.	APPROXIMATE YEAR OF LOSS OF PAVEMENT LOAD-CARRYING CAPACITY AFTER SECOND OVERLAY
22.	TOTAL 18-KIP ESAL FATIGUE CYCLES BETWEEN YEAR ZERO AND YEAR OF SECOND OVERLAY FAILURE
23.	PRESENT VALUE OF COST OF SECOND OVERLAY CONSTRUCTION (DOL/SQ YD)
24.	PRESENT VALUE OF TRAFFIC DELAY COSTS DURING SECOND OVERLAY CONSTRUCTION (DOL/SQ YD)
25.	PRESENT VALUE OF SECOND OVERLAY MAINTENANCE COST (DOL/SQ YD)
26.	PRESENT VALUE OF THE EXTENDED LIFE (DOL/SQ YD)
27.	SALVAGE VALUE OF OVERLAY LAYERS (DOL/SQ YD)
28.	TOTAL NET PRESENT VALUE OF STRATEGY (DOL/SQ YD)



58	30	0.0	0.0	71	1	6.0	4	9.7	5.5	8.76	.43	.28	0	9.7	5.5	2	6.0	650	30	22.3	7.90	.52	.22	.78	.45	17.51	
59	30	0.0	0.0	71	1	6.0	4	9.7	5.5	8.76	.43	.28	0	9.7	5.5	2*	6.0	650	36	28.2	7.65	.52	.18	1.06	.33	17.86	
60	30	0.0	0.0	71	1	6.0	4	9.7	5.5	8.76	.43	.28	0	9.7	5.5	2*	6.0	650	43	34.8	8.05	.52	.15	1.27	.26	17.30	
61	30	0.0	0.0	71	3	6.0	600	25.3	17.2	13.38	.77	.78															
62	30	0.0	0.0	71	3	6.0	650	29.2	28.7	13.95	.77	.67															
63	30	0.0	0.0	71	3*	6.0	600	38.6	30.0	13.73	.77	.48															
64	30	0.0	0.0	71	3*	6.0	650	44.2	36.1	14.33	.77	.43															
65	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.4	3.4	1	6.0	0	17	11.0	6.42	.36	.32	0.00	.56	14.47
66	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.4	3.4	2	6.0	650	24	16.2	8.85	.58	.47	.33	.56	16.93
67	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.4	3.4	2	6.0	650	28	19.9	9.30	.58	.37	.61	.47	17.00
68	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.4	3.4	2*	6.0	600	34	25.7	8.99	.58	.30	.93	.34	16.52
69	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.4	3.4	2*	6.0	650	40	32.2	9.47	.58	.25	1.21	.26	16.76
70	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.4	3.5	2	6.0	600	24	16.2	8.83	.58	.47	.33	.55	16.91
71	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.4	3.5	2	6.0	650	28	19.9	9.28	.58	.37	.61	.47	17.00
72	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.4	3.5	2*	6.0	600	34	25.7	8.98	.58	.29	.93	.34	16.51
73	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.4	3.5	2*	6.0	650	40	32.2	9.45	.58	.25	1.21	.26	16.74
74	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.4	3.5	2	6.0	600	24	16.2	8.81	.58	.46	.33	.55	16.95
75	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.4	3.5	2	6.0	650	28	19.9	9.26	.58	.37	.61	.47	17.11
76	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.4	3.5	2*	6.0	600	34	25.7	8.96	.58	.29	.93	.34	16.54
77	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.4	3.5	2*	6.0	650	40	32.2	9.43	.58	.25	1.21	.26	16.77
78	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.5	3.5	2	6.0	600	24	16.3	8.79	.58	.46	.33	.55	16.92
79	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.5	3.5	2	6.0	650	28	20.0	9.24	.57	.37	.61	.47	17.08
80	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.5	3.5	2*	6.0	600	34	25.8	8.94	.57	.29	.98	.34	16.47
81	20	0.0	0.0	98	1	4.0	0	6.5	3.5	6.56	.28	.18	0	6.0	6.5	3.5	2*	6.0	650	40	32.3	9.41	.57	.25	1.21	.26	16.75
82	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.2	4.0	1	5.0	0	18	11.7	5.48	.29	.30	0.00	.56	14.49
83	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.2	4.0	1	6.0	0	27	18.7	6.16	.35	.10	.55	.42	14.62
84	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.2	4.0	2	6.0	600	24	16.8	8.48	.56	.40	.41	.57	17.45
85	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.2	4.0	2	6.0	650	29	28.5	8.91	.56	.30	.67	.47	17.62
86	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.2	4.0	2*	6.0	600	35	26.4	8.63	.56	.26	.98	.35	17.18
87	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.2	4.0	2*	6.0	650	41	32.9	9.08	.56	.22	1.21	.26	17.37
88	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.3	4.0	1	5.0	0	15	9.3	5.45	.29	1.11	0.00	.56	15.27
89	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.3	4.0	1	6.0	0	21	14.1	6.13	.35	.13	.18	.55	14.86
90	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.3	4.0	2	6.0	600	24	16.9	8.44	.56	.39	.01	.56	17.41
91	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.3	4.0	2	6.0	650	29	20.6	8.87	.56	.30	.67	.47	17.57
92	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.3	4.0	2*	6.0	600	35	26.5	8.58	.56	.26	.98	.35	17.06
93	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.3	4.0	2*	6.0	650	41	33.0	9.04	.56	.22	1.21	.26	17.33
94	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.4	4.1	1	6.0	0	15	9.5	6.10	.35	1.07	0.00	.60	15.90
95	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.4	4.1	2	6.0	600	24	16.9	8.48	.56	.39	.41	.56	17.37
96	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.4	4.1	2	6.0	650	29	20.7	8.83	.56	.30	.67	.47	17.53
97	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.4	4.1	2*	6.0	600	35	26.5	8.54	.56	.26	.98	.34	17.02
98	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.4	4.1	2*	6.0	650	41	33.1	8.99	.56	.22	1.21	.26	17.28
99	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.5	4.1	2	6.0	600	25	17.0	8.36	.56	.39	.41	.56	17.33
100	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.5	4.1	2	6.0	650	29	20.7	8.78	.56	.30	.67	.47	17.08
101	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.5	4.1	2*	6.0	600	35	26.6	8.50	.56	.25	.98	.34	16.97
102	20	0.0	0.0	98	1	5.0	0	7.5	4.1	7.50	.35	.15	0	6.0	7.5	4.1	2*	6.0	650	41	33.1	8.95	.56	.21	1.24	.26	17.20
103	20	0.0	0.0	98	1	6.0	0	9.0	5.0	8.43	.43	.13	0	6.0	8.2	4.6	1	4.0	0	19	12.6	4.56	.23	.14	0.00	.56	14.34
104	20	0.0	0.0	98	1	6.0	0	9.0	5.0	8.43	.43	.13	0	6.0	8.2	4.6	1	5.0	0	28	19.8	5.21	.28	.07	.61	.40	14.53
105	20	0.0	0.0	98	1	6.0	0	9.0	5.0	8.43	.43	.13	0	6.0	8.2	4.6	2	6.0	600	25	17.6	8.04	.54	.33	.48	.57	17.87
106	20	0.0	0.0	98	1	6.0	0	9.0	5.0	8.43	.43	.13	0	6.0	8.2	4.6	2	6.0	650	29	21.4	8.49	.54	.26	.73	.48	18.06
107	20	0.0	0.0	98	1	6.0	0	9.0	5.0	8.43	.43	.13	0	6.0	8.2	4.6	2*	6.0	600	36	27.3	8.21	.54	.22	1.02	.35	17.58
108	20	0.0	0.0	98	1	6.0	0	9.0	5.0	8.43	.43	.13	0	6.0	8.2	4.6	2	6.0	650	42	33.9	8.65	.54	.18	1.24	.27	17.84
109	20	0.0	0.0	98	1	6.0	0	9.0	5.0	8.43	.43	.13	0	6.0	8.5	4.7	1	4.0	0	16	10.1	4.51	.22	.04	0.00	.56	



RPRDS1 - RIGID PAVEMENT REHABILITATION DESIGN SYSTEM - VERSION 1, NOV 1980  
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## PROJECT DESCRIPTION

RPRDS1 TEST - REDESIGN FOR FRATT INTCHNG O/L PROJECT, S A TX, 9BS/11/80

## OPTIMAL STRATEGY NO. 1

COMPONENT OF STRATEGY	QUANTITY
1. EXISTING PAVEMENT REMAINING LIFE AT 1ST OVERLAY, PERCENT	0.
2. YEAR OF 1ST OVERLAY PLACEMENT	2.
3. TOTAL 18-KIP ESAL CYCLES (NOW TILL 1ST OVERLAY), MILLIONS	1,17
4. COST OF MAINTAINING EXISTING PAVEMENT, DOL/SQ YD	1.24
5. 1ST OVERLAY TYPE	UNB CRCP
6. TYPE OF SHOULDER	PCC
7. 1ST OVERLAY THICKNESS, INCHES	6.0
8. PCC FLEXURAL STRENGTH OF 1ST OVERLAY, PSI	600,0
9. FATIGUE LIFE AFTER 1ST OVERLAY, YEARS	29.6
10. FATIGUE LIFE AFTER 1ST OVERLAY, 18-KIP FSAL IN MILLIONS	21.03
11. 1ST OVERLAY CONSTRUCTION COST, DOL/SQ YD	12.28
12. 1ST OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	.72
13. 1ST OVERLAY MAINTENANCE COST, DOL/SQ YD	.54
14. 1ST OVERLAY REMAINING LIFE AT 2ND OVERLAY, PERCENT	---
15. YEAR OF 2ND OVERLAY PLACEMENT	---
16. TOTAL 18-KIP ESAL CYCLES (NOW TILL 2ND OVERLAY), MILLIONS	---
17. 2ND OVERLAY TYPE	---
18. TYPE OF SHOULDER	---
19. 2ND OVERLAY THICKNESS, INCHES	---
20. PCC FLEXURAL STRENGTH OF 2ND OVERLAY, PSI	---
21. FATIGUE LIFE AFTER 2ND OVERLAY, YEARS	---
22. FATIGUE LIFE AFTER 2ND OVERLAY, 18-KIP FSAL IN MILLIONS	---
23. 2ND OVERLAY CONSTRUCTION COST, DOL/SQ YD	---
24. 2ND OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	---
25. 2ND OVERLAY MAINTENANCE COST, DOL/SQ YD	---
26. VALUE OF EXTENDED LIFE, DOL/SQ YD	.73
27. OVERLAY SALVAGE VALUE, DOL/SQ YD	.50
28. TOTAL NET PRESENT VALUE OF STRATEGY, DOL/SQ YD	13.56

RPRDS1 - RIGID PAVEMENT REHABILITATION DESIGN SYSTEM - VERSION 1, NOV 1980  
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## PROJECT DESCRIPTION

RPRDS1 TEST - REDESIGN FOR FRATT TINTCHNG 0/I PROJECT, S A TX, SBS/11/80

OPTIMAL STRATEGY NO. 2

COMPONENT OF STRATEGY	QUANTITY
1. EXISTING PAVEMENT REMAINING LIFE AT 1ST OVERLAY, PERCENT	10.
2. YEAR OF 1ST OVERLAY PLACEMENT	2.
3. TOTAL 18-KIP FSAL CYCLES (NOW TILL 1ST OVERLAY), MILLIONS	.78
4. COST OF MAINTAINING EXISTING PAVEMENT, DOL/SQ YD	1.24
5. 1ST OVERLAY TYPE	UNB CRCP
6. TYPE OF SHOULDER	PCC
7. 1ST OVERLAY THICKNESS, INCHES	6,0
8. PCC FLEXURAL STRENGTH OF 1ST OVERLAY, PSI	6000.0
9. FATIGUE LIFE AFTER 1ST OVERLAY, YEARS	34.0
10. FATIGUE LIFE AFTER 1ST OVERLAY, 18-KIP FSAL IN MILLIONS	25.29
11. 1ST OVERLAY CONSTRUCTION COST, DOL/SQ YD	12.74
12. 1ST OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	.74
13. 1ST OVERLAY MAINTENANCE COST, DOL/SQ YD	.47
14. 1ST OVERLAY REMAINING LIFE AT 2ND OVERLAY, PERCENT	---
15. YEAR OF 2ND OVERLAY PLACEMENT	---
16. TOTAL 18-KIP FSAL CYCLES (NOW TILL 2ND OVERLAY), MILLIONS	---
17. 2ND OVERLAY TYPE	---
18. TYPE OF SHOULDER	---
19. 2ND OVERLAY THICKNESS, INCHES	---
20. PCC FLEXURAL STRENGTH OF 2ND OVERLAY, PSI	---
21. FATIGUE LIFE AFTER 2ND OVERLAY, YEARS	---
22. FATIGUE LIFE AFTER 2ND OVERLAY, 18-KIP FSAL IN MILLIONS	---
23. 2ND OVERLAY CONSTRUCTION COST, DOL/SQ YD	---
24. 2ND OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	---
25. 2ND OVERLAY MAINTENANCE COST, DOL/SQ YD	---
26. VALUE OF EXTENDED LIFE, DOL/SQ YD	.93
27. OVERLAY SALVAGE VALUE, DOL/SQ YD	.50
28. TOTAL NET PRESENT VALUE OF STRATEGY, DOL/SQ YD	13.76

RPRDS1 - RIGID PAVEMENT REHABILITATION DESIGN SYSTEM - VERSION 1, NOV 1980  
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## PROJECT DESCRIPTION

RPRDS1 TEST - REDesign FOR FRATT INTCHNG O/L PROJECT, S A TX, SBS/11/80

OPTIMAL STRATEGY NO. 3

COMPONENT OF STRATEGY	QUANTITY
1. EXISTING PAVEMENT REMAINING LIFE AT 1ST OVERLAY, PERCENT	20.
2. YEAR OF 1ST OVERLAY PLACEMENT	1.
3. TOTAL 18-KIP FSAL CYCLES (NOW TILL 1ST OVERLAY), MILLIONS	.39
4. COST OF MAINTAINING EXISTING PAVEMENT, DOL/SQ YD	.98
5. 1ST OVERLAY TYPE	UNB CRCP
6. TYPE OF SHOULDER	PCC
7. 1ST OVERLAY THICKNESS, INCHES	6.0
8. PCC FLEXURAL STRENGTH OF 1ST OVERLAY, PSI	6000.0
9. FATIGUE LIFE AFTER 1ST OVERLAY, YEARS	38.2
10. FATIGUE LIFE AFTER 1ST OVERLAY, 18-KIP FSAL IN MILLIONS	29.55
11. 1ST OVERLAY CONSTRUCTION COST, DOL/SQ YD	13.22
12. 1ST OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	.76
13. 1ST OVERLAY MAINTENANCE COST, DOL/SQ YD	.47
14. 1ST OVERLAY REMAINING LIFE AT 2ND OVERLAY, PERCENT	---
15. YEAR OF 2ND OVERLAY PLACEMENT	---
16. TOTAL 18-KIP FSAL CYCLES (NOW TILL 2ND OVERLAY), MILLTONS	---
17. 2ND OVERLAY TYPE	---
18. TYPE OF SHOULDER	---
19. 2ND OVERLAY THICKNESS, INCHES	---
20. PCC FLEXURAL STRENGTH OF 2ND OVERLAY, PSI	---
21. FATIGUE LIFE AFTER 2ND OVERLAY, YEARS	---
22. FATIGUE LIFE AFTER 2ND OVERLAY, 18-KIP FSAL IN MILLIONS	---
23. 2ND OVERLAY CONSTRUCTION COST, DOL/SQ YD	---
24. 2ND OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	---
25. 2ND OVERLAY MAINTENANCE COST, DOL/SQ YD	---
26. VALUE OF EXTENDED LTFF, DOL/SQ YD	1.10
27. OVERLAY SALVAGE VALUE, DOL/SQ YD	.50
28. TOTAL NET PRESENT VALUE OF STRATEGY, DOL /SQ YD	13.83

RPRDS1 - RIGID PAVEMENT REHABILITATION DESIGN SYSTEM - VERSION 1, NOV 1980  
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## PROJECT DESCRIPTION

RPRDS1 TEST - REDESIGN FOR FRATT INTCHNG O/L PROJECT, S A TX, SBS/11/80

## OPTIMAL STRATEGY NO. 4

COMPONENT OF STRATEGY	QUANTITY
1. EXISTING PAVEMENT REMAINING LIFE AT 1ST OVERLAY, PERCENT	0.
2. YEAR OF 1ST OVERLAY PLACEMENT	2.
3. TOTAL 18-KIP ESAL CYCLES (NOW TILL 1ST OVERLAY), MILLIONS	1.17
4. COST OF MAINTAINING EXISTING PAVEMENT, DOL/SQ YD	1.24
5. 1ST OVERLAY TYPE	UNB CRCP
6. TYPE OF SHOULDER	PCC
7. 1ST OVERLAY THICKNESS, INCHES	6.0
8. PCC FLEXURAL STRENGTH OF 1ST OVERLAY, PSI	650.0
9. FATIGUE LIFE AFTER 1ST OVERLAY, YEARS	32.0
10. FATIGUE LIFE AFTER 1ST OVERLAY, 18-KIP FSAL IN MILLIONS	23.34
11. 1ST OVERLAY CONSTRUCTION COST, DOL/SQ YD	12.82
12. 1ST OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	.72
13. 1ST OVERLAY MAINTENANCE COST, DOL/SQ YD	.50
14. 1ST OVERLAY REMAINING LIFE AT 2ND OVERLAY, PERCENT	---
15. YEAR OF 2ND OVERLAY PLACEMENT	---
16. TOTAL 18-KIP ESAL CYCLES (NOW TILL 2ND OVERLAY), MILLIONS	---
17. 2ND OVERLAY TYPE	---
18. TYPE OF SHOULDER	---
19. 2ND OVERLAY THICKNESS, INCHES	---
20. PCC FLEXURAL STRENGTH OF 2ND OVERLAY, PST	---
21. FATIGUE LIFE AFTER 2ND OVERLAY, YEARS	---
22. FATIGUE LIFE AFTER 2ND OVERLAY, 18-KIP FSAL IN MILLIONS	---
23. 2ND OVERLAY CONSTRUCTION COST, DOL/SQ YD	---
24. 2ND OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	---
25. 2ND OVERLAY MAINTENANCE COST, DOL/SQ YD	---
26. VALUE OF EXTENDED LIFE, DOL/SQ YD	.84
27. OVERLAY SALVAGE VALUE, DOL/SQ YD	.52
28. TOTAL NET PRESENT VALUE OF STRATEGY, DOL/SQ YD	13.92

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## PROJECT DESCRIPTION

RPRDS1 TEST = REDESIGN FOR FRATT INTCHNG O/L PROJECT, S A TX, SBS/11/80

## OPTIMAL STRATEGY NO. 5

COMPONENT OF STRATEGY	QUANTITY
1. EXISTING PAVEMENT REMAINING LIFE AT 1ST OVERLAY, PERCENT	30.
2. YEAR OF 1ST OVERLAY PLACEMENT	0.
3. TOTAL 18-KIP ESAL CYCLES (NOW TILL 1ST OVERLAY), MILLIONS	0.00
4. COST OF MAINTAINING EXISTING PAVEMENT, DOL/SQ YD	.71
5. 1ST OVERLAY TYPE	UNB CRCP
6. TYPE OF SHOULDER	PCC
7. 1ST OVERLAY THICKNESS, INCHES	6.0
8. PCC FLEXURAL STRENGTH OF 1ST OVERLAY, PSI	6000.0
9. FATIGUE LIFE AFTER 1ST OVERLAY, YEARS	38.6
10. FATIGUE LIFE AFTER 1ST OVERLAY, 18-KIP ESAL IN MILLIONS	30.00
11. 1ST OVERLAY CONSTRUCTION COST, DOL/SQ YD	13.73
12. 1ST OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	.77
13. 1ST OVERLAY MAINTENANCE COST, DOL/SQ YD	.48
14. 1ST OVERLAY REMAINING LIFE AT 2ND OVERLAY, PERCENT	---
15. YEAR OF 2ND OVERLAY PLACEMENT	---
16. TOTAL 18-KIP ESAL CYCLES (NOW TILL 2ND OVERLAY), MILLIONS	---
17. 2ND OVERLAY TYPE	---
18. TYPE OF SHOULDER	---
19. 2ND OVERLAY THICKNESS, INCHES	---
20. PCC FLEXURAL STRENGTH OF 2ND OVERLAY, PSI	---
21. FATIGUE LIFE AFTER 2ND OVERLAY, YEARS	---
22. FATIGUE LIFE AFTER 2ND OVERLAY, 18-KIP ESAL IN MILLIONS	---
23. 2ND OVERLAY CONSTRUCTION COST, DOL/SQ YD	---
24. 2ND OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	---
25. 2ND OVERLAY MAINTENANCE COST, DOL/SQ YD	---
26. VALUE OF EXTENDED LIFE, DOL/SQ YD	1.14
27. OVERLAY SALVAGE VALUE, DOL/SQ YD	.50
28. TOTAL NET PRESENT VALUE OF STRATEGY, DOL/SQ YD	14.06

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## PROJECT DESCRIPTION

RPRDS1 TEST - REDESIGN FOR FRATT INTCHNG O/L PROJECT, S A TX, SB8/11/80

OPTIMAL STRATEGY NO. 6

COMPONENT OF STRATEGY	QUANTITY
1. EXISTING PAVEMENT REMAINING LIFE AT 1ST OVERLAY, PERCENT	10.
2. YEAR OF 1ST OVERLAY PLACEMENT	2.
3. TOTAL 18-KIP ESAL CYCLES (NOW TILL 1ST OVERLAY), MILLIONS	.78
4. COST OF MAINTAINING EXISTING PAVEMENT, DOL/SQ YD	1.24
5. 1ST OVERLAY TYPE	UNB CRCP
6. TYPE OF SHOULDER	PCC
7. 1ST OVERLAY THICKNESS, INCHES	6.0
8. PCC FLEXURAL STRENGTH OF 1ST OVERLAY, PSI	650,0
9. FATIGUE LIFE AFTER 1ST OVERLAY, YEARS	36.3
10. FATIGUE LIFE AFTER 1ST OVERLAY, 18-KIP ESAL IN MILLIONS	27.60
11. 1ST OVERLAY CONSTRUCTION COST, DOL/SQ YD	13.30
12. 1ST OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	.74
13. 1ST OVERLAY MAINTENANCE COST, DOL/SQ YD	.46
14. 1ST OVERLAY REMAINING LIFE AT 2ND OVERLAY, PERCENT	---
15. YEAR OF 2ND OVERLAY PLACEMENT	---
16. TOTAL 18-KIP ESAL CYCLES (NOW TILL 2ND OVERLAY), MILLIONS	---
17. 2ND OVERLAY TYPE	---
18. TYPE OF SHOULDER	---
19. 2ND OVERLAY THICKNESS, INCHES	---
20. PCC FLEXURAL STRENGTH OF 2ND OVERLAY, PSI	---
21. FATIGUE LIFE AFTER 2ND OVERLAY, YEARS	---
22. FATIGUE LIFE AFTER 2ND OVERLAY, 18-KIP ESAL IN MILLIONS	---
23. 2ND OVERLAY CONSTRUCTION COST, DOL/SQ YD	---
24. 2ND OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	---
25. 2ND OVERLAY MAINTENANCE COST, DOL/SQ YD	---
26. VALUE OF EXTENDED LIFE, DOL/SQ YD	1.02
27. OVERLAY SALVAGE VALUE, DOL/SQ YD	.52
28. TOTAL NET PRESENT VALUE OF STRATEGY, DOL/SQ YD	14.20

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## PROJECT DESCRIPTION

RPRDS1 TEST = REDesign FOR FRATT TINTCHNG O/L PROJECT, S A TX, 8BS/11/80

OPTIMAL STRATEGY NO. 7

COMPONENT OF STRATEGY	QUANTITY
1. EXISTING PAVEMENT REMAINING LIFE AT 1ST OVERLAY, PERCENT	20.
2. YEAR OF 1ST OVERLAY PLACEMENT	1.
3. TOTAL 18-KIP ESAL CYCLES (NOW TILL 1ST OVERLAY), MILLIONS	.39
4. COST OF MAINTAINING EXISTING PAVEMENT, DOL/SQ YD	.98
5. 1ST OVERLAY TYPE	UNB CRCP
6. TYPE OF SHOULDER	PCC
7. 1ST OVERLAY THICKNESS, INCHES	6.0
8. PCC FLEXURAL STRENGTH OF 1ST OVERLAY, PSI	650.0
9. FATIGUE LIFE AFTER 1ST OVERLAY, YEARS	40.4
10. FATIGUE LIFE AFTER 1ST OVERLAY, 18-KIP ESAL IN MILLIONS	31.86
11. 1ST OVERLAY CONSTRUCTION COST, DOL/SQ YD	13.80
12. 1ST OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	.76
13. 1ST OVERLAY MAINTENANCE COST, DOL/SQ YD	.43
14. 1ST OVERLAY REMAINING LIFE AT 2ND OVERLAY, PERCENT	---
15. YEAR OF 2ND OVERLAY PLACEMENT	---
16. TOTAL 18-KIP ESAL CYCLES (NOW TILL 2ND OVERLAY), MILLIONS	---
17. 2ND OVERLAY TYPE	---
18. TYPE OF SHOULDER	---
19. 2ND OVERLAY THICKNESS, INCHES	---
20. PCC FLEXURAL STRENGTH OF 2ND OVERLAY, PSI	---
21. FATIGUE LIFE AFTER 2ND OVERLAY, YEARS	---
22. FATIGUE LIFE AFTER 2ND OVERLAY, 18-KIP ESAL IN MILLIONS	---
23. 2ND OVERLAY CONSTRUCTION COST, DOL/SQ YD	---
24. 2ND OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	---
25. 2ND OVERLAY MAINTENANCE COST, DOL/SQ YD	---
26. VALUE OF EXTENDED LIFE, DOL/SQ YD	1.17
27. OVERLAY SALVAGE VALUE, DOL/SQ YD	.52
28. TOTAL NET PRESENT VALUE OF STRATEGY, DOL/SQ YD	14.28

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## PROJECT DESCRIPTION

RPRDS1 TEST - REDESIGN FOR FRATT INTCHNG D/L PROJECT, S A TX, SBS/11/80

OPTIMAL STRATEGY NO. 8

COMPONENT OF STRATEGY	QUANTITY
1. EXISTING PAVEMENT REMAINING LIFE AT 1ST OVERLAY, PERCENT	0,
2. YEAR OF 1ST OVERLAY PLACEMENT	2,
3. TOTAL 18-KIP ESAL CYCLES (NOW TILL 1ST OVERLAY), MILLIONS	1.17
4. COST OF MAINTAINING EXISTING PAVEMENT, DOL/SQ YD	1.24
5. 1ST OVERLAY TYPE	UNB CRCP
6. TYPE OF SHOULDER	FLEX
7. 1ST OVERLAY THICKNESS, INCHES	6.0
8. PCC FLEXURAL STRENGTH OF 1ST OVERLAY, PSI	600,0
9. FATIGUE LIFE AFTER 1ST OVERLAY, YEARS	19.6
10. FATIGUE LIFE AFTER 1ST OVERLAY, 18-KIP ESAL IN MILLIONS	12.54
11. 1ST OVERLAY CONSTRUCTION COST, DOL/SQ YD	11.97
12. 1ST OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	.72
13. 1ST OVERLAY MAINTENANCE COST, DOL/SQ YD	.87
14. 1ST OVERLAY REMAINING LIFE AT 2ND OVERLAY, PERCENT	---
15. YEAR OF 2ND OVERLAY PLACEMENT	---
16. TOTAL 18-KIP ESAL CYCLES (NOW TILL 2ND OVERLAY), MILLIONS	---
17. 2ND OVERLAY TYPE	---
18. TYPE OF SHOULDER	---
19. 2ND OVERLAY THICKNESS, INCHES	---
20. PCC FLEXURAL STRENGTH OF 2ND OVERLAY, PSI	---
21. FATIGUE LIFE AFTER 2ND OVERLAY, YEARS	---
22. FATIGUE LIFE AFTER 2ND OVERLAY, 18-KIP FSAL IN MILLIONS	---
23. 2ND OVERLAY CONSTRUCTION COST, DOL/SQ YD	---
24. 2ND OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	---
25. 2ND OVERLAY MAINTENANCE COST, DOL/SQ YD	---
26. VALUE OF EXTENDED LIFE, DOL/SQ YD	0.00
27. OVERLAY SALVAGE VALUE, DOL/SQ YD	.48
28. TOTAL NET PRESENT VALUE OF STRATEGY, DOL/SQ YD	14.32

RPPDS1 - RIGID PAVEMENT REHABILITATION DESIGN SYSTEM - VERSION 1, NOV 1980  
 CENTER FOR TRANSPORTATION RESEARCH  
 UNIVERSITY OF TEXAS AT AUSTIN

## PROJECT DESCRIPTION

RPRUS1 TEST - REDESIGN FOR FRATT INTCHNG O/L PROJECT, S A TX, 888/11/80

OPTIMAL STRATEGY NO. 9

COMPONENT OF STRATEGY	QUANTITY
1. EXISTING PAVEMENT REMAINING LIFE AT 1ST OVERLAY, PERCENT	20.
2. YEAR OF 1ST OVERLAY PLACEMENT	1.
3. TOTAL 18-KIP ESAL CYCLES (NOW TILL 1ST OVERLAY), MILLIONS	.39
4. COST OF MAINTAINING EXISTING PAVEMENT, DOL/SQ YD	.98
5. 1ST OVERLAY TYPE	ACP
6. TYPE OF SHOULDER	FLEX
7. 1ST OVERLAY THICKNESS, INCHES	6.0
8. PCC FLEXURAL STRENGTH OF 1ST OVERLAY, PSI	0.0
9. FATIGUE LIFE AFTER 1ST OVERLAY, YEARS	9.0
10. FATIGUE LIFE AFTER 1ST OVERLAY, 18-KIP FSAL IN MILLIONS	5.02
11. 1ST OVERLAY CONSTRUCTION COST, DOL/SQ YD	8.43
12. 1ST OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	.43
13. 1ST OVERLAY MAINTENANCE COST, DOL/SQ YD	.13
14. 1ST OVERLAY REMAINING LIFE AT 2ND OVERLAY, PERCENT	60.
15. YEAR OF 2ND OVERLAY PLACEMENT	8.
16. TOTAL 18-KIP FSAL CYCLES (NOW TILL 2ND OVERLAY), MILLIONS	4.57
17. 2ND OVERLAY TYPE	ACP
18. TYPE OF SHOULDER	FLEX
19. 2ND OVERLAY THICKNESS, INCHES	4.0
20. PCC FLEXURAL STRENGTH OF 2ND OVERLAY, PSI	0.0
21. FATIGUE LIFE AFTER 2ND OVERLAY, YEARS	19.7
22. FATIGUE LIFE AFTER 2ND OVERLAY, 18-KIP FSAL IN MILLIONS	12.57
23. 2ND OVERLAY CONSTRUCTION COST, DOL/SQ YD	4.56
24. 2ND OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	.23
25. 2ND OVERLAY MAINTENANCE COST, DOL/SQ YD	.14
26. VALUE OF EXTENDED LIFE, DOL/SQ YD	0.00
27. OVERLAY SALVAGE VALUE, DOL/SQ YD	.56
28. TOTAL NET PRESENT VALUE OF STRATEGY, DOL/SQ YD	14.34

RPPDS1 - RIGID PAVEMENT REHABILITATION DESIGN SYSTEM - VERSION 1, NOV 1980  
 CENTER FOR TRANSPORTATION RESEARCH  
 UNIVERSITY OF TEXAS AT AUSTIN

## PROJECT DESCRIPTION

RPPDS1 TEST - REDesign FOR FRATT INTCHNG D/L PROJECT, S A TX, 5BS/11/80

OPTIMAL STRATEGY NO. 10

COMPONENT OF STRATEGY	QUANTITY
1. EXISTING PAVEMENT REMAINING LIFE AT 1ST OVERLAY, PERCENT	30.
2. YEAR OF 1ST OVERLAY PLACEMENT	0.
3. TOTAL 18-KIP ESAL CYCLES (NOW TILL 1ST OVERLAY), MILLIONS	0.00
4. COST OF MAINTAINING EXISTING PAVEMENT, DOL/SQ YD	.71
5. 1ST OVERLAY TYPE	ACP
6. TYPE OF SHOULDER	FLEX
7. 1ST OVERLAY THICKNESS, INCHES	4.0
8. PCC FLEXURAL STRENGTH OF 1ST OVERLAY, PSI	0.0
9. FATIGUE LIFE AFTER 1ST OVERLAY, YEARS	6.9
10. FATIGUE LIFE AFTER 1ST OVERLAY, 18-KIP FSAL IN MILLIONS	3.78
11. 1ST OVERLAY CONSTRUCTION COST, DOL/SQ YD	6.82
12. 1ST OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	.22
13. 1ST OVERLAY MAINTENANCE COST, DOL/SQ YD	.13
14. 1ST OVERLAY REMAINING LIFE AT 2ND OVERLAY, PERCENT	60.
15. YEAR OF 2ND OVERLAY PLACEMENT	6.
16. TOTAL 18-KIP ESAL CYCLES (NOW TILL 2ND OVERLAY), MILLIONS	3.35
17. 2ND OVERLAY TYPE	ACP
18. TYPE OF SHOULDER	FLEX
19. 2ND OVERLAY THICKNESS, INCHES	6.0
20. PCC FLEXURAL STRENGTH OF 2ND OVERLAY, PSI	0.0
21. FATIGUE LIFE AFTER 2ND OVERLAY, YEARS	18.1
22. FATIGUE LIFE AFTER 2ND OVERLAY, 18-KIP FSAL IN MILLIONS	11.32
23. 2ND OVERLAY CONSTRUCTION COST, DOL/SQ YD	6.47
24. 2ND OVERLAY TRAFFIC DELAY COST, DOL/SQ YD	.27
25. 2ND OVERLAY MAINTENANCE COST, DOL/SQ YD	.32
26. VALUE OF EXTENDED LIFE, DOL/SQ YD	0.00
27. OVERLAY SALVAGE VALUE, DOL/SQ YD	.56
28. TOTAL NET PRESENT VALUE OF STRATEGY, DOL/SQ YD	14.37

APPENDIX H  
RPRDS-1 PROGRAM LISTING

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CONRP = CONTROL ROUTINE FOR GENERATING THE PAVEMENT RESPONSES REQUIRED FOR EACH STRATEGY.	
ENTRY/ EXITL	NEXL = NO. OF LAYERS IN EXISTING PAVEMENT. FVPT = ELASTIC MODULUS OF EXISTING PAVEMENT LAYERS. VPVT = POISSONS RATIOS OF EXISTING PAVEMENT LAYERS. THPVT = THICKNESSES OF EXISTING PAVEMENT LAYERS. WGT = WEIGHT OF SINGLE TIRE ON DESIGN AXLE LOAD. PSJ = DESIGN LOAD TIRE PRESSURE. NOV1 = NO. OF POSSIBLE FIRST OVERLAY TYPES. ITYP1 = NO/YES SWITCHES ON TYPES OF FIRST OVERLAY. ISNOV2 = NO/YES SWITCH ON IF SECOND OVERLAY CONSIDERED. KNV2 = NO. OF POSSIBLE SECOND OVERLAY TYPES. ITYP2 = NO/YES SWITCHES ON TYPES OF SECOND OVERLAY. NACT1 = NO. OF AC FIRST OVERLAY THICKNESSES CONSIDERED. ACT1 = AC FIRST OVERLAY THICKNESSES. NACT2 = NO. OF AC SECOND OVERLAY THICKNESSES CONSIDERED. ACT2 = AC SECOND OVERLAY THICKNESSES. NPCC1 = NO. OF PCC OVERLAY THICKNESSES CONSIDERED. PCC1 = PCC OVERLAY THICKNESSES. ALNOV1 = ALLOWABLE TOTAL OVERLAY THICKNESS. ECKPCC = STEIFFNESS OF CRACKED PCC. FCKAC = STEIFFNESS OF CRACKED AC. VNCHP = POISSONS RATIO FOR COMPOSITE LAYER. FVAC = ELASTIC MODULUS OF AC OVERLAY. VNVAC = POISSONS RATIO FOR AC OVERLAY. FACFAT = ELASTIC MODULUS OF AC USED IN FATIGUE EQUATION. FVPPC = ELASTIC MODULUS OF PCC OVERLAY. VNVPCC = POISSONS RATIO FOR PCC OVERLAY. FRR = ROAD BREAKER STEIFFNESS. VRP = POISSONS RATIO FOR ROAD BREAKER. THRR = ROAD BREAKER THICKNESS.
EXIT/ SII	SII = STRESS IN ORIGINAL PCC, ID OVERLAYS. SGA = STRESS IN ORIGINAL PCC, AC OVERLAY.

F1A = STRAIN IN AC OVERLAY AFTER ORIGINAL PCC CRACKED. CO 38  
 S2AA = STRESS IN ORIGINAL PCC, AC/AC OVERLAYS. CO 39  
 F1AA = STRAIN IN FIRST AC OVERLAY AFTER ORIGINAL PCC CO 40  
 CRACKED, AC/AC OVERLAYS. CO 41  
 F2AA = STRAIN IN SECOND AC OVERLAY AFTER ORIGINAL PCC CO 42  
 AND FIRST AC OVERLAY BECOME CRACKED. CO 43  
 S2AD = STRESS IN ORIGINAL PAVEMENT, AC/PCC OVERLAYS. CO 44  
 S2AP1 = STRESS IN PCC SECOND OVERLAY, AC/PCC OVERLAYS. CO 45  
 S2AP2 = STRESS IN PCC SECOND OVERLAY AFTER ORIGINAL CO 46  
 PCC BECOMES CRACKED, AC/PCC OVERLAYS. CO 47  
 S3RP = STRESS IN ORIGINAL PCC, BONDED PCC OVERLAY. CO 48  
 S3RPA = STRESS IN ORIGINAL PCC, BONDED PCC/AC OVERLAYS. CO 49  
 F3RPA = STRAIN IN AC SECOND OVERLAY AFTER ORIGINAL PCC CO 50  
 AND BONDED PCC SECOND OVERLAY BECOME CRACKED. CO 51  
 S3UP = STRESS IN ORIGINAL PCC, UNBONDED PCC OVERLAY. CO 52  
 S1UP1 = STRESS IN UNBONDED PCC OVERLAY. CO 53  
 S1UP2 = STRESS IN UNBONDED PCC OVERLAY AFTER ORIGINAL CO 54  
 PCC BECOMES CRACKED. CO 55  
 S3UPA = STRESS IN ORIGINAL PCC, UNBONDED PCC/AC OVERLAYS. CO 56  
 S1UPA1 = STRESS IN UNBONDED PCC FIRST OVERLAY, AC SECOND CO 57  
 OVERLAY. CO 58  
 S1UPA2 = STRESS IN UNBONDED PCC FIRST OVERLAY AFTER CO 59  
 ORIGINAL PCC BECOMES CRACKED, AC SECOND OVERLAY. CO 60  
 E2UPA = STRAIN IN AC SECOND OVERLAY AFTER ORIGINAL PCC CO 61  
 AND UNBONDED PCC FIRST OVERLAY BECOME CRACKED. CO 62  
 CO 63  
 COMMON /OVTYPE/ ISNOV1, NOV1, TTYP1(S1) TSN0V2, NOV2, TTYP2(S1) CO 64  
 CO 65  
 COMMON /OVTHIK/ NACT1, ACT1(R), NACT2, ACT2(R), NPCT, PCST(R1) CO 66  
 0 ALDVT, AVHDT, THBR CO 67  
 CO 68  
 COMMON /EXPVMT/ NEVL, EPVT(S1), VPVT(S1), THPVVT(S1) CO 69  
 CO 70  
 COMMON /LAYRS/ NS, THET, FCAT, VERT CO 71  
 CO 72  
 COMMON /LAYCOM/ WGT, PST, NR, RRCP1, NZ, ZZ(S1) CO 73  
 CO 74  
 COMMON /ELPROP/ CO 75  
 0 ECKPCC, ECKAC, VCOMP, CO 76  
 1 ENVAC, VNOVAC, FACEAT, CO 77  
 2 ENVPPC, VNVPCC, CO 78  
 3 FRR, VRR CO 79  
 CO 80  
 COMMON /PAVRSP/ CO 81  
 0 SR,  
 1 SPA(R1), ETAFB(S1), CO 82  
 2 SPAAF(R1), F1A(S1)(R1), E2AA(R1,R1), CO 83  
 3 SPAF(R1), S2AP1(R1,R1), S2AP2(R1,R1), CO 84  
 4 SURP(R1), CO 85  
 5 S3RPAF(R1), F3RPA(R1,R1), CO 86  
 6 S3RUP(R1), S1UP1(R1), S1UP2(R1), CO 87  
 7 S3UPAF(R1), S1UPA1(R1,R1), S1UPA2(R1,R1), E2UPA(R1,R1) CO 88  
 CO 89  
 DIMENSION RESP(2), FCAT(S1), FCPC1(R1), FCUPC1(R1) CO 90  
 CO 91  
 CO 92  
 STATEMENT FUNCTION FOR CHARACTERIZING CRACKED PAVEMENT CO 93  
 AS A SINGLE LAYER WITH A COMPOSITE MODULUS.  
 ECOMP = DEF / 643,625/DEF CO 94  
 CO 95  
 CO 96  
 CO 97  
 CO 98  
 CO 99  
 STRESS IN ORIGINAL PAVEMENT, NO OVERLAY.  
 NETTE(P,6)  
 NETTE(P,6)

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CS 6 FORMAT(5X,*S1*) NS=NEXL
DO 10 I=1,NEXL
E(1)=FPVT(1)
V(1)=VPVT(1)
TH(1)=THPVT(1)
10 CONTINUE
NZ=1
ZZ(1)=THPVT(1)
CALL FETCH(1,RESP)
SR=RESP(1)
TF(TTYP1(1),FO,01 GO TO 5)
C
C COMPOSITE MODULUS AFTER ORIGNL PCC CRACKED, REQUIRED
C ONLY IF AN AC 1ST OVERLAY IS A POSSIBLE STRATEGY.
E(1)=FCKPCC
TF(F(2),GT,F(111) F(21)E(2))
ZZ(1)=R_2
CALL FETCH(3,RESP)
DEFP=FRESP(1)
ECP=FECOMP(DEFF)
C
C PAVEMENT RESPONSES AFTER FIRST OVERLAY (AND BEFORE SEC'D).
C
C FIRST OVERLAY = AC, STRESS IN ORIGINAL PCC.
CS WRITE(2,16)
CS 16 FORMAT(5X,*S1*) NS=NEXL+1
DO 21 I=1,NEXL
EFL+1=FPVT(1)
VFL+1=VPVT(1)
THFL+1=THPVT(1)
20 CONTINUE
E(1)=FVAC
V(1)=V0VAC
NZ=1
DO 30 I=1,ACT1
TH(1)=ACT1(I)
ZZ(1)=TH(1)+TH(2)
CALL FETCH(1,RESP)
SRAT1=RESP(1)
30 CONTINUE
C
C FIRST OVERLAY = AC, STRAIN IN AC AFTER ORIGINAL PCC CRACKED
C AND COMPOSITE MODULUS AFTER AC CRACKED.
CS WRITE(2,36)
CS 36 FORMAT(5X,*S1*) NS=2
E(2)=FCCP
V(2)=VCOMP
NZ=1
DO 40 I=1,ACT1
E(1)=EADPAT
TH(1)=ACT1(I)
ZZ(1)=TH(1)
CALL FETCH(1,RESP)
E1A(I)=RESP(1)
TF(TTYP2(1),FO,01 GO TO 40
E(1)=FCKAC
ZZ(1)=R_2
CALL FETCH(3,RESP)
DEFF=RESP(1)
ECA(I)=ECOMP(DEFF)
NS=NEXL
DO 101 I=1,NEXL
E(1)=FPVT(1)
V(1)=VPVT(1)
TH(1)=THPVT(1)
101 CONTINUE
IF(TTYP1(2),FO,01 GO TO 80
C
C FIRST OVERLAY = ROUNDED PCC, STRESSES IN ORIGINAL PCC
C AND COMPOSITE MODULUS AFTER BOTH PCC LAYERS CRACKED.
CS WRITE(2,56)
CS 56 FORMAT(5X,*S1*) NS=NEXL+1
DO 102 I=1,NEXL
EFL+1=FPVT(1)
VFL+1=VPVT(1)
THFL+1=THPVT(1)
102 CONTINUE
V(1)=V0VCC
NZ=1
DO 70 I=1,NPCCT
E(1)=FVPC
E(2)=EPVT(1)
E(3)=FPVT(2)
TH(1)=PCC(1)
ZZ(1)=TH(1)+TH(2)
CALL FETCH(1,RESP)
SRAP(1)=RESP(1)
TF(TTYP2(1),FO,01 GO TO 70
E(1)=FCKPCC
E(2)=FCKPCC
TF(F(3),GT,F(211) F(31)E(2))
ZZ(1)=R_2
CALL FETCH(3,RESP)
DEPCC1=RESP(1)
ECPCC1=ECOMP(DEPCC1)
70 CONTINUE
C
C R0 CONTINUE
IF(TTYP1(3),FO,01 AND TTYP1(5),FO,01 GO TO 120
C
C FIRST OVERLAY = UNROUNDED PCC, STRESSES IN ORIGNL PCC AND PCC
C OVERLAY.
CS WRITE(2,RN)
CS 96 FORMAT(5X,*S1*) NS=NEXL+2
DO 103 I=1,NEXL
E(1)=FPVT(1)
V(1)=VPVT(1)
TH(1)=THPVT(1)
103 CONTINUE
E(1)=FVPC
V(1)=V0VCC
E(2)=FRR
V(2)=VRR
TH(2)=THRR
NZ=2
DO 104 I=1,NPCCT
TH(1)=PCC(1)
ZZ(1)=TH(1)+TH(2)
ZZ(2)=TH(1)+TH(2)+TH(3)
CALL FETCH(1,RESP)
SRUP(1)=RESP(1)
SRUP1(1)=RESP(1)
104 CONTINUE

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120 CONTINUE
C FIRST OVERLAY = UNBONDED PCC, STRESS IN PCC OVERLAY AFTER
C ORIGINAL PCC CRACKED. ALSO, COMPOSITE MODULUS AFTER BOTH PCC
C LAYERS CRACKED.
E(31) = ECKPCC
TF(TY14) .GT. E(31) E(31)=E(31)
NZ = 1
DO 110 TH1=NPCET
TH(1) = PCCT(1)
E(11) = EOVPC
ZT(1) = TH(1)
CALL FETCHY_1, RESP_1
SIMP2(1) = RESP(1)
IF (TTYP2(1) .EQ. 1) GO TO 110
E(11) = ECKPCC
ZT(1) = V_10
CALL FETCHY_3, RESP_1
DEHP1 = RESP(1)
ECPDP1(1) = ECPDP1 DEHP1 = 1
110 CONTINUE
C 120 CONTINUE
TF (TSW0D2 ,EQ 0) H1 RETURN
C C PAVEMENT RESPONSES AFTER SECOND OVERLAY.
C
TF (TTYP2(1) .EQ. 1) GO TO 300
C
SECOND OVERLAY = AC.
TF (TTYP1(1) .NE. 1) GO TO 120
C STRESS IN ORIGINAL PCC AFTER 1ST AND 2ND AC OVERLAYS.
C NOTE THAT THE TWO AC OVERLAYS ARE COMPUTED TO MINIMIZE
C COMPUTATION TIME.
HRTTE(2,126)
CS126 FORMAT//5X,*5A4*
NS = NXFL + 1
DO 130 LE1,NEXI
FV(L+1) = EPVT(1)
V(1+1) = VPVT(1)
THL(1) = THPVTL(1)
130 CONTINUE
FV1 = EOVAC
V(1) = VOVAC
NZ = 1
DO 140 TH1=NACT1
DO 140 TH1=NACT2
TH(1) = ACT1(1) + ACT2(1)
IF (TH(1) .GT. AL0VY1) GO TO 140
ZT(1) = TH(1) + TH(2)
CALL FETCHY_1, RESP_1
SIMP1(1) = RESP(1)
140 CONTINUE
C STRESS IN 1ST AC OVERLAY AFTER 2ND AC OVERLAY AND AFTER
C ORIGINAL PCC CRACKED.
HRTTE(2,146)
CS146 FORMAT//5X,*5A4*
NS = 3
F(1) = EOVAC
V(1) = VOVAC
E(2) = FACEAT
V(2) = VOVAC
E(3) = ECPDP
CO 224 V(3) = VCOMP
CO 225 TH(3) = V_10
NZ = 1
DO 150 TH1=NACT1
CO 227 DO 150 TH1=NACT2
TH(1) = ACT1(1)
CO 228 TH(2) = ACT1(1)
CO 229 DO 150 J=1,NACT2
CO 230 TH(1) = ACT2(1)
CO 231 IF (ACT1(1)+ACT2(1) .GT. AL0VY1) GO TO 150
CO 232 ZT(1) = TH(1) + TH(2)
CO 233 CALL FETCHY_2, RESP_1
CO 234 FINACT,11 = RESP(1)
CO 235
150 CONTINUE
C STRAIN IN PCC AC OVERLAY AFTER 1ST AC OVERLAY AND OBJECT AL
C PCC BECOME CRACKED.
CS HRTTE(2,156)
CS156 FORMAT//5X,*5A4*
NS = 2
E(1) = FACEAT
V(1) = VOVAC
V(2) = VCOMP
TH(2) = R_0
NZ = 1
DO 160 TH1=NACT1
E(2) = FACEAT
V(1) = VOVAC
V(2) = VCOMP
TH(1) = R_0
NZ = 1
DO 160 TH1=NACT2
IF (ACT1(1)+ACT2(1) .GT. AL0VY1) GO TO 160
TH(1) = ACT2(1)
ZT(1) = TH(1)
CALL FETCHY_2, RESP_1
E2ACT,11 = RESP(1)
160 CONTINUE
C 170 CONTINUE
TF (TTYP1(2) ,EQ 0) H1 [AND] TTYP1(4) ,EQ 0) H1 GO TO 210
C C STRESS IN ORIGINAL PAVEMENT AFTER BONDED PCC 1ST OVERLAY,
C AC 2ND OVERLAY.
HRTTE(2,176)
CS176 FORMAT//5X,*5A4*
NS = NXFL + 2
DO 180 LE1,NEXI
E(1+1) = EPVT(1)
V(1+1) = VPVT(1)
THL+2 = THPVTL(1)
180 CONTINUE
E(1) = EOVAC
V(1) = VOVAC
E(2) = EOVPC
V(2) = VOVPC
NZ = 1
DO 190 TH1=NACT1
TH(1) = PCCT(1)
DO 190 J=1,NACT2
IF (PCCT(1)+NACT2(1) .GT. AL0VY1) GO TO 190
TH(1) = ACT2(1)
ZT(1) = TH(1) + TH(2) + TH(3)
CALL FETCHY_1, RESP_1
SIMP1(1) = RESP(1)
190 CONTINUE
C STRESS IN 2ND OVERLAY (AC) AFTER ORIGINAL PAVEMENT AND BONDED
C PCC 1ST OVERLAY BEFORE CRACKED.

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PS WRITER(2,1961,F200A)
      CATION FORMATT(5X,*F200A)
      NS = 2
      F1(1) = FACE&T
      V(1) = VNAC
      V(2) = VNAC
      TH(1) = U.M
      UZ = 1
      ON 2ND TEXT&PCT
      F(2) = FRSP(1)
      ON 2RD JEL&ACT2
      IF F(1)(1) = ACT2(J1) .GT. A1(NVT) GO TO 209
      TH(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      DFBSP(1,J1) = DFBSP(1)
      208 CONTINUE
      C 210 CONTINUE
      IF F(1)(1) = 2 AND TTYPE1(5) = FN(1) AI(NVT) GO TO 308
      C STEPS IN ORIGINAL PAEMENT AND UNROTATED PCT 1ST OVERLAY
      C WRITE(2,216)
      F(2)10 FORMAT(5X,*F200A)
      NS = NFTL + 3
      ON 221 TEXT&FX1
      F(1)(1) = F0PCT(1)
      V(1)(1) = VPCT(1)
      TH(1)(1) = THVPCT(1)
      220 CONTINUE
      F(1) = ENVAC
      V(1) = VNAC
      E(1) = ENVPC
      V(2) = VNVPCT
      F(1) = ERA
      V(1) = VAR
      TH(1) = THAR
      NZ = 2
      ON 230 JEL&ACT2
      TH(1) = PCCTY
      ON 231 JEL&ACT2
      IF (THAR&DCT(1)+ACT2(J1) .GT. A1(NVT)) GO TO 230
      TH(1) = ACT2(J1)
      Z(1) = TH(1) + TH(2)
      Z(2) = TH(1) + TH(2) + TH(3) + TH(4)
      CALL FFCTH(1, DFBSP )
      DFBSP(1,J1) = DFBSP(1)
      230 CONTINUE
      F(1)(1) = DFBSP(1)
      231 CONTINUE
      C STEPS IN UNROTATED PCT 1ST OVERLAY WITH 2ND AC OVERLAY ,FTFD
      C ORIGINAL PCT CHAREN
      CS 407FF(2,230)
      F(1) = FFCTC
      IF (F(1)(1) .GT. F(1)(1) + 51&FF(1))
      NZ = 1
      ON 240 TEXT&PCT
      TH(1) = PCCTY
      ON 241 TEXT&PCT
      IF (THAR&DCT(1)+ACT2(J1) .GT. A1(NVT)) GO TO 240
      F(1)(1) = DFBSP(1)
      240 CONTINUE
      C 410
      TH(1) = TH(1) + TH(2)
      CALL FFCTH(1, DFBSP )
      Z(1) = TH(1) + TH(2)
      SPBSP(1,J1) = DFBSP(1)
      246 CONTINUE
      C STEPS IN PCT 2ND OVERLAY AFTER ORIGINAL PCT CHAREN
      CS 420
      F(1)(1) = DFBSP(1)
      247 CONTINUE
      C 424
      TH(1) = TH(1) + TH(2)
      CALL FFCTH(1, DFBSP )
      Z(1) = TH(1) + TH(2)
      SPBSP(1,J1) = DFBSP(1)
      248 CONTINUE
      C 426
      F(1)(1) = FCUP(1)
      249 CONTINUE
      C 428
      NO 250 JEL&ACT2
      TH(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      250 CONTINUE
      C 430
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      251 CONTINUE
      C 431
      NO 252 JEL&ACT2
      TH(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      252 CONTINUE
      C 432
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      253 CONTINUE
      C 433
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      254 CONTINUE
      C 434
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      255 CONTINUE
      C 435
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      256 CONTINUE
      C 436
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      257 CONTINUE
      C 437
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      258 CONTINUE
      C 438
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      259 CONTINUE
      C 439
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      260 CONTINUE
      C 440
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      261 CONTINUE
      C 441
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      262 CONTINUE
      C 442
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      263 CONTINUE
      C 443
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      264 CONTINUE
      C 444
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      265 CONTINUE
      C 445
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      266 CONTINUE
      C 446
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      267 CONTINUE
      C 447
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      268 CONTINUE
      C 448
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      269 CONTINUE
      C 449
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      270 CONTINUE
      C 450
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      271 CONTINUE
      C 451
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      272 CONTINUE
      C 452
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      273 CONTINUE
      C 453
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      274 CONTINUE
      C 454
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      275 CONTINUE
      C 455
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      276 CONTINUE
      C 456
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      277 CONTINUE
      C 457
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      278 CONTINUE
      C 458
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      279 CONTINUE
      C 459
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      280 CONTINUE
      C 460
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      281 CONTINUE
      C 461
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      282 CONTINUE
      C 462
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      283 CONTINUE
      C 463
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      284 CONTINUE
      C 464
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      285 CONTINUE
      C 465
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      286 CONTINUE
      C 466
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      287 CONTINUE
      C 467
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      288 CONTINUE
      C 468
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      289 CONTINUE
      C 469
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      290 CONTINUE
      C 470
      F(1)(1) = ACT2(J1)
      Z(1) = TH(1)
      CALL FFCTH(2, DFBSP )
      E(2)(1,J1) = DFBSP(1)
      291 CONTINUE

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CN 99
CN 100
CN 101 21801
CN 102 1121121.F21
CN 103 CNTTNUF
CN 104 DN 2K MAT4
CN 105 LL(MAT4)/2
CN 106 DN 1E34
CN 107 0MK,M,1*XW,M,1) * Q(LL,1)
CN 108 2*XW,M,1) * PM(XW,2,J,1)
CN 109 3*XW,M,1) * PM(XW,3,J,1)
CN 110 4*XW,M,1) * PM(XW,4,J,1)
CN 111 CNTTNUF
CN 112 CNTTNUF
CN 113 CNTTNUF
CN 114 CNTTNUF
CN 115 CNTTNUF
CN 116 T5(PM(1,1,1)+PM(1,3,3))+PM(1,4,3))
CN 117 FV(1)*PM(1,1,1)+PM(1,3,3)+PM(1,4,3))
CN 118 T5(PM(1,1,1)+PM(1,3,3)+PM(1,4,3))
CN 119 FV(1)*PM(1,1,1)+PM(1,3,3)+PM(1,4,3))
CN 120 FV(1)*PM(1,1,1)+PM(1,3,3)+PM(1,4,3))
CN 121 FV(1)*PM(1,1,1)+PM(1,3,3)+PM(1,4,3))
CN 122 FV(1)*PM(1,1,1)+PM(1,3,3)+PM(1,4,3))
CN 123 FV(1)*PM(1,1,1)+PM(1,3,3)+PM(1,4,3))
CN 124 FV(1)*PM(1,1,1)+PM(1,3,3)+PM(1,4,3))
CN 125 FV(1)*PM(1,1,1)+PM(1,3,3)+PM(1,4,3))
CN 126 FV(1)*PM(1,1,1)+PM(1,3,3)+PM(1,4,3))
CN 127 FV(1)*PM(1,1,1)+PM(1,3,3)+PM(1,4,3))
CN 128 FV(1)*PM(1,1,1)+PM(1,3,3)+PM(1,4,3))
CN 129 FV(1)*PM(1,1,1)+PM(1,3,3)+PM(1,4,3))
CN 130 FV(1)*PM(1,1,1)+PM(1,3,3)+PM(1,4,3))
CN 131 FV(1)*PM(1,1,1)+PM(1,3,3)+PM(1,4,3))
CN 132 FV(1)*PM(1,1,1)+PM(1,3,3)+PM(1,4,3))
CN 133 FV(1)*PM(1,1,1)+PM(1,3,3)+PM(1,4,3))

CN 134 CNTTNUF
CN 135 CNTTNUF
CN 136 CNTTNUF
CN 137 CNTTNUF
CN 138 CNTTNUF
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CN 175 CNTTNUF
CN 176 CNTTNUF
CN 177 GUARANTINE CALCTN
CN 178 COMMON /ALYSIS5/, NSI, TWT41, F(A), V(B)
CN 179 COMMON /REDUCE2/, S2(1,5), S2(2,5), S2(3,5),
CN 180 *UTR2,S1, LHS1, O2(2,5), E2(2,5), EG(2,5), SR(2,5),
CN 181 COMMON /HTP/, P, 7, AR, ARP, N, L, ITN, P, SF, NTEST, TR, IZ,
CN 182 *AZIR41, ATIR41, RTIR41, RUMT41
CN 183 *A1BQ,A, R1BQ,A, C1BQ,A, R1BQ,A, C1BQ,A, R1BQ,A
CN 184 *IMFMN(W4), TEST111
CN 185 DATA TLINK, ISYR /1H, 1H/
CN 186 C W(1)=0.147648
CN 187 C W(2)=0.6521451
CN 188 C W(3)=W(2)
CN 189 C W(4)=W(1)
CN 190 C VLS2, PAVL1
CN 191 C FL(1),PAV(1,1)/P(1)
CN 192 C V(1)=1
CN 193 C IF (V(1)=1) THEN 30
CN 194 C W(2)=W(1)
CN 195 C W(3)=W(2)
CN 196 C W(4)=W(1)
CN 197 C TEST111
CN 198 C CTEST111
CN 199 C CRTEST111
CN 200 C FTEST111
CN 201 C G1(1,2)=1.0121011
CN 202 C G1(1,2)=1.0121011
CN 203 C G1(1,2)=1.0121011
CN 204 C G1(1,2)=1.0121011
CN 205 C G1(1,2)=1.0121011
CN 206 C G1(1,2)=1.0121011
CN 207 C G1(1,2)=1.0121011
CN 208 C G1(1,2)=1.0121011
CN 209 C G1(1,2)=1.0121011
CN 210 C G1(1,2)=1.0121011
CN 211 C G1(1,2)=1.0121011
CN 212 C G1(1,2)=1.0121011
CN 213 C G1(1,2)=1.0121011
CN 214 C G1(1,2)=1.0121011
CN 215 C G1(1,2)=1.0121011
CN 216 C G1(1,2)=1.0121011
CN 217 C G1(1,2)=1.0121011
CN 218 C G1(1,2)=1.0121011
CN 219 C G1(1,2)=1.0121011
CN 220 C G1(1,2)=1.0121011
CN 221 C G1(1,2)=1.0121011
CN 222 C G1(1,2)=1.0121011
CN 223 C G1(1,2)=1.0121011
CN 224 C G1(1,2)=1.0121011
CN 225 C G1(1,2)=1.0121011
CN 226 C G1(1,2)=1.0121011
CN 227 C G1(1,2)=1.0121011
CN 228 C G1(1,2)=1.0121011
CN 229 C G1(1,2)=1.0121011
CN 230 C G1(1,2)=1.0121011
CN 231 C G1(1,2)=1.0121011

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TP01 = 1.0 - RL0VYTRL211*E1UC1
RLFPC = FATERP1 - TR011/E1UC1
GO TO 55A
54A CONTINUE
TR01 = FATERP1 + YR0VYX - RL0VYTRL211*E1UC2
RLFPC = 1.0
55B CONTINUE
RLFPC = RLEPC
TRNT02 = TR01 + TRNT01
YD2 = YEARD TRNT02, E1AYR0, E18GR 1
TF (YR2*YR1 .LT. THTNOV1 GO TO 53H
IOV2 = 1
56B CONTINUE
IOV2 = IOV2 + 1
TF (T0V2 .GT. NOV2) GO TO 53H
TF (TTYP2*T0V2) .EQ. 01 GO TO 56B
GO TO 1 57H, 68H, 69H 1, T0V2
57A CONTINUE
C FIRST OVERLAY = UNBONDED CRCP, SECOND OVERLAY = AC
IOV2 = 1
58B CONTINUE
TOV2 = 1
TF (T0V2 .GT. NACT2) GO TO 58B
TF (THRR*PCCT(T0V1)+(ACT2*T0V2) .GT. AL0V1) GO TO 56B
E1UC1 = DEATTG(FPFP, C1UCA1C1), S1UPA(T0V1), T0V2T1 1
E1UC1A = DEATTG(FR0V(TER1), C1UCA(TC1)), S1UPA(T0V1), IOV2T1 1
E1UC2 = DEATTG(FR0V(TER1), C1UCA(TC1)), S1UPA(T0V1), T0V2T1 1
E1UC3 = DEATTG(FPRA(T0V1), T0V2T1 1
E1UC4 = RLEPC*E1UC1A
E0V12X = RL0V12X*E1UC1A1
E0V1Y = (E0V12X - FATERP1/E1UC1)
E0V1Z = RL0V1Y*E1UC1Z
RL0V1Y = 1.0 - RL0V1Z
E0V1Z = RL0V2Y*E1UC1A
E0V22 = RL0V2Y*E1UC1A
E0V2 = RL0V2Y*E1UC1A
E0V12 = TRNT02 + EATERP2 + E0V12 + E0V22
TF (RL0V1Y .LT. 0.0) EAT0T2 = TRNT02 + E0V12X + E0V22
YRF1 = YEARD EAT0T2, E1AYR0, E18GR 1
CALL SAVE2(TRL1, T0V1, T0V1, T0V1, T0V1, T0V2, 0, 0, T0V2);
CS + TRNT01, YR1, EAT0T1, YRF1, TRNT02, YR2, EAT0T2, YRF2
IF (YRF2 .LT. ANTHAX1) GO TO 5AH
CALL SAVE1(TRL1, T0V1, T0V1, T0V1, T0V1, T0V2, 0, 0, T0V2);
+ TRNT01, YR1, EAT0T1, YRF1, TRNT02, YR2, EAT0T2, YRF2
TF (YRF2 .LT. ANPER1) GO TO 5AH
GO TO 56H
68H CONTINUE
C FIRST OVERLAY = UNBONDED CRCP, SECOND OVERLAY = AC
C *** PROGRAM CAN HANDLE ONLY ONE CONCRETE OVERLAY DURING ANALYSIS
C *** PERIOD
GO TO 54H
69B CONTINUE
C FIRST OVERLAY = UNBONDED CRCP, SECOND OVERLAY = JC
C *** PROGRAM CAN HANDLE ONLY ONE CONCRETE OVERLAY DURING ANALYSIS
C *** PERIOD
GO TO 56H
*****78A CONTINUE
C FIRST OVERLAY = BONDED JC
ST 359 TF (PLFPP .LT. PLHFT1) GO TO 52
ST 360 IF (T0V2P .EQ. 1) GO TO 50
ST 361 TC1 = 0
715 CONTINUE
ST 362 TC1 = TC1 + 1
ST 363 IF (TC1 .GT. NACT1) GO TO 5H
ST 364 TF (T0V1TC11 .LT. 0.0) GO TO 715
ST 365 IOV1T = 1
ST 366 IOV1T = IOV1T + 1
ST 367 TF (IOV1T .GT. WPCCT1) GO TO 735
ST 368 FIRST = DEATTG(FRFP, C1UCA(TC1)), S1PRP(T0V1T) 1
ST 369 EAT0T1 = RLEPC*E1UC1
ST 370 EAT0T1 = TRNT01 + EATERP1
ST 371 YRF1 = YEARD EAT0T1, E1AYR0, E18GR 1
ST 372 CALL SAVE2(TRL1, T0V1, T0V1, T0V1, T0V1, T0V1, 0, 0, 0, 0, 0, 0,
CS CS + TRNT01, YR1, EAT0T1, YRF1, RM, RM, RM)
ST 373 TF (YRF1 .LT. ANTHAX1) GO TO 720
ST 374 CALL SAVE1(TRL1, T0V1, T0V1, T0V1, T0V1, T0V1, 0, 0, 0, 0, 0, 0,
+ TRNT01, YR1, EAT0T1, YRF1, RM, RM, RM)
ST 375 IF (YRF1 .LT. ANPER1) GO TO 71H
ST 376 GO TO 715
72H CONTINUE
ST 380 TF (T0V2P .EQ. 01) GO TO 710
ST 381 IF (YRF1*YR1 .LT. THTNOV1) GO TO 71H
ST 382 GO TO 725 TRLX#1,NRL1
ST 383 IF (PLFPP .GE. PLFPP/TRLX11) GO TO 726
ST 384 725 CONTINUE
IRIX = NRL1
ST 385 726 CONTINUE
IRL2 = TRLX = 1
73H CONTINUE
ST 387 IPI2 = TRL2 + 1
ST 388 IF (IRL2 .GT. NRL1) GO TO 71A
ST 389 RLEPC = PLEP(IPI2)
ST 390 TR01 = (PLFPP - RLEPC)*E1UC1
ST 391 RLEPC = PLEP(IPI2)
ST 392 TRNT02 = TR01 + TRNT01
ST 393 YR2 = YEARD TRNT02, E1AYR0, E18GR 1
ST 394 TF (YR2*YR1 .LT. THTNOV1) GO TO 73H
ST 395 IOV2 = 1
ST 396 CALL SAVE2(TRL1, T0V1, T0V1, T0V1, T0V1, T0V2, 0, 0, T0V2);
ST 397 CS + TRNT01, YR1, EAT0T1, YRF1, TRNT02, YR2, EAT0T2, YRF2
ST 398 IF (YRF2 .LT. ANTHAX1) GO TO 5AH
ST 399 CALL SAVE1(TRL1, T0V1, T0V1, T0V1, T0V1, T0V2, 0, 0, T0V2);
ST 400 + TRNT01, YR1, EAT0T1, YRF1, TRNT02, YR2, EAT0T2, YRF2
ST 401 TF (YRF2 .LT. ANPER1) GO TO 5AH
ST 402 GO TO 1 77H, 80H, 81H 1, T0V2
ST 403 76H CONTINUE
ST 404 IOV2 = IOV2 + 1
ST 405 TF (T0V2 .GT. NOV2) GO TO 73H
ST 406 IF (TTYP2*T0V2) .EQ. 01 GO TO 76H
ST 407 GO TO 1 77H, 80H, 81H 1, T0V2
ST 408 78H CONTINUE
ST 409 IOV2T = 1
ST 410 IOV2T = IOV2T + 1
ST 411 TF (T0V2T .GT. NACT2) GO TO 76H
ST 412 IF (SPECT1*IOV1T*ACT2*(IOV2T) .GT. AL0V1) GO TO 76H
ST 413 E1UC1 = DEATTG(FPFP, C1UCA(TC1)), S1UPA(T0V1), T0V2T1 1
ST 414 E1UC2 = DEATTG(FPRA(T0V1), T0V2T1 1
ST 415 EATERP2 = RLEPC*E1UC1A
ST 416 E0V22 = RL0V2Y*E1UC1A
ST 417 EAT0T2 = TRNT02 + EATERP2 + E0V22
ST 418 YRF2 = YEARD EAT0T2, E1AYR0, E18GR 1
ST 419 CALL SAVE2(TRL1, T0V1, T0V1, T0V1, T0V1, T0V2, 0, 0, T0V2),
CS ST 420
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FUNCTION YEARF( W, YE, G )  

YEAR = DETERMINES THE FUTURE YEAR CORRESPONDING TO AN ACCUMULATED  

YEARLY TRAFFIC.  

ENTRYS: YE = # YEARLY TRAFFIC PRIOR TO YEAR ZERO;  

G = GROWTH RATE OF YE PER YEAR, EXPRESSED AS A  

FRACTION;  

W = ACCUMULATED YEARLY TRAFFIC FOR WHICH THE FUTURE  

CORRESPONDING YEAR IS DESIRED.  

EXIT/ YEAR = # FUTURE YEAR CORRESPONDING TO THE ACCUMULATED  

YEARLY TRAFFIC, YE.  

NOTE = THE EQUATION USED TO PREDICT THE YEARLY TRAFFIC, YE(T), IN  

SOME FUTURE YEAR, T, IS AS FOLLOWS,  

YE(T) = YE(0) * (1 + (G*T))  

THE EQUATION FOR THE YEAR CORRESPONDING TO THE ACCUMULATED  

TRAFFIC (WHEN G IS NOT EQUAL TO ZERO) IS,  

YEAR = (T - G*YE) / (G*YE + G^2/2 + R^2*G^2/4R - 1) / (2^R*G)  

RETURN  

10 CONTINUE  

THE EQUATION FOR THE CASE WHEN G IS EQUAL TO ZERO IS,  

YEARH = W/YE  

RETURN  

END

```

SUBROUTINE SAVF( T1, T2, T3, T4, T5, T6, T7, T8, T9, T10,  
+ A1, A2, A3, A4, A5, A6, A7, AR )  
COMMON /NSAVE1/, /NSAVE2/  
  
NSAVE1 = /NSAVE1 + 1  
WRITE(2,1000) NSAVE1,T1,T2,T3,T4,T5,T6,T7,T8,T9,T10,A1,A2,A3,A4,  
+ A5,A6,A7,AR  
1000 FORMAT(1H ,1B,1H3,4F8.3,F7.2)  
RETURN  
END

```

SUBROUTINE SAVF( T1, T2, T3, T4, T5, T6, T7, T8, T9, T10,  

+ A1, A2, A3, A4, A5, A6, A7, AR )  

COMMON /NSAVE1/, /NSAVE2/  

NSAVE2 = /NSAVE2 + 1  

WRITE(2,1000) NSAVE2,T1,T2,T3,T4,T5,T6,T7,T8,T9,T10,A1,A2,A3,A4,  

+ A5,A6,A7,AR  

1000 FORMAT(1H ,1B,1H3,4F8.3,F7.2)  

RETURN  

END

```

SUBROUTINE SETOUT  
COMMON /SETOUT/ = THICKNESS OUTPUT OF STRATEGIES  
  
WRTE(6,1000)  
1000 FORMAT(1H1  
+ //7X,23(1H)  
+ //7X,23H R E A V E M E N T O U T P U T  
+ //7X,23(1H)  
WRTE(6,1000)  
2000 FORMAT( //7X,7HTHE FOLLOWING IS A LIST OF THE COMPONENTS WHICH BE  
+ MAKE UP A FEASIBLE OVERLAY/TX,72HDESIGN STRATEGY. THE COLUMN NUMBER  
+ FERS REFER TO THE COLUMN HEADINGS ON THE//7X,75HLIST OF FEASIBLE STRATE  
+ GIES WHICH FOLGS ON THE NEXT PAGE. THE DESCRIPTIONS//7X,  
+ 76HTH THESE HEADINGS ALSO CORRESPOND TO THOSE IN THE LIST OF OPTIME  
+ AL STRATEGIES//7X,64HWHICH SUCCEED THE LIST OF FEASIBLE STRATEGIES,SE  
+ //  
+ //RX,20HCOL. COMPONENT OF STRATEGY/RX,3HNO./RX,2H24 ,125/1H=1 1SF  
WRTE(6,2100)  
2100 FORMAT(1RX,16H 0. STRATEGY NO.  
2/RX,21H 1. EXISTING PAVEMENT REMAINING LIFE AT TIME OF FIRST OVERLAY  
+ RX PLACEMENT (PERCENT)  
3/RX,47H 2. APPROXIMATE YEAR OF FIRST OVERLAY PLACEMENT  
4/RX,17H 3. TOTAL TX-KTP ESAL FATIGUE CYCLES BETWEEN YEAR ZERO AND SE  
+ YEAR OF FIRST OVERLAY PLACEMENT, MILITONS  
5/RX,67H 4. PRESENT VALUE OF EXISTING PAVEMENT MAINTENANCE COST (DOLL  
+ L\$000)  
6/RX,22H 5. FIRST OVERLAY TYPE  
+ RX,20H 1 = ASPHALTIC CONCRETE  
+ RX,22H 2 = BONDED CRCP  
+ RX,20H 3 = UNBONDED CRCP  
+ RX,21H 4 = BONDED TCP  
+ RX,23H 5 = UNBONDED JCP  
+ RX,50H NOTE = 6 = AFTER NUMBER INDICATES PCC SHOULDER REQUIRENS  
+ 1  
WRTE(6,2200)  
2200 FORMAT(1  
7 RX,20H 7. THICKNESS OF FIRST OVERLAY (INCHES)  
8/RX,40H 8. FLEXURAL STRENGTH OF FIRST OVERLAY (PSI)  
9/RX,43H 9. APPROXIMATE YEAR OF LOSS OF PAVEMENT LOAD-CARRYING CAPAB  
+ EITY AFTER FIRST OVERLAY  
0/RX,20H10. TOTAL TX-KTP ESAL FATIGUE CYCLES BETWEEN YEAR ZERO AND SE  
+ YEAR OF FIRST OVERLAY FAILURE  
1/RX,47H11. PRESENT VALUE OF COST OF FIRST OVERLAY CONSTRUCTION (DOL  
+ L\$000)



```

        + FFCACHE#FAVGR1#FPCRTINV11#VCAFSH1#SYST
        SORRY = 0.0
        ON TO A1
        25 COUNTNIF
        C FIRST OVERLAY = RONDEN FRCP
        TFR1 = TDCSY YP1, 2, HAVINGTINV11,
        SEC1X = FRCAC/SYT
        SEC1X = (FFCPR1#FPR1)+FRCU11#PCCTRINV11#VCCR1#FPR11#SYNT
        4 + (FFCASH#FRCU11#PCCTRINV11#VCAFSH1#SYST
        SORRY = 0.0
        ON TO A1
        25 COUNTNIF
        SORRY = FRCAC/SYT
        SORRY = FFCPR1#FPR11#PCCTRINV11#VCCR1#FPR11
        SORRY = V.0
        ON TO A1
        25 COUNTNIF
        C FIRST OVERLAY = UNLOADEN FRCP
        TFR1 = TDCSY YP1, 1, HAVR1
        + TDCSY YP1, 2, HAVINGTINV11,
        SEC1X = FRCAC/SYT
        TFR1 = NF 1, ON TO S5
        OVERLAY = (FFCPR1#FRCU11#PCCTRINV11#VCCR1#FPR11#SYNT
        + (FFCASH#FRCU11#PCCTRINV11#VCAFSH1#SYST
        SORRY = 0.0
        ON TO A1
        25 COUNTNIF
        SORRY = FRCAC/SYT
        SORRY = FFCPR1#FPR11#PCCTRINV11#VCCR1#FPR11
        SORRY = 0.0
        ON TO A1
        25 COUNTNIF
        C FIRST OVERLAY = RONDEN FRCP
        TFR1 = TDCSY YP1, 2, HAVINGTINV11,
        TFR1 = NF 1, ON TO S5
        SEC1X = FRCAC/SYT
        SORRY = FFCPR1#FPR11#PCCTRINV11#VCCR1#FPR11#SYNT
        + (FFCASH#FRCU11#PCCTRINV11#VCAFSH1#SYST
        SORRY = 0.0
        ON TO A1
        25 COUNTNIF
        SEC1X = FRCAC/SYT
        SORRY = FFCPR1#FPR11#PCCTRINV11#VCCR1#FPR11
        SORRY = 0.0
        ON TO A1
        25 COUNTNIF
        C FIRST OVERLAY = UNLOADEN FRCP
        TFR1 = TDCSY YP1, 1, HAVR1
        + TDCSY YP1, 2, HAVINGTINV11,
        SEC1X = FRCAC/SYT
        TFR1 = NF 1, ON TO S5
        OVERLAY = (FFCPR1#FRCU11#PCCTRINV11#VCCR1#FPR11#SYNT
        + (FFCASH#FRCU11#PCCTRINV11#VCAFSH1#SYST
        SORRY = 0.0
        ON TO A1
        25 COUNTNIF
        SORRY = FRCAC/SYT
        SORRY = FFCPR1#FPR11#PCCTRINV11#VCCR1#FPR11
        SORRY = 0.0
        ON TO A1
        25 COUNTNIF
        C FIRST OVERLAY = RONDEN FRCP
        TFR1 = TDCSY YP1, 1, HAVR1
        + TDCSY YP1, 2, HAVINGTINV11,
        SEC1X = FRCAC/SYT
        TFR1 = NF 1, ON TO S5
        OVERLAY = (FFCPR1#FRCU11#PCCTRINV11#VCCR1#FPR11#SYNT
        + (FFCASH#FRCU11#PCCTRINV11#VCAFSH1#SYST
        SORRY = 0.0
        ON TO A1
        25 COUNTNIF
        SORRY = FRCAC/SYT
        SORRY = FFCPR1#FPR11#PCCTRINV11#VCCR1#FPR11
        SORRY = 0.0
        ON TO A1
        25 COUNTNIF
        C SECOND OVERLAY = FRCP
        TDCP2 = TDCSY YP2, 1, HAVINGCPTINV21
        SEC2X = FOCAC/SYT
        INVRCPX = FRCAC+(AVG111#AC2P1#INV21)*VFC1#SYNT
        + (FFCASH#FRCU11#PCCTRINV21#VCAFSH1#SYST
        SRC2X = 0.0
        ON TO 140
        12A COUNTNIF
        C
        C SECOND OVERLAY = FRCP
        TDCP2 = TDCSY YP2, 2, HAVINGCPTINV21
        JF FIC2 -NF 1, ON TH 125
        SEC2X = FOCAC/SYT
        INVRCPX = (FRCR1#FPR2)+(AVG111#AC2P1#INV21)*VFC1#SYNT
        + (FFCASH#FRCU11#PCCTRINV21#VCAFSH1#SYST
        SRC2X = 0.0
        ON TO 140
        12A COUNTNIF
        C
        C SECOND OVERLAY = FRCP
        TDCP2 = TDCSY YP2, 2, HAVINGCPTINV21
        JF FIC2 -NF 1, ON TH 125
        SEC2X = FOCAC/SYT
        INVRCPX = (FRCR1#FPR2)+(AVG111#AC2P1#INV21)*VFC1#SYNT
        + (FFCASH#FRCU11#PCCTRINV21#VCAFSH1#SYST
        SRC2X = 0.0
        ON TO 140
        12A COUNTNIF
        C
        C SECOND OVERLAY = FRCP
        TDCP2 = TDCSY YP2, 2, HAVINGCPTINV21
        JF FIC2 -NF 1, ON TH 125
        SEC2X = FOCAC/SYT
        INVRCPX = (FRCR1#FPR2)+(AVG111#AC2P1#INV21)*VFC1#SYNT
        + (FFCASH#FRCU11#PCCTRINV21#VCAFSH1#SYST
        SRC2X = 0.0
        ON TO 140
        12A COUNTNIF
        C
        C SECOND OVERLAY = FRCP
        TDCP2 = TDCSY YP2, 2, HAVINGCPTINV21
        JF FIC2 -NF 1, ON TH 125
        SEC2X = FOCAC/SYT
        INVRCPX = (FRCR1#FPR2)+(AVG111#AC2P1#INV21)*VFC1#SYNT
        + (FFCASH#FRCU11#PCCTRINV21#VCAFSH1#SYST
        SRC2X = 0.0
        ON TO 140
        12A COUNTNIF
        C
        C SECOND OVERLAY = FRCP
        TDCP2 = TDCSY YP2, 2, HAVINGCPTINV21
        JF FIC2 -NF 1, ON TH 125
        SEC2X = FOCAC/SYT
        INVRCPX = (FRCR1#FPR2)+(AVG111#AC2P1#INV21)*VFC1#SYNT
        + (FFCASH#FRCU11#PCCTRINV21#VCAFSH1#SYST
        SRC2X = 0.0
        ON TO 140
        12A COUNTNIF
        C
        C COUNTNIF
        ON TH 210, 211, 212, 213, 1, TEPYD
        211 COUNTNIF
        212 COUNTNIF
        FAIL MINTSY YP1, YRF1, YRP2, MRC2, DRACC, DRACCH, MRC2C, CO 190
        SORRY = 0.0
    
```

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+ DRACC, DRACCA, DRACC, EPMNTC, OVHTC1, OVHTC2 1 CO 192 C COMPUTE TOTAL STRATEGY COST CO 254
GO TO 260 CO 193 C TOTCST = EPMNTC+CC1+TC1+OVHTC1+CC2+TC2+OVHTC2+TVFXLGS+LV CO 255
213 CONTINUE CO 194 C PRINT EACH FEASIBLE STRATEGY CO 256
CALL MNTEST(YR1, YRF1, YR2, YRF2, DRACJ, DRACJA, DRACJR, DRACJ, CO 195 C CALL PRNTSTR(ISTR) 1 CO 257
+ DRACF, DRACFA, DRACFR, DRACF, EPMNTC, OVHTC1, OVHTC2 1 CO 196 C PRINT EACH FEASIBLE STRATEGY CO 258
GO TO 260 CO 197 C CALL PRNTSTR(ISTR) 1 CO 259
214 CONTINUE CO 198 C OPTIMIZIE BY ARRANGING IN ORDER OF INCREASING COST CO 260
GO TO 1, 215, 216 1, TERTYP CO 199 C CALL ORDER CO 261
215 CONTINUE CO 200 C CALL ORDER CO 262
CALL MNTEST(YR1, YRF1, YR2, YRF2, DRACC, DRACCA, DRACC, DRACC, CO 201 C CALL ORDER CO 263
+ DRACC, DRACCA, DRACC, EPMNTC, OVHTC1, OVHTC2 1 CO 202 C 520 CONTINUE CO 264
GO TO 260 CO 203 C RETURN CO 265
216 CONTINUE CO 204 C 900 CONTINUE CO 266
CALL MNTEST(YR1, YRF1, YR2, YRF2, DRACJ, DRACJA, DRACJR, DRACJ, CO 205 C WRITE(6,1400)
+ DRACF, DRACFA, DRACFR, DRACF, EPMNTC, OVHTC1, OVHTC2 1 CO 206 C 1400 FORMAT(//18X,4THREA SORRY, NO FEASIBLE STRATEGIES COULD BE CO 267
GO TO 260 CO 207 C 1 GENERATED. //18X,3AH#* CHECK CONSTRAINTS AND/OR INCREASE CO 268
217 CONTINUE CO 208 C 2 RANGE OF OVERLAY THICKNESSES. ) CO 269
GO TO 1, 218, 219 1, TERTYP CO 209 C STOP CO 270
218 CONTINUE CO 210 C END CO 271
CALL MNTEST(YR1, YRF1, YR2, YRF2, DRACJ, DRACJA, DRACJR, DRACJ, CO 211 C
+ DRACF, DRACFA, DRACFR, DRACF, EPMNTC, OVHTC1, OVHTC2 1 CO 212 C
GO TO 260 CO 213 C
219 CONTINUE CO 214 C
CALL MNTEST(YR1, YRF1, YR2, YRF2, DRACJ, DRACJA, DRACJR, DRACJ, CO 215 C
+ DRACF, DRACFA, DRACFR, DRACF, EPMNTC, OVHTC1, OVHTC2 1 CO 216 C
GO TO 260 CO 217 C
220 CONTINUE CO 218 C
221 CONTINUE CO 219 C
CALL MNTEST(YR1, YRF1, YR2, YRF2, DRACF, DRACFA, DRACFR, DRACF, CO 220 C
+ DRACC, DRACCA, DRACC, EPMNTC, OVHTC1, OVHTC2 1 CO 221 CC FUNCTION TDOSY(VR, TDODV, WPSY) 1
GO TO 260 CO 222 C TD 1
240 CONTINUE CO 223 C TD 2
250 CONTINUE CO 224 C TD 3
CALL MNTEST(YR1, YRF1, YR2, YRF2, DRJCPA, DRJCPB, DRJCP, CO 225 C TD 4
+ DRACJ, DRACJA, DRACJR, EPMNTC, OVHTC1, OVHTC2 1 CO 226 C TD 5
260 CONTINUE CO 227 C TD 6
CONVERT MAINTENANCE COST FROM DOLLARS/MILE TO DOLLARS/SY CO 228 C TD 7
EPMNTC = EPMNTC/(1760.*OVWOTH/3.) CO 229 C TD 8
OVHTC1 = OVHTC1/(1760.*OVWOTH/3.) CO 230 C TD 9
OVHTC2 = OVHTC2/(1760.*OVWOTH/3.) CO 231 C TD 10
CO 232 C TD 11
CO 233 C TD 12
CO 234 C TD 13
CO 235 C TD 14
CO 236 C TD 15
TF(YRF2 .GE. RM1) YRF2=YRF1+0.5 CO 237 C TD 16
TVEXL = 0.0 CO 238 C TD 17
TF(YNDF .LT. NANPER) GO TO 310 CO 239 C TD 18
DO 300 TVRNANDER, NYRF CO 240 C TD 19
YR = YRF CO 241 C TD 20
TVFXL = TVFXL + PVAL1*YVFXL, YR, DISCRT 1 CO 242 C TD 21
300 CONTINUE CO 243 C TD 22
310 CONTINUE CO 244 C TD 23
CO 245 C TD 24
CO 246 C TD 25
CO 247 C TD 26
CO 248 C TD 27
TF(YRF2 .GE. RM1) YRF2=ANDER CO 249 C TD 28
YRSALV = MAX(Y NANPER, YRF) CO 250 C TD 29
SALVX = (PESALV/100.0)*(OVFC1*X+OVFC2*X) CO 251 C TD 30
SALV = PPVAL1*SALVX, YRSALV, DISCRT 1 CO 252 C TD 31
CO 253 C TD 32
PVSN = PERCENT VEHICLES STOPPED BY ROAD EQUIPMENT, CO 254 C TD 33
OVERLAY DIRECTION, CO 255 C TD 34
PVSN = PERCENT VEHICLES STOPPED BY ROAD EQUIPMENT,

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\*NON-OVERLAY DIRECTION.  
 DE00 = AVERAGE DELAY PER VEHICLE STOPPED IN RETRACTED ZONE, OVERLAY DIRECTION, HOURS.  
 DEON = AVERAGE DELAY PER VEHICLE STOPPED IN RETRACTED ZONE, NON-OVERLAY DIRECTION, HOURS.  
 HPSY = OVERLAY CONSTRUCTION RATE, HOURS/RY.  
 NLANE = NO. OF OVERLAY LANES.  
 WL = LANE WIDTH, FEET.  
 OVLLEN = OVERLAY LENGTH, MILES.  
 ADT = THRTTAL AVERAGE DAILY TRAFFIC, BOTH DIRECTIONS. (DELAY COSTS WILL BE COMPUTED ON THE BASIS THAT THE ADT IS SPLIT EVENLY IN BOTH DIRECTIONS)  
 GR = TRAFFIC GROWTH RATE, PERCENT PER YEAR.  
 EXIT/ TDCSY = PRESENT VALUE OF FUTURE TRAFFIC DELAY COST DUE TO OVERLAY CONSTRUCTION, DOLLARS/RY.  
  
 NOTE - THIS ROUTINE IS AN MODIFICATION OF ONE CALLED TDC3 IN THE RIGID PAVEMENT SYSTEM, RPS3, DEVELOPED BY CARMICHAEL AND DOCUMENTED IN CFRH 123-26, "MODIFICATION AND IMPLEMENTATION OF THE RIGID PAVEMENT DESIGN SYSTEM". SOME COST IMPROVEMENTS WERE APPROPRIATED BY DANIEL AND DOCUMENTED IN CFRH 177-14, "A METHODOLOGY TO DETERMINE AN OPTIMUM TIME TO OVERLAY". SOME IMPROVEMENTS WERE ALSO MADE FOR TDCP03 IN OPERATION INTO RPS4-1 BY SEEDS. RIGID PAVEMENT REHABILITATION DESIGN SYSTEM, MASTERS THESIS, 1988, UNIVERSITY OF TEXAS. TWO ADDITIONAL ROUTINES ARE PART OF THE PACKAGE, TDPHCAL (DISTRIBUTION OF ADT FOR TEXAS) AND PPVAL (EST. PRESENT VALUE OF SOME FUTURE COST).  
  
 COMMON /TDC/ ILOC, MODEL, NOLD, NOLN, N1, N2, HPMOD, DAYPUR, DNOZ, DTSD, DTSN, AAS, ASRD, ASND, PVSD, PVSN, DE00, DEON  
 COMMON /PROJECT/ NLANE, WL, OVLLEN, SHWDTH  
 COMMON /TRAFFIC/ ADT, GR, E1AYR0, E18GR  
 COMMON /INTRST/ DISRET  
 DIMENSION AVPH(24)  
 DIMENSION FCSP(6,7), CURB(6,7), CDR(1,2), CAP(4,3)  
  
 THE FOLLOWING ARE TABLES CONTAINING THE USER COSTS:  
  
 COST OF SLOWING DOWN IN A RURAL AREA IN TEXAS,  
  
 EXCESS COST ABOVE CONTINUING AT INITIAL SPEED  
 IT INCLUDES OPERATING AS WELL AS TIME COST OF SPEED CHANGE CYCLE  
 \*\*DOLLARS PER 1000 CYCLES\*\*  
 DATA FCSP/ 15.312, 322.889, 57.814, 91.886, 140.831, 217.839,  
 1 17.819, 34.836, 71.577, 110.699, 191.322, 248.1, 295.518,  
 2 51.398, 97.434, 167.124, 340.1, 58.543, 72.177, 137.379,  
 3 84.0, 43.762, 101.934, 54.0, 56.784, 64.0/  
  
 COST OF SLOWING DOWN IN AN URBAN AREA  
 DATA CDR/13.666, 21.268, 35.238, 54.267, 81.123, 122.614, 0.1,  
 1 10.123, 23.274, 41.012, 67.074, 106.445, 240.1, 11.708,  
 2 28.871, 51.554, 88.750, 340.1, 15.551, 38.750, 72.721, 46.0,  
 3 44.444  
  
 3 21.4225, 53.467, 56.0, 29.694, 4.60/  
 TD 35 C  
 TD 36 C COST OF OPERATING AT A INITIAL SPEED IN TEXAS  
 TD 37 C DIFFERENCE OF TWO VALUES GIVES THE EXCESS COST OF OPERATING AT  
 TD 38 C REDUCED SPEED  
 TD 39 C IT INCLUDES OPERATING AS WELL AS TIME COST  
 TD 40 C \*\* DOLLARS PER 1000 VEHICLE MILES \*\*  
 TD 41 C  
 TD 42 C DATA CURB/1355.69, 711.144, 495.42, 387.68, 323.71, 242.20,  
 1 255.32, 233.17, 214.77, 208.74, 202.29, 190.27, 125.16,  
 2 654.95, 455.77, 354.11, 296.65, 257.64, 230.55, 211.14,  
 3 196.94, 186.57, 179.23, 174.88/  
  
 TD 43 C COST OF TOLTING  
 TD 44 C IT INCLUDES OPERATING AS WELL TIME COST  
 TD 45 C \*\* DOLLARS PER 1000 VEHICLE HOURS \*\*  
 TD 46 C  
 TD 47 C  
 TD 48 C  
 TD 49 C  
 TD 50 C  
 TD 51 C  
 TD 52 C  
 TD 53 C  
 TD 54 C  
 TD 55 C  
 TD 56 C  
 TD 57 C  
 TD 58 C  
 TD 59 C  
 TD 60 C  
 TD 61 C  
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 TD 158 C









FENSTORD ALT. NETHAY NORTHEAST  
IN 1 ■ KSTR1STR11  
■ KSTR1STR11  
■ KSTR1STR21  
■ KSTR1STR21  
■ KSTR1STR31  
■ KSTR1STR31  
■ KSTR1STR41  
■ KSTR1STR41  
■ KSTR1STR51  
■ KSTR1STR51  
■ KSTR1STR71

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28 //////////////////////////////////////////////////////////////////// - RIGHT OFWAY REHABILITATION DESIGN SYSTEM - VPOU
29 ARSON 1, NAVI TEAM
30 //////////////////////////////////////////////////////////////////// - TRANSPORTATION RESEARCH
31 //////////////////////////////////////////////////////////////////// - 20HUNIVERSITY OF TEXAS AT AUSTIN///
32 //////////////////////////////////////////////////////////////////// - 1040POINT STRATEGY NO. 104///
33 //////////////////////////////////////////////////////////////////// - 1040POINT STRATEGY NO. 104///
34 11.24 *1X.214 FORMATTED
35 *5X.61H 1. EXISTING PAVEMENT REHABTING LIFE AT 1ST OVERLAY: PFRCENT
36 *5X.61H 1. 99
37 *5X.61H 1. 99
38 *5X.34H 2. YEAR OF 1ST OVERLAY PLACEMENT, PAX,PIG,IR, 01
39 *5X.62H 3. TOTAL 1A-KIP ESAL CYCLES (NOW TILL 1ST OVERLAY): MLLION 101
40 *5X.62H 3. 101
41 *5X.51H 4. 102
42 *5X.51H 4. 102
43 12.07 FORMAT/
44 *5X.21H 5. CRASH OF MAINTAINING EXISTING PAVEMENT, DOL/SA YD,SY, 01
45 *5X.21H 5. 103
46 *5X.21H 6. 104
47 *5X.30H 7. 1ST OVERLAY THICKNESS, INCHES,21X,F10.1/ 01
48 *5X.30H 7. PCC FLEXURAL STRENGTH OF 1ST OVERLAY, PST,16Y,F10.1/ 01
49 *5X.42H 9. 1ST OVERLAY FATIGUE LIFE AFTER 1ST OVERLAY, YEARS,20X,F10.1/ 01
50 *5X.42H 9. 105
51 *5X.61H 1. 1ST OVERLAY CONSTRUCTION COST, DOL/SD YN,17X,F10.2/ 01
52 *5X.61H 1. 106
53 *5X.45H 1. 1ST OVERLAY TRAFFIC DELAY COST, DOL/SD YN,16Y,F10.2/ 01
54 *5X.45H 1. 107
55 *5X.45H 1. 1ST OVERLAY MAINTENANCE COST, DOL/SD YD,10X,F10.2/ 01
56 *5X.75H 10. 1ST OVERLAY REMAINING LIFE AT 2ND OVERLAY, PFRCENT,7X, 01
57 *5X.75H 10. 117
58 *5X.34H 15. YEAR OF 2ND OVERLAY PLACEMENT,28X,F10.0/ 01
59 *5X.62H 6. TOTAL 1A-KIP ESAL CYCLES (NOW TILL 2ND OVERLAY): MLLION 120
60 *5X.62H 6. 120
61 14.04 FORMAT/
62 *5X.51H 4. 1ST OVERLAY REMAINING LIFE AT 2ND OVERLAY, PFRCENT,14X,01 01
63 *5X.51H 4. 122
64 *5X.34H 15. YEAR OF 2ND OVERLAY PLACEMENT,35X,3H---/ 01
65 *5X.62H 6. TOTAL 1A-KIP ESAL CYCLES (NOW TILL 2ND OVERLAY): MLLION 125
66 *5X.62H 6. 125
67 15.04 FORMAT/
68 *5X.21H 17. 2ND OVERLAY TYPE,43X,3H---/ 01
69 *5X.21H 17. TYPE OF SHMULDR,07X,A4S,3H---/ 01
70 *5X.30H 18. 2ND OVERLAY THICKNESS, INCHES,35X,3H---/ 01
71 *5X.30H 18. PCC FLEXURAL STRENGTH OF 2ND OVERLAY, PST,23Y,3H---/ 01
72 16.04 FORMAT/
73 *5X.71H 17. 2ND OVERLAY FATIGUE LIFE AFTER 2ND OVERLAY, YEARS,20X,F10.1/ 01
74 *5X.71H 17. 104
75 *5X.45H 18. 2ND OVERLAY CONSTRUCTION COST, DOL/SD YN,17X,F10.2/ 01
76 *5X.45H 18. 104
77 *5X.62H 19. 2ND OVERLAY TRAFFIC DELAY COST, DOL/SD YN,16Y,F10.2/ 01
78 *5X.62H 19. 104
79 *5X.45H 20. 2ND OVERLAY MAINTENANCE COST, DOL/SD YD,10X,F10.2/ 01
80 *5X.45H 20. 105
81 *5X.45H 21. 2ND OVERLAY REMAINING LIFE AT 2ND OVERLAY, PFRCENT,7X, 01
82 *5X.45H 21. 106
83 *5X.45H 21. 106
84 16.04 FORMAT/
85 *5X.42H 21. 2ND OVERLAY TYPE,43X,3H---/ 01
86 *5X.42H 21. 107
87 *5X.42H 21. 107
88 *5X.42H 21. 108
89 *5X.42H 21. 109
90 *5X.62H 22. 2ND OVERLAY THICKNESS, INCHES,35X,3H---/ 01
91 *5X.62H 22. 109
92 *5X.45H 23. 2ND OVERLAY CONSTRUCTION COST, DOL/SD YN,20X,3H---/ 01
93 *5X.45H 23. 109
94 *5X.45H 23. 110
95 *5X.62H 23. 2ND OVERLAY TRAFFIC DELAY COST, DOL/SD YN,20X,3H---/ 01
96 *5X.62H 23. 111

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+5X,40H25,	2ND OVERLAY MAINTENANCE COST, DOL/SD YD,25X,TH----	OU 152
17.00 FORMATTED,		OU 153
+5X,5AH26,	VALUE OF EXTENDED LIFE, DOL/SD YD,24X,F19,2/	OU 154
+5X,37H27,	OVERLAY SALVAGE VALUE, DOL/SD YD,25X,F19,2/	OU 155
+5X,51H28,	TOTAL NET PRESENT VALUE OF STRATEGY, DOL/SD YD,11X,	OU 156
+#1W,21		OU 157
C	END	OU 158
		OU 159

#### THE AUTHORS

Stephen B. Seeds received his Bachelor of Science in Civil Engineering with Honors in December of 1977 from The University of Texas at Austin. In January 1978, he entered the Graduate School at The University of Texas, and accomplished much of his graduate research at the University's Center for Transportation Research under the Cooperative Research Program between the University of Texas and the Texas State Department of Highways and Public Transportation.

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