A TECHNIQUE FOR MEASURING THE DISPLACEMENT VECTOR THROUGHOUT THE BODY OF A PAVEMENT STRUCTURE SUBJECTED TO CYCLIC LOADING by

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## PREFACE

This is the second report issued under Research Study 2-8-69-136, Design and Evaluation of Flexible Pavements, being conducted at the Texas Transportation Institute as part of the cooperative research program with the Texas Highway Department and the Department of Transportation, Federal Highway Administration.

The first report is
"Seasonal Variations of Pavement Deflections in Texas," by Rudell Poehl and Frank H. Scrivner, Research Report 136-1, Texas Transportation Institute, January, 1971.

The authors wish to thank all members of the Institute who assisted in this research. They would like to express special appreciation to Mr. Frank H. Scrivner and Mr. Lionel J. Milberger. Their help throughout the study has been particularly valuable. Thanks are also due Mr. C. H. Michalak for his assistance in the data reduction phase and Mr. John Salyer for his assistance during the fabrication and testing phases.

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The opinions, findings and conclusions expressed in this publication are those of the authors and not necessarily those of the Department of Transportation, Federal Highway Administration.


#### Abstract

A measuring technique was developed to determine the displacement vector throughout the body of a pavement structure subjected to Dynaflect loading. The instrumentation used for these measurements is described and the displacement vector fields observed in three different pavement structures are shown and compared.

Key Words: Deflections, Displacement, Measurement, Pavement-Structure, Vector-Field.


## SUMMARY

A technique is described for observation of the displacement vector field, or motions of the points within the body of a pavement structure under the influence of cyclic loading. An oscillating load of 1000 lbs . at 8 cycles per second produced by the Dynaflect is applied to the surface. The vertical and horizontal components of the displacements were measured by emplacing a sensor in a small hole drilled into the body of the pavement. Observed displacements are shown for three different pavement structures. The measurements were repeated at a different location on each structure and the replicate data sets are shown and compared. Their differences are seen to be small in comparison with the differences observed between structures.

The measured displacement fields are shown to have considerable similarity to fields computed for layered elastic structures. It is concluded that a practical fieldworthy technique has been developed for observing the vector displacement response of a pavement structure and that the development of a useful and practical mathematical model representing the displacement vector throughout a pavement structure should be possible.

## IMPLEMENTATION STATEMENT

The end results of this research study are expected to provide a significant improvement to the empirical deflection equation currently being used in the Texas Highway Department's flexible pavement design system. Use of the present equation has pointed out several weak points and a pressing need for a more accurate one. This report describes the measurement technique developed and typical data to be used to improve the equation.

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## 1. INTRODUCTION

This is a progress report on Phase 2 of a research study entitled "Design and Evaluation of Flexible Pavements" being conducted by the Texas Transportation Institute and sponsored by the Texas Highway Department and the Federal Highway Administration. The objective of this phase of the research, as quoted from the Study Proposal, is "to develop from full-scale testing, a mathematical model estimating the displacement vector at any given point within a pavement structure subjected to Dynaflect loading, given this vector at the surface, the thickness of each layer and a stiffness parameter for each material." Two different models for estimating the vertical component of the displacement vector on a pavement's surface were developed in Research Study $32(1,2)$. The second and more accurate model was used in the development of the flexible pavement design system (3) which is being expanded and implemented in study 123 (4). Use of this model has pointed out several weak points and a pressing need for a still more accurate one.

An accurate model for predicting the displacement vector within any given pavement structure will provide design engineers with a means of calculating strains within the structure and will be an important step in the development of a more realistic approach to pavement design. Thus, it is expected that this study will represent a significant step toward obtaining a more rational pavement design theory.

Several researchers have reported measurements of stresses and strains in situ (5, 6, 7, 8). However, placing stress or strain sensors within a pavement structure tends to destroy the continuity of the material and therefore alters the distribution of the quantities being measured. In contrast, displacement measurements should be substantially unaffected by small perturbations of the system.

Any displacement measurement requires a reference point. As pointed out in Reference 9, the Dynaflect* technique of applying a cyclic force makes it possible to employ an inertial reference point which is immune to measurement errors caused by reference point motion. Other methods of measuring displacement require a physical, tangible, reference point which must be sufficiently remote to remain undisturbed during the measurement, at least to the extent set by the desired accuracy of the measurement. Such a point would be quite deep or quite far away if on the surface. Thus, the measurement would require the determination of an extremely small change in a relatively large distance, a requirement which is believed to lead to unacceptably large errors. According1y an extention of the Dynaflect measuring technique, employing geophones as displacement sensors, was adopted for this study.

Surface deflections of a pavement structure, as normally measured with the Dynaflect, provide insufficient data to define the response of the entire structure to the loading on its surface. Thus, measurement of the displacement vector field throughout the pavement structure was undertaken in this study to provide data for developing the model

[^0]required in the study's objective, or for verifying existing models such as linear elasticity, linear viscoelasticity, etc.

The purpose of this report is to describe the apparatus and technique developed to measure both horizontal and vertical components of the displacement vector. It includes typical measurements obtained, as well as the replication errors encountered.

## 2. SCOPE OF MEASUREMENTS PROGRAM

The A\&M pavement test facility is being used to obtain data for analysis. This facility, located at the University's Research Annex, was constructed for the purpose of providing a means for evaluating nondestructive testing techniques, and more particularly, for evaluating testing equipment purporting to furnish information concerning the in situ characteristics of the individual layers in a flexible pavement. It consists of thirty-two 12 x 40 ft . test sections having different structural characteristics in accordance with the principles of statistical experiment design. The design of the facility is described in detail in Reference 1. Plan and cross-sectional views of the test facility are shown in Figure 1 .

The displacement vector field of a test section is induced by loading the section with a Dynaflect. This instrument, shown in Figure 2, produces a vertical dynamic load of 1000 pounds, oscillating sinusoidally with time at 8 Hz (cycles per second), which is applied to the surface through two steel wheels spaced 20 inches apart. A complete description is given in References 9 and 10. Vertical displacement measurements are made on the surface of the pavement using low-frequency geophones whose output voltage is directly proportional to the amplitude of the sinusoidal motion.

The displacement vector field was determined on a test section by measuring separately the horizontal and vertical components of motion at selected depths and horizontal distances from the points of application of the surface loads. To make an individual component measurement a miniature geophone -- either one designed for horizontal motion or one



TYPICAL CROSS-SECTION (A-A above)

Figure 1: Texas A\&M pavement test facility.


Figure 2: Dynaflect trailer in normal use with five-geophone array on pavement surface.
designed for vertical motion -- was clamped in place in a small diameter hole drilled vertically in the pavement section. The measurement depth was altered by clamping the geophone at various depths, while the horizontal distance from the points of application of the surface load was altered by moving the Dynaflect forward on the surface various distances. Utilizing this concept as illustrated in Figure 3, sufficient measurements were made to define both the vertical and horizontal component fields in the region from zero to about 5 feet in depth and from approximately 1 to 18 feet in horizontal distance. Because of the 20 inch spacing of the Dynaflect load wheels, it was not practical to make measurements at horizontal distances less than 10 inches.

To date displacement vector fields have been measured at two locations on each of three test sections. The planned program includes replicate measurements on all thirty-two of the test sections. Replicate measurements, made on opposite ends of each test section, will permit analysis of overall precision. Replication errors observed on a test section reflect not only the variability of the measuring process but also include the effects of variations in the structural properties of the section. The combined variability will define the limiting prediction accuracy for the displacement model being sought.


Figure 3: Conceptual representation of the technique used to measure vector displacements within a pavement section.

## 3. MEASURING TECHNIQUE

### 3.1 Basic Technique

Extension of the Dynaflect technique to the measurements of the displacement vector throughout the pavement structure was accomplished by using a pair of suitable geophones -- one responsive only to the vertical component of motion, the other responsive only to the horizontal component -- and clamping them one at a time at selected depths in a single hole in the structure. With either geophone placed at a given depth, the Dynaflect was positioned at a succession of locations on the surface ranging from directly above the hole up to 18 feet away.

### 3.2 Geophone Emplacement

In order to minimize disturbance to the pavement sections, miniature geophones were obtained and an emplaceable assembly was designed which was sufficiently small to fit within a 1-3/4 inch diameter hole. The down-hole geophone assembly is shown in Figure 4. It comprises a waterproof aluminum housing in which one geophone, either horizontal or vertical, is mounted. 'Two spring-loaded pistons can be released to expand outward and clamp the device in the hole. Flexible steel cables (fishing leader wire) extend above the surface to permit the release and retraction of the pistons. A removable hollow rod, through which the electrical output cable passes, permits the $1-5 / 8$ inch diameter device to be lowered into the hole with the pistons retracted. At the desired depth the pistons are released. The rod is then disconnected and removed from the hole, leaving the unit in place with slack wires extending to the surface. The unit is retrieved by reversing this procedure. A cross section of the down-hole device is shown in Figure 5.


Figure 4: Subsurface geophone assembly being placed in hole in pavement section.


Figure 5: Cross-sectional view of subsurface geophone assembly.

### 3.3 Drilling Technique

After disappointing results were obtained with several types of drill-rigs and drill-bits, a satisfactory combination was found. All of the successful holes, useable for geophone emplacement, have been drilled with a Clipper Core Drill Model D-30-P using a diamond corebarrel, 1-3/4 diameter by 14 inches long. This drill, shown in Figure 6 , is used with a continuous flow of compressed air while penetrating the hot-mix asphaltic concrete surface layer and the limestone base or subbase layers. The same core-barrel is employed, without air-flow, to penetrate the softer embankment and subgrade materials. Where the material is soft clay, the drill is used without rotation.

Several types of drill-bits which were tried in connection with this work are shown in Figure 7. The diamond core-barrel is at the extreme right.

It was decided before undertaking this work that air must be employed during drilling because water would alter or damage the pavement sections. In spite of this precaution, water trapped in the embankment material invaded several of the holes during the measurement period within one or two hours after hole completion. No adverse effects were attributable to this water in those sections in which it was possible to complete the measurement sequence. In one group of sections, however, the hole walls collapsed and prevented emplacement of the geophone. It is planned to drain the excess water from the saturated zones prior to making more measurements on these sections.

### 3.4 Measuring Procedure

The measuring procedure developed for this investigation began with emplacement of the vertical geophone at the greatest chosen depth.


[^1]

Figure 7: Various drill-bits tried in connection with drilling holes for displacement measurements. Best results were obtained with the diamond core barrel shown at the extreme right.

The Dynaflect was then positioned on the surface directly over the hole. After reading and recording the geophone output voltage the Dynaflect was moved away from the hole to each of a series of preselected distances. The geophone signal was read and recorded at each location. At the end of each such series of measurements the geophone was retrieved and repositioned at a shallower depth in the hole. Upon completion of the entire grid of measurements the above procedure was repeated using the horizontal geophone. When using the latter, in addition to recording the magnitude of its output signal, the phase angle was observed to determine whether the horizontal displacement was toward or away from the load.

Ordinarily one hole and one entire set of vertical and horizontal displacement measurements can be completed within a day. At the end of each set of horizontal or vertical measurements the geophone used for that set was calibrated by observing its response to a 0.005 inch oscillatory motion provided by the Dynaflect calibrator unit. The calibration factor thus established was utilized to convert the recorded voltage readings to displacements in millionths of an inch. Using a Hewlett Packard Model 502A Wave Analyzer to read these voltages, displacements as small as one millionth of an inch could be measured (See Figure 8). Thus far the observed movements have ranged from less than one millionth to two thousandths of an inch.


Figure 8: Operator reading the geophone output signal magnitude on Wave Analyzer. The oscilloscope at the left is used to observe the phase angle of the geophone signals to determine direction.
4. Transformation of Measurements to A Single Load Vector Field

As previously mentioned, the dynaflect applies a 10001 lb . load to the surface through two wheels which are spaced 20 inches apart. Hence, when the Dynaflect is centered over a hole, its two load application points are equidistant at a 10 inch radial (horizontal) distance from the hole. Moving the Dynaflect forward a distance, $x$, along a straight line increases both of these radial distances while maintaining their equality. The radial distance, $r$, from the hole to either of the load application points is given by

$$
r=\sqrt{x^{2}+10^{2}}
$$

In order to simplify the presentation of the data, the observed measurements were converted to the case of a single 1000 lb . axially symmetrical load acting at a distance, $r$, from the hole, by assuming that the displacement vectors at any depth, $z$, produced by the two 500 lb . 10 ads were of equal magnitude and were vectorially additive. The vertical displacement components produced by each of the two loads are alike in both magnitude and direction; therefore, the vertical component for a single 500 lb . load would be half the measured value, and for a single 1000 lb . load it would be equal to the measured value. This measured value is represented by the symbol, w.

The horizontal components of motion produced by each load wheel are alike in magnitude but, unlike the vertical components, are directed along lines parallel to the radial (horizontal) lines on the surface joining the hole with the individual load application points. Hence, when the Dynaflect is centered over the hole, the horizontal components due to each load wheel are in opposite directions. Since this represents a null of horizontal motion, the horizontal measurement is
omitted at this position. The horizontal measurement closest to the loads is made with the Dynaflect axle 6 inches away from the hole and the most remote measurement is made when it is 18 ft . (or 216 inches) away. At any given forward distance, $x$, (See Figure 9) the horizontal displacement components produced by each load wheel are equal in magnitude but are separated by an angle $2 \alpha$, where

$$
\alpha=\arctan (10 / x)
$$

Thus the measured horizontal displacement, $M_{h}$, is related to the horizontal displacement, $u$, resulting from a single 1000 lb . load, by

$$
\mathbf{u}=M_{h} \sec \alpha
$$

as may be verified by reference to Figure 9 .
Sec $\alpha$ can be regarded as a correction factor which is applied to the measured values of horizontal displacement to transform them to values which would have been obtained in the assumed axially symmetrical case. Figure 10 is a plot of $\sec \alpha$ versus $x$. From this plot it can be seen that the correction factor approaches unity very quickly as the Dynaflect is moved forward to increase the horizontal distance x. Thus, the principle of Saint-Venant is illustrated, in that the correction factor becomes insignificant at values of $x$ exceeding two or three times the 20 -inch distance between the load wheels (11).


Figure 9: The relation of the horizontal displacement vectors produced by each load wheel to the measured horizontal displacement.


Figure 10: The relationship of forward distance of Dynaflect to the correction factor applied to the measured horizontal displacement in the transformation to a single load point.

## 5. GEOMETRICAL LIMITS OF VECTOR FIELD

Since the existing dimensions of the Dynaflect make it inconvenient to measure vertical displacements at locations closer than $x=0$ (or $r=10$ inches) from the load application points, or horizontal displacements at locations closer than $x=6$ inches (or $r=11.7$ inches), these dimensions form the close-in limits of the measured displacement fields. The far-out 1imit of $x=216$ inches (or $r=216.2$ inches) was selected upon consideration of the finite ( 40 ft. ) length of the sections and the observed diminution of the displacements with distance and with depth. The deep limit, at $z \approx 65$ inches below the surface, was selected on the basis that the test facility comprises 53 inches of selected materials on a reasonably uniform clay foundation which is regarded as extending infinitely downward. In view of the observed displacement behavior it is believed that the outer limits of the measured fields have been placed amply far to encompass the region of major interest and to permit reasonable extrapolation beyond this region.

Thus, the geometrical limits of the transformed vector fields determined from the measurements are as follows:

Field of the component $u$ -

$$
11.7 \text { in. } \leq \mathrm{r} \leq 216.2 \text { in., } 0 \leq \mathrm{z} \leq 65 \text { in. (approx.) }
$$

Field of the component $w$ -

$$
10 \text { in. } \leq r \leq 216.2 \text { in. } 0 \leq z \leq 65 \text { in. (approx.) }
$$

## 6. MEASURED DISPLACEMENTS

Replicate measurements of displacements have been made on three pavement sections and are shown in Figures 11,12 and 13 . In each of these figures the layer thicknesses determined in the measurement holes are shown at the top, contours of equal vertical displacement, $w$, are shown in the center, and contours of equal horizontal displacement, $u$, are shown at the bottom. The data used to prepare these figures are given in Appendix A.

Observed w values are positive everywhere in all plots; thus all points had a component of motion downward. Both positive and negative values were found for $u$. Positive values indicate a component of motion directed outward from the load axis; negative values indicate motion toward it.

For all three sections the fields shown for replication 1 are very similar to those for replication 2 . The differences between the replications are quite small in comparison to the differences between sections. The main difference between sections that can be seen in the $w$ fields is in the magnitude near the load. More striking differences between sections appear in the u-fields. The general magnitude of the displacements in the three sections shown are clearly related to the designs; that is, the magnitudes are in inverse order of pavement strength.

Figure 14 shows $w$ and $u$ fields for two assumed homogeneous elastic half-spaces which have values of Poisson's ratio of 0.5 and 0.25 respectively. To prepare these fields, displacements were calculated using the point load equations for $w$ and $u$ given in Reference 11 . The vertical


Figure 11: Displacement fields measured in section 25. Numerical values on contours denote displacements in microinches (inches $\times 10^{-6}$ ).


Figure 12: Displacement fields measured in section 31. Numerical values on contours denote displacements in microinches (inches $\times 10^{-6}$ ).


Figure 13: Displacement fields measured in section 32. Numerical values on contours denote displacements in microinches (inches $\times 10^{-6}$ ).


Figure 14: Computed displacement fields for homogeneous isotropic elastic half spaces. Numerical values on contours denote displacements in microinches (inches $\times 10^{-6}$ ).
displacement is positive everywhere for both cases; however, the horizontal displacement is positive everywhere only for the limiting case of Poisson's ratio equal to 0.5 . When Poisson's ratio has any value less than 0.5 a negative region occurs near the surface.

Figure 15 shows $w$ and $u$ fields for a pair of two-layer elastic systems. The two cases differ in that one is for Poisson's ratio equal to 0.5 in both layers and the other is for Poisson's ratio equal to 0.25 in both layers. Both cases are for a 19 inch thick top layer having an elastic modulus of 600,000 psi above an infinitely thick layer having an elastic modulus of 20,000 psi. The dimension of 19 inches was chosen to match the total design pavement thickness (depth to top of embankment) of section 25. The displacements shown were calculated by using a computer program developed by the Chevron Oil Company (12, 13) using a 1000 lb . load on a circular area having a radius of 1.41 inches. The radius approximates that of the contact area of a Dynaflect load wheel (14).

The measurements made on section 25 , Figure 1 , are somewhat similar to the fields computed for the two-layer elastic systems illustrated in Figure 15. The general shapes of both the $u$ and the $w$ fields are alike and the position of the zero contour for $u$ in both cases is approximately horizontal and about 10 inches from the pavement surface. Work toward developing elastic layered system fields to match the observed fields is continuing.


Figure 15: Computed displacement fields for two-layer elastic systems. Numerical values on contours denote displacements in microinches (inches $\times 10^{-6}$ ).

## 7. REPLICATION ERRORS

As previously mentioned, replicate measurements were made on opposite ends of a test section and their differences generally were found to be quite small when compared with differences between sections, as evidenced by Figures 11, 12 and 13. The differences between the measurements made on the same section are due to both the variability of the measuring process as well as the variability in the structural characteristics of the section at its two ends. In the measurement procedure used, all points were not replicated. Thus, in the determination of the replication errors only the points which were replicated could be compared.

Plots of the replication errors (half the difference between the observations) versus the mean observation (half the sum of the observations) are shown in Figures 16,17 and 18 . Also shown on these plots are the percentage error lines which include three-fourths of the replication errors. As can be seen in these figures the data are somewhat biased as indicated by sloping trends in many of the plots. This indicates a consistant difference between the two ends of a section. Nevertheless when disregarding the reasons for the errors, the errors found in w are very small when compared to the range of the measured values and the errors found in $u$ are thought to be acceptable. The larger percentage errors found in $u$ are chiefly due to the fact that the relative magnitude of $u$ changes much more rapidly within the measured field than does the relative magnitude of $w$. This is evidenced by the crowding of the contour lines in the plots of the u-fields, Figures 11, 12 and 13.



Figure 16: Replication errors for section 25 (half the difference between observations) versus mean observations. Scales are in microinches. Multiple occurrences of points are indicated by number.



Figure 17: Replication errors for section 31 (half the difference between observations) versus mean observations. Scales are in microinches. Multiple occurrences of points are indicated by number.



Figure 18: Replication errors for section 32 (half the difference between observations) versus mean observations. Scales are in microinches. Multiple occurrences of points are indicated by number.

Table 1 is a summary of the replication measurements. It shows the average, the average absolute, and the range of the mean observations. From these values one can note that the sections measured were very different. The table also contains the maximum absolute and the root mean square of the replication errors as well as the percentage error values which will include half and three-fourths of the errors. Values in the last column are displayed graphically in Figures 16,17 and 18 .

Table 1: Summary of Replication Measurements

|  |  |  |  | Mean Observation ${ }^{1}$ |  |  | Replication Error ${ }^{2}$ |  | Percent Error ${ }^{3}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Section | Variable <br> Measured | Number of Comparisons | Average | Average Absolute | Range | Maximum <br> Absolute | Root Mean Square | $1 / 2$ of Errors. < | $3 / 4$ of Errors < |
|  | 25 | w | 98 | 223.6 | 223.6 | 31 to 424 | 57 | 26.4 | 10 | 12 |
|  | 25 | u | 104 | 4.1 | 15.6 | -44 to 36 | 13 | 2.9 | 10 | 20 |
|  | 31 | w | 196 | 301.4 | 301.4 | 30 to 1545 | 303 | 52.8 | 5 | 8 |
|  | 31 | u | 182 | 33.4 | 51.3 | -210 to 166 | 97 | 13.6 | 10 | 19 |
| $\underset{\underset{i}{1}}{\underset{i}{\omega}}$ | 32 | w | 112 | 433.9 | 433.9 | 30 to 2912 | 307 | 60.9 | 3 | 6 |
|  | 32 | u | 89 | 94.6 | 123.4 | -686 to 556 | 126 | 34.0 | 13 | 20 |
| 1 Mean of two replicated observations, $\left(w_{1}+w_{2}\right) / 2$ or $\left(u_{1}+u_{2}\right) / 2$. |  |  |  |  |  |  |  |  |  |  |
| 2 One half of the difference between two replicated observations, $\left(w_{1}-w_{2}\right) / 2$ or $\left(u_{1}-u_{2}\right) / 2$. |  |  |  |  |  |  |  |  |  |  |
| ${ }^{3}$ Replication error divided by mean observation, expressed as a percentage. |  |  |  |  |  |  |  |  |  |  |

## 8. CONCLUSIONS

From the results to date in this study the following conclusions appear warranted:

1. A practical fieldworthy measuring technique has been developed for use with the Dynaflect to observe the displacement vector throughout the body of a pavement section.
2. Replication errors observed on a test section are reasonably sma11 compared to variations between sections.
3. The observed vector displacement fields resemble fields computed for a layered elastic system to which an equal static load is applied.
4. It appears feasible to determine for each section a set of elastic layers for which the computed displacement fields will substantially match the observations.
5. Examination of the data indicates that it should be possible to formulate a useful and practical mathematical model representing the displacement response of the several pavement sections.

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## APPENDIX A

Included in this appendix are lists of the components, $w$ and $u$ respectively, for three pavement sections. These values are measurements transformed to represent values which would have been observed for a single load point as explained in Section 4. The drilling record for each measurement hole is also given.

## SECTION 25 REPLICATION 1

W - DATA (MICRO-INCHES) FOR SINGLE 1000 LB. LOAD



SECTION 25 REPLICATION 1
U - DATA (MICRO-INCHES) FOR SINGLE 1000 LB. LOAD



SECTION 25 REPLICATION 2
W - DATA (MICRO-INCHES) FOR SINGLE 1000 LB. LOAD



## SECTION 25 REPLICATIDN 2 <br> U - DATA (MICRO-INCHES) FOR SINGLE 1000 LB. LOAD




## SECTION 31 REPLICATION 1 <br> W - DATA (MICRO-INCHES) FOR SINGLE 1000 LB. LOAD



## SECTION 31 REPLICATION 1 <br> U - DATA (MICRO-INCHES) FOR SINGLE 1000 LB. LOAD



```
    SECTION 31 REPLICATION 2
H - DATA (MICRO-INCHES) FOR SINGLE 1000 LB. LOAD
```

|  | $\begin{gathered} \text { DEPTH } \\ Z \end{gathered}$ |  |  |  | $R A D I A L$ |  | D | S T | NCE |  | (IN.) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | (IN.) | 10.0 | 11.7 | 15.6 | 20.6 | 26.0 | 37.4 | 49.0 | 60.8 | 72.7 | 96.5 | 120.4 | 144.3 | . 3 | . 2 |
|  | 0.0 | 1393 | 1515 | 1212 | 999 | 757 | 499 | 333 | 224 | 136 | 74 | 46 | 43 | 36 | 30 |
|  | 0.7 | 1818 | 1454 | 1272 | 1030 | 757 | 499 | 333 | 224 | 136 | 75 | 48 | 43 | 36 | 30 |
|  | 8.0 | 1393 | 1363 | 1121 | 969 | 742 | 515 | 333 | 224 | 115 | 72 | 48 | 43 | 36 | 31 |
|  | 13.0 | 1242 | 1272 | 1090 | 939 | 727 | 530 | 333 | 224 | 142 | 78 | 51 | 45 | 36 | 30 |
|  | 17.0 | 1242 | 1121 | 969 | 848 | 681 | 499 | 327 | 206 | 139 | 78 | 53 | 46 | 36 | 31 |
|  | 24.0 | 878 | 848 | 818 | 742 | 575 | 469 | 303 | 212 | 139 | 84 | 54 | 45 | 37 | 33 |
| > | 29.0 | 696 | 742 | 696 | 606 | 515 | 393 | 290 | 212 | 133 | 90 | 54 | 46 | 37 | 31 |
| $\infty$ | 36.0 | 515 | 560 | 530 | 515 | 454 | 363 | 275 | 206 | 139 | 87 | 57 | 48 | 36 | 31 |
|  | 41.0 | 530 | 515 | 454 | 442 | 381 | 306 | 254 | 190 | 130 | 84 | 56 | $\cdots 48$ | 36 | 30 |
|  | 48.0 | 448 | 384 | 372 | 360 | 318 | 290 | 224 | 172 | 121 | 87 | 57 | 48 | 36 | 31 |
|  | 53.0 | 363 | 348 | 333 | 312 | 303 | 263 | 218 | 163 | 124 | 90 | 60 | 51 | 37 | 31 |
|  | 50.0 | 287 | 284 | 278 | 266 | 233 | 206 | 175 | 151 | 118 | 84 | 60 | 49 | 36 | 30 |
|  | 65.0 | 260 | 242 | 248 | 224 | 212 | 212 | 175 | 151 | 109 | 84 | 60 | 51 | 36 | 31 |
|  | 72.0 | 199 | 196 | 199 | 199 | 181 | 172 | 151 | 133 | 106 | 81 | 57 | 48 | 36 | 31 |


| LAYER | R | N G |  | D A T A |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | DEPTH | Z | (IN.) | **** | MATERIAL | **** |
| NO. | FROM |  | TO |  |  |  |
| 1 | 0.0 |  | 0.7 | SURF | E TREATM |  |
| 2 | 0.7 |  | 8.0 | LIMES | DONE + CEM | NT |
| 3 | 8.0 |  | 75.0 | PLAST | C CLAY, | IST |
| 4 | 75.0 |  | 84.0 | PLAST | C Clay. |  |

## SECTION 31 REPLICATION 2 <br> U - DATA (MICRO-INCHES) FOR SINGLE 1000 LB. LOAD




## SECTION 32 REPLICATION 1 <br> W - DATA (MICRO-INCHES) FOR SINGLE 1000 LB. LOAD




## SECTION 32 REPLICATION 1 <br> U - DATA (MICRO-INCHES) FOR SINGLE 1000 LB. LOAD




## SECTION 32 REPLICATION 1 <br> U - DATA (MICRO-INCHES) FOR SINGLE 1000 LB. LOAD




## SECTION 32 REPLICATION 2 <br> W - DATA (MICRO-INCHES) FOR SINGLE 1000 LB. LOAD



| LAYER | $R$ | N G |  | D ATA |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | DEPTH | 2 | (IN.) | **** | MATERIAL | * *** |
| NO. | FROM |  | TO |  |  |  |
| 1 | 0.0 |  | 0.7 | SURF | E TREATM |  |
| 2 | 0.7 |  | 8.0 | LIMES | ONE (RAW) |  |
| 3 | 8.0 |  | 72.0 | PLAST | C CLAY, M | IST |

## SECTION 32 REPLICATION 2 <br> U - DATA (MICRO-INCHES) FOR SINGLE 1000 LB. LOAD





[^0]:    * Registered trademark, Radiation Engineering \& Manufacturing Company (REMCO), 7450 Winscott Road, Fort Worth, Texas.

[^1]:    Figure 6: Drill-rig used to bore 1-3/4 inch diameter holes for measurement of displacement vector fields.

